

Differentiable manifolds and the Stokes' Theorem

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- 1 Manifolds
- 2 Tangent Space and differential forms
- 3 Integration of Differential n -Forms

1 Manifolds

2 Tangent Space and differential forms

3 Integration of Differential n -Forms

Stokes' Theorem:

$$\int_M d\omega = \int_{\partial M} \omega$$

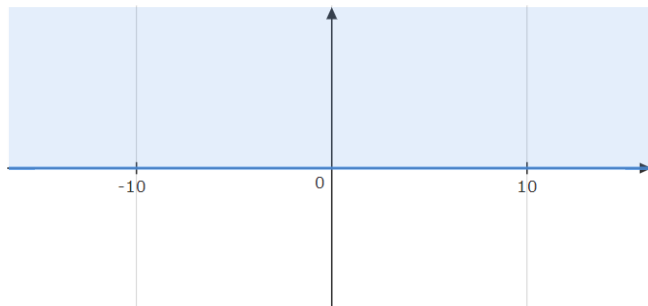
Special cases:

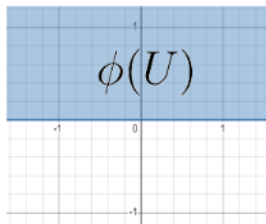
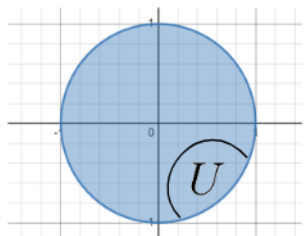
$$\int_{\partial D} Pdx + Qdy = \int_D \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dA$$

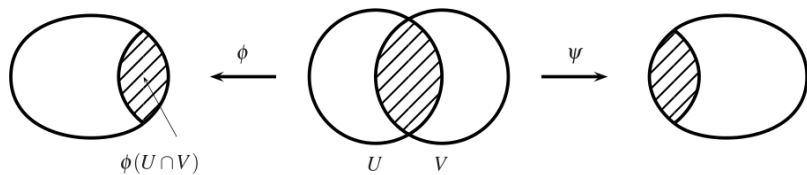
$$\int_{\partial V} F \cdot dS = \int_V \operatorname{div} F$$

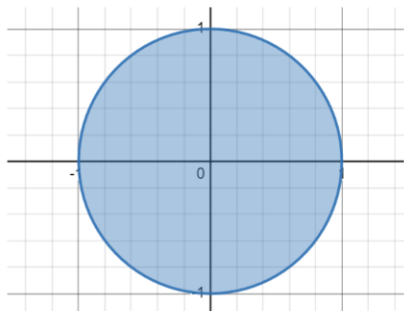
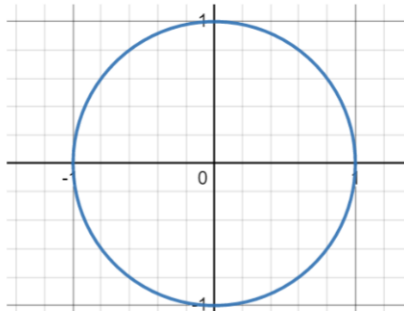
Upper Half Space

The upper half space is $\mathcal{H}^n = \{(x_1, \dots, x_n) \in \mathbb{R}^n \mid x_n \geq 0\}$. Its boundary is $\partial\mathcal{H}^n = \{(x_1, \dots, x_n) \in \mathbb{R}^n \mid x_n = 0\}$.





