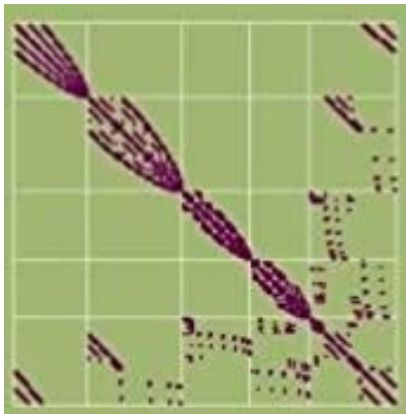


Lecture 08:

Iterative Solvers of $Ax = b$ The Jacobi and CG Methods 1

CS 111: Intro to Computational Science
Spring 2023

Ziad Matni, Ph.D.
Dept. of Computer Science, UCSB



Carl Gustav Jacob Jacobi (1804 – 1851)

Administrative

- New homework...!
- Lab tomorrow
- Quiz 2 results will be out on Canvas today
 - Median grade = 8/10 Average = 7.9/10
- Preliminary slides for this lecture available on Canvas

$Ax = b$ Solvers We've Learned So Far

- Solving $Ax = b$ can be easier to do if we first “decompose” A :

• LU Factorization	$P.A = L.U$	<i>Useful for most matrices</i>
• Cholesky	$A = R.R^T$	<i>Useful for SPD matrices</i>
• QR Factorization	$A = Q.R$	<i>Useful for real matrices</i>

New iterative methods we'll learn:

- *Jacobi Method*
- *Conjugate Gradient Method*

Jacobi Method

An **iterative** algorithm for determining the solutions of a **diagonally dominant** system of linear equations.

- **Diagonally dominant:**

- for every row of the matrix, the *absolute value* of the diagonal entry in a row **is greater than or equal to** the *sum of absolute values* of all the other (non-diagonal) entries in that row

Diagonally Dominant Example

For example,

$$\mathbf{A} = \begin{bmatrix} -4 & 2 & 1 \\ 1 & 6 & -2 \\ -1 & -3 & -5 \end{bmatrix} \text{ is a strictly diagonally dominant matrix}$$

because:

$$|a_{00}| > |a_{01}| + |a_{02}|, \text{ that is, } 4 > (2 + 1)$$

$$|a_{11}| > |a_{10}| + |a_{12}|, \text{ that is, } 6 > (1 + 2)$$

$$|a_{22}| > |a_{20}| + |a_{21}|, \text{ that is, } 5 > (1 + 3)$$

Jacobi Method

- Simple, programmable, efficient
 - Not always the most *accurate* results (but we can get them *fast*)
 - Also, not the most efficient iterative algorithm out there
- Given a system: $A\mathbf{x} = \mathbf{b}$, solve for \mathbf{x}
- We can start with a *guess* for \mathbf{x}
 - Good starting point is the **zero vector** (i.e. $\mathbf{x} = [0, 0, 0, \dots]$)
 - We'll call it the **0th approximation**, or $\mathbf{x}^{(0)}$
 - We'll iterate some process to keep guessing for a better and better solution
 - Our *iteration* will lead to a **convergence** of $\mathbf{x}^{(n)}$ to an approximate correct answer
 - But matrix \mathbf{A} really needs to be “strictly diagonally dominant”

Jacobi Method

CALCULATION DEMO
Coming up!!!

Given a current (k^{th}) approximation for \mathbf{x} as:

