

Introduction to Biomechanics

EID 424
Bioengineering Applications in Sports Medicine
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Outline

- + Introduction and history
- + Measurements
 - + Motion
 - + Force
- + Calculations
 - + 2-D
 - + 3-D
- + Applications
- + Complications



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Introduction

- + Broad field
 - + Analysis of human motion
 - + Forces in car crash impacts
 - + Motion of insects
 - + Large role in robotics
 - + Strength of reconstructions/implants
 - + Flow in blood vessels
 - + Mechanical properties of plants

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Introduction

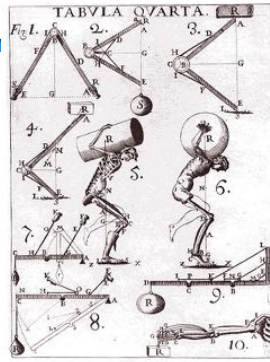
- + Last time I was at ASB meeting:
 - + Recovering from tripping
 - + Mechanisms of ACL injury
 - + Evaluation of riot helmets
 - + Beat helmets with baseball bat
 - + Instrumented cockroach!



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History

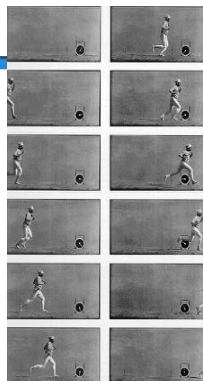
- + Borelli
 - + Considered father of biomechanics
 - + *De Motu Animalium* (1680-1681)



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History: Lots of Pictures

- + Marey (1838-1904)
 - + Pioneer in use of many technologies
 - + Photography
 - + Measurement of forces



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History

+ Muybridge (1830-1904)

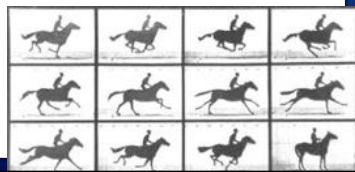
- + Sequential pictures of many activities
 - + Walking
 - + Running
 - + Jumping
 - + Marching
 - + Wrestling (eww)
 - + Many others



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History Tidbits

- + Marey tested idea that “cats always land on their feet”
 - + Filmed cats after having been dropped upside-down
- + Muybridge settled famous bet [1876]
 - + Do horses fly?



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Currently

- + Motion capture techniques no longer limited to biomechanics
- + Entertainment industry now largest customer
 - + Film
 - + Video games



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How Big is Entertainment?

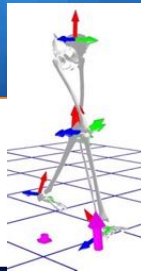
- + Several biomechanists won a technical achievement Oscar in 2005
 - + Work with techniques for producing smooth animation of motion capture data
- + Pictured:
 - + Ton van den Bogert
 - + Cleveland Clinic
 - + Mr. Simulation
 - + Moderates biomch-I
 - + Dan India
 - + VP Sales, Qualisys
 - + A decent human despite being a salesman
 - + Buys beer every year for the Biomechanics Interest Group at the American College of Sports Medicine Conference
- + Oscar statue
 - + Developed new finite-element model of human body
 - + Got into biomechanics to support crystal meth addiction
 - + Writing self-help book in rehab



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Kinematics

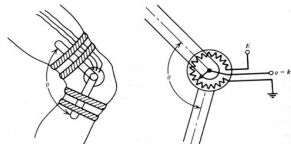
Motions of the Body



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Simple: The Basic Electrogoniometer

- + Goniometer
 - + Device that measures angle
 - + Electrify it!
- + Not the most accurate
- + Careful placement import
 - + Align with center of rotation: joint
 - + Center of rotation usually not fixed



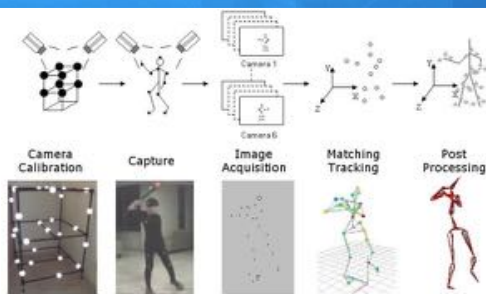
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Basic Technique

- + Attach markers to subject
 - + Brighter than anything in background
 - + Attach to useful points (landmarks)
 - + Passive (reflective) vs active
- + Record motions with > 1 cameras
 - + Allows reconstruction of 3-dimensional data from camera images
- + Analyze
 - + Joint angles
 - + Velocities/accelerations
 - + Forces!

