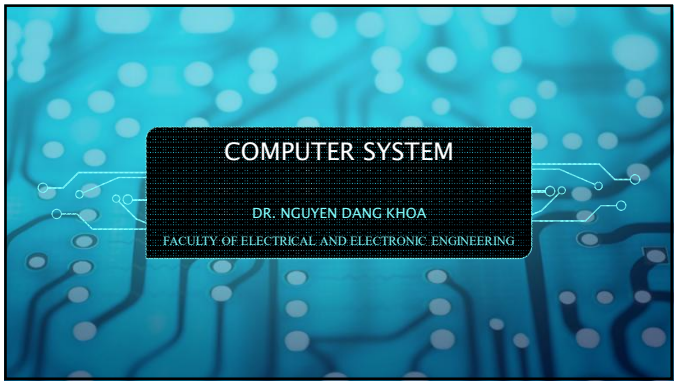

Instruction Pointer

- The running a program is managed by Instruction pointer (IP)
- How does the instruction pointer work?

```
Address     int main()
            {
0x0001          int a, b, c;   <-- Instruction pointer (IP) stores the address of command
0x0004          a=5;           <-- Instruction pointer
0x0008          b=6;           <-- Instruction pointer
0x00012         c=a+b;         <-- Instruction pointer
            }
```

Instruction Pointer

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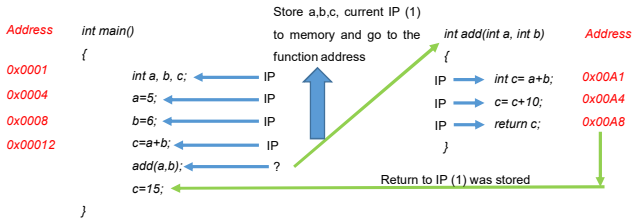
```
Address     int main()
            {
0x0001          int a, b, c;   <-- IP
0x0004          a=5;           <-- IP
0x0008          b=6;           <-- IP
0x00012         c=a+b;         <-- IP
                add(a,b);      <-- ?
                c=15;
            }
```

```
int add(int a, int b)
{
        int c= a+b;
        c= c+10;
        return c;
}
```

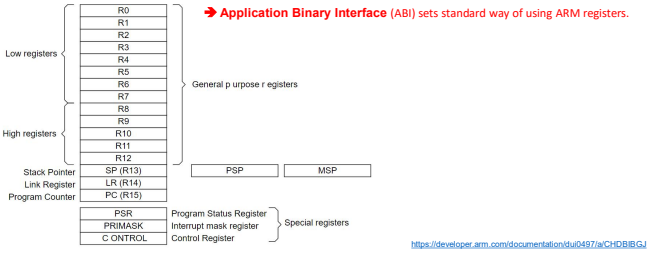
Instruction Pointer

- The running a program is managed by Instruction pointer (IP)
- How does the instruction pointer work?



Instruction Pointer

- What proposes for IP?
  - **lr** and **sp** used for stack management (*link register, stack pointer*)
  - **pc** is the next instruction – we can use it to exit a function call (*program counter*)



➔ **Application Binary Interface** (ABI) sets standard way of using ARM registers.

https://developer.arm.com/documentation/dui0497/a/CHDBIBGJ

Instruction Pointer

- What proposes for IP?
  - **lr** and **sp** used for stack management (*link register, stack pointer*)
  - **pc** is the next instruction – we can use it to exit a function call (*program counter*)

Name	Type[1]	Reset value	Description
R0-R12	RW	Unknown	*General-purpose registers*
MSP	RW	See description	*Stack Pointer*
PSP	RW	Unknown	*Stack Pointer*
LR	RW	Unknown	*Link Register*
PC	RW	See description	*Program Counter*
PSR	RW	Unknown[b]	*Program Status Register*
APSR	RW	Unknown	*Application Program Status Register*
IPSR	RO	0x00000000	*Interrupt Program Status Register*
EPSR	RO	Unknown[b]	*Execution Program Status Register*
PRIMASK	RW	0x00000000	*Priority Mask Register*
CONTROL	RW	0x00000000	*CONTROL register*

Instruction Pointer

- What proposes for IP?
  - **lr** (link register) contains the address of the next instruction after a function call.
    - We use this to tell the code what to run after a function finishes.
    - The current address of code to be run is stored in the program counter (**pc**). Setting this to the value in **lr** makes the program resume after a function has finished.

```
FunctionLabel:
;do something
mov pc,lr ;set pc to the next line of the caller
```

➔ Maybe lr is changed ➔ store it in the stack

- Alternatively (better)

```
FunctionLabel:
push {lr}
;do something
pop {pc}
```

