

Graphics Systems and Models

2ND WEEK, 2022



Graphics System

Wang

- Six major elements:

- *Input dev*

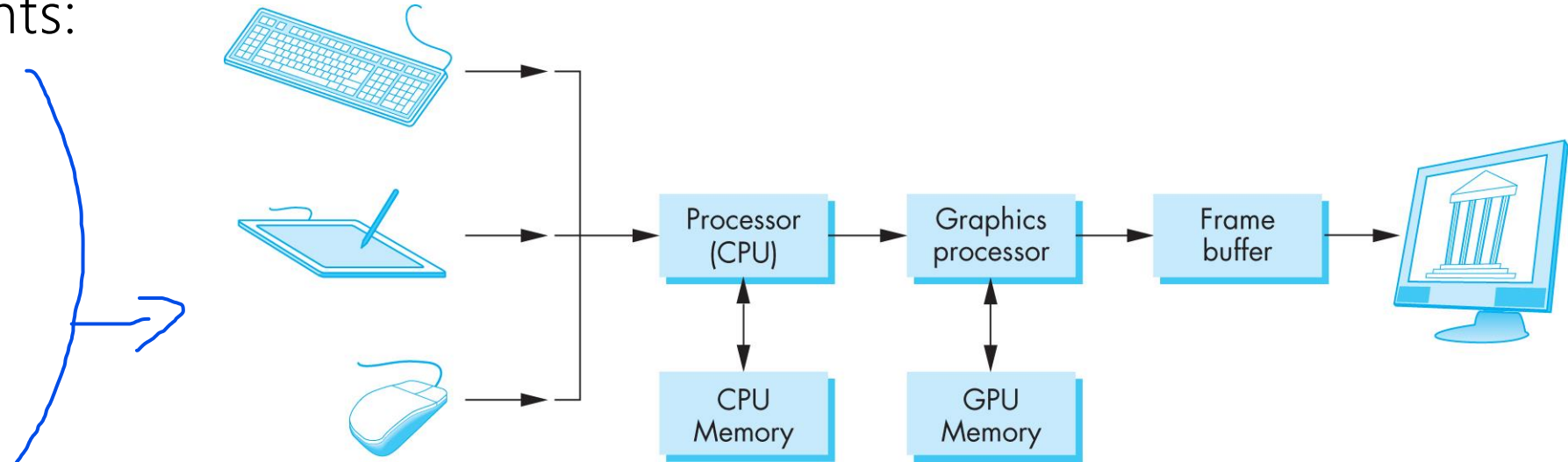
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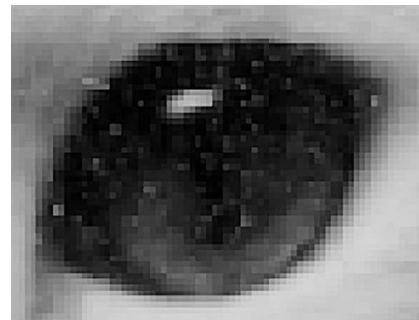
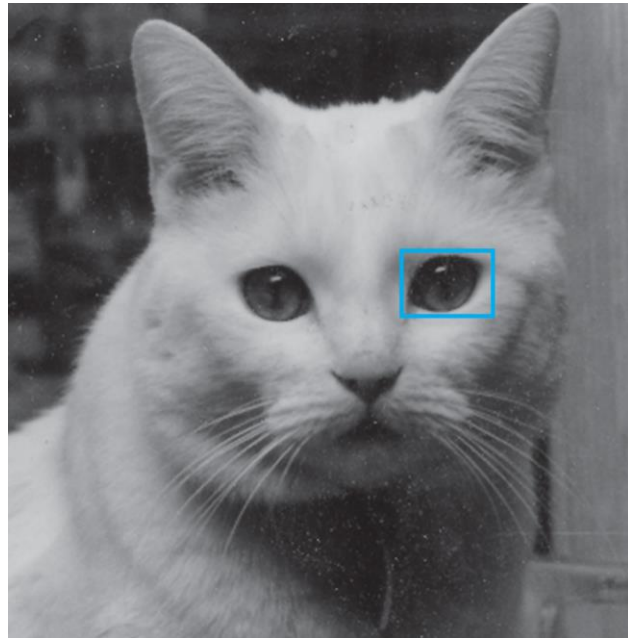


Input dev

A Graphics System

Pixels and Frame Buffers (1)


- Raster graphics
 - Image produced as an array (the raster) of picture elements (pixels) in the (a part of memory where the pixels are stored)



