



robot2/map Broadcaster: default authority Average rate: 5.828 Buffer length: 1.201 Most recent transform: 90.217 Oldest transform: 89.016 robot2/odom Broadcaster: default authority Average rate: 30.166 Buffer length: 1.326 Most recent transform: 89.342 Oldest transform: 88.016 robot2/base footprint Broadcaster: default authority Average rate: 10000.0 Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 robot2/base\_link Broadcaster: default authority Average rate:  $10\overline{0}00.0$ Average rate:  $10\overline{0}00.0$ Average rate: 10000.0 Average rate: 15.523 Average rate: 15.523 Buffer length: 1.224 Buffer length: 0.0 Buffer length: 0.0 Buffer length: 0.0 Buffer length: 1.224 Most recent transform: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Most recent transform: 89.274 Most recent transform: 89.274 Oldest transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 Oldest transform: 88.05 Oldest transform: 88.05 robot2/wheel\_right\_link robot2/imu link robot2/base\_scan robot2/wheel left link

Broadcaster: default authority

Average rate:  $10\overline{0}00.0$ 

Most recent transform: 0.0

Oldest transform: 0.0

robot2/caster back right link

Buffer length: 0.0

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robot1/camera\_rgb\_optical\_frame

Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0