

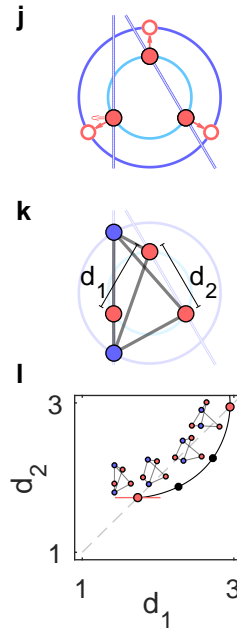
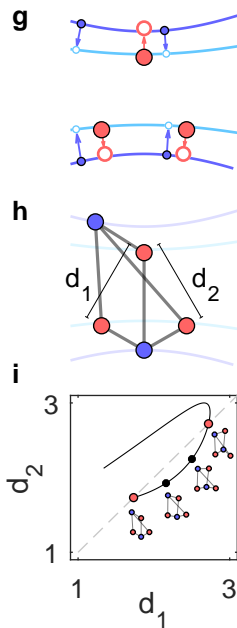
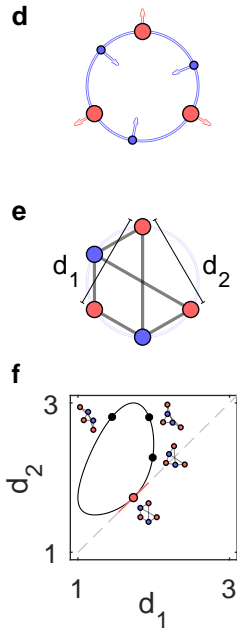
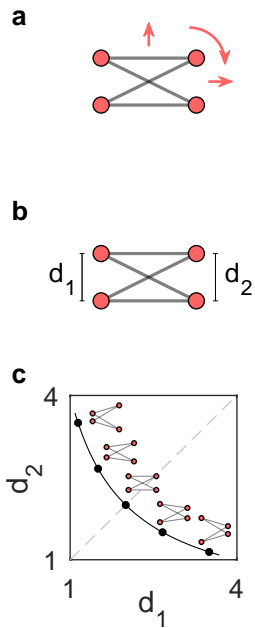
Design
↓
Construct
↓
Trajectory

4-bar linkage

Velocity

Displacement

Velocity + Displacement



- designed node
- variable node
- designed motion
- variable motion
- || variable positions
- designed distance