

ALPHA GO

α - β search + heuristics



too hard!

Solutions ?

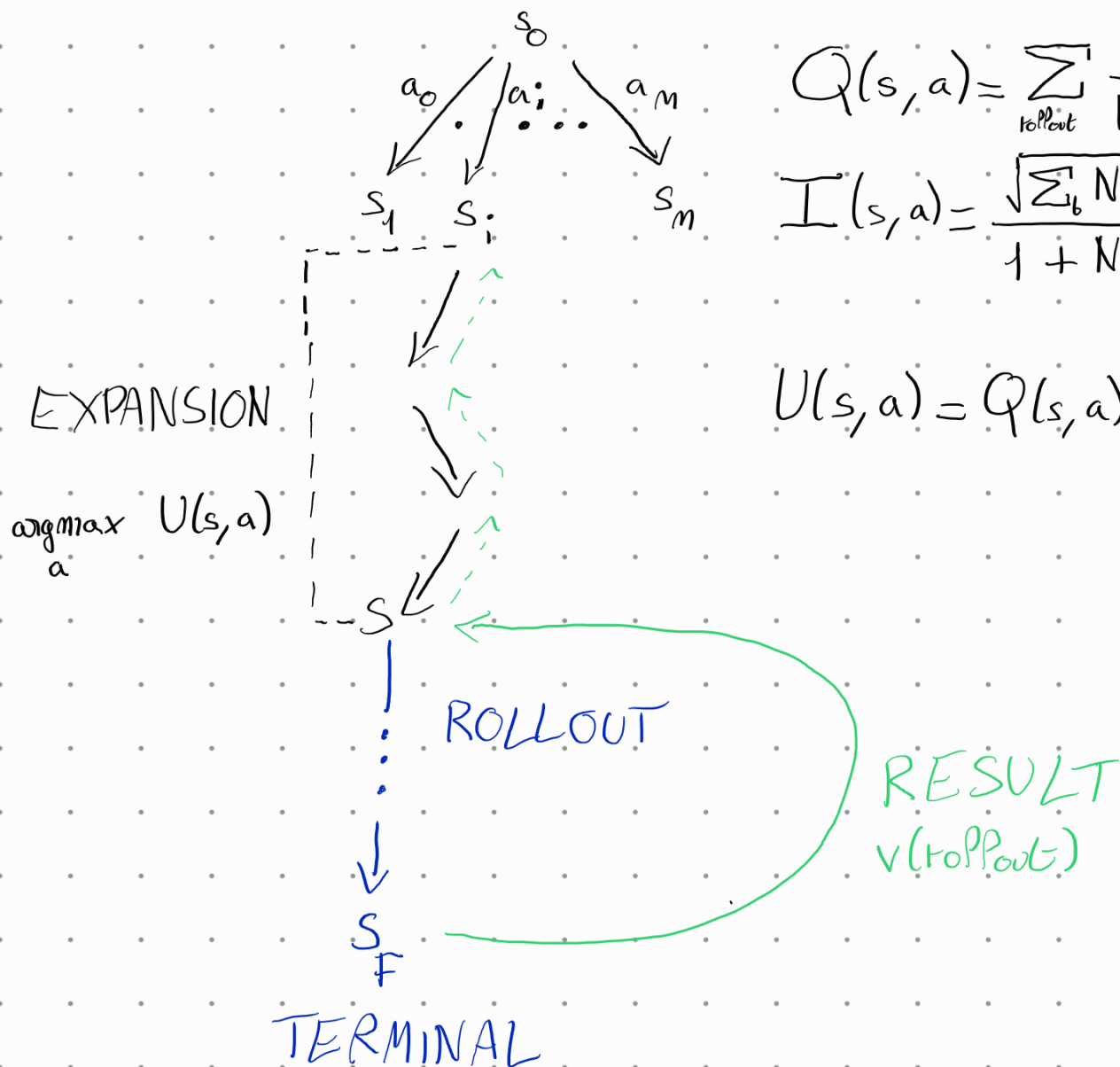
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When branching factor is high

MCTS (1940s) is great!