Pixels

Pixels and Frame Buffers (2)

- - The number of pixels in the frame buffer
 - To determine the detail that you can see in the image

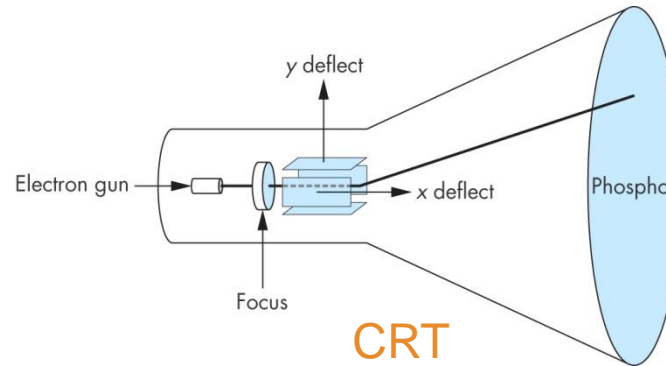
-  _____ or _____ of the frame buffer
- The number of bits that are used for each pixel
 - To determine how many colors can be represented
 - Ex) 8 bits per pixel: $2^8=256$ colors 24 bits (true-color system), 12 or more bits (HDR – High dynamic range)

The CPU and GPU

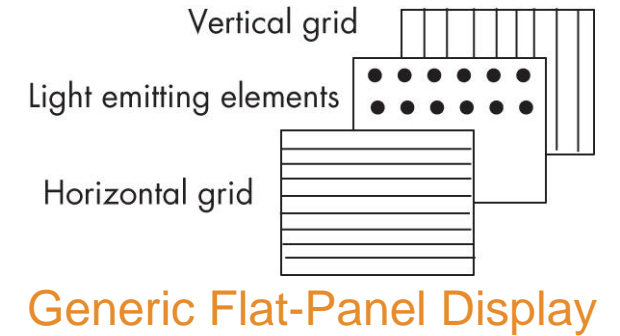
- _____(CPU)
 - Doing both the normal processing and the graphics processing
 - Rasterization or scan conversion
 - Conversion of geometric entities (such as lines, circles, and polygons) to pixel colors and locations in the frame buffer
- _____(GPU)
 - Custom-tailored to carry out specific graphics functions
 - High degree of parallelism

Output Devices

- Cathode-ray tube (CRT)



- Flat-panel monitors
 - Light-emitting diodes (LEDs), liquid-crystal displays (LCDs), and plasma panels
- Projection systems
 - Digital light projection (DLP)
- Hard-copy devices

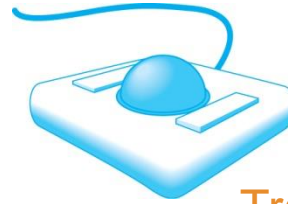


Input Devices

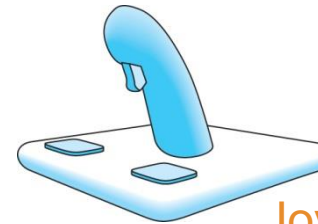
- Most graphics systems provide a keyboard and at least one other input device
 - Pointing devices



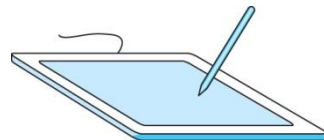
Mouse



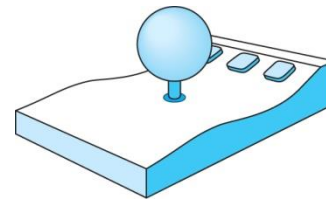
Trackball



Joystick



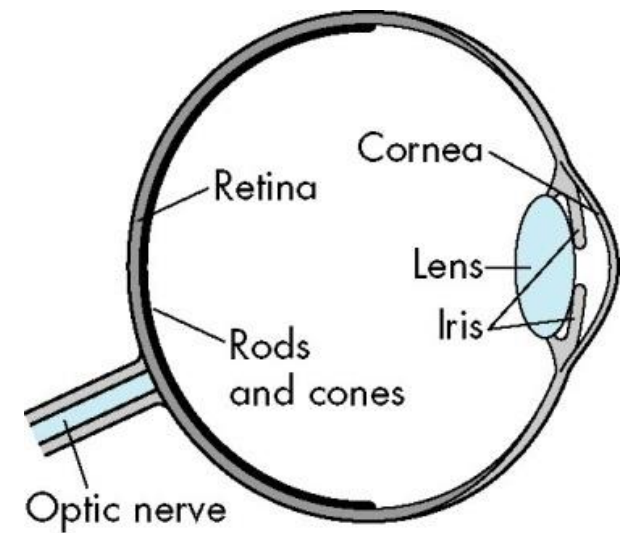
Data Tablet



Spaceball

Image Formation (1)

