We will focus mostly on square matrics

$$\frac{x}{x} = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$$
 vector

Matrix-vector multiplication $\vec{y} = A\vec{x}$

$$y' = \sum_{j=0}^{n-1} A_{ij} X_{j}$$

Matrix multiplication

$$C = AB$$

$$Cij = \sum_{k=0}^{n-1} A_{ik}B_{ki}$$

transpose B-AT Bij - Aji

Ex
$$A = \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix}$$
 $B = \begin{bmatrix} 3 & 1 \\ 1 & 3 \end{bmatrix}$ $AB = ?$

$$AB = \begin{bmatrix} 1 & -3 \\ 3 & 4 \end{bmatrix}$$

Determinant is a number : del(A)

2x2 | A | = | A 00 A 01 | = A 00 A 11 - A 01 A 10

3×3 |Al= | Aoo Aoi Aos | = Abolded Aso Asi Asi

= A00 | A11 A12 | - A01 | A20 A21 | + A02 | A30 A21 | = A00 | A31 A32 | - A01 | A30 A22 | + A02 | A30 A21 |

Triangular matrix (upper and lower)

Aoo Aoi Aos 7
Aio Aii O
Aii Aii
O Aii Aii
Aio Aii Aii
Aio Aii Aii

Note del (triangular matix) = product main diagonal

| Atrianglar | = 11 Aii

Inverse A = D A'A = AA' = II ~ identity madrix

If def(A) =0 A is singular and A-1 does not exist

(rows, columns of A are not linearly independent)

Solving a linear equations w/ a unknowns $A = \vec{b}$ n onkowns $\begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}$ NXA coefficients in A, and A constants in b= (b)
we need det(A) +0 for solution We create augmented coeff metrix of A and b (A1b) = (A1b) = (Ani) Ani) bold Ani) bold Ani) In solving linear egas we can Scale row by a constant priot: two rows can be interchanged. eliminate: a row can be replaced by the sum of that row u/ a multiple of any other row We will also solve eigenvalue problem 6= VK-VA (A-AI) V = 3

We have a linear equations and n unknowns in V plus I unknown in) -> We won't find unique Solutions For a nontrivial solution (V×3) We need A-AII not to have an invose so 1 A- XI (= 0 Error Analysis (worst case scenario) Consider special dx) example (AIL) = (1,2969 0,8642) You are given approx solution $\hat{\chi} = (-.4870)$ Create residual vector 7

7 = 6 - A = D 7 = (-1e-8) not bad exact Solution $\dot{X} = \begin{pmatrix} 0 \\ -0 \end{pmatrix}$. ?! Weild. Very small changes to A will yield very big changes to our solution.

Maybe A is 'close to' having det(A) = 0 4-5 (close to being singular) case det(A) = -9.999e-9) (in out Define Frobenius norm | | All = [= [] | Aij |] (1) Infinity norm | | All & = Max \(\frac{\lambda^{-1}}{2} \) | Aij \ (Maximum absolute row-som norm) We can show that condition number K(A) determines sensitivity to (Egn) Small perturbation (4.31) K(A) = 11 A11 11 A-111 Salving Ax=6 L = lower triangular matrix First solve LX=5 For n=3 $\begin{pmatrix}
L_{10} & L_{11} & 0 \\
L_{20} & L_{21} & L_{22}
\end{pmatrix}
\begin{pmatrix}
X_{0} \\
X_{1} \\
X_{2}
\end{pmatrix} = \begin{pmatrix}
b_{1} \\
b_{3}
\end{pmatrix}$ Xo = 60/200 Loo Xo = bo X1 = 6, - L10 X0 L10 X0 + L11 X1 = b1 Loo Xo + Loi Xi + Los Xo = ba X = 60 - 600 X0 - 601 X1