

Review Part 1

Part 1. Concepts to review

- a) Classification of equations
 - Order of an equation.
 - ODE vs PDE.
 - Linear vs nonlinear.
- b) Definition of solutions
 - Requirements for a function to be a solution
 - Maximum interval of existence for an initial value problem: this is the largest possible interval on which the solution is defined and it also contains the initial point at which the initial condition is specified.
- c) First order linear equations
 - These are equations of the form $a_1(x)y'(x) + a_0y(x) = g(x), x \in I$. For initial value problems, one specifies $y(x_0) = y_0$ for some $x_0 \in I$.
 - If a_1, a_0, g are continuous on I and $a_1(x) \neq 0$ for all $x \in I$, then the existence and uniqueness of a solution y to an initial value problem on I is guaranteed.
 - Note that here y exists on the entirety of I , not just a sub-interval.
 - A special case of this is when one consider equations of the form $y'(x) + a_0(x)y(x) = g(x)$. If a_0, g are continuous on \mathbb{R} , then a unique solution to an initial value problem over \mathbb{R} exists globally over \mathbb{R} .
 - Can be solved explicitly using the method of integrating factors.
- d) Structure of solutions to first order linear equations
 - The general solution to the inhomogeneous problem is any particular solution plus the general solution to the homogeneous problem.
 - The homogeneous part of the solutions can be scaled, the inhomogeneous part of the solution cannot be scaled.
 - The method of integrating factors recovers both the homogeneous solution and the inhomogeneous solution simultaneously.
- e) General first order equations
 - The existence and uniqueness theorems guarantees the (local, not global) existence and uniqueness of solutions to initial value problems.
 - If uniqueness failed for an initial value problem, the conditions of the theorem must not have been met.
- f) Separable equations
 - After identifying the constant functions, an implicit solution can usually be found via “separating the variables.”
 - Sometimes explicit solutions and intervals of existence can be found if the implicit relation is simple.
 - Standard techniques: manipulating identities involving \ln , removing absolute values by working over a smaller interval and absorbing the \pm sign into the arbitrary constant coming from the constant of integration.
- g) Autonomous equations
 - Special type of separable equations.
 - Solution curves are strictly monotone.
 - Non-constant solution curves converge to constant solutions either going forward in time or backwards in time.
 - One can perform stability analysis on the critical points (which correspond to constant functions) by doing a simple sign analysis.
- h) Bernoulli equations
 - Can be solved explicitly using a substitution method.
 - By introducing a suitable function $v = v(y)$, one may write down a first order linear equation in v and solve for v , and use it to recover y .
- i) Differential equations with homogeneous functions
 - Can be solved implicitly (sometimes explicitly) using a substitution method.
 - By introducing a suitable function $v = v(x, y)$, one may write down a separable equation for v and solve for v , and use it to recover y .
 - Important to also look for constant solutions in v when solving the corresponding separable equation.
- j) General strategies for solving ODEs
 - When one is manipulating an equation, one is identifying candidate solutions.

