

# Bayesian Networks

CS161

Prof. Guy Van den Broeck

# Motivation from Logic

- Starting from logic:

$$\textit{Toothache} \Rightarrow \textit{Cavity}$$

- Rule is wrong; some exceptions:

$$\textit{Toothache}$$

$$\Rightarrow \textit{Cavity} \vee \textit{GumProblems} \vee \textit{Abscess} \vee \dots$$

- This is intractable to model
- Perhaps make the rule causal:

$$\textit{Cavity} \Rightarrow \textit{Toothache}$$

... but this rule is wrong as well...

# Motivation from Logic

The monotonicity of logic is the problem... again

- Either you model everything exhaustively
  - Intractable to model; we are too ignorant
  - Even if you could, you will never be able to act
- Assume too much and get stuck when things don't go as expected

Epistemological change: we no longer believe in a set of possible worlds (models), we believe in a probability for each world!

# World View

- Propositional
  - Global properties that are true or false
- Probabilistic
  - Belief is still a set of possible world
  - But now they have a degree of belief  $\text{Pr}(\cdot)$
  - Knowledge Base  $\text{KB} \approx \text{Pr}$
- *“Uncertainty is epistemological – pertaining to an agent’s beliefs of the world – rather than ontological – how the world is.”* [Poole et al.]
  - We can have different beliefs about the same world
  - What’s the probability that the world ends tomorrow?

# Decision-Making Motivation

- Acting with partial (noisy) sensor information
  - ⇒ Consider ever logically possible explanation
- Example: drive to airport
  - ⇒ No plan is guaranteed to achieve goal
  - ⇒ Yet the agent must act
- Decisions depend on
  - Relative importance of goals (*utility*)
  - The likelihood of achieving them (*probability*)
  - ⇒ Maximum expected utility

# Propositions are only Boolean?

- Categorical variables
  - Weather=sunny, Weather=rainy, Weather=snowy
  - 3 Boolean variables that are mutually exclusive
    - Sometimes called “indicator variables”
    - Can all be encoded in sentences...
- Continuous variables
  - Temperature=73.514, Temperature=78.785, ...
  - Infinitely many Boolean variables (and worlds).
    - In logic, see SAT Modulo Theories (SMT)
    - Special accommodations for continuous variables in statistics; we will mostly stick to the discrete world.

# Sentences or “Events”

- Knowledge is a probability for every world:  $\Pr(\omega)$
- What is the probability of a sentence  $\alpha$ ?  
(also called an “event”  $\alpha$  in probability)
- Need to axiomatize probability [Kolmogorov]:
  1. Probabilities are non-negative:  $0 \leq \Pr(\alpha)$
  2. The probability of a true event is 1:  $\Pr(\text{true}) = 1$
  3. If  $\alpha$  and  $\beta$  are mutually exclusive, then  
 $\Pr(\alpha \vee \beta) = \Pr(\alpha) + \Pr(\beta)$ .

# Sentences or “Events”

- Knowledge is a probability for every world:  $\text{Pr}(\omega)$
- What is the probability of a sentence  $\alpha$ ?  
(also called an “event”  $\alpha$  in probability)
- A sentence  $\alpha$  is equivalent to the disjunction of its models:  $\alpha \equiv \omega_1 \vee \omega_8 \vee \omega_{11} \vee \omega_{17} \vee \dots$

$$\text{Pr}(\alpha) = \sum_{\omega \models \alpha} \text{Pr}(\omega) = \sum_{\omega \in \text{Mods}(\alpha)} \text{Pr}(\omega)$$



# Properties of Probability

- Complement events

- $\Pr(\alpha) + \Pr(\neg\alpha) = 1$

- Why?

- Inclusion-exclusion

- $\Pr(\alpha \vee \beta) = \Pr(\alpha) + \Pr(\beta) - \Pr(\alpha \wedge \beta)$

- Why?

$$\Pr(\text{Earthquake}) = \Pr(\omega_1) + \Pr(\omega_2) + \Pr(\omega_3) + \Pr(\omega_4) = .1$$

$$\Pr(\text{Burglary}) = \Pr(\omega_1) + \Pr(\omega_2) + \Pr(\omega_5) + \Pr(\omega_6) = .2$$

$$\Pr(\text{Earthquake} \wedge \text{Burglary}) = \Pr(\omega_1) + \Pr(\omega_2) = .02$$

$$\Pr(\text{Earthquake} \vee \text{Burglary}) = .1 + .2 - .02 = .28$$

# Conditional Probability

- What if I observe new information in the form of a sentence  $\beta$ ?
- Belief changes from  $\Pr(\alpha)$  to  $\Pr(\alpha|\beta)$
- Can also be axiomatized...
- But briefly

$$\Pr(\alpha|\beta) = \frac{\Pr(\alpha \wedge \beta)}{\Pr(\beta)}$$

$$\begin{array}{ll} \Pr(\text{Burglary}) & = .2 \\ \Pr(\text{Burglary}|\text{Earthquake}) & = .2 \end{array}$$

$$\begin{array}{ll} \Pr(\text{Alarm}) & = .2442 \\ \Pr(\text{Alarm}|\text{Earthquake}) & \approx .75 \uparrow \end{array}$$

