

OSPRAY

**AN OPEN, SCALABLE, PARALLEL, RAY TRACING
BASED RENDERING ENGINE FOR HIGH-FIDELITY
VISUALIZATION**

Version 1.1.2
December 1, 2016

Contents

1	OSPRay Overview	3
1.1	OSPRay Support and Contact	3
1.2	Version History	3
2	Building OSPRay from Source	10
2.1	Prerequisites	10
2.2	Compiling OSPRay	11
3	OSPRay API	12
3.1	Objects	13
3.1.1	Parameters	13
3.1.2	Data	14
3.2	Volumes	14
3.2.1	Structured Volume	14
3.2.2	Transfer Function	16
3.3	Geometries	16
3.3.1	Triangle Mesh	17
3.3.2	Spheres	17
3.3.3	Cylinders	17
3.3.4	Streamlines	17
3.3.5	Isosurfaces	18
3.3.6	Slices	18
3.3.7	Instances	19
3.4	Renderer	19
3.4.1	SciVis Renderer	19
3.4.2	Path tracer	20
3.4.3	Model	20
3.4.4	Lights	21
3.4.5	Materials	23
3.4.6	Texture	25
3.4.7	Texture Transformations	26
3.4.8	Cameras	26
3.4.9	Picking	29
3.5	Framebuffer	30
	Pixel Operation	31
3.6	Rendering	32
4	Examples	33
4.1	Tutorial	33
4.2	Qt Viewer	34
4.3	Volume Viewer	34
4.4	Demos	34

Chapter 1

OSPRay Overview

OSPRay is an open source, scalable, and portable ray tracing engine for high-performance, high-fidelity visualization on Intel® Architecture CPUs. OSPRay is released under the permissive [Apache 2.0 license](#).

The purpose of OSPRay is to provide an open, powerful, and easy-to-use rendering library that allows one to easily build applications that use ray tracing based rendering for interactive applications (including both surface- and volume-based visualizations). OSPRay is completely CPU-based, and runs on anything from laptops, to workstations, to compute nodes in HPC systems.

OSPRay internally builds on top of [Embree](#) and [ISPC \(Intel® SPMD Program Compiler\)](#), and fully utilizes modern instruction sets like Intel® SSE, AVX, AVX2, and AVX-512 to achieve high rendering performance.

1.1 OSPRay Support and Contact

OSPRay is under active development, and though we do our best to guarantee stable release versions a certain number of bugs, as-yet-missing features, inconsistencies, or any other issues are still possible. Should you find any such issues please report them immediately via [OSPRay's GitHub Issue Tracker](#) (or, if you should happen to have a fix for it, you can also send us a pull request); for missing features please contact us via email at ospray@googlegroups.com.

For recent news, updates, and announcements, please see our complete [news/updates](#) page.

Join our [mailing list](#) to receive release announcements and major news regarding OSPRay.

1.2 Version History

1.2.1 Changes in v1.1.2:

- Various bugfixes related to normalization, epsilons and debug messages

1.2.2 Changes in v1.1.1:

- Fixed support of first generation Intel® Xeon Phi™ coprocessor (codename Knights Corner) and the COI device
- Fix normalization bug that caused rendering artifacts

1.2.3 Changes in v1.1.0:

- New “scivis” renderer features

- Single sided lighting (enabled by default)
- Many new volume rendering specific features
 - * Adaptive sampling to help improve the correctness of rendering high frequency volume data
 - * Pre-integration of transfer function for higher fidelity images
 - * Ambient occlusion
 - * Volumes can cast shadows
 - * Smooth shading in volumes
 - * Single shading point option for accelerated shading
- Add preliminary support for adaptive accumulation in the MPI device
- Camera specific features
 - Initial support for stereo rendering with the perspective camera
 - Option `architectural` in perspective camera, rectifying vertical edges to appear parallel
 - Rendering a subsection of the full view with `imageStart/imageEnd` supported by all cameras
- This will be our last release supporting the first generation Intel Xeon Phi coprocessor (codename Knights Corner)
 - Future major and minor releases will be upgraded to the latest version of Embree, which no longer supports Knights Corner
 - Depending on user feedback, patch releases are still made to fix bugs
- Enhanced output statistics in `ospBenchmark` application
- Many fixes to the OSPRay SDK
 - Improved CMake detection of compile-time enabled features
 - Now distribute OSPRay configuration and ISPC CMake macros
 - Improved SDK support on Windows
- OSPRay library can now be compiled with `-Wall` and `-Wextra` enabled
 - Tested with GCC v5.3.1 and Clang v3.8
 - Sample applications and modules have not been fixed yet, thus applications which build OSPRay as a CMake subproject should disable them with `-DOSPRAY_ENABLE_APPS=OFF` and `-DOSPRAY_ENABLE_MODULES=OFF`
- Minor bug fixes, improvements, and cleanups
 - Regard shading normal when bump mapping
 - Fix internal CMake naming inconsistencies in macros
 - Fix missing API calls in C++ wrapper classes
 - Fix crashes on MIC
 - Fix thread count initialization bug with TBB
 - CMake optimizations for faster configuration times
 - Enhanced support for scripting in both `ospGlutViewer` and `ospBenchmark` applications

1.2.4 Changes in v1.0.0:

- New OSPRay SDK
 - OSPRay internal headers are now installed, enabling applications to extend OSPRay from a binary install
 - CMake macros for OSPRay and ISPC configuration now a part of binary releases

- * CMake clients use them by calling `include(${OSPRAY_USE_FILE})` in their CMake code after calling `find_package(ospray)`
- New OSPRay C++ wrapper classes
 - * These act as a thin layer on top of OSPRay object handles, where multiple wrappers will share the same underlying handle when assigned, copied, or moved
 - * New OSPRay objects are only created when a class instance is explicitly constructed
 - * C++ users are encouraged to use these over the `ospray.h` API
- Complete rework of sample applications
 - New shared code for parsing the commandline
 - Save/load of transfer functions now handled through a separate library which does not depend on Qt
 - Added `ospCvtParaViewTfcn` utility, which enables `ospVolumeViewer` to load color maps from ParaView
 - GLUT based sample viewer updates
 - * Rename of `ospModelViewer` to `ospGlutViewer`
 - * GLUT viewer now supports volume rendering
 - * Command mode with preliminary scripting capabilities, enabled by pressing `:`` key (not available when using Intel C++ compiler (icc))
 - Enhanced support of sample applications on Windows
- New minimum ISPC version is 1.9.0
- Support of Intel® AVX-512 for second generation Intel Xeon Phi processor (codename Knights Landing) is now a part of the `OSPRAY_BUILD_ISA` CMake build configuration
 - Compiling AVX-512 requires `icc` to be enabled as a build option
- Enhanced error messages when `ospLoadModule()` fails
- Added `OSP_FB_RGBA32F` support in the `DistributedFrameBuffer`
- Updated Glass shader in the path tracer
- Many miscellaneous cleanups, bugfixes, and improvements

1.2.5 Changes in v0.10.1:

- Fixed support of first generation Intel Xeon Phi coprocessor (codename Knights Corner)
- Restored missing implementation of `ospRemoveVolume()`

1.2.6 Changes in v0.10.0:

- Added new tasking options: Cilk, Internal, and Debug
 - Provides more ways for OSPRay to interact with calling application tasking systems
 - * Cilk: Use Intel® Cilk™ Plus language extensions (icc only)
 - * Internal: Use hand written OSPRay tasking system
 - * Debug: All tasks are run in serial (useful for debugging)
 - In most cases, Intel Threading Building Blocks (Intel TBB) remains the fastest option
- Added support for adaptive accumulation and stopping