- The idea is to identify the correct “form” of the solution by making a series of forward implications, at the price of potentially working over smaller and smaller sub-intervals.
 - Once a correct candidate form has been identified, one can proceed to verify that the candidate solution is a genuine solution and also identify the maximal interval of existence.
 - The maximal interval of existence in general depends on the initial condition specified.
- k) Directional fields and the method of isoclines
- Method for sketching solution curves without solving for them analytically.
 - Identifying the isoclines can help sketch out the directional field much faster than computing the linear elements point-by-point.
 - Directional fields for autonomous equations are easiest to sketch: the slopes are always constant along each horizontal line.
- l) Exact differential equations
- These are equations of the form $M(x, y(x)) + N(x, y(x))y'(x) = 0, x \in I$.
 - Necessary and sufficient condition for the equation to be exact in a region: $M_y(x, y) = N_x(x, y)$ in some region R .
 - If an equation is exact, an implicit solution of the form $F(x, y(x)) = C, x \in I$ can be recovered by using $F_x = M$ and $F_y = N$.
- m) Linear independence and the Wronskian
- a) Linear combination: if f_1, \dots, f_k are k functions, the function f defined via $f = c_1f_1 + \dots + c_kf_k$ where c_1, \dots, c_k are k real numbers is a linear combination of the functions f_1, \dots, f_k .
 - b) Linear independence is a concept from linear algebra that encodes the notion of “non-redundancy” when we consider all possible linear combinations that can be built from a set of functions.
 - c) The linear independence of functions is encoded in an object called the Wronskian.
 - d) Under certain conditions, the vanishing of the Wronskian over an interval I implies the linear dependence of a set of functions. If the Wronskian is non-zero at any point $t_0 \in I$ then the set of functions is linearly independent.
 - e) If the functions in question are solutions to linear homogeneous differential equations over an interval I , then the Wronskian is either never zero or always equal to zero over I .

Part 2. First order linear equations

Problem 1.1. Consider the initial value problem

$$\begin{cases} y'(x) + 4xy(x) = x^3 e^{x^2}, & x \in \mathbb{R} \\ y(0) = -1. \end{cases} \quad (1.1)$$

- a) Find a candidate solution to the initial value problem.
- b) Verify that the candidate solution from the previous part is a solution on $J = \mathbb{R}$.
- c) Is the solution to the initial value problem unique?

Part a). Since this is a first order linear equation, we can use the method of integrating factors. We may choose an integrating factor μ to be

$$\mu(x) = \exp\left(\int 4x \, dx\right) = e^{2x^2}, \quad x \in \mathbb{R}. \quad (1.2)$$

Then upon multiplying both sides of the original equation by μ , we find that

$$\frac{d}{dx}[e^{2x^2} y(x)] = x^3 e^{3x^2}, \quad x \in \mathbb{R}. \quad (1.3)$$

We note that by performing integration by parts,

$$\int x^3 e^{3x^2} \, dx = \frac{1}{6} \int x^2 (6x) e^{3x^2} \, dx = \frac{1}{6} \left(x^2 e^{3x^2} - \int 2x e^{3x^2} \, dx \right) = \frac{1}{6} \left(x^2 e^{3x^2} - \frac{e^{3x^2}}{3} + C \right). \quad (1.4)$$

Therefore we find that

$$y(x) = \frac{e^{x^2}}{18} (3x^2 - 1) + C e^{-2x^2}. \quad (1.5)$$

If $y(0) = -1$, then we require

$$y(0) = -\frac{1}{18} + C = -1 \implies C = \frac{-17}{18}. \quad (1.6)$$

□

Part b). To verify that y defined via

$$y(x) = \frac{e^{x^2}}{18} (3x^2 - 1) - \frac{17}{18} e^{-2x^2}, \quad x \in \mathbb{R} \quad (1.7)$$

is a solution to the initial value problem on $J = \mathbb{R}$, we first note that

$$y(0) = -\frac{1}{18} - \frac{17}{18} = -1. \quad (1.8)$$

Then, we note that

$$y'(x) = \frac{e^{x^2}}{18} (6x + 2x(3x^2 - 1)) + \frac{17}{18} (4x) e^{-2x^2} = \frac{e^{x^2}}{18} (6x^3 + 4x) + \frac{17}{18} (4x) e^{-2x^2} \quad (1.9)$$

We may then verify that

$$y'(x) + 4xy(x) = \frac{e^{x^2}}{18} (6x^3 + 4x) + \frac{17}{18} (4x) e^{-2x^2} + \frac{e^{x^2}}{18} (12x^3 - 4x) - \frac{17}{18} (4x) e^{-2x^2} \quad (1.10)$$

$$= \frac{e^{x^2}}{18} (6x^3 + 4x) + \frac{e^{x^2}}{18} (12x^3 - 4x) + \underbrace{\frac{17}{18} (4x) e^{-2x^2} - \frac{17}{18} (4x) e^{-2x^2}}_{=0} \quad (1.11)$$

$$= \frac{18x^3 e^{x^2}}{18} = x^3 e^{x^2}, \quad x \in \mathbb{R}. \quad (1.12)$$

