



Most recent transform: 0.0 Oldest transform: 0.0

robot1/camera\_rgb\_optical\_frame

robot2/map Broadcaster: default authority Average rate: 7.481 Buffer length: 0.401 Most recent transform: 6.404 Oldest transform: 6.003 robot2/odom Broadcaster: default authority Average rate: 30.543 Buffer length: 0.884 Most recent transform: 5.587 Oldest transform: 4.703 robot2/base footprint Broadcaster: default authority Average rate: 10000.0 Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 robot2/base\_link Broadcaster: default authority Average rate:  $10\overline{0}00.0$ Average rate: 10000.0 Average rate: 10000.0 Average rate: 15.931 Average rate: 15.931 Buffer length: 0.816 Buffer length: 0.0 Buffer length: 0.0 Buffer length: 0.0 Buffer length: 0.816 Most recent transform: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Most recent transform: 5.519 Most recent transform: 5.519 Oldest transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 Oldest transform: 4.703 Oldest transform: 4.703 robot2/wheel left link robot2/wheel\_right\_link robot2/imu link robot2/base\_scan

Broadcaster: default authority

Average rate:  $10\overline{0}00.0$ 

Most recent transform: 0.0

Oldest transform: 0.0

robot2/caster back right link

Buffer length: 0.0