(UCB, 2002)



$$Q(s, a) = \sum_{\text{rollout}} \frac{1}{N(s, a)} \cdot v(\text{rollout})$$

$$I(s, a) = \frac{\sqrt{\sum_b N(s, b)}}{1 + N(s, a)}$$

$$U(s, a) = Q(s, a) + c_T \cdot I(s, a)$$

We play with $\pi_s(a) = \frac{N(s, a)^T}{\sum_b N(s, b)^T}$

ISSUES:

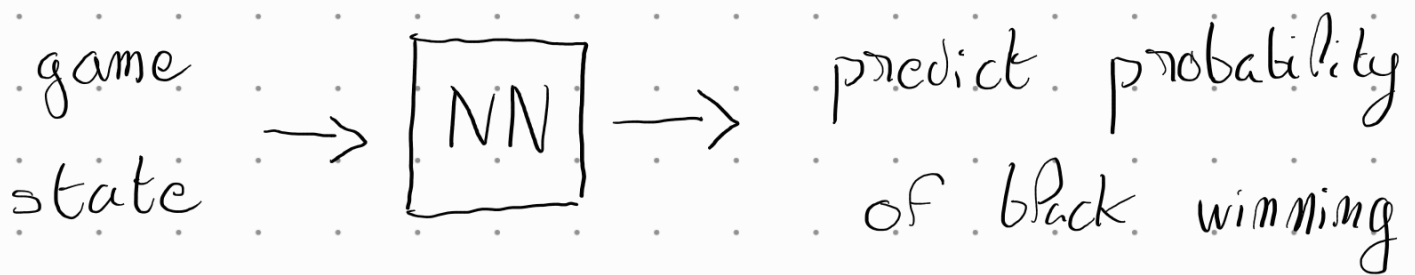
- Random policy
 - Pot of games

So Pet's use

"modern tech."

Neural Networks

Basic Idea :



Supervised Training on PRO Games

David Silver (DeepMind)

- 4 weeks on 50 GPUs
- 12 layer CNN
- 57% accuracy on test set
(SOTA was 44%)

Reinforcement Learning

Train with RL with policy gradient

Self-Play (bootstrap f previous NN)

David Silver

- 1 week on 50 GPUs

- 80% accuracy

↳ amateur level



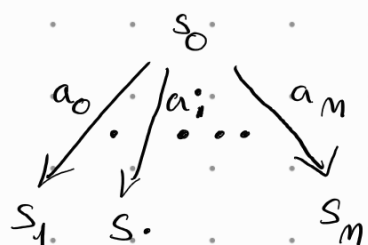
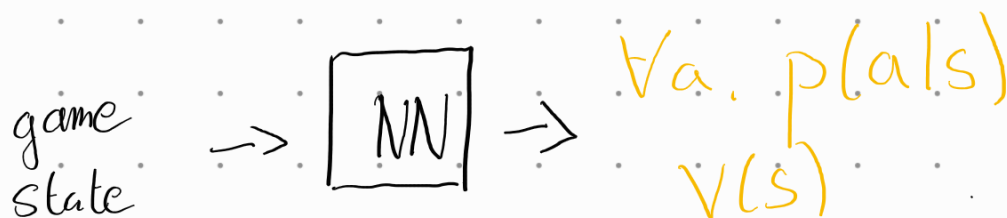
SOLUTION

?

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Gotta Mix'em app!

MCTS + NN + RL = Alpha Go



$$Q(s, a) = \sum_{s'} \frac{1}{N(s, a)} \cdot v(s')$$

$$I(s, a) = \frac{\sqrt{\sum_b N(s, b)}}{1 + N(s, a)} p(a|s)$$

$$U(s, a) = Q(s, a) + c_T \cdot I(s, a)$$

EXPANSION

$$\operatorname{argmax}_a U(s, a)$$



$v(s)$ RESULT

(PUCT)

We play with $\pi_s(a) = \frac{N(s, a)^T}{\sum_b N(s, b)^T}$

$v(s)$: value function

↳ better topouts estimations

$p(a|s)$: policy function

↳ bias exploration towards
promising branches