Therefore the candidate solution from part a) is a solution over \mathbb{R} . □

Part c). Yes. We note that the equation is in the form of

$$y'(x) + a_0(x)y(x) = f(x), \quad x \in \mathbb{R}, \quad (1.13)$$

for

$$a_0(x) = 4x, \quad f(x) = x^3 e^{x^2}, \quad x \in \mathbb{R}. \quad (1.14)$$

Since a_0, f are both continuous over \mathbb{R} , by the existence and uniqueness theorem for first order linear differential equations, the solution is unique. \square

Problem 1.2. Consider the initial value problem

$$\begin{cases} xy'(x) + 3y(x) = x^3, & x \in \mathbb{R} \\ y(1) = 10. \end{cases} \quad (1.15)$$

- Find a candidate solution via the method of integrating factors. You may assume that the candidate solution solves the equation without verifying.
- What is the maximal interval of existence of the solution? Explain your reasoning.
- Is the solution that you found unique?
- What happens if we change the initial condition to $y(0) = 1$?

Part a). Since the initial condition is specified at $x = 1$, we may restrict to the interval $I = (0, \infty)$ for now and study the equation

$$y'(x) + \frac{3}{x}y(x) = x^2, \quad x > 0. \quad (1.16)$$

An integrating factor for this equation can be chosen to be

$$\mu(x) = \exp\left(\int \frac{3}{x} dx\right) = \exp(3 \ln |x|) = \exp(\ln x^3) = x^3, \quad x > 0. \quad (1.17)$$

Therefore upon multiplying both sides of the equation by μ , we arrive at the equation

$$\frac{d}{dx}[x^3 y(x)] = x^5, \quad x > 0. \quad (1.18)$$

Then via direct integration,

$$x^3 y(x) = \frac{x^6}{6} + C, \quad x \in \mathbb{R}, \quad (1.19)$$

where C is an arbitrary constant. This implies that

$$y(x) = \frac{x^3}{6} + Cx^{-3}, \quad x > 0. \quad (1.20)$$

If $y(1) = 10$, then we must have

$$y(1) = \frac{1}{6} + C = 10 \implies C = \frac{59}{6}. \quad (1.21)$$

Thus a candidate solution to the initial value problem is

$$y(x) = \frac{x^3}{6} + \frac{59}{6}x^{-3}, \quad x > 0. \quad (1.22)$$

□

Part b). From part a) we see that the maximal interval of existence is $J = (0, \infty)$, since it is the largest interval that contains 1 and on which the function y is a solution to the initial value problem. Note that we cannot extend J past 0 since the function x^{-3} is singular at $x = 0$. □

Part c). Yes. If we restrict to the interval $I = (0, \infty)$, then y solving the original equation is equivalent to y solving the equation

$$y'(x) - \frac{3}{x}y(x) = x^2, \quad x \in I. \quad (1.23)$$

Since a_0, f defined via

$$a_0(x) = -\frac{3}{x}, \quad f(x) = x^2, \quad x \in I \quad (1.24)$$

are continuous over I , by the existence and uniqueness theorem for first order linear equations we know that the function identified in the previous parts is the unique solution to the initial value problem. □

Part d). We note that if the initial condition is $y(0) = 1$, then we cannot include any contributions from the homogeneous solutions as they are singular at $x = 0$. Furthermore, the particular solution

$$y_p(0) = \frac{0^3}{6} = 0 \neq 1, \quad (1.25)$$

therefore we see that there are no solutions to the initial value problem. □

Problem 1.3. Consider the initial value problem

$$\begin{cases} y'(t) - \frac{2}{(t+1)(t-1)}y(t) = t-1, & t \in I \\ y(t_0) = 0 \end{cases} \quad (1.26)$$

where $t_0 \in I$ is and I is an unspecified interval.

