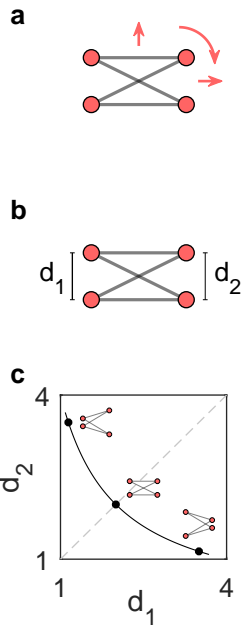
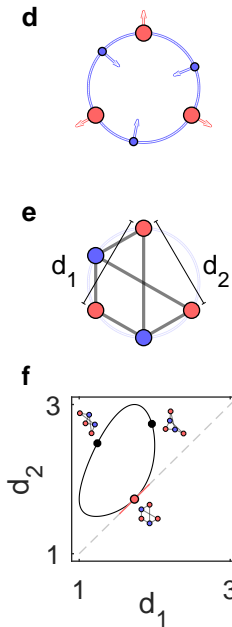


Design
↓
Construct
↓
Trajectory

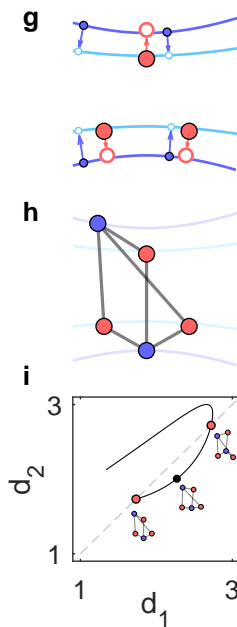
4-bar linkage



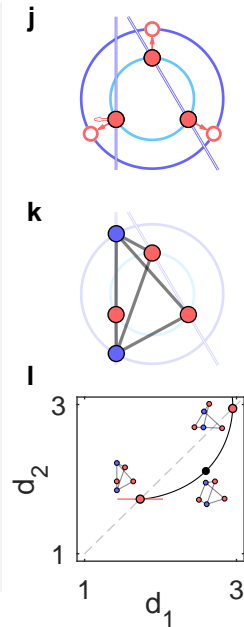
Velocity









Displacement



Vel. + Disp.



-  designed node
-  variable node
-  designed motion
-  variable motion
-  variable solutions
-  designed distance