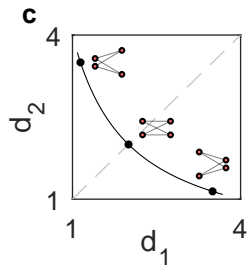
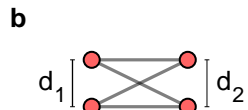
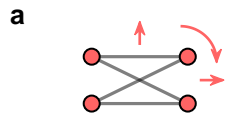
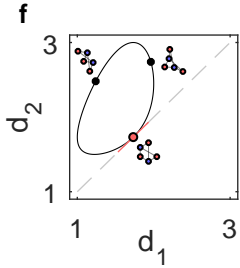
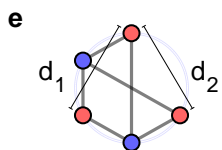
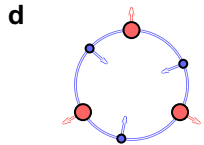


Design  
↓  
Construct  
↓  
Trajectory

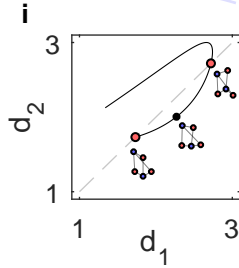
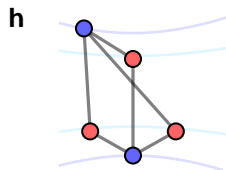
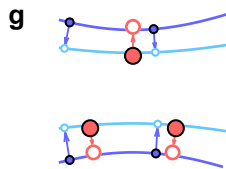
4-bar linkage



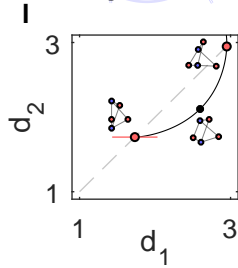
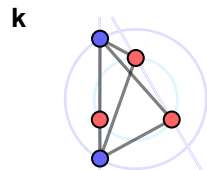
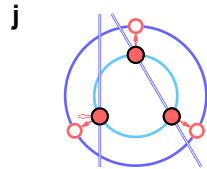
Velocity



Displacement



Vel. + Disp.



● designed node

● variable node

→ designed motion

→ variable motion

||| variable positions

—●— designed distance