- `ospRenderFrame` now returns an estimation of the variance in the rendered image if the framebuffer was created with the `OSP_FB_VARIANCE` channel
 - If the renderer parameter `varianceThreshold` is set, progressive refinement concentrates on regions of the image with a variance higher than this threshold
- Added support for volumes with `voxelType ushort` (16-bit unsigned integers)
- `OSPTexture2D` now supports sRGB formats – actually most images are stored in sRGB. As a consequence the API call `ospNewTexture2D()` needed to change to accept the new `OSPTextureFormat` parameter.
- Similarly, OSPRay’s framebuffer types now also distinguishes between linear and sRGB 8-bit formats. The new types are `OSP_FB_NONE`, `OSP_FB_RGBA8`, `OSP_FB_SRGBA`, and `OSP_FB_RGBA32F`
- Changed “scivis” renderer parameter defaults
 - All shading (AO + shadows) must be explicitly enabled
- OSPRay can now use a newer, pre-installed Embree enabled by the new `OSPRAY_USE_EXTERNAL_EMBREE` CMake option
- New `ospcommon` library used to separately provide math types and OS abstractions for both OSPRay and sample applications
 - Removes extra dependencies on internal Embree math types and utility functions
 - `ospray.h` header is now C99 compatible
- Removed loaders module, functionality remains inside of `ospVolumeViewer`
- Many miscellaneous cleanups, bugfixes, and improvements:
 - Fixed data distributed volume rendering bugs when using less blocks than workers
 - Fixes to CMake `find_package()` config
 - Fix bug in `GhostBlockBrickVolume` when using doubles
 - Various robustness changes made in CMake to make it easier to compile OSPRay

1.2.7 Changes in v0.9.1:

- Volume rendering now integrated into the “scivis” renderer
 - Volumes are rendered in the same way the “dvr” volume renderer renders them
 - Ambient occlusion works with implicit isosurfaces, with a known visual quality/performance trade-off
- Intel Xeon Phi coprocessor (codename Knights Corner) COI device and build infrastructure restored (volume rendering is known to still be broken)
- New support for CPack built OSPRay binary redistributable packages
- Added support for HDRI lighting in path tracer
- Added `ospRemoveVolume()` API call
- Added ability to render a subsection of the full view into the entire framebuffer in the perspective camera
- Many miscellaneous cleanups, bugfixes, and improvements:
 - The depthbuffer is now correctly populated by in the “scivis” renderer
 - Updated default renderer to be “ao1” in `ospModelViewer`
 - `TriangleMesh` `postIntersect` shading is now 64-bit safe
 - `Texture2D` has been reworked, with many improvements and bug fixes

- Fixed bug where MPI device would freeze while rendering frames with Intel TBB
- Updates to CMake with better error messages when Intel TBB is missing

1.2.8 Changes in v0.9.0:

The OSPRay v0.9.0 release adds significant new features as well as API changes.

- Experimental support for data-distributed MPI-parallel volume rendering
- New SciVis-focused renderer (“raytracer” or “scivis”) combining functionality of “obj” and “ao” renderers
 - Ambient occlusion is quite flexible: dynamic number of samples, maximum ray distance, and weight
- Updated Embree version to v2.7.1 with native support for Intel AVX-512 for triangle mesh surface rendering on the Intel Xeon Phi processor (codename Knights Landing)
- OSPRay now uses C++11 features, requiring up to date compiler and standard library versions (GCC v4.8.0)
- Optimization of volume sampling resulting in volume rendering speedups of up to 1.5x
- Updates to path tracer
 - Reworked material system
 - Added texture transformations and colored transparency in OBJ material
 - Support for alpha and depth components of framebuffer
- Added thinlens camera, i.e. support for depth of field
- Tasking system has been updated to use Intel Threading Building Blocks (Intel TBB)
- The `ospGet*()` API calls have been deprecated and will be removed in a subsequent release

1.2.9 Changes in v0.8.3:

- Enhancements and optimizations to path tracer
 - Soft shadows (light sources: sphere, cone, extended spot, quad)
 - Transparent shadows
 - Normal mapping (OBJ material)
- Volume rendering enhancements:
 - Expanded material support
 - Support for multiple lights
 - Support for double precision volumes
 - Added `ospSampleVolume()` API call to support limited probing of volume values
- New features to support compositing externally rendered content with OSPRay-rendered content
 - Renderers support early ray termination through a maximum depth parameter
 - New OpenGL utility module to convert between OSPRay and OpenGL depth values
- Added panoramic and orthographic camera types

- Proper CMake-based installation of OSPRay and CMake `find_package()` support for use in external projects
- Experimental Windows support
- Deprecated `ospNewTriangleMesh()`; use `ospNewGeometry("triangles")` instead
- Bug fixes and cleanups throughout the codebase

1.2.10 Changes in v0.8.2:

- Initial support for Intel AVX-512 and the Intel Xeon Phi processor (code-name Knights Landing)
- Performance improvements to the volume renderer
- Incorporated implicit slices and isosurfaces of volumes as core geometry types
- Added support for multiple disjoint volumes to the volume renderer
- Improved performance of `ospSetRegion()`, reducing volume load times
- Improved large data handling for the `shared_structured_volume` and `block_bricked_volume` volume types
- Added support for DDS horizon data to the seismic module
- Initial support in the Qt viewer for volume rendering
- Updated to ISPC 1.8.2
- Various bug fixes, cleanups and documentation updates throughout the codebase

1.2.11 Changes in v0.8.1:

- The volume renderer and volume viewer can now be run MPI parallel (data replicated) using the `--osp:mpi` command line option
- Improved performance of volume grid accelerator generation, reducing load times for large volumes
- The volume renderer and volume viewer now properly handle multiple isosurfaces
- Added small example tutorial demonstrating how to use OSPRay
- Several fixes to support older versions of GCC
- Bug fixes to `ospSetRegion()` implementation for arbitrarily shaped regions and setting large volumes in a single call
- Bug fix for geometries with invalid bounds; fixes streamline and sphere rendering in some scenes
- Fixed bug in depth buffer generation

1.2.12 Changes in v0.8.0:

- Incorporated early version of a new Qt-based viewer to eventually unify (and replace) the existing simpler GLUT-based viewers
- Added new path tracing renderer (`ospray/render/pathtracer`), roughly based on the Embree sample path tracer
- Added new features to the volume renderer:
 - Gradient shading (lighting)
 - Implicit isosurfacing
 - Progressive refinement
 - Support for regular grids, specified with the `gridOrigin` and `gridSpacing` parameters
 - New `shared_structured_volume` volume type that allows voxel data to be provided by applications through a shared data buffer
 - New API call to set subregions of volume data (`ospSetRegion()`)

- Added a subsampling-mode, enabled with a negative spp parameter; the first frame after scene changes is rendered with reduced resolution, increasing interactivity
- Added multi-target ISA support: OSPRay will now select the appropriate ISA at run time
- Added support for the Stanford SEP file format to the seismic module
- Added `--osp:numthreads <n>` command line option to restrict the number of threads OSPRay creates
- Various bug fixes, cleanups and documentation updates throughout the codebase

1.2.13 Changes in v0.7.2:

- Build fixes for older versions of GCC and Clang
- Fixed time series support in ospVolumeViewer
- Corrected memory management for shared data buffers
- Updated to ISPC 1.8.1
- Resolved issue in XML parser

Chapter 2

Building OSPRay from Source

The latest OSPRay sources are always available at the [OSPRay GitHub repository](#). The default master branch should always point to the latest tested bugfix release.

2.1 Prerequisites

OSPRay currently supports both Linux and Mac OS X (and experimentally Windows). In addition, before you can build OSPRay you need the following prerequisites:

- You can clone the latest OSPRay sources via:

```
git clone https://github.com/ospray/ospray.git
```

- To build OSPRay you need [CMake](#), any form of C++11 compiler (we recommend using the [Intel® C++ compiler \(icc\)](#), but also support GCC and Clang), and standard Linux development tools. To build the demo viewers, you should also have some version of OpenGL and the GL Utility Toolkit (GLUT or freeglut), as well as Qt 4.6 or higher.
- Additionally you require a copy of the [Intel® SPMD Program Compiler \(ISPC\)](#). Please obtain a copy of the latest binary release of ISPC (currently 1.9.1) from the [ISPC downloads page](#). The build system looks for ISPC in the PATH and in the directory right “next to” the checked-out OSPRay sources.¹ Alternatively set the CMake variable ISPC_EXECUTABLE to the location of the ISPC compiler.
- Per default OSPRay uses the [Intel® Threading Building Blocks \(TBB\)](#) as tasking system, which we recommend for performance and flexibility reasons. Alternatively you can set CMake variable OSPRAY_TASKING_SYSTEM to OpenMP, Internal, or Cilk (icc only).
- OSPRay also heavily uses [Embree](#), installing version 2.12 is recommended. If Embree is not found by CMake its location can be hinted with the variable embree_DIR. As a fallback OSPRay also includes its own copy of Embree.

¹ For example, if OSPRay is in ~/Projects/ospray, ISPC will also be searched in ~/Projects/ispc-v1.9.1-linux and ~/Projects/ispc-v1.9.0-linux

Depending on your Linux distribution you can install these dependencies using yum or apt-get. Some of these packages might already be installed or might have slightly different names.

