

User Manual (Fiat Visio)

1. Introduction

1.1 Purpose

The user manual explains the use and operation of our code and allows for any parties to setup and execute our code successfully. The first draft of this document was written on May 1, 2017 and finalized on May 18, 2017. The authors of this document are: Daniel Kim and Jason Ligon. Daniel was responsible for sections 3, 4 and part of 5 whereas Jason was responsible for sections 1, 2, and also part of 5.

1.2 Definitions, Acronyms and Abbreviations

There will be some use of acronyms and abbreviations used throughout the document in order to provide brevity and more concise reading. The following acronyms and abbreviations are:

- CNN - convolutional neural network
- NN - artificial neural network
- R-CNN - region-based convolutional neural network
- MOT - Multiple Object Tracking database
 - MOT16 - Multiple Object Tracking database from year 2016

2. Hardware Configuration

The only hardware requirements required to run our code are the same requirements to run MATLAB, as that is the environment that our code uses. The requirements from the MATLAB state:

- Processors: any Intel or AMD x86-64 processor
- Memory (RAM): 2GB, 4GB with Simulink
- Disk Space: 4-6GB

However, due to the implementation and usage of NN being computationally intensive, the following recommended requirements are:

- Processor: any 4 core Intel or AMD x86-64 processor
- Memory (RAM): 4GB
- Graphics: dedicated graphics card with at least 1GB GPU memory
- Disk Space: 7GB

3. System Parameters

Our code does not require for any parameters to be entered during runtime. However, the file and folder locations of the training images and test images are hardcoded into our code and scripts and must be set to proper values when running the code on machines that the code was not written on. Both ROICreate.m and RCNN.m require folder paths to be set properly for the code to execute. At the end of the execution of ROICreate.m, a table with the title "Traffic" will be created, and this table must be saved as a .mat file to be used in the RCNN.m code.