- a) At which points t_0 is the existence and uniqueness of a solution not guaranteed?
- b) Suppose the interval is $I = (-1, 1)$. Find an analytic expression for the solution to the initial value problem where $t_0 = 0$. You may skip the verification step. (Note: $|t-1| = -(t-1)$ if $t \in (-1, 1)$.)

Part a). Consider the functions a_0, f defined via

$$a_0(t) = \frac{2}{(t+1)(t-1)}, \quad t \neq \pm 1 \quad (1.27)$$

and

$$f(t) = t-1, \quad t \in \mathbb{R}. \quad (1.28)$$

Since a_0, f are both continuous away from the points $t = \pm 1$ but a_0 is not continuous when $t = \pm 1$, we see that the existence and uniqueness of solutions is not guaranteed when $t_0 = \pm 1$. Therefore the existence and uniqueness of solutions is guaranteed on the intervals $(-\infty, -1)$, $(-1, 1)$, and $(1, \infty)$. \square

Part b). Since this is a first order linear equation, we can solve it using the method of integrating factors. We may choose an integrating factor μ as

$$\begin{aligned} \mu(t) &= \exp \left(-2 \int \frac{1}{(t+1)(t-1)} dt \right) = \exp \left(\int \frac{1}{t+1} - \frac{1}{t-1} dt \right) \\ &= \exp (|t+1| - |t-1|) = \exp \left(\ln \left| \frac{t+1}{t-1} \right| \right) = \frac{t+1}{-(t-1)}, \quad t \in I. \end{aligned} \quad (1.29)$$

Note: since integrating factors are agnostic to scaling factors, choosing

$$\mu(t) = \frac{t+1}{t-1}, \quad t \in I \quad (1.30)$$

is fine too. For the sake of simplicity we will choose the latter one. Then

$$\frac{d}{dt} \left(\frac{t+1}{t-1} y(t) \right) = t+1, \quad (1.31)$$

which implies that

$$y(t) = \frac{t-1}{t+1} \left(\frac{t^2}{2} + t + C \right), \quad t \in I. \quad (1.32)$$

where C is arbitrary. \square

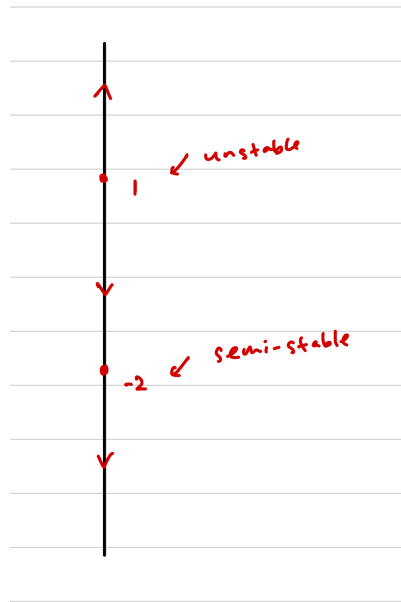
Part 3. Autonomous equations and stability analysis

Problem 1.4. Consider the differential equation

$$y'(x) = (y(x) - 1)(y(x) + 2)^2((y(x))^2 + 1), \quad x \in \mathbb{R}. \quad (1.33)$$

- Draw the one-dimensional phase portrait for this differential equation.
- Let $y(t)$ be the solution satisfying the initial condition $y(0) = 0$. Can the value of y ever be less than -2 ? Why or why not?

Part a). We note that since $(y + 2)^2(y^2 + 1) \geq 0$ for all $y \in \mathbb{R}$, the sign of $(y - 1)(y + 2)^2(y^2 + 1)$ only depends on the linear factor $y - 1$. This leads to the following sketch for the one-dimensional phase portrait.