Type the following to install the dependencies using yum:

```
sudo yum install cmake.x86_64
sudo yum install tbb.x86_64 tbb-devel.x86_64
sudo yum install freeglut.x86_64 freeglut-devel.x86_64
sudo yum install qt-devel.x86_64
```

Type the following to install the dependencies using apt-get:

```
sudo apt-get install cmake-curses-gui
sudo apt-get install libtbb-dev
sudo apt-get install freeglut3-dev
sudo apt-get install libqt4-dev
```

Under Mac OS X these dependencies can be installed using [MacPorts](#):

```
sudo port install cmake tbb freeglut qt4
```

2.2 Compiling OSPRay

Assume the above requisites are all fulfilled, building OSPRay through CMake is easy:

- Create a build directory, and go into it

```
user@mymachine[~/Projects]: mkdir ospray/release
user@mymachine[~/Projects]: cd ospray/release
```

(We do recommend having separate build directories for different configurations such as release, debug, etc).

- The compiler CMake will use will default to whatever the CC and CXX environment variables point to. Should you want to specify a different compiler, run cmake manually while specifying the desired compiler. The default compiler on most linux machines is gcc, but it can be pointed to clang instead by executing the following:

```
user@mymachine[~/Projects/ospray/release]: cmake
-DMAKE_CXX_COMPILER=clang++ -DCMAKE_C_COMPILER=clang ..
```

CMake will now use Clang instead of GCC. If you are ok with using the default compiler on your system, then simply skip this step. Note that the compiler variables cannot be changed after the first cmake or cmake run.

- Open the CMake configuration dialog

```
user@mymachine[~/Projects/ospray/release]: cmake ..
```

- Make sure to properly set build mode and enable the components you need, etc; then type 'c'onfigure and 'g'enerate. When back on the command prompt, build it using

```
user@mymachine[~/Projects/ospray/release]: make
```

- You should now have libospray.so as well as a set of sample viewers. You can test your version of OSPRay using any of the examples on the [OSPRay Demos and Examples](#) page.

Chapter 3

OSPRay API

To access the OSPRay API you first need to include the OSPRay header

```
#include "ospray/ospray.h"
```

The API is compatible with C99 and C++. Then initialize the OSPRay rendering engine with

```
void ospInit(int *argc, const char **argv);
```

OSPRay parses (and removes) its known command line parameters, so you could just pass `argc` and `argv` from your application's main function. For an example see the [tutorial](#). The following parameters (which are prefixed by convention with "--osp:") are understood:

Table 3.1 – Command line parameters accepted by OSPRay's `ospInit`.

Parameter	Description
--osp:debug	enables various extra checks and debug output, and disables multi-threading
--osp:numthreads <n>	use n threads instead of per default using all detected hardware threads
--osp:loglevel <n>	set logging level, default 0; increasing n means increasingly verbose log messages
--osp:verbose	shortcut for --osp:loglevel 1
--osp:vv	shortcut for --osp:loglevel 2
--osp:mpi	enables MPI mode for parallel rendering, to be used in conjunction with <code>mpirun</code>

As an alternative to command line parameters (which still have precedence) OSPRay can also be configured by environment variables (which are prefixed by convention with "OSPRAY_"):

Variable	Description
OSPRAY_THREADS	equivalent to --osp:numthreads
OSPRAY_LOG_LEVEL	equivalent to --osp:loglevel

Table 3.2 – Environment variables interpreted by OSPRay.

OSPRay's functionality can be extended via plugins, which are implemented in shared libraries. To load plugin name from `libospray_module_<name>.so` (on Linux and Mac OS X) or `ospray_module_<name>.dll` (on Windows) use

```
int32_t ospLoadModule(const char *name);
```

Modules are searched in OS-dependent paths, which include the application directory. `ospLoadModule` returns 0 if the plugin could be loaded and an error code > 0 otherwise.

3.1 Objects

All entities of OSPRay (the renderer, volumes, geometries, lights, cameras, ...) are a specialization of `OSPObject` and share common mechanism to deal with parameters and lifetime.

An important aspect of object parameters is that parameters do not get passed to objects immediately. Instead, parameters are not visible at all to objects until they get explicitly committed to a given object via a call to

```
void ospCommit(OSPObject);
```

at which time all previously additions or changes to parameters are visible at the same time. If a user wants to change the state of an existing object (e.g., to change the origin of an already existing camera) it is perfectly valid to do so, as long as the changed parameters are recommitted.

The commit semantic allow for batching up multiple small changes, and specifies exactly when changes to objects will occur. This is important to ensure performance and consistency for devices crossing a PCI bus, or across a network. In our MPI implementation, for example, we can easily guarantee consistency among different nodes by MPI barrier'ing on every commit.

Note that OSPRay uses reference counting to manage the lifetime of all objects, so one cannot explicitly “delete” any object. Instead, to indicate that the application does not need and does not access the given object anymore, call

```
void ospRelease(OSPObject);
```

This decreases its reference count and if the count reaches 0 the object will automatically get deleted.

3.1.1 Parameters

Parameters allow to configure the behavior of and to pass data to objects. However, objects do *not* have an explicit interface for reasons of high flexibility and a more stable compile-time API. Instead, parameters are passed separately to objects in an arbitrary order, and unknown parameters will simply be ignored. The following functions allow adding various types of parameters with name `id` to a given object:

```
// add a C-string (zero-terminated char *) parameter
void ospSetString(OSPObject, const char *id, const char *s);

// add an object handle parameter to another object
void ospSetObject(OSPObject, const char *id, OSPObject object);

// add an untyped pointer -- this will *ONLY* work in local rendering!
void ospSetVoidPtr(OSPObject, const char *id, void *v);

// add scalar and vector integer and float parameters
void ospSetf (OSPObject, const char *id, float x);
void ospSet1f (OSPObject, const char *id, float x);
void ospSet1i (OSPObject, const char *id, int32_t x);
void ospSet2f (OSPObject, const char *id, float x, float y);
void ospSet2fv(OSPObject, const char *id, const float *xy);
void ospSet2i (OSPObject, const char *id, int x, int y);
void ospSet2iv(OSPObject, const char *id, const int *xy);
void ospSet3f (OSPObject, const char *id, float x, float y, float z);
void ospSet3fv(OSPObject, const char *id, const float *xyz);
```

```

void ospSet3i (OSPObject, const char *id, int x, int y, int z);
void ospSet3iv(OSPObject, const char *id, const int *xyz);
void ospSet4f (OSPObject, const char *id, float x, float y, float z, float w);
void ospSet4fv(OSPObject, const char *id, const float *xyzw);

// additional functions to pass vector integer and float parameters in C++
void ospSetVec2f(OSPObject, const char *id, const vec2f &v);
void ospSetVec2i(OSPObject, const char *id, const vec2i &v);
void ospSetVec3f(OSPObject, const char *id, const vec3f &v);
void ospSetVec3i(OSPObject, const char *id, const vec3i &v);
void ospSetVec4f(OSPObject, const char *id, const vec4f &v);

```

3.1.2 Data

There is also the possibility to aggregate many values of the same type into an array, which then itself can be used as a parameter to objects. To create such a new data buffer, holding numItems elements of the given type, from the initialization data pointed to by source and optional creation flags, use

```

OSPData ospNewData(size_t numItems,
                  OSPDataType,
                  const void *source,
                  const uint32_t dataCreationFlags = 0);

```

The call returns an OSPData handle to the created array. The flag OSP_DATA_SHARED_BUFFER indicates that the buffer can be shared with the application. In this case the calling program guarantees that the source pointer will remain valid for the duration that this data array is being used. The enum type OSPDataType describes the different data types that can be represented in OSPRay; valid constants are listed in the table below.

To add a data array as parameter named id to another object call

```

void ospSetData(OSPObject, const char *id, OSPData);

```

3.2 Volumes

Volumes are volumetric datasets with discretely sampled values in 3D space, typically a 3D scalar field. To create a new volume object of given type type use

```

OSPVolume ospNewVolume(const char *type);

```

The call returns NULL if that type of volume is not known by OSPRay, or else an OSPVolume handle.

3.2.1 Structured Volume

Structured volumes only need to store the values of the samples, because their addresses in memory can be easily computed from a 3D position. A common type of structured volumes are regular grids. OSPRay supports two variants that differ in how the volumetric data for the regular grids is specified.