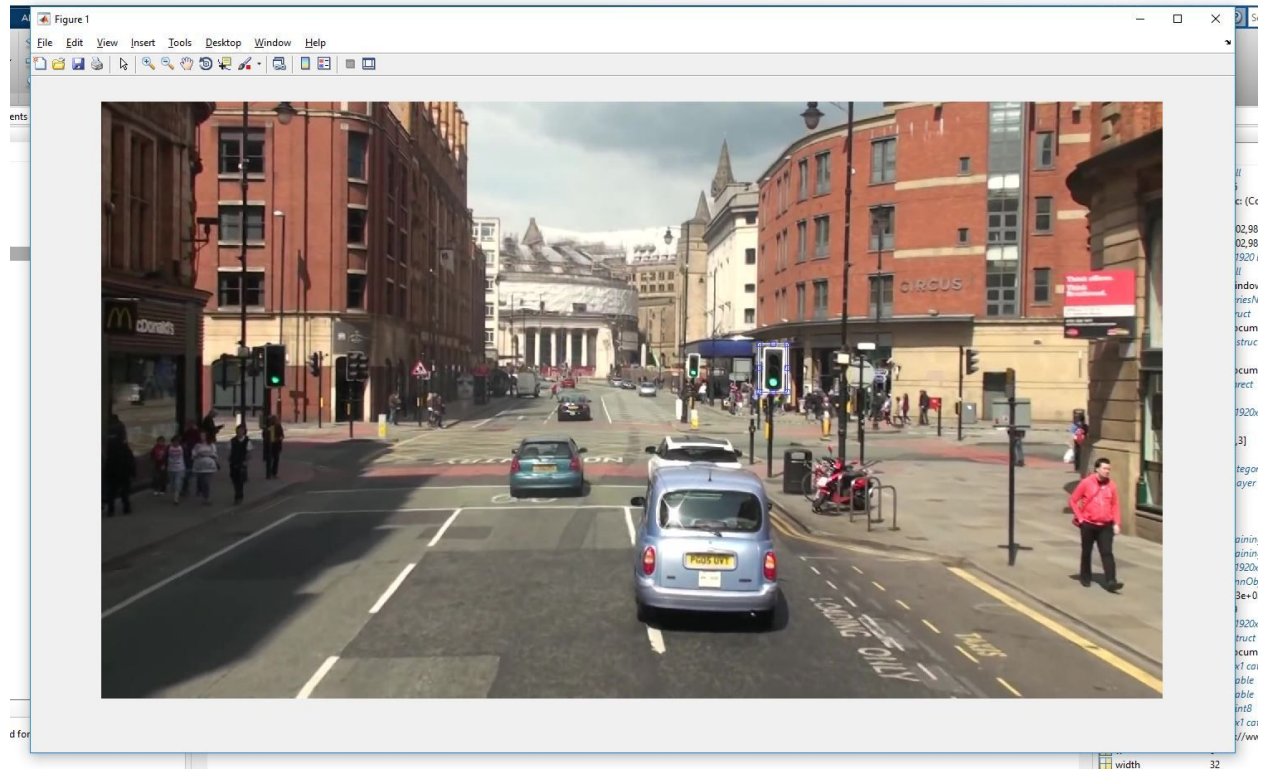
4. Operation Procedure

The proper steps to correctly run our code are listed in the following steps:

1. Open MATLAB and move the source files into the MATLAB folder (the folder on your machine where MATLAB files are saved to by default).
2. Load, but do not run, the ROICreate.m file.
3. If needed, edit the folder path of the folder that the desired training images are stored in. By default, the folder path for the training images used on the development machine is listed.
4. Run the ROICreate.m file in MATLAB and select the ROI around the target object for detection.
5. After the ROI is drawn, the size can be adjusted and moved. When finish, double-click inside the ROI box to proceed to the next training image.
6. Repeat the previous step until each training image is shown and an ROI is selected and the window closes.
7. After ROICreate.m is finished running, proceed to the MATLAB window and save the "Traffic" table created from the code and as a .mat file in the MATLAB folder.
8. Load the RNN.m file and, similar to the ROICreate.m file, if needed, set the folder path of the training and test images that will be used to test the performance of the R-CNN.
9. Run the code and it will automatically download the CIFAR-10 database and create a NN that will be trained with the database.
10. The code will output the accuracy of the pre-trained network and proceed to train the R-CNN using the training images and labels set from the ROICreate.m code.
11. The code will then begin to display the test images one at a time with a ROI drawn around any traffic light that it detects within the image.
12. Click on each image to proceed to the next image, and the this will repeat until all of the test images are shown and the program will then end.

5. Demonstration

The following images shows our code in action and displays some of the various steps outlined the previous (4) Operation Procedure section:



This image shows the ROICreate.m file being executed and is the ROI selection step of the source file. The blue rectangular outline around the traffic light towards the center of the image is the traffic light object that we had chosen to draw a ROI around.

