

Publications

- Jonas Kulhanek**, Erik Dernerbb, and Robert Babuskabb. 2021. Visual navigation in real-world indoor environments using end-to-end deep reinforcement learning. *IEEE Robotics and Automation Letters*.
- Jonáš Kulhánekbb, Erik Dernerbb, Tim de Bruinbb, and Robert Babuškabb. 2019. Vision-based navigation using deep reinforcement learning. In *2019 European Conference on Mobile Robots (ECMR)*, pages 1–8. IEEE.
- Jonáš Kulhánekbb, Vojtěch Hudečekbb, Tomáš Nekvindabb, and Ondřej Dušekbb. 2021. Augpt: Dialogue with pre-trained language models and data augmentation. *arXiv preprint arXiv:2102.05126*.
- Jonáš Kulhánekbb. 2019. Visual navigation using deep reinforcement learning. Bachelor’s thesis, 05.
- Jonáš Kulhánekbb. 2020. End-to-end dialogue systems with pretrained language models. Master’s thesis, 05.