# Product Rule

# Basic Properties of Probability

# Betting Semantics

# Inconsistent Beliefs

Agent 1		Agent 2		Outcomes and payoffs to Agent 1			
Proposition	Belief	Bet	Stakes	$a, b$	$a, \neg b$	$\neg a, b$	$\neg a, \neg b$
$a$	0.4	$a$	4 to 6	-6	-6	4	4
$b$	0.3	$b$	3 to 7	-7	3	-7	3
$a \vee b$	0.8	$\neg(a \vee b)$	2 to 8	2	2	2	-8
				-11	-1	-1	-1

# Computing Probabilities: Example

	<i>toothache</i>		$\neg$ <i>toothache</i>	
	<i>catch</i>	$\neg$ <i>catch</i>	<i>catch</i>	$\neg$ <i>catch</i>
<i>cavity</i>	0.108	0.012	0.072	0.008
$\neg$ <i>cavity</i>	0.016	0.064	0.144	0.576

# Monotonicity of Belief?

- Recall: monotonicity of logic
- Is it possible to observe something new and undo prior beliefs?

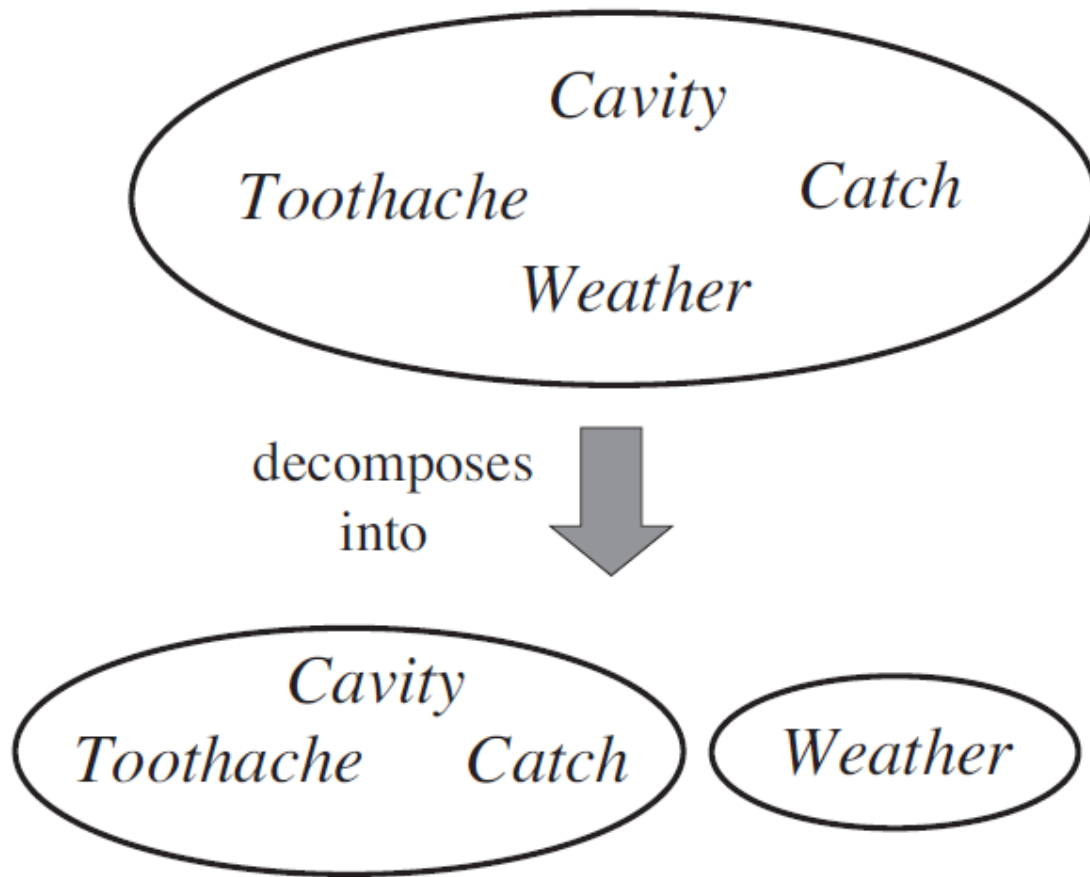
$$\begin{array}{lcl} \Pr(\text{Alarm}) & = & .2442 \\ \Pr(\text{Alarm}|\text{Earthquake}) & \approx & .75 \uparrow \end{array}$$

