Appendix

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1 Proof of Theorem 1

Given $Z = \mathcal{D}(R) = U \Sigma_{\lambda} V^{T}$, we have

$$(vec(\boldsymbol{Z}^T))^T = [\boldsymbol{u}_1^T \boldsymbol{\Sigma}_{\lambda} \boldsymbol{V}^T, \cdots, \boldsymbol{u}_i^T \boldsymbol{\Sigma}_{\lambda} \boldsymbol{V}^T, \cdots, \boldsymbol{u}_m^T \boldsymbol{\Sigma}_{\lambda} \boldsymbol{V}^T] = (vec(\boldsymbol{U}^T))^T (\boldsymbol{I} \otimes \boldsymbol{\Sigma}_{\lambda} \boldsymbol{V}^T), \quad (1)$$

$$vec(\mathbf{Z}) = [(\mathbf{U}\boldsymbol{\Sigma}_{\lambda}\mathbf{v}_{1})^{T}, \cdots, (\mathbf{U}\boldsymbol{\Sigma}_{\lambda}\mathbf{v}_{i})^{T}, \cdots, (\mathbf{U}\boldsymbol{\Sigma}_{\lambda}\mathbf{v}_{n})^{T}]^{T} = (\mathbf{I} \otimes \mathbf{U}\boldsymbol{\Sigma}_{\lambda})vec(\mathbf{V}^{T}),$$
 (2)

where u_i^T and v_i^T are respectively the ith row of U and V. Then, the partial derivatives in (i) are straightfoward. The partial derivative of Z with respect to the r-th diagonal element of the matrix Σ is

$$\frac{\partial \mathbf{Z}}{\partial \sigma_{r,r}} = vec(\mathbf{G}),$$

where

$$G_{ij} = U_{i,r}V_{j,r},$$

- and $\sigma_{r,r}$ is the r-th diagonal element of the singular value matrix Σ .
- In order to calculate $\frac{\partial U}{\partial R}$, $\frac{\partial \Sigma}{\partial R}$, $\frac{\partial V}{\partial R}$, we do a perturbation analysis on the equation $R = U \Sigma V^T$. Let Δ_R , Δ_U , Δ_Σ and Δ_V be infinitesimally small perturbations to R, U, Σ and V, respectively. Then

$$R + \Delta_{R} = (U + \Delta_{U})(\Sigma + \Delta_{\Sigma})(V + \Delta_{V})^{T}$$

$$= U\Sigma V^{T} + \Delta_{U}\Sigma V^{T} + U\Delta_{\Sigma}V^{T} + U\Delta_{\Sigma}\Delta_{V}^{T}$$

$$+ U\Sigma\Delta_{V}^{T} + \Delta_{U}\Sigma\Delta_{V}^{T} + \Delta_{U}\Delta_{\Sigma}\Delta_{V}^{T} + \Delta_{U}\Delta_{\Sigma}V^{T}.$$
(3)

Ignoring the higher-order infinitesimals, we obtain

$$\Delta_R = \Delta_U \Sigma V^T + U \Delta_\Sigma V^T + U \Sigma \Delta_V^T$$
(4)

or equivalently,

$$U^{T} \Delta_{R} V = U^{T} \Delta_{U} \Sigma + \Delta_{\Sigma} + \Sigma \Delta_{V}^{T} V.$$
 (5)

U and V are both orthogonal matrices, and so are their perturbed versions, i.e.

$$(U + \Delta_U)^T (U + \Delta_U) = I$$

$$(V + \Delta_V)^T (V + \Delta_V) = I.$$
(6)

Then 10

$$U^T \Delta_U + \Delta_U^T U = 0 \tag{7a}$$

$$\boldsymbol{V}^T \boldsymbol{\Delta}_{\boldsymbol{V}} + \boldsymbol{\Delta}_{\boldsymbol{V}}^T \boldsymbol{V} = \mathbf{0}. \tag{7b}$$

Together with (5), we obtain

$$U^{T} \Delta_{R} V = -\Delta_{U}^{T} U \Sigma + \Delta_{\Sigma} - \Sigma V^{T} \Delta_{V}.$$
 (8)

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Let $\Delta_{R_{ij}}$ be the perturbation on the element R_{ij} of matrix \boldsymbol{R} . Let \boldsymbol{u}_i^T be the i-th row of \boldsymbol{U} , and \boldsymbol{v}_j^T be the j-th row of \boldsymbol{V} . Setting the elements of $\Delta_{\boldsymbol{R}}$ to zero except $\Delta_{R_{ij}}$, we obtain from (8) that

$$\Delta_{R_{i,i}} u_i v_i^T = -\Delta_U^T U \Sigma + \Delta_{\Sigma} - \Sigma V^T \Delta_V, \tag{9}$$

14 or equivalently

$$\boldsymbol{u}_{i}\boldsymbol{v}_{j}^{T} = -\frac{\boldsymbol{\Delta}_{U}^{T}}{\boldsymbol{\Delta}_{R_{ij}}}\boldsymbol{U}\boldsymbol{\Sigma} + \frac{\boldsymbol{\Delta}_{\boldsymbol{\Sigma}}}{\boldsymbol{\Delta}_{R_{ij}}} - \boldsymbol{\Sigma}\boldsymbol{V}^{T}\frac{\boldsymbol{\Delta}_{\boldsymbol{V}}}{\boldsymbol{\Delta}_{R_{ij}}}.$$
(10)