The first variant shares the voxel data with the application. Such a volume type is created by passing the type string “shared_structured_volume” to ospNewVolume. The voxel data is laid out in memory in XYZ order and provided to the volume via a [data](#) buffer parameter named “voxelData”.

The second regular grid variant is optimized for rendering performance: data locality in memory is increased by arranging the voxel data in smaller blocks.

Type/Name	Description
OSP_VOID_PTR	void pointer
OSP_DATA	data reference
OSP_OBJECT	generic object reference
OSP_CAMERA	camera object reference
OSP_FRAMEBUFFER	framebuffer object reference
OSP_LIGHT	light object reference
OSP_MATERIAL	material object reference
OSP_TEXTURE	texture object reference
OSP_RENDERER	renderer object reference
OSP_MODEL	model object reference
OSP_GEOMETRY	geometry object reference
OSP_VOLUME	volume object reference
OSP_TRANSFER_FUNCTION	transfer function object reference
OSP_PIXEL_OP	pixel operation object reference
OSP_STRING	C-style zero-terminated character string
OSP_CHAR	8 bit signed character scalar
OSP_UCHAR	8 bit unsigned character scalar
OSP_UCHAR[234]	... and [234]-element vector
OSP_USHORT	16 bit unsigned integer scalar
OSP_INT	32 bit signed integer scalar
OSP_INT[234]	... and [234]-element vector
OSP_UINT	32 bit unsigned integer scalar
OSP_UINT[234]	... and [234]-element vector
OSP_LONG	64 bit signed integer scalar
OSP_LONG[234]	... and [234]-element vector
OSP_ULONG	64 bit unsigned integer scalar
OSP_ULONG[234]	... and [234]-element vector
OSP_FLOAT	32 bit single precision floating point scalar
OSP_FLOAT[234]	... and [234]-element vector
OSP_FLOAT3A	... and aligned 3-element vector
OSP_DOUBLE	64 bit double precision floating point scalar

Table 3.3 – Valid named constants for OSPDataType.

This volume type is created by passing the type string “block_bricked_volume” to `ospNewVolume`. Because of this rearrangement of voxel data it cannot be shared with the application anymore, but has to be transferred to OSPRay via

```
int ospSetRegion(OSPVolume, void *source,
                 const vec3i &regionCoords,
                 const vec3i &regionSize);
```

The voxel data pointed to by `source` is copied into the given volume starting at position `regionCoords`, must be of size `regionSize` and be placed in memory in XYZ order. Note that OSPRay distinguishes between volume data and volume parameters. This function must be called only after all volume parameters (in

particular dimensions and voxelType, see below) have been set and *before* `ospCommit(volume)` is called. Memory for the volume is allocated on the first call to this function. If allocation is unsuccessful or the region size is invalid, the return value is 0, and non-zero otherwise.

The common parameters understood by both structured volume variants are summarized in the table below. If voxelRange is not provided for a volume OSPRay will compute it based on the voxel data, which may result in slower data updates.

Type	Name	Description
vec3i	dimensions	number of voxels in each dimension (x, y, z)
string	voxelType	data type of each voxel, currently supported are: “uchar” (8 bit unsigned integer) “ushort” (16 bit unsigned integer) “float” (32 bit single precision floating point) “double” (64 bit double precision floating point)
vec2f	voxelRange	minimum and maximum of the scalar values
vec3f	gridOrigin	origin of the grid in world-space, default (0, 0, 0)
vec3f	gridSpacing	size of the grid cells in world-space, default (1, 1, 1)

Table 3.4 – Parameters to configure a structured volume.

3.2.2 Transfer Function

Transfer functions map the scalar values of volumes to color and opacity and thus they can be used to visually emphasize certain features of the volume. To create a new transfer function of given type type use

```
OSPTransferFunction ospNewTransferFunction(const char *type);
```

The call returns NULL if that type of transfer functions is not known by OSPRay, or else an OSPTransferFunction handle to the created transfer function. That handle can be assigned to a volume as parameter “transferFunction” using `ospSetObject`.

One type of transfer function that is built-in in OSPRay is the linear transfer function, which interpolates between given equidistant colors and opacities. It is create by passing the string “piecewise_linear” to `ospNewTransferFunction` and it is controlled by these parameters:

Type	Name	Description
vec3f[]	colors	data array of RGB colors
float[]	opacities	data array of opacities
vec2f	valueRange	domain (scalar range) this function maps from

Table 3.5 – Parameters accepted by the linear transfer function.

3.3 Geometries

Geometries in OSPRay are objects that describe surfaces. To create a new geometry object of given type type use

```
OSPGeometry ospNewGeometry(const char *type);
```

The call returns NULL if that type of geometry is not known by OSPRay, or else an OSPGeometry handle.

3.3.1 Triangle Mesh

A traditional triangle mesh (indexed face set) geometry is created by calling `ospNewGeometry` with type string “triangles”. Once created, a triangle mesh recognizes the following parameters:

Type	Name	Description
<code>vec3f(a)[]</code>	<code>vertex</code>	data array of vertex positions
<code>vec3f(a)[]</code>	<code>vertex.normal</code>	data array of vertex normals
<code>vec4f[]</code>	<code>vertex.color</code>	data array of vertex colors (RGBA)
<code>vec2f[]</code>	<code>vertex.texcoord</code>	data array of vertex texture coordinates
<code>vec3i(a)[]</code>	<code>index</code>	data array of triangle indices (into vertex.*)

Table 3.6 – Parameters defining a triangle mesh geometry.

3.3.2 Spheres

A geometry consisting of individual spheres, each of which can have an own radius, is created by calling `ospNewGeometry` with type string “spheres”. The spheres will not be tessellated but rendered procedurally and are thus perfectly round. To allow a variety of sphere representations in the application this geometry allows a flexible way of specifying the data of center position and radius within a [data](#) array:

Table 3.7 – Parameters defining a spheres geometry.

Type	Name	Default	Description
float	<code>radius</code>	0.01	radius of all spheres (if <code>offset_radius</code> is not used)
OSPData	<code>spheres</code>	NULL	memory holding the data of all spheres
int	<code>bytes_per_sphere</code>	16	size (in bytes) of each sphere within the <code>spheres</code> array
int	<code>offset_center</code>	0	offset (in bytes) of each sphere’s “ <code>vec3f center</code> ” position (in object-space) within the <code>spheres</code> array
int	<code>offset_radius</code>	-1	offset (in bytes) of each sphere’s “float radius” within the <code>spheres</code> array (-1 means disabled and use <code>radius</code>)

3.3.3 Cylinders

A geometry consisting of individual cylinders, each of which can have an own radius, is created by calling `ospNewGeometry` with type string “cylinders”. The cylinders will not be tessellated but rendered procedurally and are thus perfectly round. To allow a variety of cylinder representations in the application this geometry allows a flexible way of specifying the data of offsets for start position, end position and radius within a [data](#) array. All parameters are listed in the table below.

3.3.4 Streamlines

A geometry consisting of multiple stream lines of constant radius is created by calling `ospNewGeometry` with type string “streamlines”. The stream lines are internally assembled from connected (and rounded) cylinder segments and are thus perfectly round. The parameters defining this geometry are listed in the table below.

Table 3.8 – Parameters defining a cylinders geometry.

Type	Name	Default	Description
float	radius	0.01	radius of all cylinders (if <code>offset_radius</code> is not used)
OSPData	cylinders	NULL	memory holding the data of all cylinders
int	bytes_per_cylinder	28	size (in bytes) of each cylinder within the <code>cylinders</code> array
int	offset_v0	0	offset (in bytes) of each cylinder’s “vec3f v0” position (the start vertex, in object-space) within the <code>cylinders</code> array
int	offset_v1	12	offset (in bytes) of each cylinder’s “vec3f v1” position (the end vertex, in object-space) within the <code>cylinders</code> array
int	offset_radius	-1	offset (in bytes) of each cylinder’s “float radius” within the <code>cylinders</code> array (-1 means disabled and use <code>radius</code> instead)

Type	Name	Description
float	radius	radius of all stream lines, default 0.01
vec3fa[]	vertex	data array of all vertices for <i>all</i> stream lines
vec3fa[]	vertex.color	data array of corresponding vertex colors
int32[]	index	data array of indices to the first vertex of a link

Table 3.9 – Parameters defining a stream-lines geometry.