<i>world</i>	Earthquake	Burglary	Alarm	$\Pr(.)$
$\omega_1$	true	true	true	.0190
$\omega_2$	true	true	false	.0010
$\omega_3$	true	false	true	.0560
$\omega_4$	true	false	false	.0240
$\omega_5$	false	true	true	.1620
$\omega_6$	false	true	false	.0180
$\omega_7$	false	false	true	.0072
$\omega_8$	false	false	false	.7128

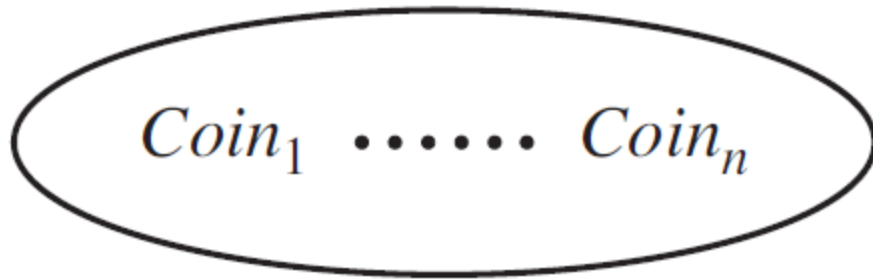
- Example:
  - Alarm and not Earthquake:  $.1620 + .0072 = 0.1692$
  - Not Earthquake:  $.9$
  - Alarm given not Earthquake:  $.188$



