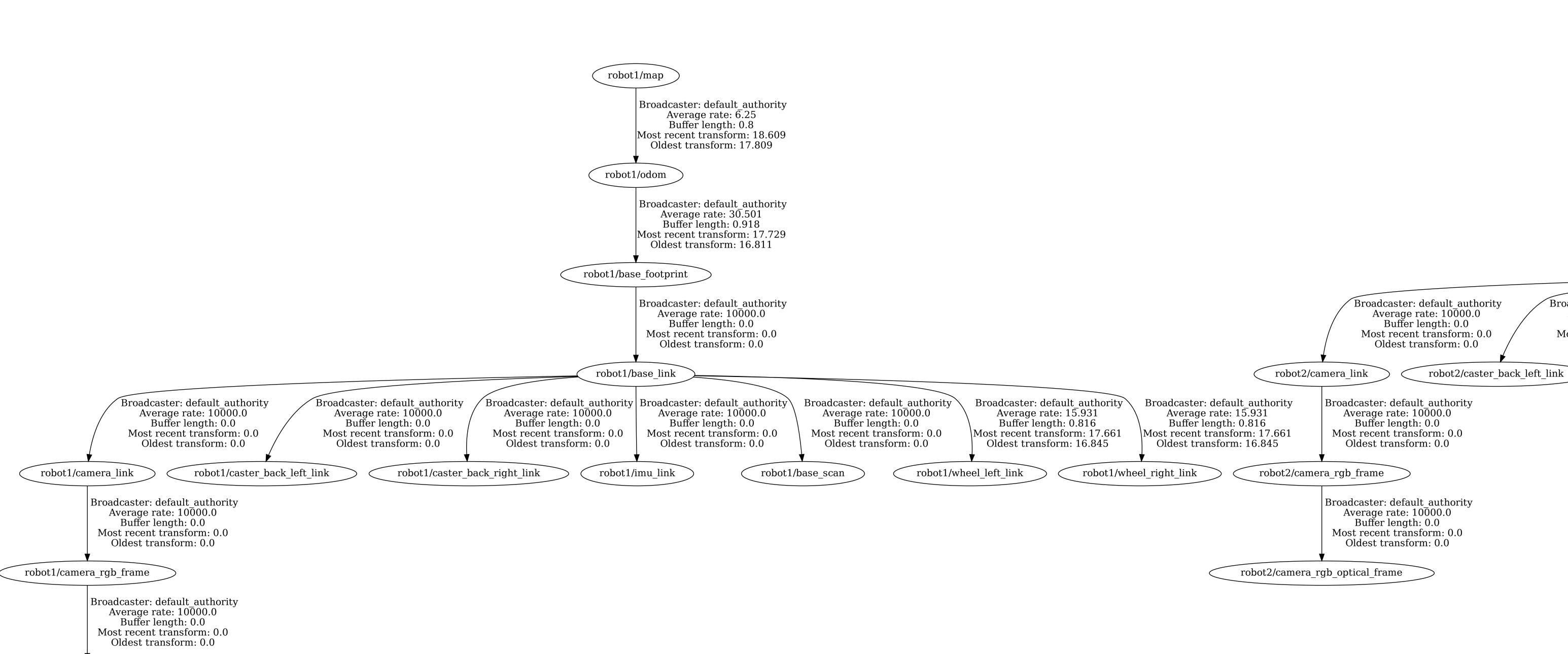


Recorded at time: 1736590647.1821969

robot1/camera_rgb_optical_frame



robot2/map Broadcaster: default authority Average rate: 6.25 Buffer length: 0.8 Most recent transform: 18.609 Oldest transform: 17.809 robot2/odom Broadcaster: default authority Average rate: 30.501 Buffer length: 0.918 Most recent transform: 17.715 Oldest transform: 16.797 robot2/base footprint Broadcaster: default authority Average rate: 10000.0 Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 robot2/base_link Broadcaster: default authority Average rate: $10\overline{0}00.0$ Average rate: $10\overline{0}00.0$ Average rate: 10000.0 Average rate: 15.837 Average rate: 15.837 Buffer length: 0.884 Buffer length: 0.0 Buffer length: 0.0 Buffer length: 0.0 Buffer length: 0.884 Most recent transform: 17.715 Most recent transform: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Most recent transform: 17.715 Oldest transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 Oldest transform: 16.831 Oldest transform: 16.831 robot2/wheel left link robot2/wheel_right_link robot2/imu link robot2/base_scan

Broadcaster: default authority

Average rate: $10\overline{0}00.0$

Most recent transform: 0.0

Oldest transform: 0.0

robot2/caster back right link

Buffer length: 0.0