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Basic Technique



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Technologies

- | | |
|--|--|
| <ul style="list-style-type: none"> + Camera-based <ul style="list-style-type: none"> + Usually infrared + Markers reflect light <ul style="list-style-type: none"> + Or emit light + Markers on subject show up brightly against background | <ul style="list-style-type: none"> + Electromagnetic <ul style="list-style-type: none"> + Transmitter emits magnetic field + Markers contain three orthogonal coils + Field couples into coils <ul style="list-style-type: none"> + Distance, orientation relative to transmitter determine received signal |
|--|--|

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Historically

- + Multiple video cameras
 - + Each records to VCR
 - + All synchronized
- + Manually digitize points of interest in *each* frame on *every* tape
- + Painful
 - + Grad students

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Camera-Based Motion Analysis

- | | |
|--|---|
| + Very accurate <ul style="list-style-type: none">+ Often 1mm or better resolution | + Expensive! <ul style="list-style-type: none">+ System with fast cameras can be \$250-\$500K |
| + Relatively easily-understood technology | + Often requires intervention in post-processing |
| + Well-accepted <ul style="list-style-type: none">+ Gold standard | + Requires line of sight |

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Electromagnetic Motion Analysis

- + Can be much cheaper than cameras
 - + \$20K and up, if memory serves
- + No line of sight
- + No post-processing
- + Distorted by nearby metal
 - + Room can be calibrated
 - + Don't move transmitter
 - + In reality, some big distortions cannot be (metal force plates)
- + EMG?

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Marker Pros and Cons

- | | |
|---|--|
| <ul style="list-style-type: none"> + Active + Sampled sequentially + No post-processing + Need wires for power, control + Subject tethered? + Wires interfere with motion | <ul style="list-style-type: none"> + Passive + All markers sampled in every frame + Inexpensive <ul style="list-style-type: none"> + Reflective balls + Often time-consuming post-processing <ul style="list-style-type: none"> + Fix swapping markers, etc. + Least hindering to subject |
|---|--|

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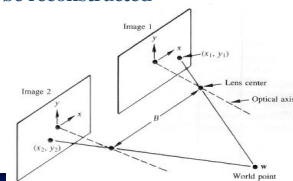
Current Research Area

- + Lots of effort going into research for markerless motion capture
- + Automatically track points in video from one frame to the next
- + Microsoft Kinect does this reasonably enough for video games, but not for research/clinical measurements

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Cameras are 2-D How Do I Get 3-D?

- + Multiple cameras
- + If...
 - + The same scene is viewed by more than one camera
 - + The positions and orientations of the cameras relative to each other are known
- + 3-D image of scene can be reconstructed
- + Stereo imaging



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Stereo Imaging

- + Reconstruct 3-D data based on 2-D camera images
- + Direct linear transform (DLT) [Abdel-Aziz, Kahara, 1971]
 - + Use a structure with markers at known points to calibrate system
 - + At least 6 points
- + Like most things in this field, becomes an optimization problem
 - + Minimize residuals

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Camera Calibration

- + Traditionally, used calibration structure
 - + Precisely measured
 - + Typically, large and heavy
 - + Should approximate size of measurement volume
- + Modern systems use wand calibration
 - + Four markers on ground at right angle to determine coordinate system
 - + Two markers on ends of wand waved through volume to be calibrated
 - + Calibration dance

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People Do Use 2-D

- + One camera
- + No or easy calibration
 - + Measure distance to plane in which motion is taking place
- + Measure joint angles in one plane
 - + Typically, sagittal (i.e., view from the side)
- + Careful!
 - + Are you sure you're getting the plane you want?

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Motion System Vendors

- + Motion Analysis Corp
- + Vicon
- + Qualisys
- + BTS Bioengineering
- + Innovative Sports Training (The Motion Monitor)
- + Charnwood Dynamics (Coda)
- + Northern Digital (Optotrak)
- + Peak Performance
- + Simi Reality Motion Systems

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Enough Technology, What Are We Measuring?

- + Measure and *quantify* motions of the body
 - + Specifically, motions of the *skeleton*, since that is the structure that is bearing weight
- + Joint angles/rotations
 - + Interested in joint *centers*

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Enough Technology, What Are We Measuring?

- + A body in space has 6 degrees of freedom
 - + 3 translations (x-, y-, z-)
 - + 3 rotations (yaw, pitch, roll)
- + Segments of human body may be more constrained than having full freedom
- + Sometimes 2-D analysis is enough

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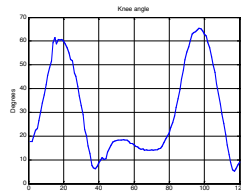
2-D Techniques

- + Place markers on joints
 - + Use bony landmarks for repeatability
- + Compute joint angles from lines drawn through markers
- + Cannot get rotations this way
- + Are we really getting the plane we're looking for?