# Independence



# Independence



decomposes  
into

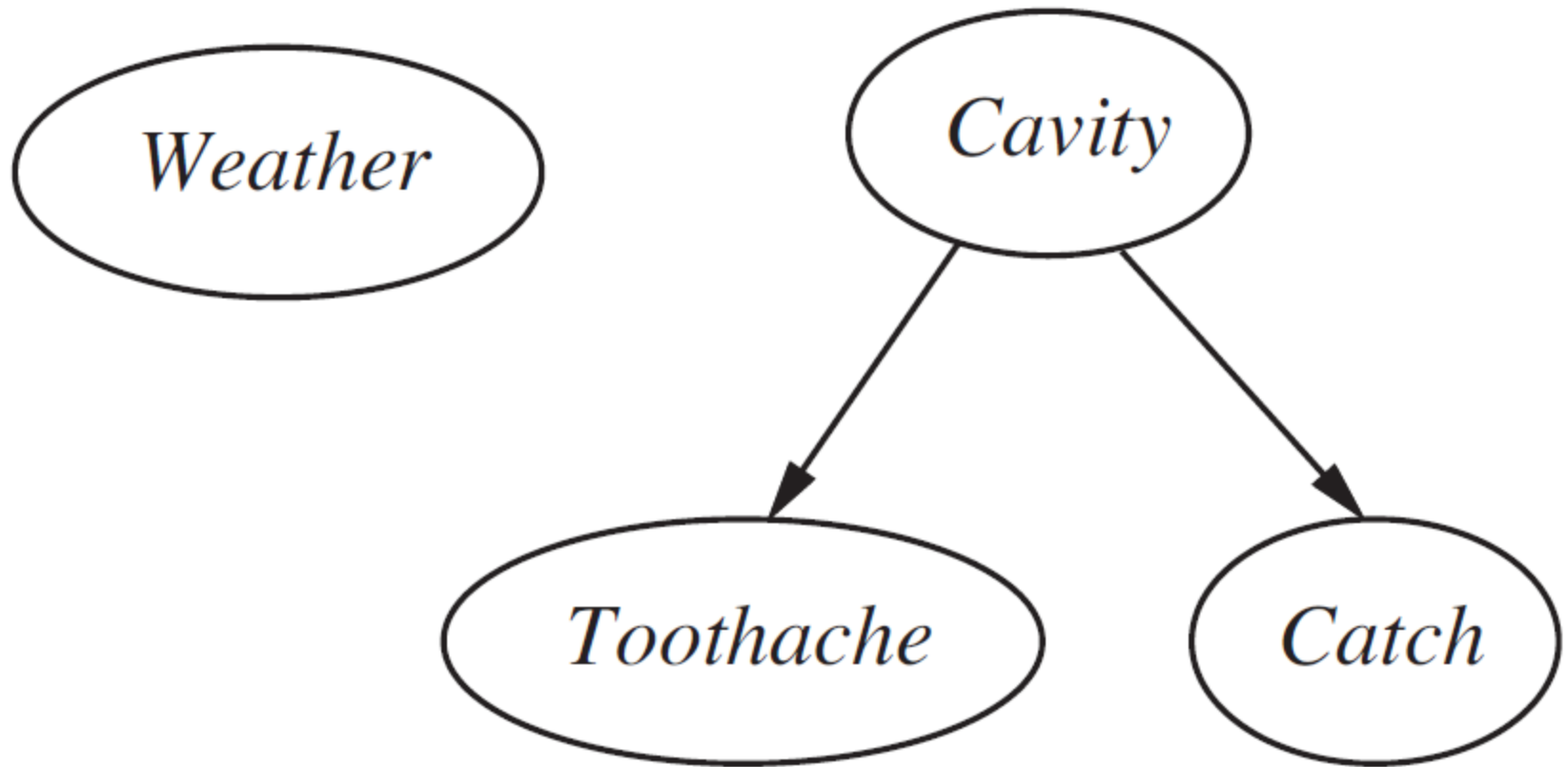


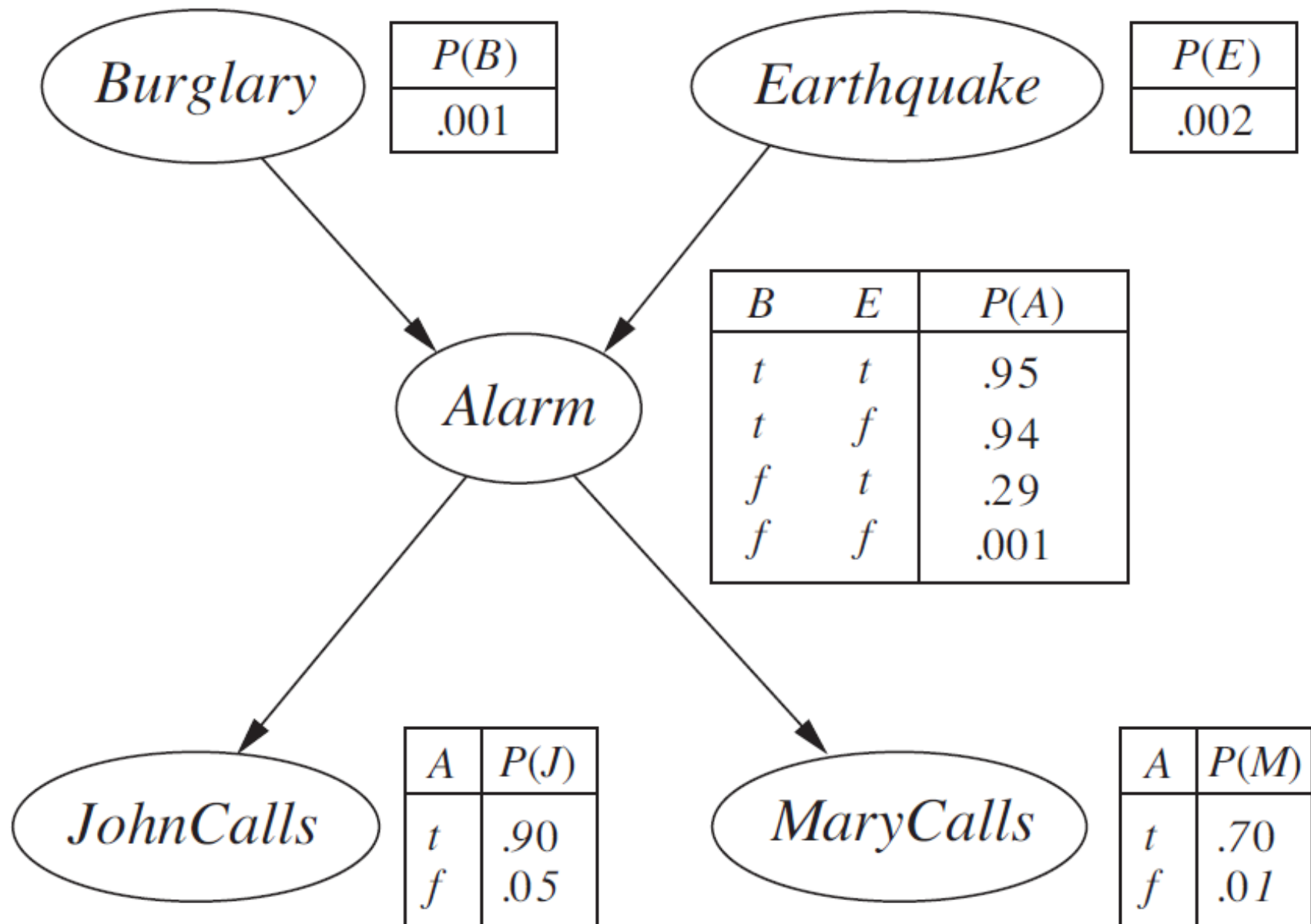
# Naïve Bayes Assumption