Each stream line is specified by a set of (aligned) `vec3fa` control points in `vertex`; all vertices belonging to the same logical stream line are connected via [cylinders](#) of a fixed radius `radius`, with additional [spheres](#) at each vertex to make for a smooth transition between the cylinders.

A streamlines geometry can contain multiple disjoint stream lines, each streamline is specified as a list of linear segments (or links) referenced via `index`: each entry `e` of the `index` array points the first vertex of a link (`vertex[index[e]]`) and the second vertex of the link is implicitly the directly following one (`vertex[index[e]+1]`). For example, two stream lines of vertices (A-B-C-D) and (E-F-G), respectively, would internally correspond to five links (A-B, B-C, C-D, E-F, and F-G), and would be specified via an array of vertices [A,B,C,D,E,F,G], plus an array of link indices [0,1,2,4,5].

3.3.5 Isosurfaces

OSPRay can directly render multiple isosurfaces of a volume without first tessellating them. To do so create an isosurfaces geometry by calling `ospNewGeometry` with type string “`isosurfaces`”. Each isosurface will be colored according to the provided volume’s [transfer function](#).

Type	Name	Description
float[]	isovalues	data array of isovalues
OSPVolume	volume	handle of the volume to be isosurfaced

Table 3.10 – Parameters defining an isosurfaces geometry.

3.3.6 Slices

One tool to highlight interesting features of volumetric data is to visualize 2D cuts (or slices) by placing planes into the volume. Such a slices geometry is created by calling `ospNewGeometry` with type string “`slices`”. The planes are defined

by the coefficients (a, b, c, d) of the plane equation $ax + by + cz + d = 0$. Each slice is colored according to the provided volume's [transfer function](#).

Type	Name	Description
vec4f[]	planes	data array with plane coefficients for all slices
OSPVolume	volume	handle of the volume that will be sliced

Table 3.11 – Parameters defining a slices geometry.

3.3.7 Instances

OSPRay supports instancing via a special type of geometry. Instances are created by transforming another given [model](#) `modelToInstantiate` with the given affine transformation `transform` by calling

```
OSPGeometry ospNewInstance(OSPModel modelToInstantiate, const affine3f &transform);
```

3.4 Renderer

A renderer is the central object for rendering in OSPRay. Different renderers implement different features and support different materials. To create a new renderer of given type `type` use

```
OSPRenderer ospNewRenderer(const char *type);
```

The call returns NULL if that type of renderer is not known, or else an OSPRenderer handle to the created renderer. General parameters of all renderers are

Type	Name	Description
OSPModel	model	the model to render
OSPCamera	camera	the camera to be used for rendering
OSPLight[]	lights	data array with handles of the lights
float	epsilon	ray epsilon to avoid self-intersections, default 10^{-6}
int	spp	samples per pixel, default 1
int	maxDepth	maximum ray recursion depth
float	varianceThreshold	threshold for adaptive accumulation

Table 3.12 – Parameters understood by all renderers.

OSPRay's renderers support a feature called adaptive accumulation, which accelerates progressive [rendering](#) by stopping the rendering and refinement of image regions that have an estimated variance below the `varianceThreshold`. This feature requires a [framebuffer](#) with an `OSP_FB_VARIANCE` channel.

3.4.1 SciVis Renderer

The SciVis renderer is a fast ray tracer for scientific visualization which supports volume rendering and ambient occlusion. It is created by passing the type string "scivis" or "raytracer" to `ospNewRenderer`. In addition to the [general parameters](#) understood by all renderers the SciVis renderer supports the following special parameters:

Table 3.13 – Special parameters understood by the SciVis renderer.

Type	Name	Default	Description
bool	shadowsEnabled	false	whether to compute (hard) shadows
int	aoSamples	0	number of rays per sample to compute ambient occlusion
float	aoOcclusionDistance	10^{20}	maximum distance to consider for ambient occlusion
float	aoWeight	0.25	amount of ambient occlusion added in shading
bool	oneSidedLighting	true	if true back-facing surfaces (wrt. light) receive no illumination
vec3f	bgColor	white	background color (RGB)
bool	backgroundEnabled	true	whether to color the background with bgColor
OSPTexture2D	maxDepthTexture	NULL	screen-sized float texture with maximum far distance per pixel

The SciVis renderer supports depth composition with images of other renderers, for example to incorporate help geometries of a 3D UI that were rendered with OpenGL. The screen-sized [texture](#) `maxDepthTexture` must have format `OSP_TEXTURE_R32F` and flag `OSP_TEXTURE_FILTER_NEAREST`. The fetched values are used to limit the distance of primary rays, thus objects of other renderers can hide objects rendered by OSPRay.

3.4.2 Path tracer

The path tracer supports soft shadows, indirect illumination and realistic materials. In addition to the [general parameters](#) understood by all renderers the path tracer supports the following special parameters:

Table 3.14 – Special parameters understood by the path tracer.

Type	Name	Default	Description
float	minContribution	0.01	sample contributions below this value will be neglected to speed-up rendering
float	maxContribution	∞	samples are clamped to this value before they are accumulated into the framebuffer
OSPTexture2D	backplate	NULL	texture image used as background, replacing visible lights in infinity (e.g. the HDRI light)

3.4.3 Model

Models are a container of scene data. They can hold the different [geometries](#) and [volumes](#) as well as references to (and [instances](#) of) other models. A model is associated with a single logical acceleration structure. To create an (empty) model call

```
OSPModel ospNewModel();
```

The call returns an `OSPModel` handle to the created model. To add an already created geometry or volume to a model use

```
void ospAddGeometry(OSPModel, OSPGeometry);
void ospAddVolume(OSPModel, OSPVolume);
```

An existing geometry or volume can be removed from a model with

```
void ospRemoveGeometry(OSPModel, OSPGeometry);
void ospRemoveVolume(OSPModel, OSPVolume);
```

3.4.4 Lights

To let the given renderer create a new light source of given type type use

```
OSPLight ospNewLight(OSPRenderer renderer, const char *type);
```

The call returns NULL if that type of camera is not known by the renderer, or else an OSPLight handle to the created light source. All light sources¹ accept the following parameters:

¹ The [HDRI Light](#) is an exception, it knows about intensity, but not about color.

Type	Name	Description
vec3f(a)	color	color of the light
float	intensity	intensity of the light (a factor)

Table 3.15 – Parameters accepted by the all lights.

The following light types are supported by most OSPRay renderers.

3.4.4.1 Directional Light / Distant Light

The distant light (or traditionally the directional light) is thought to be very far away (outside of the scene), thus its light arrives (almost) as parallel rays. It is created by passing the type string “distant” to ospNewLight. In addition to the [general parameters](#) understood by all lights the distant light supports the following special parameters:

Type	Name	Description
vec3f(a)	direction	main emission direction of the distant light
float	angularDiameter	apparent size (angle in degree) of the light

Table 3.16 – Special parameters accepted by the distant light.

Setting the angular diameter to a value greater than zero will result in soft shadows when the renderer uses stochastic sampling (like the [path tracer](#)). For instance, the apparent size of the sun is about 0.53°.

3.4.4.2 Point Light / Sphere Light

The sphere light (or the special case point light) is a light emitting uniformly in all directions. It is created by passing the type string “sphere” to ospNewLight. In addition to the [general parameters](#) understood by all lights the sphere light supports the following special parameters:

Type	Name	Description
vec3f(a)	position	the center of the sphere light, in world-space
float	radius	the size of the sphere light

Table 3.17 – Special parameters accepted by the sphere light.

Setting the radius to a value greater than zero will result in soft shadows when the renderer uses stochastic sampling (like the [path tracer](#)).

3.4.4.3 Spot Light

The spot light is a light emitting into a cone of directions. It is created by passing the type string “spot” to `ospNewLight`. In addition to the [general parameters](#) understood by all lights the spot light supports the special parameters listed in the table.

Table 3.18 – Special parameters accepted by the spot light.

Type	Name	Description
vec3f(a)	position	the center of the spot light, in world-space
vec3f(a)	direction	main emission direction of the spot
float	openingAngle	full opening angle (in degree) of the spot; outside of this cone is no illumination
float	penumbraAngle	size (angle in degree) of the “penumbra”, the region between the rim (of the illumination cone) and full intensity of the spot; should be smaller than half of openingAngle
float	radius	the size of the spot light, the radius of a disk with normal direction

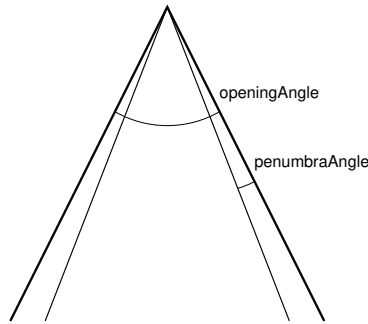


Figure 3.1 – Angles used by SpotLight.