□

Part b). We note that since -2 is a critical point, $y(x) = -2$ for $x \in \mathbb{R}$ is a constant solution to the equation. Since different solution curves cannot cross due to uniqueness, it is not possible for any solution curve to start above -2 at $x = 0$ (note that $y(0) = 0 > -2$) and then fall below -2 . □

Part 4. Separable equations

Problem 1.5. Consider the differential equation

$$y'(x) = \frac{x((y(x))^2 + 1)}{2y(x)}, \quad x \in \mathbb{R}. \quad (1.34)$$

- a) Does the equation admit any constant solutions?
- b) Find the general candidate implicit solution to the equation. You do not need to specify the interval of existence.

Part a). We note that the function h defined via

$$h(y) = \frac{y^2 + 1}{2y}, \quad y \in \mathbb{R} \setminus \{0\} \quad (1.35)$$

does not admit any critical points. In other words, no constant value of y makes h equal to zero, therefore the equation does not admit any constant solutions. \square

Part b). Note that if y is a solution to the original equation, then

$$\frac{2y(x)}{(y(x))^2 + 1} y'(x) = x, \quad x \in \mathbb{R}. \quad (1.36)$$

Thus we have the identity

$$\int \frac{2y}{y^2 + 1} dy = \int x dx. \quad (1.37)$$

This implies that

$$\ln(y(x)^2 + 1) = \frac{x^2}{2} + C, \quad x \in I \quad (1.38)$$

is the general implicit solution to the equation over some interval I , and C is an arbitrary constant. \square

Problem 1.6. Consider the differential equation

$$y'(x) = (y(x))^8 e^{-x^4}, \quad x \in \mathbb{R} \quad (1.39)$$

- a) Does the equation admit any constant solutions?
- b) What is one solution y satisfying $y(0) = 0$? Is this solution unique? (Hint: you don't need to solve for the general solution if you did part a) correctly.)

Part a). Yes, the equation admits the constant solution $y(x) = 0$ for all $x \in \mathbb{R}$. □

Part b). Clearly, the zero function identified in the previous part is a solution satisfying the initial condition $y(0) = 0$. Note that if we define the function f via

$$f(x, y) = y^8 e^{-x^4}, \quad (x, y) \in \mathbb{R}^2, \quad (1.40)$$

we have

$$\frac{\partial f}{\partial y}(x, y) = 8y^7 e^{-x^4}, \quad (x, y) \in \mathbb{R}^2. \quad (1.41)$$

Here we see that f and $\frac{\partial f}{\partial y}$ are continuous on \mathbb{R}^2 , therefore the zero solution must also be the unique solution to the initial value problem. □

Problem 1.7. Consider the initial value problem

$$\begin{cases} y'(x) = \frac{-\sin(x)}{2y(x)}, & x \in \mathbb{R} \\ y(0) = \frac{1}{\sqrt{2}}. \end{cases} \quad (1.42)$$

- a) Find a candidate implicit solution to the initial value problem. You do not need to specify the interval of existence.
- b) Identify a candidate explicit solution to the initial value problem and identify the maximal interval of existence.

Part a). First note that the equation does not admit any constant solutions. If y is a solution to the initial value problem, then

$$2y(x)y'(x) = -\sin(x), \quad x \in \mathbb{R}. \quad (1.43)$$

This implies that

$$(y(x))^2 = \cos(x) + C, \quad x \in I \quad (1.44)$$

for some interval I . If $y(0) = \frac{1}{\sqrt{2}}$, then

$$\frac{1}{2} = 1 + C \implies C = -\frac{1}{2}. \quad (1.45)$$

Therefore the implicit solution to the initial value problem is

$$(y(x))^2 = \cos(x) - \frac{1}{2}, \quad x \in I. \quad (1.46)$$

□

b). We note that since $y(0) > 0$, we can write y explicitly as

$$y(x) = \sqrt{\cos(x) - \frac{1}{2}}, \quad x \in I \quad (1.47)$$

for some interval I . Since $y(x)$ cannot be equal to 0 for the original equation to be well-defined, we require

$$\cos(x) - \frac{1}{2} > 0 \iff \cos(x) > \frac{1}{2}, \quad x \in I. \quad (1.48)$$

The largest interval for which this is true that contains 0 is $I = (-\pi/3, \pi/3)$.