$$\mathbf{P}(Cause, Effect_1, \dots, Effect_n) = \mathbf{P}(Cause) \prod_i \mathbf{P}(Effect_i \mid Cause)$$

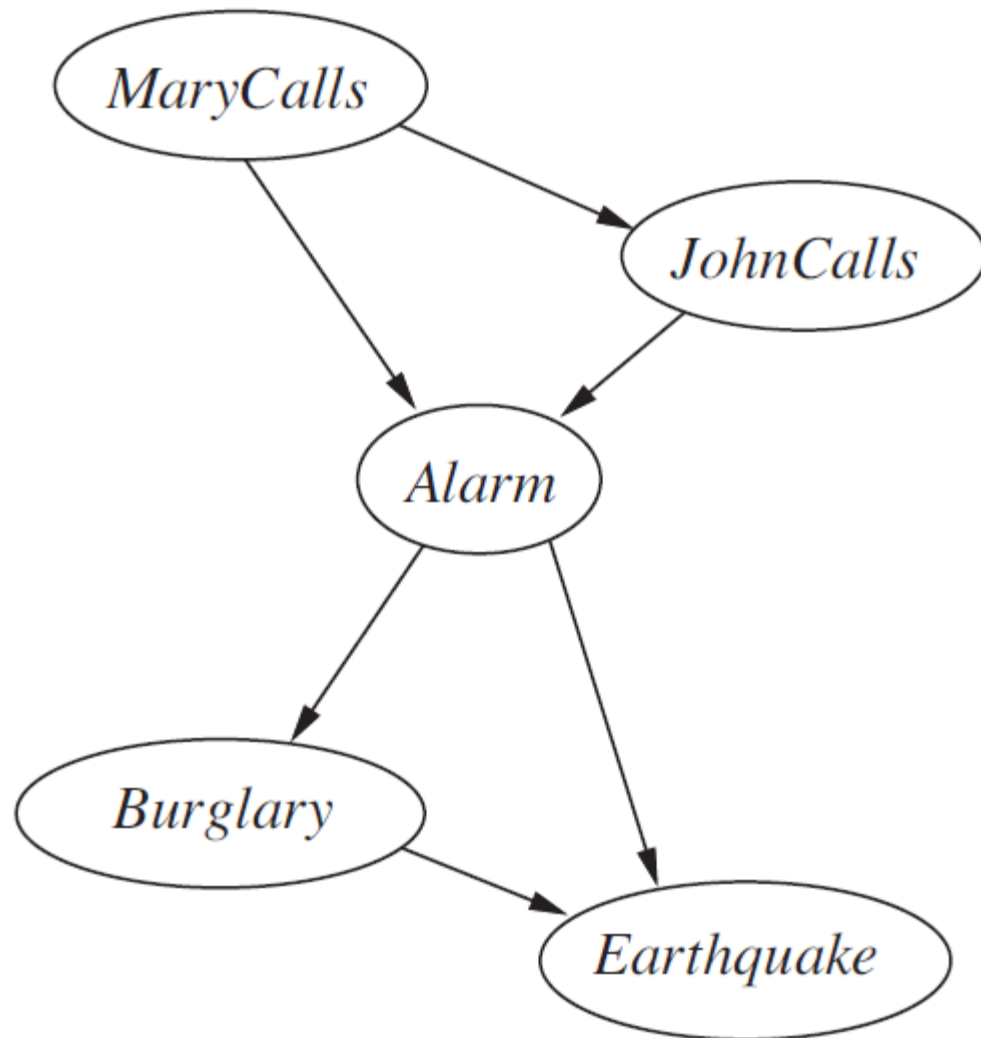
This is how spam filters work!