Setting the radius to a value greater than zero will result in soft shadows when the renderer uses stochastic sampling (like the [path tracer](#)).

3.4.4.4 Quad Light

The quad² light is a planar, procedural area light source emitting uniformly on one side into the half space. It is created by passing the type string “quad” to `ospNewLight`. In addition to the [general parameters](#) understood by all lights the spot light supports the following special parameters:

² actually a parallelogram

Type	Name	Description
vec3f(a)	position	world-space position of one vertex of the quad light
vec3f(a)	edge1	vector to one adjacent vertex
vec3f(a)	edge2	vector to the other adjacent vertex

Table 3.19 – Special parameters accepted by the quad light.

The emission side is determined by the cross product of $\text{edge1} \times \text{edge2}$. Note that only renderers that use stochastic sampling (like the path tracer) will compute soft shadows from the quad light. Other renderers will just sample the position of the quad light, which results in hard shadows.

3.4.4.5 HDRI Light

The HDRI light is a textured light source surrounding the scene and illuminating it from infinity. It is created by passing the type string “hdri” to `ospNewLight`.

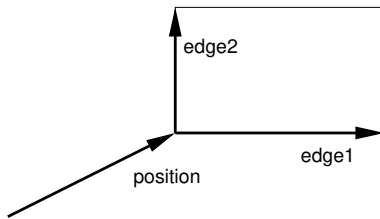


Figure 3.2 – Defining a Quad Light.

In addition to the [parameter intensity](#) the HDRI light supports the following special parameters:

Table 3.20 – Special parameters accepted by the HDRI light.

Type	Name	Description
vec3f(a)	up	up direction of the light in world-space
vec3f(a)	dir	direction to which the center of the texture will be mapped to (analog to panoramic camera)
OSPTexture2D	map	environment map in latitude / longitude format

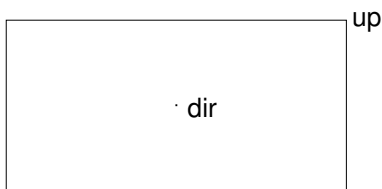


Figure 3.3 – Orientation and Mapping of an HDRI Light.

Note that the currently only the [path tracer](#) supports the HDRI light.

3.4.4.6 Ambient Light

The ambient light surrounds the scene and illuminates it from infinity with constant radiance (determined by combining the [parameters color and intensity](#)). It is created by passing the type string “ambient” to `ospNewLight`.

3.4.5 Materials

Materials describe how light interacts with surfaces, they give objects their distinctive look. To let the given renderer create a new material of given type type call

```
OSPMaterial ospNewMaterial(OSPRenderer, const char *type);
```

The call returns NULL if the material type is not known by the renderer, or else an `OSPMaterial` handle to the created material. The handle can then be used to assign the material to a given geometry with

```
void ospSetMaterial(OSPGeometry, OSPMaterial);
```

3.4.5.1 OBJ Material

The OBJ material is the workhorse material supported by both the [SciVis renderer](#) and the [path tracer](#). It offers widely used common properties like diffuse and specular reflection and is based on the [MTL material format](#) of Lightwave’s OBJ scene files. To create an OBJ material pass the type string “OBJMaterial” to `ospNewMaterial`. Its main parameters are

Type	Name	Default	Description
vec3f	Kd	white 0.8	diffuse color
vec3f	Ks	black	specular color
float	Ns	10	shininess (Phong exponent), usually in $[2-10^4]$
float	d	opaque	opacity
vec3f	Tf	black	transparency filter color
OSPTexure2D	map_Bump	NULL	normal map

Table 3.21 – Main parameters of the OBJ material.

In particular when using the path tracer it is important to adhere to the principle of energy conservation, i.e. that the amount of light reflected by a surface is not larger than the light arriving. Therefore the path tracer issues a warning and renormalizes the color parameters if the sum of Kd, Ks, and Tf is larger than one in any color channel. Similarly important to mention is that almost all materials of the real world reflect at most only about 80% of the incoming light. So even for a white sheet of paper or white wall paint do better not set Kd larger than 0.8; otherwise rendering times are unnecessary long and the contrast in the final images is low (for example, the corners of a white room would hardly be discernible).

Note that currently only the path tracer implements colored transparency with Tf and normal mapping to simulate small geometric features via map_Bump. The normals n in the normal map are wrt. the local tangential shading coordinate system and are encoded as $1/2(n + 1)$, thus a texel $(0.5, 0.5, 1)$ ³ represents the unperturbed shading normal $(0, 0, 1)$. Because of this encoding a linear [texture](#) format is recommended for the normal map. Note that the orientation of normal maps is important for a visually consistent look: by convention OSPRay uses a coordinate system with the origin in the lower left corner; thus a convexity will look green towards the top of the texture image (see also the example image of a normal map). If this is not the case flip the normal map vertically or invert its green channel.

³ respectively $(127, 127, 255)$ for 8 bit textures



Figure 3.4 – Normal map representing an exalted square pyramidal frustum.

All parameters (except Tf) can be textured by passing a [texture](#) handle, prefixed with “map_”. The fetched texels are multiplied by the respective parameter value. Texturing requires [geometries](#) with texture coordinates, e.g. a [triangle mesh](#) with `vertex.texcoord` provided. The color textures `map_Kd` and `map_Ks` are typically in one of the sRGB gamma encoded formats, whereas textures `map_Ns` and `map_d` are usually in a linear format (and only the first component is used). The path tracer additionally supports [texture transformations](#) for all textures.

3.4.5.2 Glass

The [path tracer](#) offers a realistic a glass material, supporting refraction and volumetric attenuation (i.e. the transparency color varies with the geometric thickness). To create a Glass material pass the type string “Glass” to `ospNewMaterial`. Its parameters are

Type	Name	Default	Description
float	eta	1.5	index of refraction
vec3f	attenuationColor	white	resulting color due to attenuation
float	attenuationDistance	1	distance affecting attenuation

Table 3.22 – Parameters of the Glass material.

For convenience, the rather counterintuitive physical attenuation coefficients will be calculated from the user inputs in such a way, that the `attenuationColor` will be the result when white light traveled trough a glass of thickness `attenuationDistance`.

3.4.6 Texture

To create a new 2D texture of size `size` (in pixels) and with the given format and flags use

```
OSPTexture2D ospNewTexture2D(const vec2i &size,
                             const OSPTextureFormat,
                             void *source = NULL,
                             const uint32_t textureCreationFlags = 0);
```

The call returns NULL if the texture could not be created with the given parameters, or else an `OSPTexture2D` handle to the created texture. The supported texture formats are:

Name	Description
OSP_TEXTURE_RGBA8	8 bit [0–255] linear components red, green, blue, alpha
OSP_TEXTURE_SRGBA	8 bit sRGB gamma encoded color components, and linear alpha
OSP_TEXTURE_RGBA32F	32 bit float components red, green, blue, alpha
OSP_TEXTURE_RGB8	8 bit [0–255] linear components red, green, blue
OSP_TEXTURE_SRGB	8 bit sRGB gamma encoded components red, green, blue
OSP_TEXTURE_RGB32F	32 bit float components red, green, blue
OSP_TEXTURE_R8	8 bit [0–255] linear single component
OSP_TEXTURE_R32F	32 bit float single component

Table 3.23 – Supported texture formats by `ospNewTexture2D`, i.e. valid constants of type `OSPTextureFormat`.

The texel data addressed by `source` starts with the texels in the lower left corner of the texture image, like in OpenGL. Similar to [data](#) buffers the texel data can be shared by the application by specifying the `OSP_TEXTURE_SHARED_BUFFER` flag. Per default a texture fetch is filtered by performing bi-linear interpolation of the nearest 2×2 texels; if instead fetching only the nearest texel is desired (i.e. no filtering) then pass the `OSP_TEXTURE_FILTER_NEAREST` flag. Both texture creating flags can be combined with a bitwise OR.

