

Robot Eyes Report

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Abstract

The team were given the task of creating a disparity map from a pair of stereo images using techniques that were talked about in class.

References

1 Introduction

2 Background

3 Description of Algorithm

4 Description of Images

5 Results and Comments

6 Conclusion

The team had never worked with matlab before and were pleased with what they were able to achieve within this short space of time.

7 Future Work

If the team had more time available we would like to.

Acknowledgements

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