# Bayesian Networks

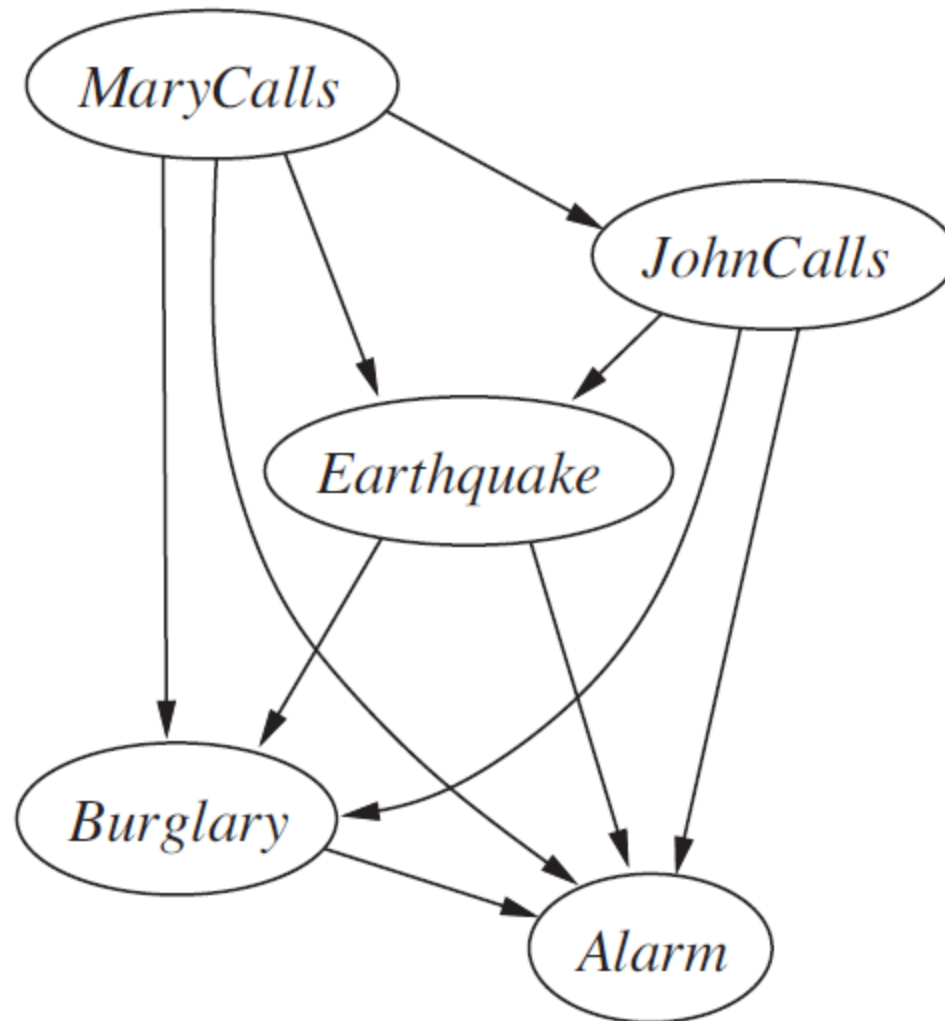




# Conditional Independence and Order



# Conditional Independence and Order