3.4.7 Texture Transformations

Many materials with textures also offer to manipulate the placement of these textures with the help of texture transformations. If so, this convention shall be used. The following parameters (prefixed with “texture_name.”) are combined into one transformation matrix:

Type	Name	Description
vec4f	transform	interpreted as 2×2 matrix (linear part), column-major
float	rotation	angle in degree, counterclock-wise, around center
vec2f	scale	enlarge texture, relative to center (0.5, 0.5)
vec2f	translation	move texture in positive direction (right/up)

Table 3.24 – Parameters to define texture coordinate transformations.

The transformations are applied in the given order. Rotation, scale and translation are interpreted “texture centric”, i.e. their effect seen by an user are relative to the texture (although the transformations are applied to the texture coordinates).

3.4.8 Cameras

To create a new camera of given type type use

```
OSPCamera ospNewCamera(const char *type);
```

The call returns NULL if that type of camera is not known, or else an OSPCamera handle to the created camera. All cameras accept these parameters:

Type	Name	Description
vec3f(a)	pos	position of the camera in world-space
vec3f(a)	dir	main viewing direction of the camera
vec3f(a)	up	up direction of the camera
float	nearClip	near clipping distance
vec2f	imageStart	start of image region (lower left corner)
vec2f	imageEnd	end of image region (upper right corner)

Table 3.25 – Parameters accepted by all cameras.

The camera is placed and oriented in the world with pos, dir and up. The region of the camera sensor that is rendered to the image can be specified in normalized screen-space coordinates with imageStart (lower left corner) and imageEnd (upper right corner). This can be used, for example, to crop the image or to achieve asymmetrical view frusta. Note that values outside the default range of [0–1] are valid, which is useful to easily realize overscan or film gate, or to emulate a shifted sensor.

3.4.8.1 Perspective Camera

The perspective camera implements a simple thinlens camera for perspective rendering, supporting optionally depth of field and stereo rendering, but no motion blur. It is created by passing the type string “perspective” to ospNewCamera. In addition to the [general parameters](#) understood by all cameras the perspective camera supports the special parameters listed in the table below.

Note that when setting the aspect ratio a non-default image region (using imageStart & imageEnd) needs to be regarded.

Table 3.26 – Parameters accepted by the perspective camera.

Type	Name	Description
float	fovy	the field of view (angle in degree) of the frame's height
float	aspect	ratio of width by height of the frame
float	apertureRadius	size of the aperture, controls the depth of field
float	focusDistance	distance at where the image is sharpest when depth of field is enabled
bool	architectural	vertical edges are projected to be parallel
int	stereoMode	0: no stereo (default), 1: left eye, 2: right eye, 3: side-by-side
float	interpupillaryDistance	distance between left and right eye when stereo is enabled

In architectural photography it is often desired for aesthetic reasons to display the vertical edges of buildings or walls vertically in the image as well, regardless of how the camera is tilted. Enabling the `architectural` mode achieves this by internally leveling the camera parallel to the ground (based on the up direction) and then shifting the lens such that the objects in direction `dir` are centered in the image. If finer control of the lens shift is needed use `imageStart` & `imageEnd`. Because the camera is now effectively leveled its image plane and thus the plane of focus is oriented parallel to the front of buildings, the whole façade appears sharp, as can be seen in the example images below.



Figure 3.5 – Example image created with the perspective camera, featuring depth of field.

3.4.8.2 Orthographic Camera

The orthographic camera implements a simple camera with orthographic projection, without support for depth of field or motion blur. It is created by passing the type string “orthographic” to `ospNewCamera`. In addition to the [general parameters](#) understood by all cameras the orthographic camera supports the following

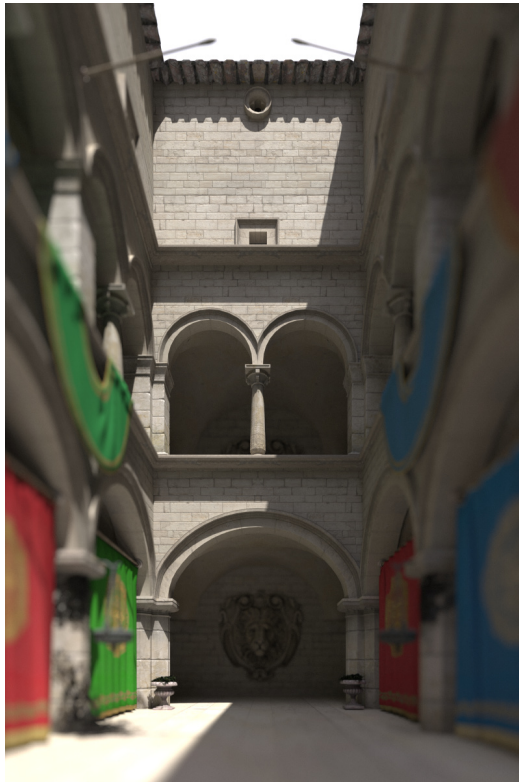


Figure 3.6 – Enabling the architectural flag corrects the perspective projection distortion, resulting in parallel vertical edges.

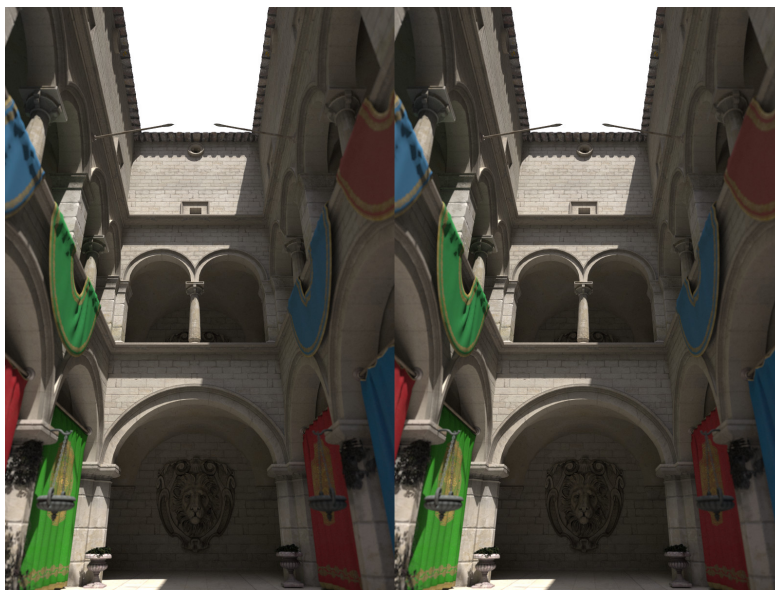


Figure 3.7 – Example 3D stereo image using stereoMode side-by-side.

special parameters:

Type	Name	Description
float	height	size of the camera's image plane in y, in world coordinates
float	aspect	ratio of width by height of the frame

Table 3.27 – Parameters accepted by the orthographic camera.

For convenience the size of the camera sensor, and thus the extent of the scene that is captured in the image, can be controlled with the `height` parameter. The same effect can be achieved with `imageStart` and `imageEnd`, and both methods can be combined. In any case, the aspect ratio needs to be set accordingly to get an undistorted image.



Figure 3.8 – Example image created with the orthographic camera.

3.4.8.3 Panoramic Camera

The panoramic camera implements a simple camera without support for motion blur. It captures the complete surrounding with a latitude / longitude mapping and thus the rendered images should best have a ratio of 2:1. A panoramic camera is created by passing the type string “panoramic” to `ospNewCamera`. It is placed and oriented in the scene by using the [general parameters](#) understood by all cameras.

3.4.9 Picking

To get the world-space position of the geometry (if any) seen at $[0-1]$ normalized screen-space pixel coordinates `screenPos` use

```
void ospPick(OSPPickResult*, OSPRenderer, const vec2f &screenPos);
```

The result is returned in the provided `OSPPickResult` struct:



Figure 3.9 – Latitude / longitude map created with the panoramic camera.

```
typedef struct {
    vec3f position; // the position of the hit point (in world-space)
    bool hit;       // whether or not a hit actually occurred
} OSPickResult;
```

Note that `ospPick` considers exactly the same camera of the given renderer that is used to render an image, thus matching results can be expected. If the camera supports depth of field then the center of the lens and thus the center of the circle of confusion is used for picking.