- Calling function:

```
bl FunctionLabel
```

Instruction Pointer

```
Delay:
    mov r3,$3F000000        ; RPi2 and 3
    orr r3,$00003000
    mov r4,$80000           ;~0.5s
    ldrd r6,r7,[r3,#4]
    mov r5,r6
    loopt1:                 ;label still has to be different from all the others
        ldrd r6,r7,[r3,#4]
        sub r8,r6,r5
        cmp r8,r4
        bls loopt1          ;branch if lower or same (<=)
mov pc,lr                   ;return

;;➔ two labels ➔ lr????
```

Instruction Pointer

```
Delay:
    push {lr}
    mov r3,$3F000000        ; RPi2 and 3
    orr r3,$00003000
    mov r4,$80000           ;~0.5s
    ldrd r6,r7,[r3,#4]
    mov r5,r6
    loopt1:                 ;label still has to be different from all the others
        ldrd r6,r7,[r3,#4]
        sub r8,r6,r5
        cmp r8,r4
        bls loopt1          ;branch if lower or same (<=)
pop {pc}                    ;return
;; ➔ safety
```

Instruction Pointer

```
Delay:
    mov r3,$3F000000        ; RPi2 and 3
    orr r3,$00003000
    mov r4,$80000           ;~0.5s
    ldrd r6,r7,[r3,#4]
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    loopt1:                 ;label still has to be different from all the others
        ldrd r6,r7,[r3,#4]
        sub r8,r6,r5
        cmp r8,r4
        bls loopt1          ;branch if lower or same (<=)
bx lr                       ;branch to lr without updating PC
;; ➔ This way works best with the FASMARM compiler
```

NEW COMMAND

For details

- **B** loopA ; Branch to loopA
- **BL** funC ; Branch with link (Call) to function funC, return address stored in LR
- **BX** LR ; Return from function call
- **BLX** R0 ; Branch with link and exchange (Call) to a address stored in R0
- **BEQ** labelD ; Conditionally branch to labelD if last flag setting instruction set the Z flag, else do not branch.

Function

```
Delay:
    mov r3,$3F000000
    orr r3,$00003000
    mov r4,$80000
    ldrd r6,r7,[r3,#4]
    mov r5,r6
    loopt1:
        ldrd r6,r7,[r3,#4]
        sub r8,r6,r5
        cmp r8,r4
        bls loopt1
bx lr
;; save to timer3.asm
```

```
;;; test.asm
mov r0,$3F000000
orr r0,$00200000
mov r1,#1
lsl r1,#24              ;GPIO18
str r1,[r0,#4]
mov r1,#1
lsl r1,#18
loop$:
    str r1,[r0,#32]     ;on
    bl Delay            ;call Delay
    str r1,[r0,#44]     ;off
    bl Delay            ;call Delay
b loop$
include "TIMER3.asm"
```

Passing Arguments to Function

```
int main()
{
        int a, b, c;
        a=5;
        b=6;
        c=a+b;
        add(a,b);
        c=15;
}
```

```
int add(int a, int b)
{
        int c= a+b;
        c= c+10;
        return c;
}
```

We have to pass (a,b) to add() function.
How?

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We have to pass (a,b) to add() function.
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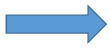

```
int main()
{
        int a, b, c;
        a=5;
        b=6;
        c=a+b;
        push {a,b}
        add(a,b);
        c=15;
}
```

```
int add()
{
        pop {a,b}
        int c= a+b;
        c= c+10;
        return c;
}
```

Recursion presentation

```
void Increment(counter[], digitIdx)
{
    if (digitIdx <= maxDigitIdx)
    {
        if (counter[digitIdx] == radix-1) //carry
        {
                counter[digitIdx]=0;
                Increment(counter[], digitIdx+1);
        } else {
                counter[digitIdx]++;        //increment
        }
    }
}
```

```
void Increment(counter[], digitIdx)
{
    if (digitIdx <= maxDigitIdx)
    {
        if (counter[digitIdx] == radix-1) //carry
        {
                counter[digitIdx]=0;
                Increment(counter[], digitIdx+1);
        } else {
                counter[digitIdx]++;          //increment
        }
    }
}
```

```
Increment:
;r0 = counter_address ;r1 = digit  ;r2 = maxDigit ;r3 = radix-1
mov r4,r1                       ;copy for later to a temp variable
cmp r1,r3;; ➔cmp r1, r2                 ;if digit == maxDigit
return
beq end;; ➔bls end
cmp r0[r1], r3                  ;if this digit != radix-1 (e.g. 9)
bne continue                    ;just add 1 (increment)
;carry
mov r0[r1], #0                  ;reset this counter
add r4,#1                       ;add 1 to copy of digit
push {lr}
                ;backup lr (we'll need it later when the next line returns)
bl Increment
pop {lr}
b end ;all done
continue:
add r0[r1], #1                  ;increment
end:                            ;call display function here
bx lr
```