15 From (7), we obtain

$$\boldsymbol{U}^{T} \frac{\Delta_{\boldsymbol{U}}}{\Delta_{R_{ij}}} + \frac{\Delta_{\boldsymbol{U}}^{T}}{\Delta_{R_{ij}}} \boldsymbol{U} = \boldsymbol{0}$$
 (11a)

$$\boldsymbol{V}^{T} \frac{\Delta_{\boldsymbol{V}}}{\Delta_{R_{ij}}} + \frac{\Delta_{\boldsymbol{V}}^{T}}{\Delta_{R_{ij}}} \boldsymbol{V} = \boldsymbol{0}. \tag{11b}$$

Define
$$m{F} = \lim_{\Delta_{R_{ij}} \to 0} m{U}^T \frac{\Delta_U}{\Delta_{R_{ij}}}, \ m{E} = \lim_{\Delta_{R_{ij}} \to 0} m{V}^T \frac{\Delta_V}{\Delta_{R_{ij}}}, \ \text{and} \ m{C} = \lim_{\Delta_{R_{ij}} \to 0} (m{u}_i m{v}_j^T - \frac{\Delta_\Sigma}{\Delta_{R_{ij}}}) \ . \ \text{Then (9)}$$

17 is rewritten as

$$C = -F^T \Sigma - \Sigma E. \tag{12}$$

From (11), F and E are both antisymmetric matrices, i.e.

$$TriU(\mathbf{F}) = -TriL(\mathbf{F})^{T}$$
 and $TriU(\mathbf{E}) = -TriL(\mathbf{E})^{T}$, (13)

where the diagonal elements of F and E are all zero. Then from (12), we obtain

$$\frac{\partial \mathbf{\Sigma}}{\partial R_{ij}} = vec\left(\lim_{\Delta_{R_{ij}} \to 0} \frac{\Delta_{\mathbf{\Sigma}}}{\Delta_{R_{ij}}}\right) = vec(diag(\mathbf{u}_i \mathbf{v}_j^T)), \tag{14}$$

$$C = TriL(\mathbf{u}_i \mathbf{v}_j^T) + TriU(\mathbf{u}_i \mathbf{v}_j^T), \tag{15}$$

 $TriU(\mathbf{C})\mathbf{\Sigma}^{-1} = -TriU(\mathbf{F}^T) - \mathbf{\Sigma}TriU(\mathbf{E})\mathbf{\Sigma}^{-1}.$ (16)

22 and

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$$TriL(\mathbf{C})\Sigma^{-1} = -TriL(\mathbf{F}^{T}) - \Sigma TriL(\mathbf{E})\Sigma^{-1}.$$
(17)

Taking transpose on both sides of (17), together with $TriU(\mathbf{F}^T) = TriL(\mathbf{F})^T = -TriU(\mathbf{F}) = TriU(\mathbf{F})$

 $-TriL(\mathbf{F}^T)^T$, we obtain

$$\Sigma^{-1}(TriL(\mathbf{C}))^{T} = TriU(\mathbf{F}^{T}) + \Sigma^{-1}TriU(\mathbf{E})\Sigma.$$
(18)

25 Adding (16) to (18), we obtain

$$TriU(\mathbf{C})\Sigma^{-1} + \Sigma^{-1}(TriL(\mathbf{C}))^{T} = \Sigma^{-1}TriU(\mathbf{E})\Sigma - \Sigma TriU(\mathbf{E})\Sigma^{-1}.$$
 (19)

26 Let

$$P = TriU(C)\Sigma^{-1} + \Sigma^{-1}(TriL(C))^{T}.$$
(20)

Then, solving (19), we obtain the (i, j)th element of E as

$$E_{ij} = \begin{cases} \frac{P_{ij}}{(\sigma_{i,i}^{-1}\sigma_{j,j} - \sigma_{i,i}\sigma_{j,j}^{-1})} & i < j \\ 0 & i = j \\ \frac{-P_{ji}}{(\sigma_{j,j}^{-1}\sigma_{i,i} - \sigma_{j,j}\sigma_{i,i}^{-1})} & i > j \end{cases}$$
 (21)

28 From (12), we obtain

$$F = -((C + \Sigma E)\Sigma^{-1})^{T} = -((TriL(u_{i}v_{j}^{T}) + TriU(u_{i}v_{j}^{T}) + \Sigma E)\Sigma^{-1})^{T}.$$
 (22)

Finally, from the definition of F and E, we obtain

$$\frac{\partial \mathbf{U}}{\partial R_{ij}} = vec \left(\lim_{\Delta R_{ij} \to 0} \frac{\Delta_{\mathbf{U}}}{\Delta_{R_{ij}}} \right) = vec \left(\mathbf{U} \mathbf{F} \right), \tag{23}$$

$$\frac{\partial \mathbf{V}}{\partial R_{ij}} = vec \left(\lim_{\Delta_{R_{ij}} \to 0} \frac{\Delta_{\mathbf{V}}}{\Delta_{R_{ij}}} \right) = vec \left(\mathbf{V} \mathbf{E} \right). \tag{24}$$

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