□

Part 5. Bernoulli differential equations**Problem 1.8.** Solve the initial value problem

$$\begin{cases} y'(x) = y(x)(x(y(x))^3 - 1), & x \in \mathbb{R} \\ y(0) = 3^{1/3}. \end{cases} \quad (1.49)$$

What is the maximal interval of existence of the solution?

Solution. We note that if y is a solution to the equation, then

$$y'(x) + y(x) = x(y(x))^4, \quad x \in \mathbb{R}. \quad (1.50)$$

This is a Bernoulli differential equation, and we use the substitution

$$v(x) = (y(x))^{-3}, \quad x \in I \quad (1.51)$$

on an interval for which $y(x) \neq 0$ for all $x \in I$. Then

$$v'(x) = -3(y(x))^{-4}, \quad x \in I \quad (1.52)$$

and also y satisfies the equation

$$(y(x))^{-4}y'(x) + y^{-3}(x) = x, \quad x \in I. \quad (1.53)$$

Therefore v satisfies the equation

$$-\frac{1}{3}v'(x) + v(x) = x, \quad x \in I, \quad (1.54)$$

or

$$v'(x) - 3v(x) = -3x, \quad x \in I. \quad (1.55)$$

Therefore v satisfies a first order linear equation and we may choose an integrating factor μ via

$$\mu(x) = \exp\left(\int -3 \, dx\right) = e^{-3x}, \quad x \in I. \quad (1.56)$$

Thus

$$\frac{d}{dx}[e^{-3x}v(x)] = -3xe^{-3x}, \quad x \in I. \quad (1.57)$$

Thus

$$e^{-3x}v(x) = \int x(-3e^{-3x}) \, dx = xe^{-3x} - \frac{e^{-3x}}{-3} + C, \quad x \in I \quad (1.58)$$

where C is an arbitrary constant. Therefore

$$v(x) = x + \frac{1}{3} + Ce^{3x}, \quad x \in I. \quad (1.59)$$

If $y(0) = 3^{1/3}$, then $v(0) = (y(0))^{-3} = \frac{1}{3}$. Thus

$$v(0) = \frac{1}{3} + Ce^{3x} = \frac{1}{3} \implies C = 0. \quad (1.60)$$

Thus a candidate solution to the initial value problem is

$$y(x) = \left(x + \frac{1}{3}\right)^{-1/3}, \quad x \in I. \quad (1.61)$$

Here we see that the maximal interval of existence is $J = (-1/3, \infty)$. □

Part 6. Differential equations with homogeneous functions**Problem 1.9.** Solve the initial value problem

$$\begin{cases} (3x + y(x))y'(x) = x + 3y(x), & x \in \mathbb{R} \\ y(1) = 1. \end{cases} \quad (1.62)$$

What is the maximal interval of existence of the solution?