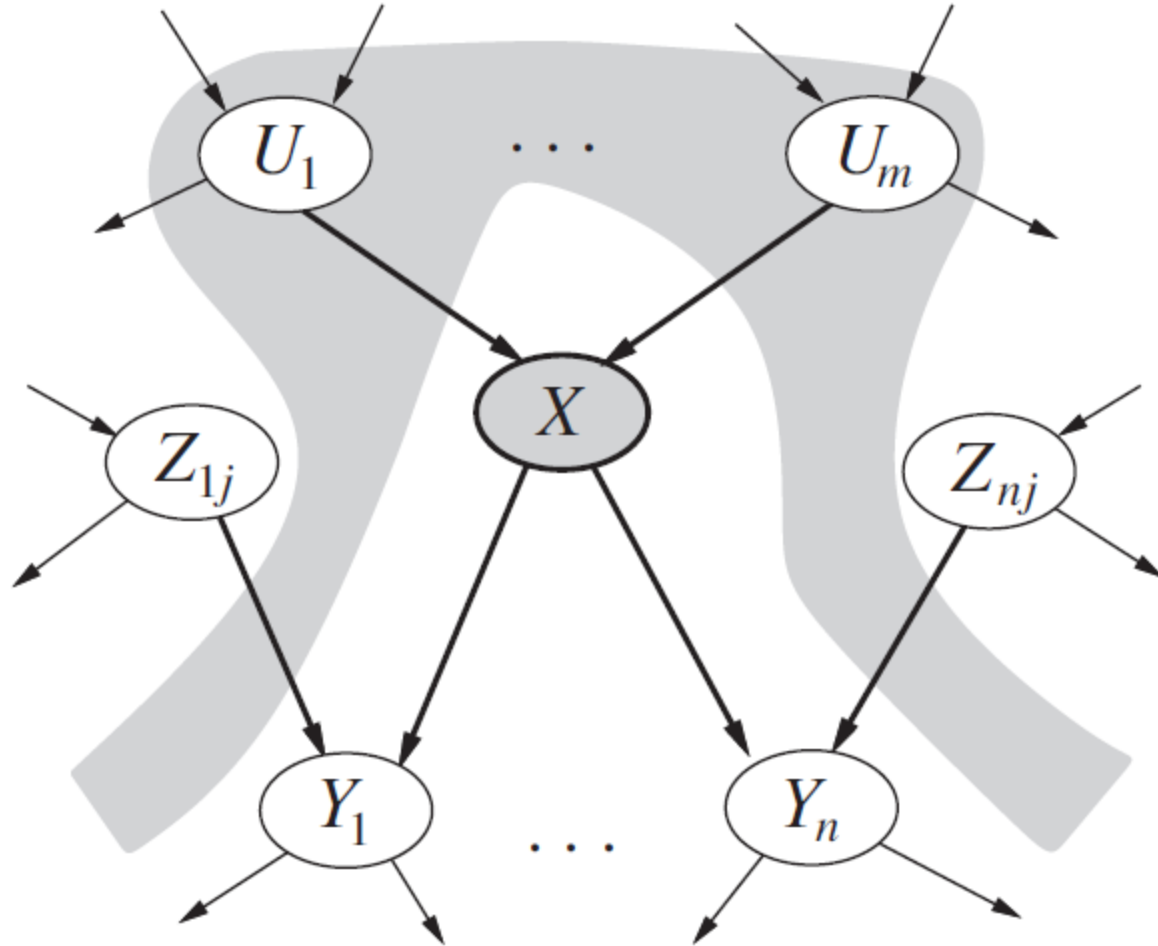


# Topological Semantics

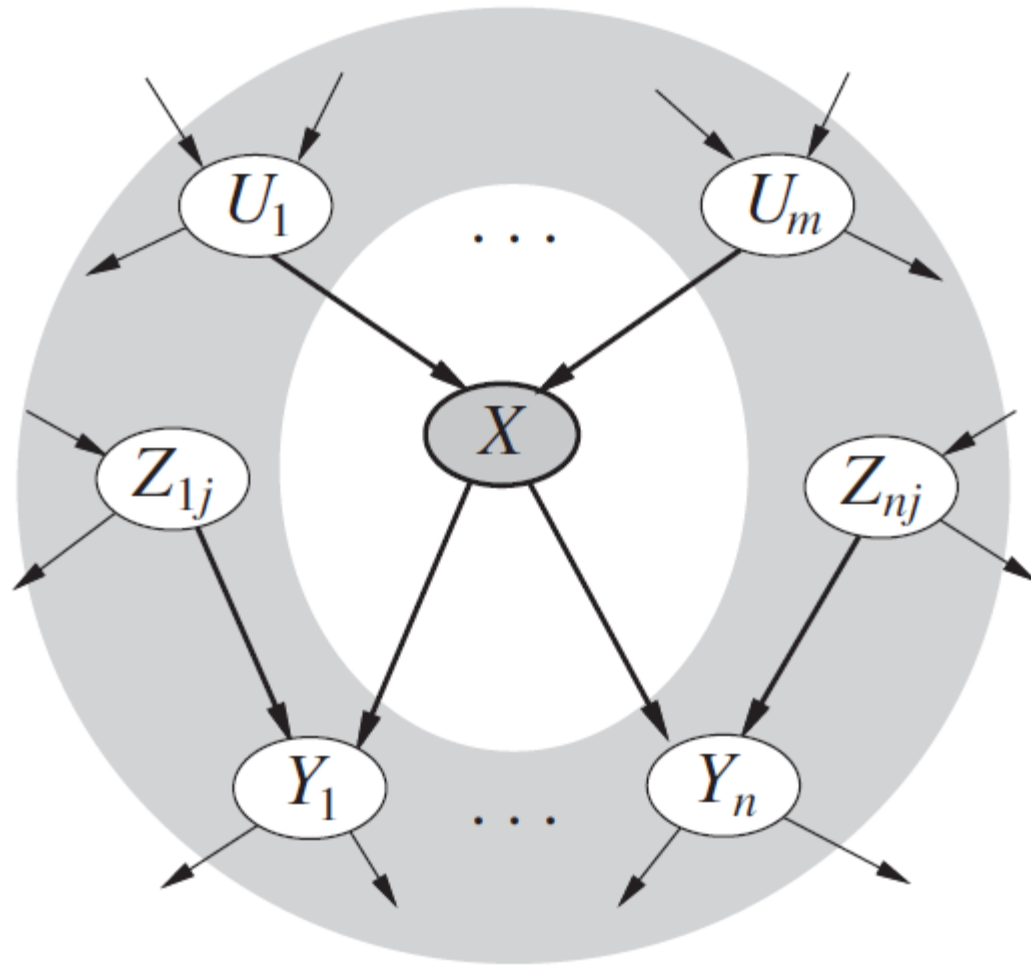
*What knowledge is encoded in  
Bayesian network structure?*