- There always has been analogous process how image are formed by physical imaging systems
 - Cameras
 - Microscopes
 - Telescopes
 - Human visual system
 - Rods and cones are light sensors
 - Rods – monochromatic, night vision
 - Cones – color sensitive
 - Three types of cones
 - Only three values (the tristimulus values) are sent to the brain



The Human Visual System

Image Formation (2)

- Elements of image formation
 - Independent of any viewer and of any image-formation process
 - _____ (_____)
 - To form the image of objects
 - _____ sources

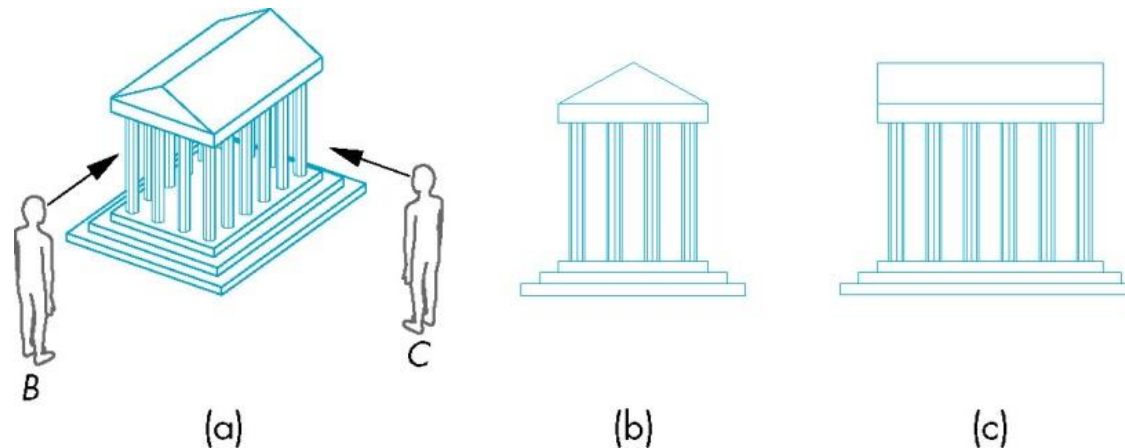
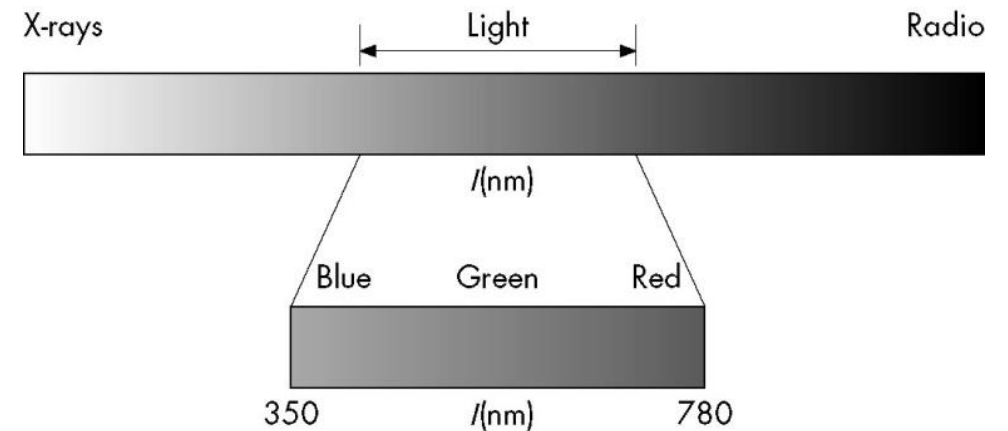