Solution. We note that if y is a solution to the initial value problem, we may assume that there exists an interval I not containing 0 for which

$$y'(x) = \frac{x + 3y(x)}{3x + y(x)} = \frac{1 + 3\frac{y(x)}{x}}{3 + \frac{y(x)}{x}}, \quad x \in I. \quad (1.63)$$

If we define the function v via

$$v(x) = \frac{y(x)}{x}, \quad x \in I, \quad (1.64)$$

then $y = xv$ and

$$y'(x) = v(x) + xv'(x), \quad x \in I. \quad (1.65)$$

Therefore v satisfies the separable equation

$$v(x) + xv'(x) = \frac{1 + 3v}{3 + v}, \quad x \in I. \quad (1.66)$$

This implies that

$$xv'(x) = \frac{1 - (v(x))^2}{v(x) + 3} = \frac{(1 - v(x))(1 + v(x))}{v + 3}, \quad x \in I. \quad (1.67)$$

Here we note that $v(x) = \pm 1$ for $x \in I$ are constant solutions to this equation, and if $y(1) = 1$, then $v(1) = 1/1 = 1$. Thus the constant solution $v(x) = 1$ satisfies the initial condition on v , and $y(x) = x, x \in I$ is a candidate solution for the initial value problem for y .

We note that if $y(x) = x, x \in \mathbb{R}$, then

$$(3x + y(x))y'(x) = (3x + x)(1) = 4x \text{ and } x + 3y(x) = x + 3x = 4x. \quad (1.68)$$

Therefore $y(x) = x, x \in \mathbb{R}$ is a candidate solution to the initial value problem with its maximal interval of existence being $J = \mathbb{R}$. We also note that if we define the function f via

$$f(x, y) = \frac{x + 3y}{3x + y}, \quad (x, y) \in \mathbb{R} \text{ such that } 3x + y \neq 0 \quad (1.69)$$

then

$$\frac{\partial f}{\partial y}(x, y) = \frac{(3x + y)(3) - (x + 3y)(1)}{(3x + y)^2}, \quad (x, y) \in \mathbb{R} \text{ such that } 3x + y \neq 0, \quad (1.70)$$

and we see that $f, \frac{\partial f}{\partial y}$ are continuous at any point away from the line $3x + y = 0$. Since $3(1) + 1 = 4 \neq 0$, the initial point $(1, 1)$ does not lie on this line, so by the existence and uniqueness theorem the solution $y(x) = x, x \in \mathbb{R}$ we identified is the unique solution to the initial value problem.

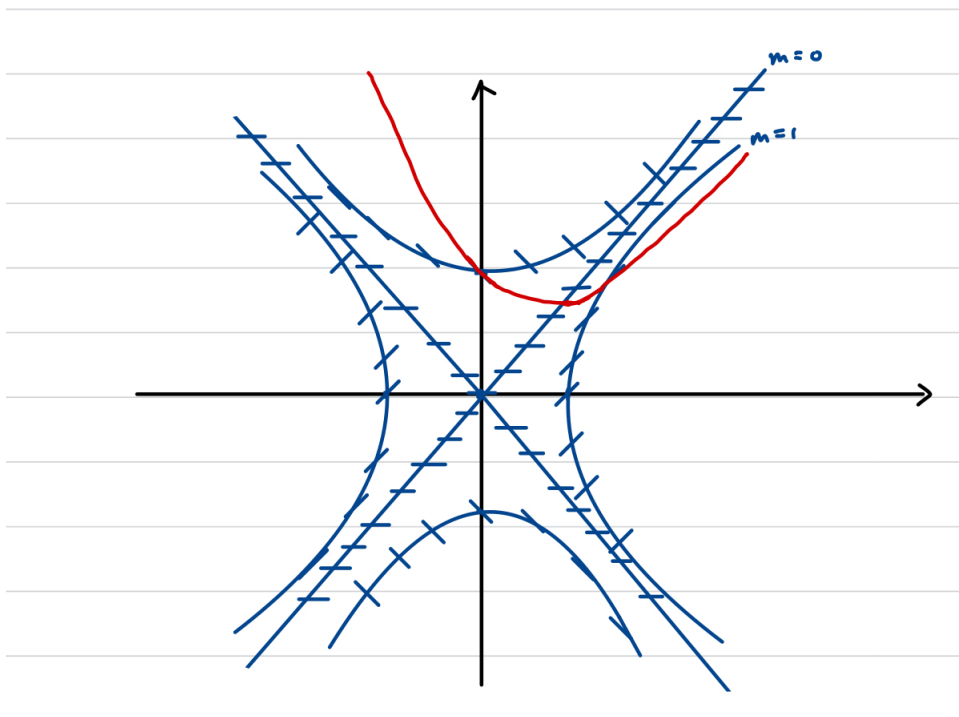
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Part 7. Isoclines and directional fields