3.5 Framebuffer

The framebuffer holds the rendered 2D image (and optionally auxiliary information associated with pixels). To create a new framebuffer object of given size (in pixels), color format, and channels use

```
OSPFramebuffer ospNewFramebuffer(const vec2i &size,
                                const OSPFramebufferFormat format = OSP_FB_SRGBA,
                                const uint32_t framebufferChannels = OSP_FB_COLOR);
```

The parameter `format` describes the format the color buffer has *on the host*, and the format that `ospMapFramebuffer` will eventually return. Valid values are:

Name	Description
OSP_FB_NONE	framebuffer will not be mapped by the application
OSP_FB_RGBA8	8 bit [0–255] linear component red, green, blue, alpha
OSP_FB_SRGBA	8 bit sRGB gamma encoded color components, and linear alpha
OSP_FB_RGBA32F	32 bit float components red, green, blue, alpha

Table 3.28 – Supported color formats of the framebuffer that can be passed to `ospNewFramebuffer`, i.e. valid constants of type `OSPFramebufferFormat`.

The parameter `framebufferChannels` specifies which channels the framebuffer holds, and can be combined together by bitwise OR from the values of `OSPFramebufferChannel` listed in the table below.

If a certain channel value is *not* specified, the given buffer channel will not be present. Note that `ospray` makes a very clear distinction between the *external* format of the framebuffer and the internal one: The external format is the format the user specifies in the `format` parameter; it specifies what color format `OSPRay` will eventually *return* the framebuffer to the application (when calling `ospMapFramebuffer`): no matter what `OSPRay` uses internally, it will simply return a 2D array of pixels of that format, with possibly all kinds of reformatting,

Name	Description
OSP_FB_COLOR	RGB color including alpha
OSP_FB_DEPTH	Euclidean distance to the camera (<i>not</i> to the image plane)
OSP_FB_ACCUM	accumulation buffer for progressive refinement
OSP_FB_VARIANCE	estimate of the current variance, see rendering

Table 3.29 – Framebuffer channels constants (of type `OSPFramebufferChannel`), naming optional information the framebuffer can store. These values can be combined by bitwise OR when passed to `ospNewFramebuffer` or `ospClearFramebuffer`.

compression/decompression, etc, going on in-between the generation of the *internal* framebuffer and the mapping of the externally visible one.

In particular, `OSP_FB_NONE` is a perfectly valid pixel format for a framebuffer that an application will never map. For example, an application driving a display wall may well generate an intermediate framebuffer and eventually transfer its pixel to the individual displays using an `OSPPixelOp` [pixel operation](#).

A framebuffer can be freed again using

```
void ospFreeFramebuffer(OSPFramebuffer);
```

Because OSPRay uses reference counting internally the framebuffer may not immediately be deleted at this time.

The application can map the given channel of a framebuffer – and thus access the stored pixel information – via

```
const void *ospMapFramebuffer(OSPFramebuffer,
                               const OSPFramebufferChannel = OSP_FB_COLOR);
```

Note that only `OSP_FB_COLOR` or `OSP_FB_DEPTH` can be mapped. The origin of the screen coordinate system in OSPRay is the lower left corner (as in OpenGL), thus the first pixel addressed by the returned pointer is the lower left pixel of the image.

A previously mapped channel of a framebuffer can be unmapped by passing the received pointer mapped to

```
void ospUnmapFramebuffer(const void *mapped, OSPFramebuffer);
```

The individual channels of a framebuffer can be cleared with

```
void ospFramebufferClear(OSPFramebuffer, const uint32_t framebufferChannels);
```

When selected, `OSP_FB_COLOR` will clear the color buffer to black (0, 0, 0, 0), `OSP_FB_DEPTH` will clear the depth buffer to inf, `OSP_FB_ACCUM` will clear the accumulation buffer to black, resets the accumulation counter `accumID` and also clears the variance buffer (if present) to inf.

Pixel Operation

A pixel operation are functions that are applied to every pixel that gets written into a framebuffer. Examples include post-processing, filtering, blending, tone mapping, or sending tiles to a display wall. To create a new pixel operation of given type type use

```
OSPPixelOp ospNewPixelOp(const char *type);
```

The call returns NULL if that type is not known, or else an `OSPPixelOp` handle to the created pixel operation.

To set a pixel operation to the given framebuffer use

```
void ospSetPixelOp(OSPFramebuffer, OSPPixelOp);
```

3.6 Rendering

To render a frame into the given framebuffer with the given renderer use

```
float ospRenderFrame(OSPFrameBuffer, OSPRenderer,  
                    const uint32_t framebufferChannels = OSP_FB_COLOR);
```

The third parameter specifies what channel(s) of the framebuffer is written to⁴. What to render and how to render it depends on the renderer's parameters. If the framebuffer supports accumulation (i.e. it was created with `OSP_FB_ACCUM`) then successive calls to `ospRenderFrame` will progressively refine the rendered image. If additionally the framebuffer has an `OSP_FB_VARIANCE` channel then `ospRenderFrame` returns an estimate of the current variance of the rendered image, otherwise `inf` is returned. The estimated variance can be used by the application as a quality indicator and thus to decide whether to stop or to continue progressive rendering.

⁴This is currently not implemented, i.e. all channels of the framebuffer are always updated.

Chapter 4

Examples

4.1 Tutorial

A minimal working example demonstrating how to use OSPRay can be found at `apps/ospTutorial.cpp`¹. On Linux build it in the `build_directory` with

¹ A C99 version is available at `apps/ospTutorial.c`.

```
g++ ../apps/ospTutorial.cpp -I ../ospray/include -I .. -I ../ospray/embree/common \
    ./libospray.so -Wl,-rpath,. -o ospTutorial
```

On Windows build it in the `build_directory\Configuration` with

```
cl ../apps/ospTutorial.cpp /EHsc -I ../ospray/include -I .. -I ../ospray/embree/common ^
-I ../ospray/embree/common ospray.lib
```

Running `ospTutorial` will create two images of two triangles, rendered with the Scientific Visualization renderer with full Ambient Occlusion. The first image `firstFrame.ppm` shows the result after one call to `ospRenderFrame` – jagged edges and noise in the shadow can be seen. Calling `ospRenderFrame` multiple times enables progressive refinement, resulting in antialiased edges and converged shadows, shown after ten frames in the second image `accumulated-Frames.png`.

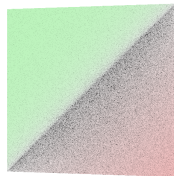


Figure 4.1 – First frame.

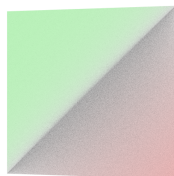


Figure 4.2 – After accumulating ten frames.

4.2 Qt Viewer

OSPRay also includes a demo viewer application `ospQtViewer`, showcasing all features of OSPRay.

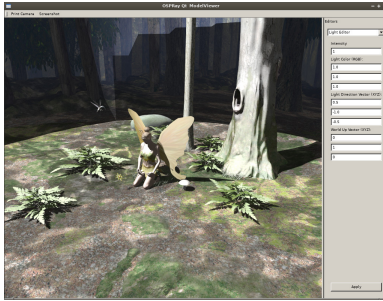


Figure 4.3 – Screenshot of `ospQtViewer`.

4.3 Volume Viewer

Additionally, OSPRay includes a demo viewer application `ospVolumeViewer`, which is specifically tailored for volume rendering.

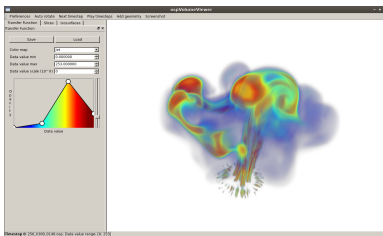


Figure 4.4 – Screenshot of `ospVolumeViewer`.

4.4 Demos

Several ready-to-run demos, models and data sets for OSPRay can be found at the [OSPRay Demos and Examples](#) page.

© 2013–2016 Intel Corporation

Intel, the Intel logo, Xeon, Intel Xeon Phi, and Intel Core are trademarks of Intel Corporation in the U.S. and/or other countries.

*Other names and brands may be claimed as the property of others.

Optimization Notice: Intel's compilers may or may not optimize to the same degree for non-Intel microprocessors for optimizations that are not unique to Intel microprocessors. These optimizations include SSE2, SSE3, and SSSE3 instruction sets and other optimizations. Intel does not guarantee the availability, functionality, or effectiveness of any optimization on microprocessors not manufactured by Intel. Microprocessor-dependent optimizations in this product are intended for use with Intel microprocessors. Certain optimizations not specific to Intel microarchitecture are reserved for Intel microprocessors. Please refer to the applicable product User and Reference Guides for more information regarding the specific instruction sets covered by this notice.

Notice Revision #20110804