Image Seen by Three Different Viewers

Light and Images

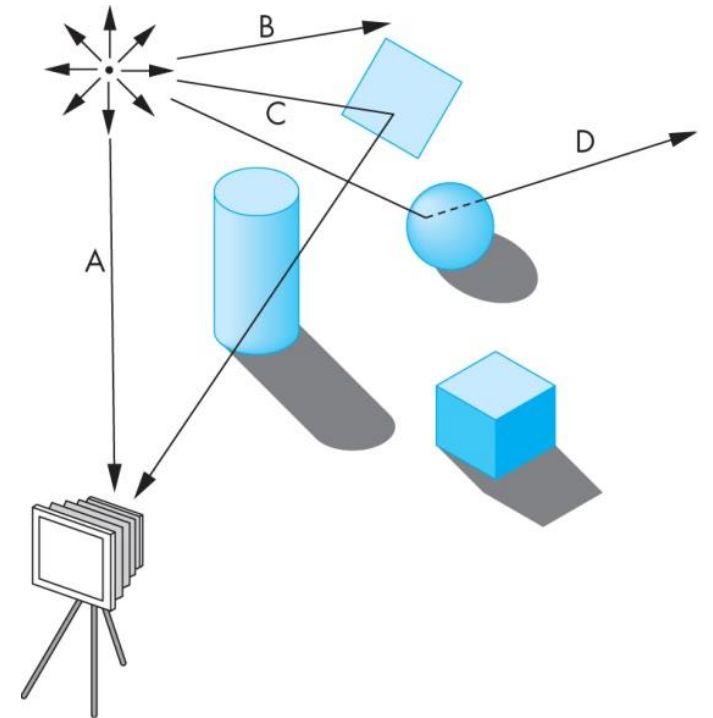
- Interaction between light and the surfaces of the objects
→ How much light enters the camera
- Visual Spectrum = visible light
 - Wavelengths in the range 350~780nm
 - Long wavelengths: reds
 - Short wavelengths: blues



The Electromagnetic Spectrum

Imaging Models

- - Image formation techniques
 - Following rays of light from a point source finding which rays enter the lens of the camera
- - Based on conservation of energy