Epoch	Iteration	Time Elapsed (seconds)	Mini-batch Loss	Mini-batch Accuracy	Base Learning Rate
1	50	2.94	2.3023	14.84%	0.001000
1	100	4.21	2.3021	16.41%	0.001000
1	150	5.49	2.3011	10.94%	0.001000
1	200	6.77	2.2966	20.31%	0.001000
1	250	8.05	2.2882	16.41%	0.001000
1	300	9.33	2.1252	26.56%	0.001000
1	350	10.61	2.0211	21.88%	0.001000
2	400	11.89	1.8798	27.34%	0.001000
2	450	13.16	1.8414	21.09%	0.001000
2	500	14.44	1.7822	29.69%	0.001000
2	550	15.72	1.7133	42.97%	0.001000
2	600	16.99	1.7968	34.38%	0.001000
2	650	18.27	1.7024	35.94%	0.001000
2	700	19.54	1.5878	42.19%	0.001000
2	750	20.82	1.5763	40.63%	0.001000
3	800	22.10	1.4098	44.53%	0.001000
3	850	23.38	1.4706	42.19%	0.001000
3	900	24.65	1.4371	48.44%	0.001000
3	950	25.93	1.5837	41.41%	0.001000
3	1000	27.21	1.2616	50.78%	0.001000
3	1050	28.50	1.5773	43.75%	0.001000
3	1100	29.78	1.4143	48.44%	0.001000
3	1150	31.06	1.4690	51.56%	0.001000
4	1200	32.33	1.3689	50.00%	0.001000
4	1250	33.62	1.2556	53.91%	0.001000
4	1300	34.90	1.2656	53.13%	0.001000
4	1350	36.18	1.3506	53.13%	0.001000
4	1400	37.46	1.1166	60.16%	0.001000
4	1450	38.74	1.1195	57.81%	0.001000
4	1500	40.02	1.1375	57.03%	0.001000
4	1550	41.31	1.0727	58.59%	0.001000
5	1600	42.59	1.1207	58.59%	0.001000
5	1650	43.87	1.1122	54.69%	0.001000
5	1700	45.16	1.1744	64.06%	0.001000
5	1750	46.45	0.9955	66.41%	0.001000
5	1800	47.74	1.0010	69.53%	0.001000
5	1850	49.04	1.1675	63.28%	0.001000
5	1900	50.33	0.9754	64.84%	0.001000

	18		6700		175.40		0.4198		85.16%		0.000010	
	18		6750		176.72		0.4154		84.38%		0.000010	
	18		6800		178.02		0.5649		84.38%		0.000010	
	18		6850		179.33		0.5418		81.25%		0.000010	
	18		6900		180.65		0.5262		85.16%		0.000010	
	18		6950		181.96		0.5410		78.91%		0.000010	
	18		7000		183.28		0.4930		80.47%		0.000010	
	19		7050		184.59		0.5451		83.59%		0.000010	
	19		7100		185.89		0.4719		81.25%		0.000010	
	19		7150		187.18		0.6232		78.91%		0.000010	
	19		7200		188.49		0.6470		78.91%		0.000010	
	19		7250		189.80		0.3901		86.72%		0.000010	
	19		7300		191.14		0.4625		85.16%		0.000010	
	19		7350		192.46		0.4099		85.94%		0.000010	
	19		7400		193.76		0.3936		86.72%		0.000010	
	20		7450		195.06		0.5344		81.25%		0.000010	
	20		7500		196.36		0.4561		85.94%		0.000010	
	20		7550		197.65		0.5820		82.03%		0.000010	
	20		7600		198.95		0.3895		85.94%		0.000010	
	20		7650		200.25		0.5070		82.03%		0.000010	
	20		7700		201.55		0.5389		84.38%		0.000010	
	20		7750		202.85		0.4247		87.50%		0.000010	
	20		7800		204.17		0.4414		85.94%		0.000010	
	21		7850		205.47		0.5596		78.91%		0.000010	
	21		7900		206.78		0.6002		78.13%		0.000010	
	21		7950		208.07		0.4109		84.38%		0.000010	
	21		8000		209.38		0.5347		81.25%		0.000010	
	21		8050		210.68		0.4359		84.38%		0.000010	
	21		8100		211.98		0.3330		86.72%		0.000010	
	21		8150		213.27		0.5254		79.69%		0.000010	
	22		8200		214.58		0.3645		85.16%		0.000010	
	22		8250		215.89		0.4614		82.81%		0.000010	
	22		8300		217.19		0.4698		78.91%		0.000010	
	22		8350		218.51		0.4386		87.50%		0.000010	
	22		8400		219.82		0.4995		79.69%		0.000010	
	22		8450		221.13		0.3810		87.50%		0.000010	
	22		8500		222.44		0.3777		88.28%		0.000010	
	22		8550		223.75		0.4736		85.16%		0.000010	
	23		8600		225.08		0.4678		82.03%		0.000010	
	23		8650		226.38		0.4131		84.38%		0.000010	
	23		8700		227.68		0.4059		85.94%		0.000010	
	23		8750		228.98		0.5558		84.38%		0.000010	

