

# Publication Overview

2004 – 2020

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`https://github.com/jkerdels/pub\_overview`

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# Decentral Control in Robot Teams

Bar

Foo

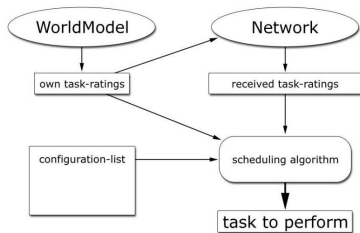


Figure from Ziegler et al. [1].

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[1] J. Ziegler et al. *Virtual Robot - Adaptive Ressource Management in Robot Teams*. Technical Report 0204. presented at International RoboCup Worldchampion, Lissboa, July 2004. University of Dortmund, 2004 [PDF](#) [bibtex](#)

[2] I. Dahm et al. "Decentral control of a robot-swarm". In: *Autonomous Decentralized Systems, 2005. ISADS 2005. Proceedings*. Apr. 2005, pp. 347–351. DOI: 10.1109/ISADS.2005.1452083

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Bar

Foo

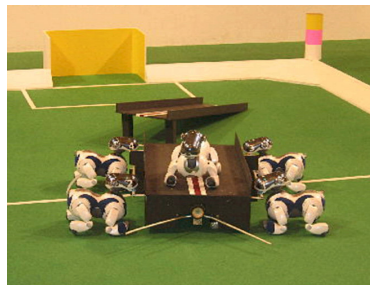


Figure from Dahm et al. [3].

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[3] [Ingo Dahm et al.](#) *Virtual Robot: Automatic Analysis of Situations and Management of Resources in a Team of Soccer Robots.* [Tech. rep. PG 442 Final Report.](#) [University of Dortmund,](#) 2004 [PDF](#) [bibtex](#)

# References I

- [1] J. Ziegler et al. *Virtual Robot - Adaptive Ressource Management in Robot Teams*. Technical Report 0204. presented at International RoboCup Worldchampion, Lissboa, July 2004. University of Dortmund, 2004.
- [2] I. Dahm et al. "Decentral control of a robot-swarm". In: *Autonomous Decentralized Systems, 2005. ISADS 2005. Proceedings*. Apr. 2005, pp. 347–351. DOI: 10.1109/ISADS.2005.1452083.
- [3] Ingo Dahm et al. *Virtual Robot: Automatic Analysis of Situations and Management of Resources in a Team of Soccer Robots*. Tech. rep. PG 442 Final Report. University of Dortmund, 2004.