Ray Interactions

Imaging Systems

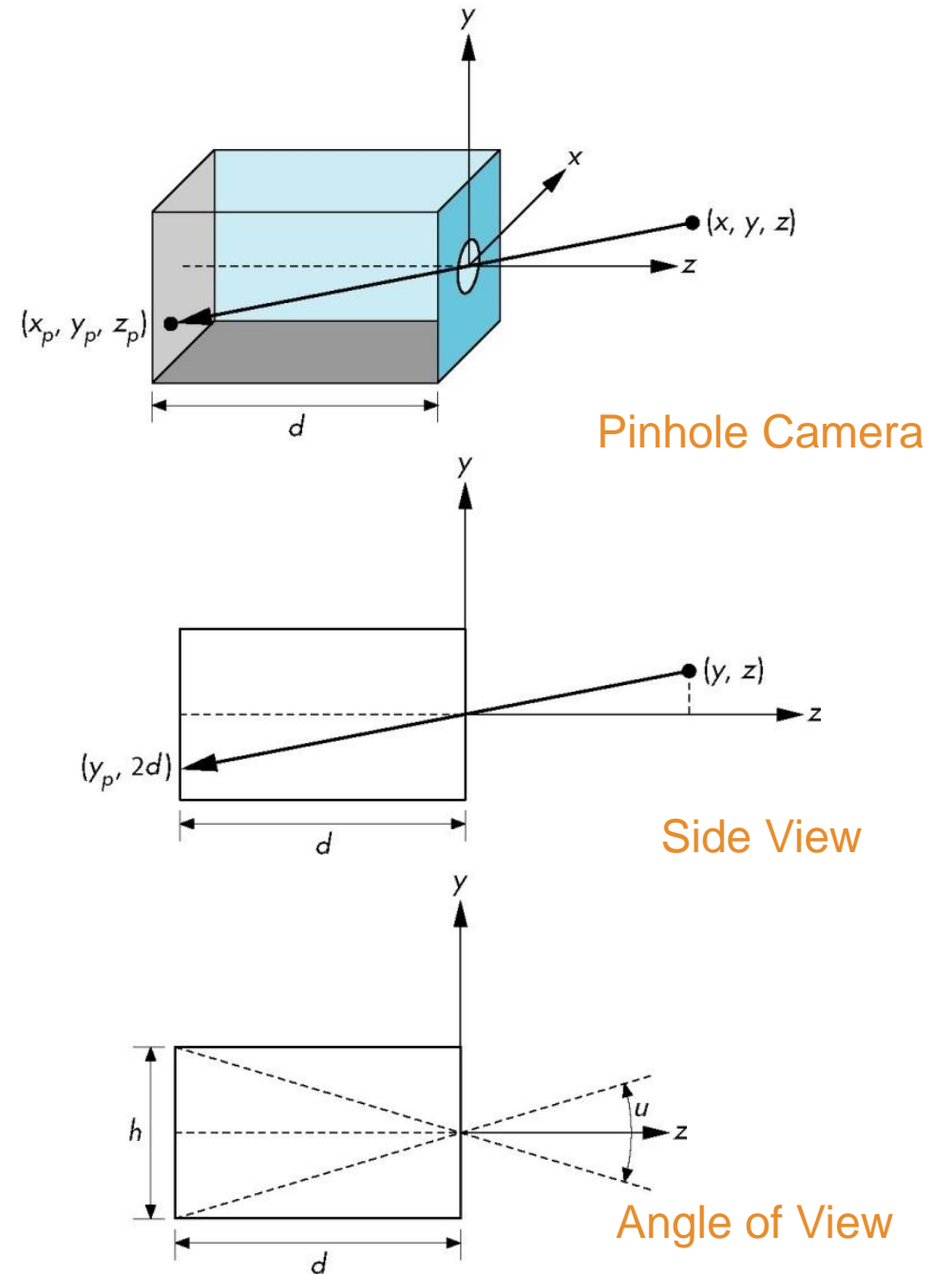
- Pinhole Camera

- Projection of point (x, y, z)

$$x_p = -\frac{x}{z/d} \quad y_p = -\frac{y}{z/d} \quad z_p = -d$$

- Field of view (angle of view)

$$\theta = 2 \tan^{-1} \frac{h}{2d}$$



정명준

Synthetic-Camera Model (1)

- Conceptual foundation for three-dimensional computer graphics



- Line from the center of lens to a point on the object



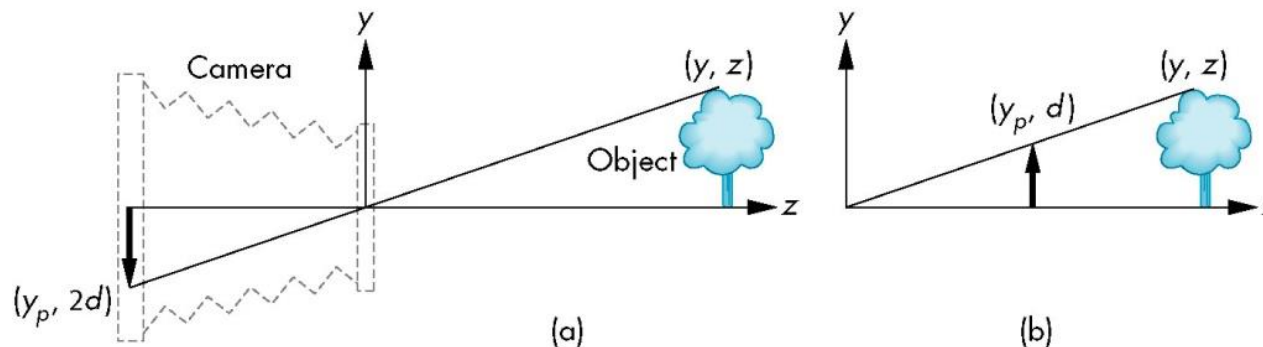
_____ (_____)