	36		13800		360.58		0.3976		85.16%		0.000000	
	36		13850		361.91		0.5309		82.03%		0.000000	
	36		13900		363.23		0.4212		85.94%		0.000000	
	36		13950		364.53		0.3278		87.50%		0.000000	
	36		14000		365.83		0.5067		80.47%		0.000000	
	37		14050		367.13		0.3564		87.50%		0.000000	
	37		14100		368.43		0.4501		82.03%		0.000000	
	37		14150		369.74		0.4600		78.13%		0.000000	
	37		14200		371.07		0.4346		87.50%		0.000000	
	37		14250		372.39		0.4974		79.69%		0.000000	
	37		14300		373.68		0.3735		87.50%		0.000000	
	37		14350		374.99		0.3688		87.50%		0.000000	
	37		14400		376.29		0.4642		85.16%		0.000000	
	38		14450		377.61		0.4670		82.81%		0.000000	
	38		14500		378.92		0.4023		86.72%		0.000000	
	38		14550		380.23		0.4060		85.16%		0.000000	
	38		14600		381.57		0.5467		85.16%		0.000000	
	38		14650		382.89		0.5263		81.25%		0.000000	
	38		14700		384.20		0.5150		84.38%		0.000000	
	38		14750		385.50		0.5267		80.47%		0.000000	
	38		14800		386.81		0.4823		80.47%		0.000000	
	39		14850		388.10		0.5323		85.16%		0.000000	
	39		14900		389.40		0.4564		80.47%		0.000000	
	39		14950		390.70		0.6140		79.69%		0.000000	
	39		15000		392.00		0.6294		78.91%		0.000000	
	39		15050		393.29		0.3781		88.28%		0.000000	
	39		15100		394.59		0.4526		84.38%		0.000000	
	39		15150		395.88		0.4022		87.50%		0.000000	
	39		15200		397.18		0.3914		86.72%		0.000000	
	40		15250		398.47		0.5185		81.25%		0.000000	
	40		15300		399.79		0.4523		87.50%		0.000000	
	40		15350		401.11		0.5650		80.47%		0.000000	
	40		15400		402.42		0.3862		87.50%		0.000000	
	40		15450		403.71		0.4959		80.47%		0.000000	
	40		15500		405.04		0.5291		84.38%		0.000000	
	40		15550		406.37		0.4136		86.72%		0.000000	
	40		15600		407.67		0.4302		85.16%		0.000000	
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accuracy =

0.7601

The past 3 images show the training process of the CIFAR-10 dataset with our CNN that will serve to act as our pre-trained network. Here we can see that the accuracy of the performance of the CIFAR trained network is 76.01%.

Step 2 of 3: Training a neural network to classify objects in training data...

Epoch	Iteration	Time Elapsed (seconds)	Mini-batch Loss	Mini-batch Accuracy	Base Learning Rate
25	50	19.70	0.0053	100.00%	0.001000
50	100	38.82	0.0003	100.00%	0.001000
75	150	58.05	0.0109	98.98%	0.001000
100	200	76.97	0.0006	100.00%	0.001000

Network training complete.

Step 3 of 3: Training bounding box regression models for each object class...100.00%...done.

R-CNN training complete.

The image above shows the training portion on our R-CNN with our traffic light training dataset which uses the pre-trained network previously seen.



This image shows one of the test images that was processed by our R-CNN along with the ROI drawn around the network's detection of a traffic light object.



This image shows another successful traffic light detection and also demonstrates our model's invariance to scale when compared to the previous test image.



This image shows yet another traffic light detection and also demonstrates our model's invariance to lighting compared to the two previous test image examples.