

CS 311 Programming Assignment 1 Report

1.) Algorithm for the method buildDataStructure()

- First calculate the required size of the hash table, size $> 1.5n$ where n is the number of points from the input.
- Create the Hash Table by finding a prime number $p \geq \text{size}$, set the size of the hash table to be this prime number.
- For each point q , calculate $\text{floor}(q)$ and use this as the key for a Tuple t . The value of the tuple will be the point itself. Store t in the hash table in position $h(\text{floor}(q))$, where h is the hash function for the table.

2.) Algorithm for the method npHashNearestPoints(float p)

- Create an empty ArrayList for storing nearest points.
- First, find the 3 possible buckets any potential neighboring points could lie in. Do this by calculating $h(\text{floor}(p-1))$, $h(\text{floor}(p))$, and $h(\text{floor}(p+1))$, and looking the keys up in the hash table to get the corresponding buckets.
- For each bucket, loop over all the Tuples. Compare the value of the Tuple (q), with p . if $\text{Abs}(p-q) \leq 1$, then we have found a nearest point, so we add it to our list.
- Return the ArrayList

3.) Runtime comparison

- Naive: 212,614 ms \Rightarrow 212.61 s \Rightarrow 3.5 minutes
- Hash: 156,055 ms \Rightarrow 156.05 s \Rightarrow 2.6 minutes
- As our input size increases, we will see a greater separation between the two runtimes. This is because the naïve solution is $O(n)$ while the hash solution is $O(N(p))$ where $N(p)$ is the number of nearest points to p .
- Note: we are including the time it takes to write a file in the runtimes.