- The center of the lens



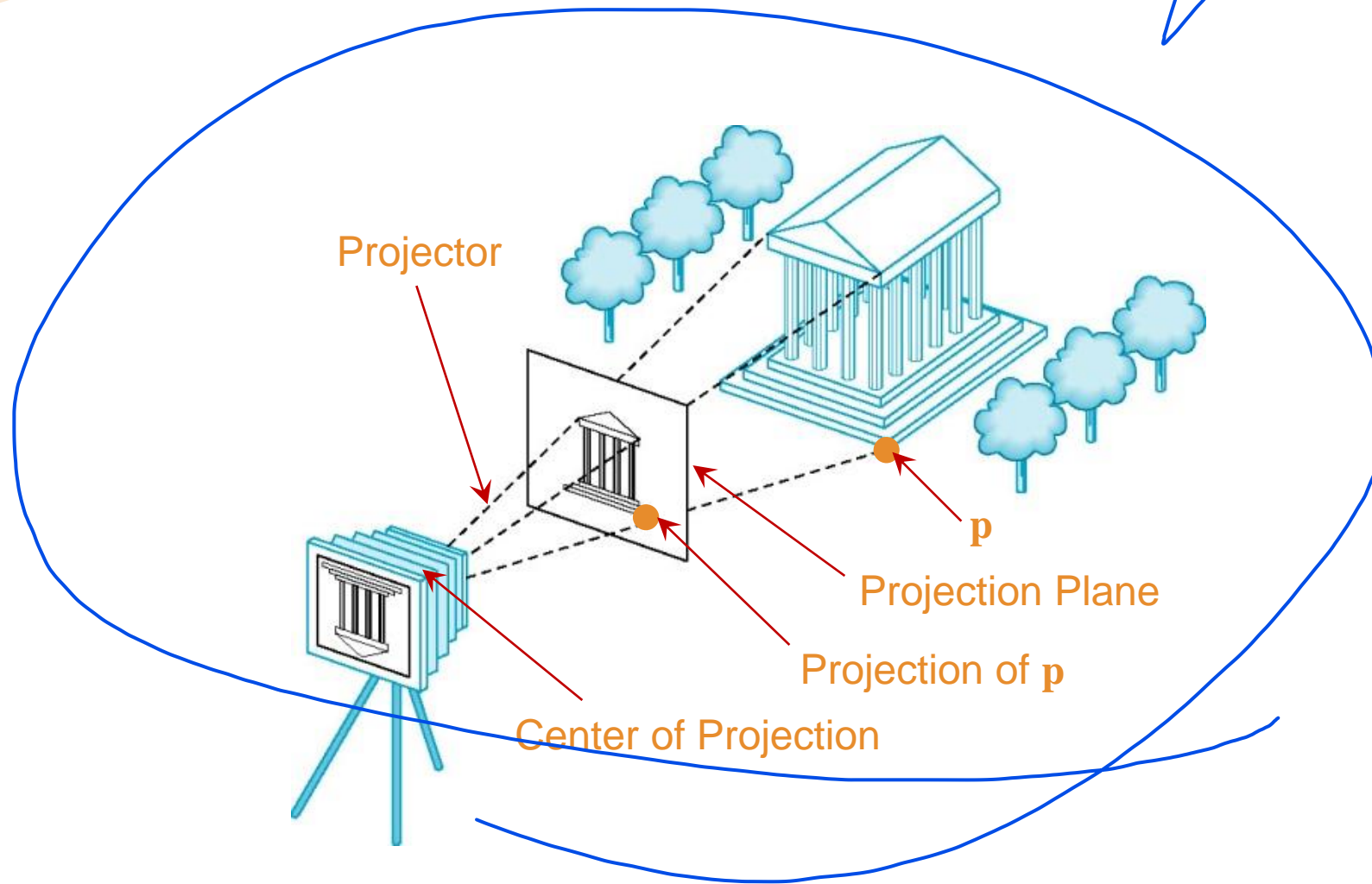
Projection plane

- Virtual image plane that are moved in front of the lens



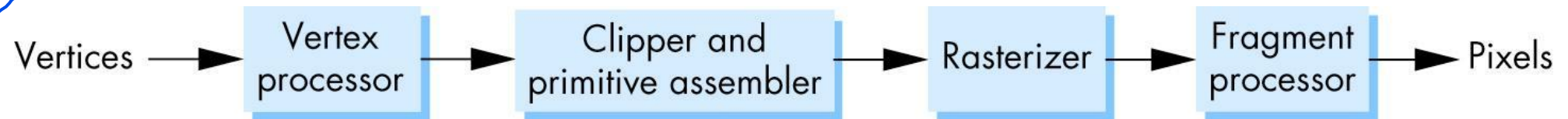
Equivalent views of image formation

Synthetic-Camera Model (2)