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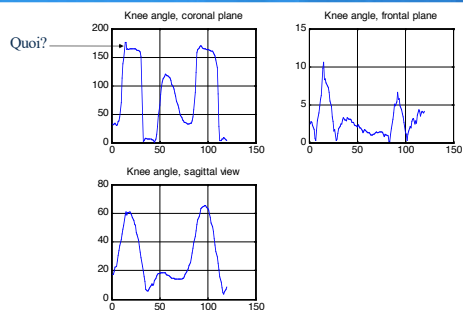
2-D Example: Gait

- + Markers on greater trochanter, femoral condyle, lateral malleolus give knee angle
- + Knee angle dominated by sagittal plane motion



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2-D Example: Gait



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3-D Techniques

- + Place markers on body segments
 - + *At least 3 markers per segment*
 - + Can define coordinate system for each segment
- + Calculate rotations of one segment relative to another
 - + Transformation matrices
 - + Beware!
 - + Order of rotations can matter!
 - + Gimbal lock
 - + Second rotation is 90°

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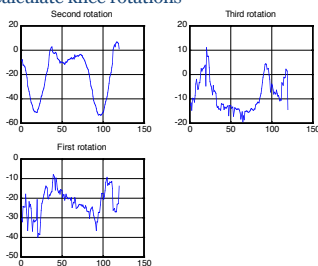
3-D Techniques

- + How to place consistently?
- + Be sure to collect neutral trial
 - + Estimate location of joint centers

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3-D Example: Gait

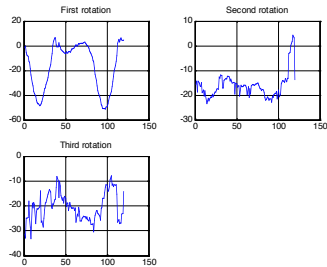
- + Marker triads on thigh, leg
- + Calculate knee rotations



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3-D Example: Gait

+ Changed rotation order



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Why None of This Really Works

- + Want to measure movements of *skeleton*
- + Markers on surface of *skin*
 - + Motion of markers relative to bone
 - + Skin artifact
 - + Mount markers on bone pins, insert surgically
 - + Yeah, maybe in Sweden
- + Inconsistent placement
 - + Use bony landmarks for reference
- + Determination of joint centers?
 - + Calibrate with static trials, regression, tables of "normal" values
 - + Papers written on this

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Motion is Only Half the Story

- + Motion of skeleton is of little consequence without knowing forces to which it is subjected
- + Can be measured with a force plate

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Kinetics

Forces on and of the Body

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Force Plate

- + Big hunk-o-metal with sensors embedded
 - + Big and heavy
 - + ???
 - + Strain gauge or piezoelectric sensors
- + *Very* sensitive
 - + Can see heartbeat on best, well-installed ones
- + Best bang for the buck in your motion lab
 - + ~\$20K
- + Must be well-isolated from surrounding vibration

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Got Room in the Basement?

- + Upper floors not recommended
 - + Buildings sway, vibrate
- + Dig a pit
- + Fill with sand
- + Block of concrete floating in sand
- + Bolt force plate to concrete

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Portable Force Plates

- + Feet somewhat isolated from floor with rubber
 - + Think record player
- + Not as sensitive, precise as regular plate
- + Not good for high-impact activities

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Force Plate Outputs

- + Forces in three directions
- + Moments about three axes
- + Point of application of force (center of pressure)
- + Crazy accurate when installed correctly

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Force Data Normalizations

- + As usual, difficult to compare data between subjects directly
- + Forces typically normalized to body weight
- + Moments normalized to:
 - + Body weight
 - + Body weight * height

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Force Plate Limitations

- + Plates relatively small
 - + Capture only one stride/jump/etc
 - + Subjects sometimes have difficulty hitting plate
 - + Is this representative?
 - + Usually perform multiple trials, average them
 - + Must normalize time at this point, e.g., % of gait cycle
- + Targeting issues
 - + Want subject performing motion normally
 - + Often cover plate to resemble floor

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Force Plate Manufacturers

- + AMTI
 - + <http://www.amtiweb.com/>
- + Bertec
 - + <http://www.bertec.com/>
 - + Non-conductive plate for electromagnetic systems
- + Kistler
 - + <http://www.kistler.com/>
- + BTS
 - + <http://www.btsbioengineering.com/>

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Combining Motion and Force

- + Combine motion and force plate measurements to estimate forces acting at joints of body
- + Combine with Newton's laws of motion
- + Assume body is a connected set of rigid links
- + *Inverse dynamics*

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Completely neglected...

- + The entire field of crushing things or pulling them apart



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Completely neglected...

- + The wonderful world of modeling and simulation
 - + Can be as simple as a mass on a spring
 - + See work of Claire Farley
 - + Can be *very* complicated and involve lots of partial differential equations
 - + Read *anything* by Ton van den Bogert

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