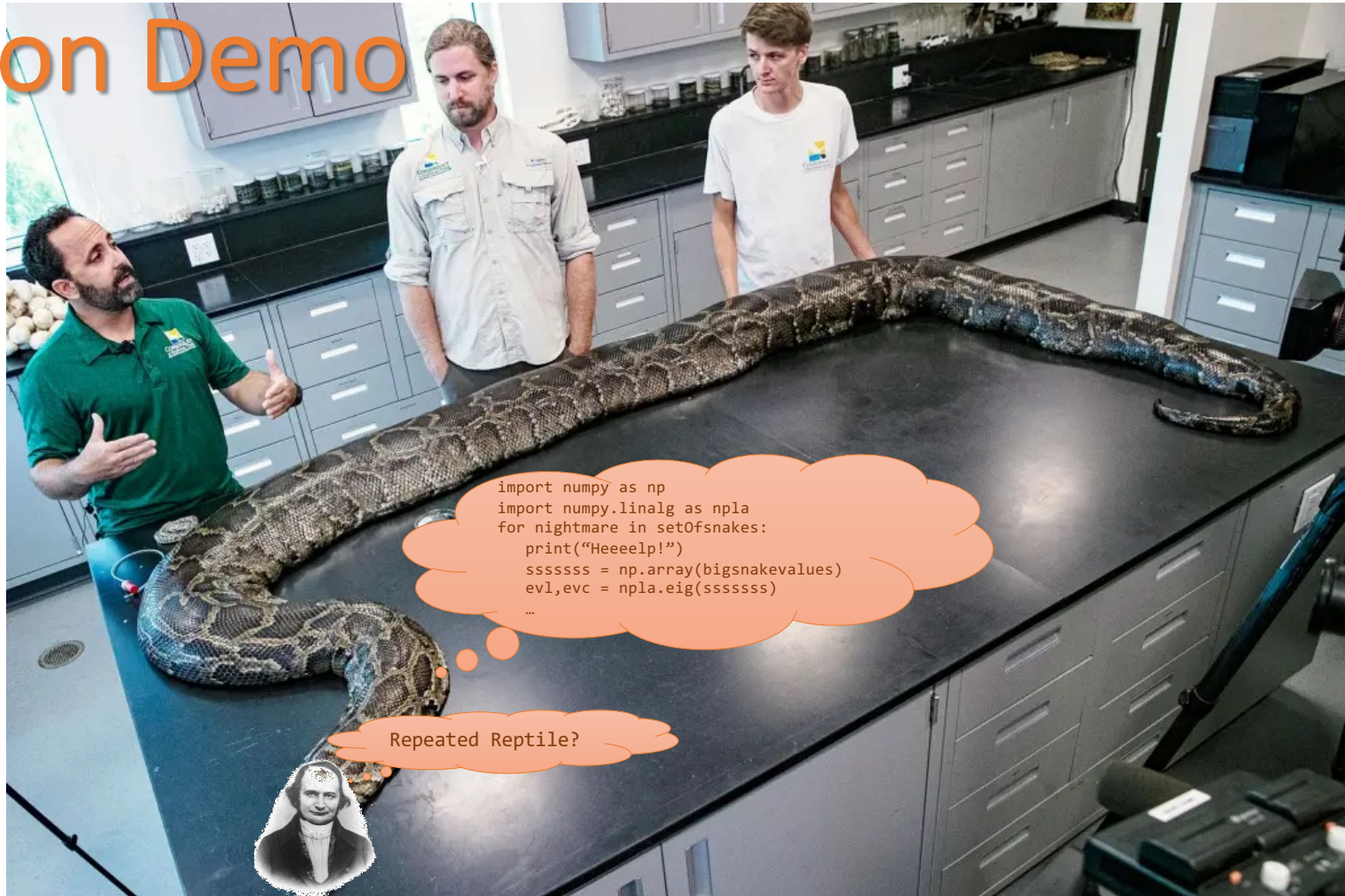
$$\mathbf{x}^{(k)} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ \dots \end{bmatrix}$$

- Find the $(k+1)^{\text{th}}$ solution.
- Keep repeating (iterating) until your “error” is “small enough”
 - Would indicate a *convergence* to the correct value
 - You want to see the error decrease as you keep iterating
 - In a real application, you don’t always know if you’re close to an answer, but in class, we’ll “cheat” and compare with the “ideal” \mathbf{x} .
- We’ll do an “error analysis” with each iteration
 - To see the difference of the norms w.r.t. the ideal answer
 - We’ll want to define a “threshold” of an acceptable stop-point for convergence

Jacobi Method

- **Strict row diagonal dominance** is a **sufficient** *but not necessary* condition for Jacobi's Method to converge
 - It sometimes converges even if this condition is not satisfied (though it'll do so much slower)
- The standard convergence condition (for any iterative method) is when the **spectral radius** of the iteration matrix is less than 1
 - Written as: $\rho(\mathbf{D}^{-1}\mathbf{C}) < 1$
 - It means that the **max. eigenvalue** of $\mathbf{D}^{-1}\mathbf{C}$ should be < 1
- A nice write-up to read (optional) on Wikipedia: https://en.wikipedia.org/wiki/Jacobi_method

Python Demo



```
import numpy as np
import numpy.linalg as npla
for nightmare in setOfsnakes:
    print("Heeeelp!")
    sssssss = np.array(bigsnakevalues)
    evl, evc = npla.eig(sssssss)
    ...
```

Repeated Reptile?

Your TO DOs!

- Work on your homework!

</LECTURE>