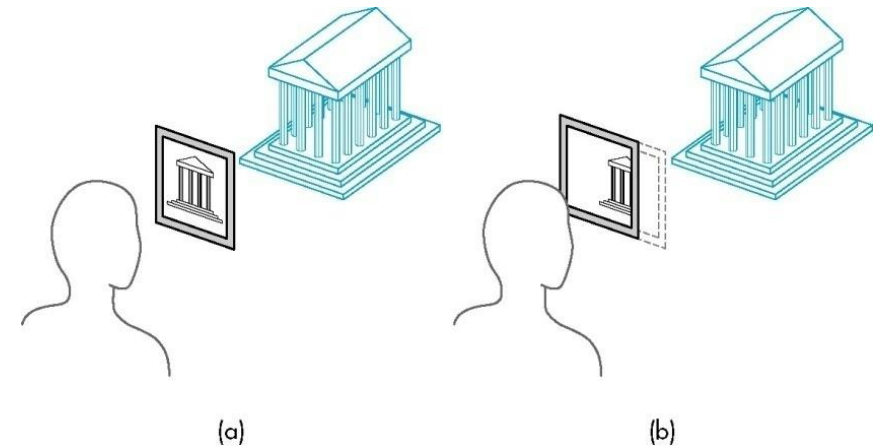
Graphics Architecture

- Graphics pipeline
 - Geometry – collection of primitive types and vertices



Geometric pipeline

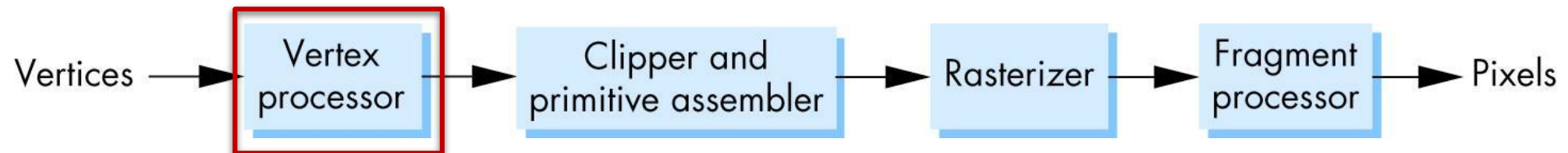
- - World and view transformation
 - Projection
 - Lighting



Clipping

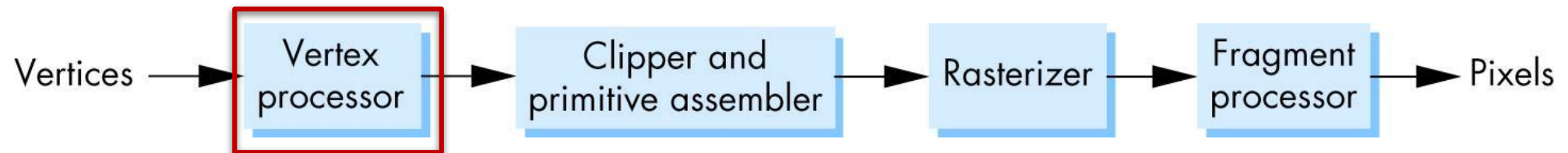
Vertex Processing (1)

- Much of the work in the pipeline is in converting object representations from one coordinate system to another
 - Object coordinates
 - Camera (eye) coordinates
 - Screen coordinates
- Every change of coordinates is equivalent to a matrix transformation
- Vertex processor also computes vertex colors



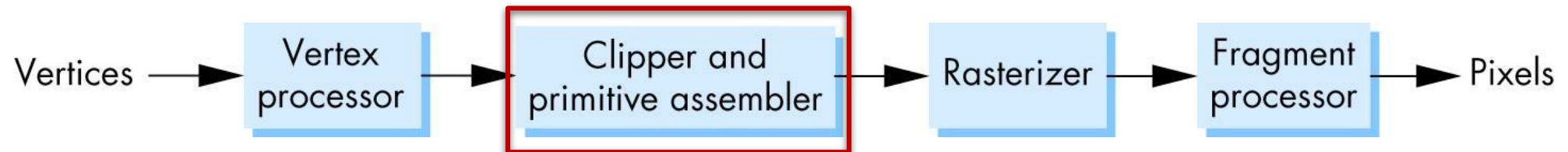
Vertex Processing (2)

- Projection is the process that combines the 3D viewer with the 3D objects to produce the 2D image
 - Perspective projection: all projectors meet at the center of projection
 - Parallel projection: projectors are parallel, center of projection is replaced by a direction of projection