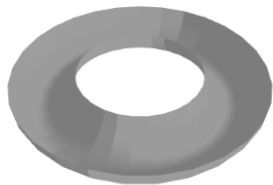


M  ∂M 

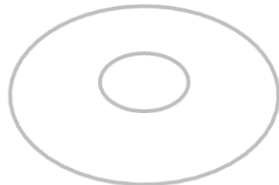
M



M



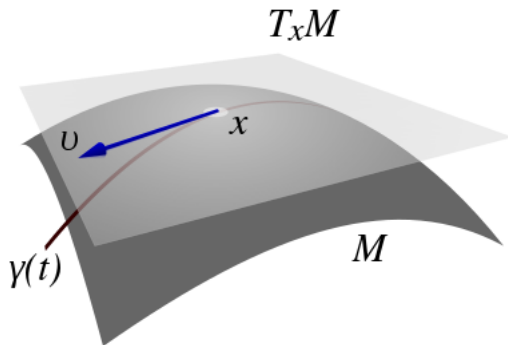
∂M



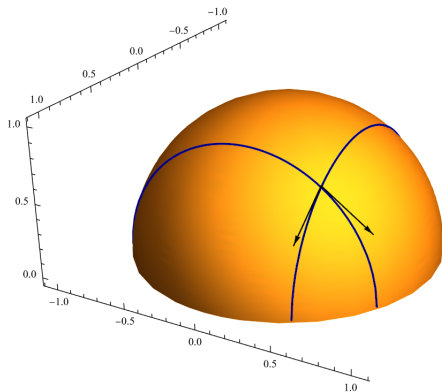
1 Manifolds

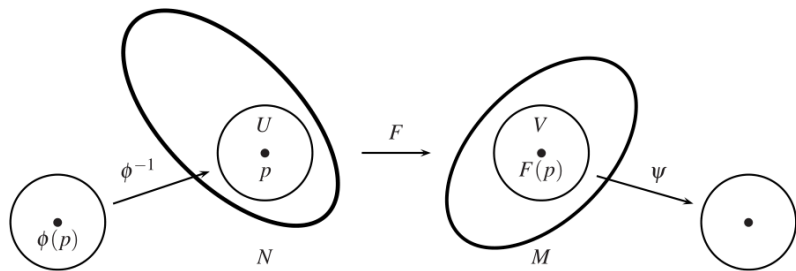
2 Tangent Space and differential forms

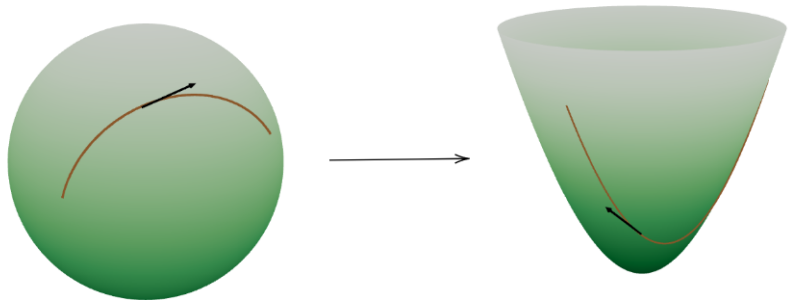
3 Integration of Differential n -Forms



Tangent vectors







Alternating:

$$\omega_p(v_1, \dots, v_i, v_{i+1}, \dots, v_k) = -\omega_p(v_1, \dots, v_{i+1}, v_i, \dots, v_k)$$

Multilinear:

$$\omega_p(v_1, \dots, v_i + cw_i, \dots, v_k) = \omega_p(v_1, \dots, v_i, \dots, v_k) + c\omega_p(v_1, \dots, w_i, \dots, v_k)$$

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Partition of Unity

Let $\{(U_\alpha, \phi_\alpha)\}_{\alpha \in A}$ be an atlas on M . A partition of unity on a manifold M is a collection of nonnegative smooth functions $\{\rho_\alpha : M \rightarrow \mathbb{R}\}_{\alpha \in A}$ such that

- i the collection of supports, $\{\text{supp } \rho_\alpha\}_{\alpha \in A}$, is locally finite,
- ii $\sum_{\alpha \in A} \rho_\alpha = 1$.
- iii $\text{supp } \rho_\alpha \subset U_\alpha$ for all $\alpha \in A$.

Stokes' theorem

Let M be an oriented n dimensional manifold with non empty boundary, and let ω be a differential $(n-1)$ -form on M with compact support. Give ∂M the boundary orientation, and let $\iota : \partial M \rightarrow M$ be the inclusion map. Writing $\int_{\partial M} \iota^* \omega$ as $\int_{\partial M} \omega$,

$$\int_{\partial M} \omega = \int_M d\omega$$

$$\begin{aligned}
\int_0^\infty \frac{\partial f_i}{\partial x_i} dx_i &= \lim_{a \rightarrow \infty} \int_0^a \frac{\partial f_i}{\partial x_i} dx_i \\
&= \lim_{a \rightarrow \infty} (f_i(\dots, a, \dots) - f_i(\dots, 0, \dots)) \\
&= -f_i(\dots, 0, \dots) \\
\int_{-\infty}^0 \frac{\partial f_i}{\partial x_i} dx_i &= \lim_{a \rightarrow -\infty} \int_a^0 \frac{\partial f_i}{\partial x_i} dx_i \\
&= \lim_{a \rightarrow -\infty} (f_i(\dots, 0, \dots) - f_i(\dots, a, \dots)) \\
&= f_i(\dots, 0, \dots) \\
\int_{-\infty}^\infty \frac{\partial f_i}{\partial x_i} dx_i &= 0
\end{aligned}$$

$$\oint_{\partial D} Pdx + Qdy = \int_D (Q_x - P_y) dA$$