Problem 1.10. Sketch the solution curve to the initial value problem

$$\begin{cases} y'(x) = x^2 - (y(x))^2, & x \in \mathbb{R} \\ y(0) = 1. \end{cases} \quad (1.71)$$

Solution. We note that $x^2 - y^2 = m$ are hyperbolas with vertices lying on $(\pm\sqrt{m}, 0)$ for $m > 0$, hyperbolas with vertices lying on $(0, \pm\sqrt{m})$ for $m < 0$, and $m = 0$ corresponds to the lines $y = \pm x$. Here is a very rough sketch:



□

Part 8. Exact differential equations**Problem 1.11.** Find an implicit solution to the initial value problem

$$\begin{cases} (e^x + y(x)) + (2 + x + y(x)e^{y(x)})y'(x) = 0, & x \in \mathbb{R} \\ y(0) = 1. \end{cases} \quad (1.72)$$

You do not need to specify the interval of existence.

Solution. Define M, N via

$$M(x, y) = e^x + y, \quad N(x, y) = 2 + x + ye^y, \quad (x, y) \in \mathbb{R}^2. \quad (1.73)$$

Then

$$M_y(x, y) = 1, \quad N_x(x, y) = 1, \quad (x, y) \in \mathbb{R}^2. \quad (1.74)$$

Therefore the equation is exact. Thus there exists a function F with $F_x = M, F_y = N$. We note that $F_x = M$ implies

$$F(x, y) = \int e^x + y \, dx + g(y) = e^x + xy + g(y), \quad (x, y) \in \mathbb{R}^2, \quad (1.75)$$

and thus

$$F_y(x, y) = x + g'(y) = N(x, y) = 2 + x + ye^y, \quad (x, y) \in \mathbb{R}^2. \quad (1.76)$$

Thus we must have

$$g'(y) = ye^y + 2 \implies g(y) = ye^y - e^y + 2y + C, \quad (1.77)$$

where C is an arbitrary constant. Thus

$$F(x, y(x)) = e^x + xy(x) + y(x)e^{y(x)} - e^{y(x)} + 2y(x) = C, \quad x \in I \quad (1.78)$$

is an implicit solution to the equation over some interval $x \in I$, where C is an arbitrary constant. Since $y(0) = 1$, we require

$$C = e^0 + 0(1) + 1e^1 - e^1 + 2(1) = 3. \quad (1.79)$$

Thus an implicit solution to the initial value problem is

$$e^x + xy(x) + y(x)e^{y(x)} - e^{y(x)} + 2y(x) = 3, \quad x \in I. \quad (1.80)$$

□

Part 9. Wronskian and linear independence**Problem 1.12.** Are the functions y_1, y_2 defined via

$$y_1(x) = \cos(\ln x), \quad y_2(x) = \sin(\ln x), \quad x > 0 \quad (1.81)$$

linearly independent over $I = (0, \infty)$?*Solution.* We calculate

$$W(y_1, y_2)(x) = \det \begin{pmatrix} \cos(\ln x) & \sin(\ln x) \\ -\frac{\sin(\ln x)}{x} & \frac{\cos(\ln x)}{x} \end{pmatrix} = \frac{1}{x} (\cos^2(\ln x) + \sin^2(\ln x)) = \frac{1}{x} \neq 0, \quad x > 0. \quad (1.82)$$

Therefore the two functions are linearly independent over I .

□