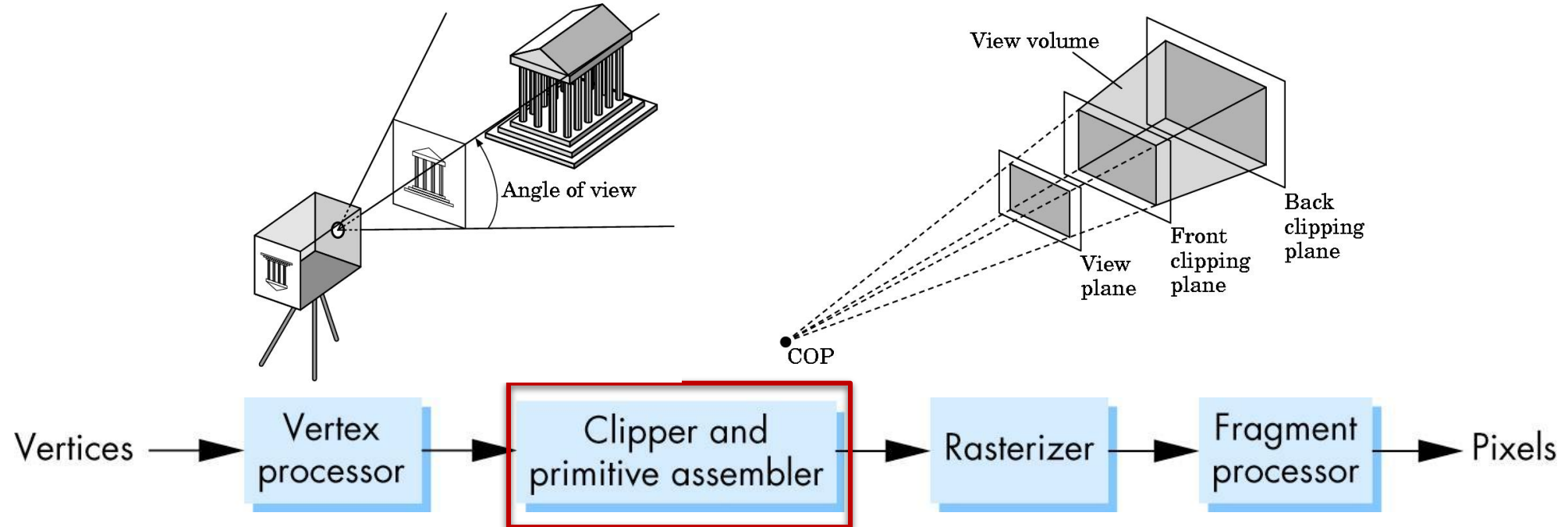
Primitive Assembly

- Vertices must be collected into geometric objects before clipping and rasterization can take place
 - Line segments
 - Polygons
 - Curves and surfaces



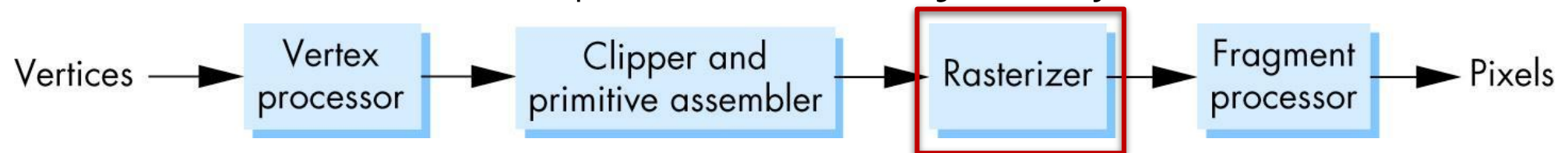
Clipping

- Just as a real camera cannot “see” the whole world, the virtual camera can only see part of the world or object space
 - Objects that are not within this volume are said to be clipped out of the scene



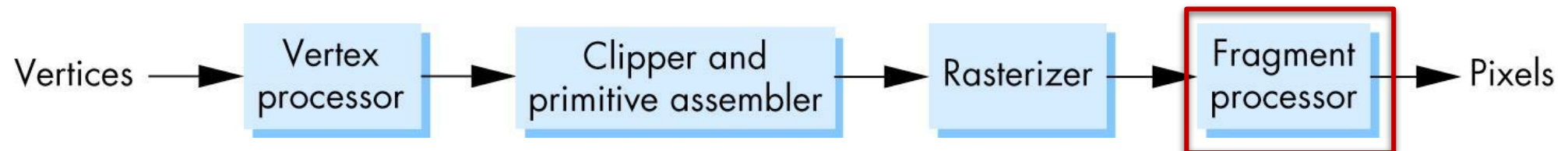
Rasterization

- If an object is not clipped out, the appropriate pixels in the frame buffer must be assigned colors
- Rasterizer produces a set of fragments for each object
- Fragments are “potential pixels”
 - Have a location in frame buffer
 - Color and depth attributes
- Vertex attributes are interpolated over objects by the rasterizer



Fragment Processing

- Fragments are processed to determine the color of the corresponding pixel in the frame buffer
- Colors can be determined by texture mapping or interpolation of vertex colors
- Fragments may be blocked by other fragments closer to the camera
 - Hidden-surface removal



☆ 중점사항 정리

Summary

- Graphics system
- ☆ $P_{ixels} \rightarrow R_{aster} \rightarrow F_{ramebuffer}$
 - Resolution, depth (precision)
- CPU vs. GPU
- Image formation
- Synthetic-camera model
- Graphics pipeline