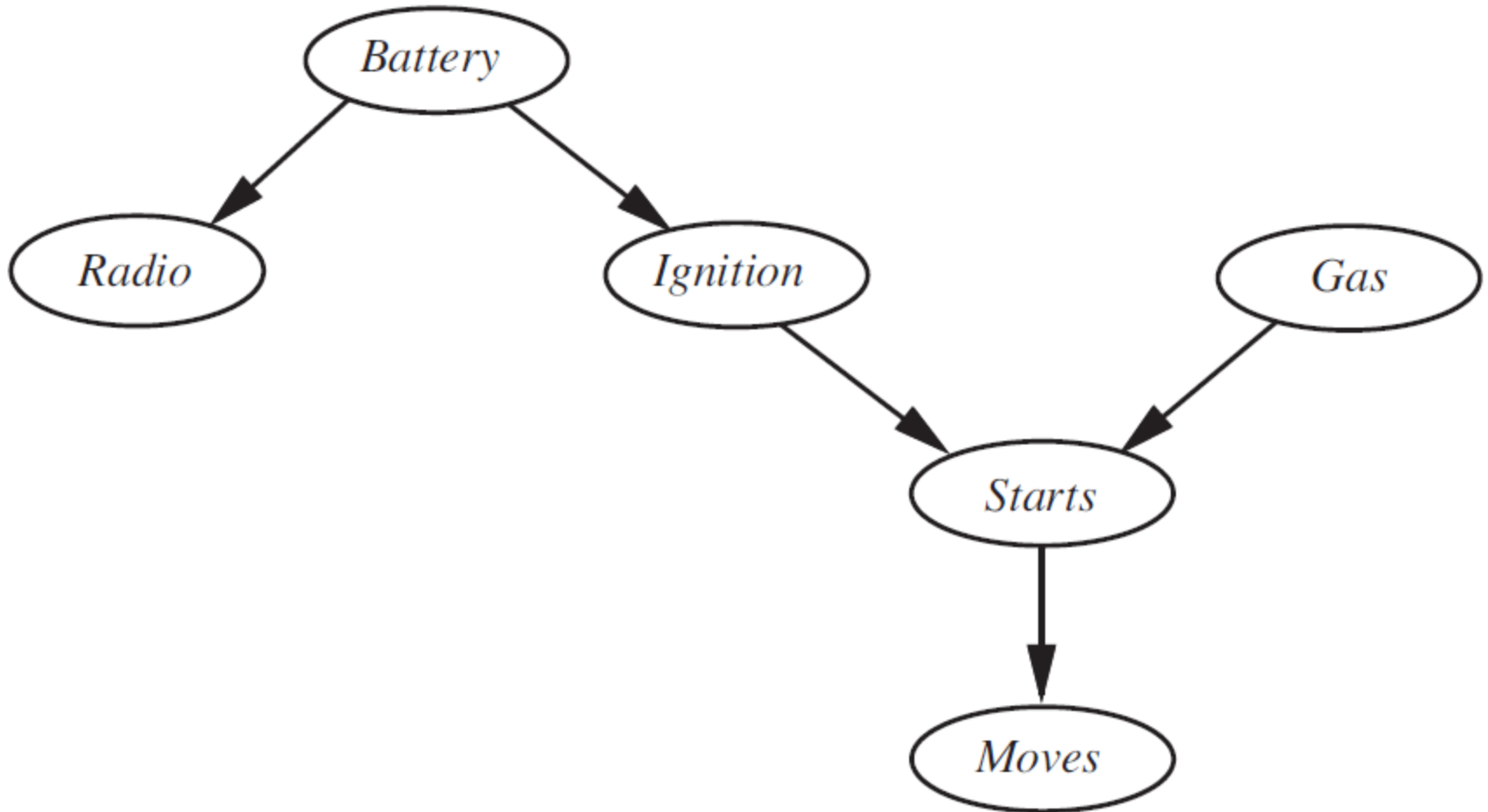
# Markovian Assumptions



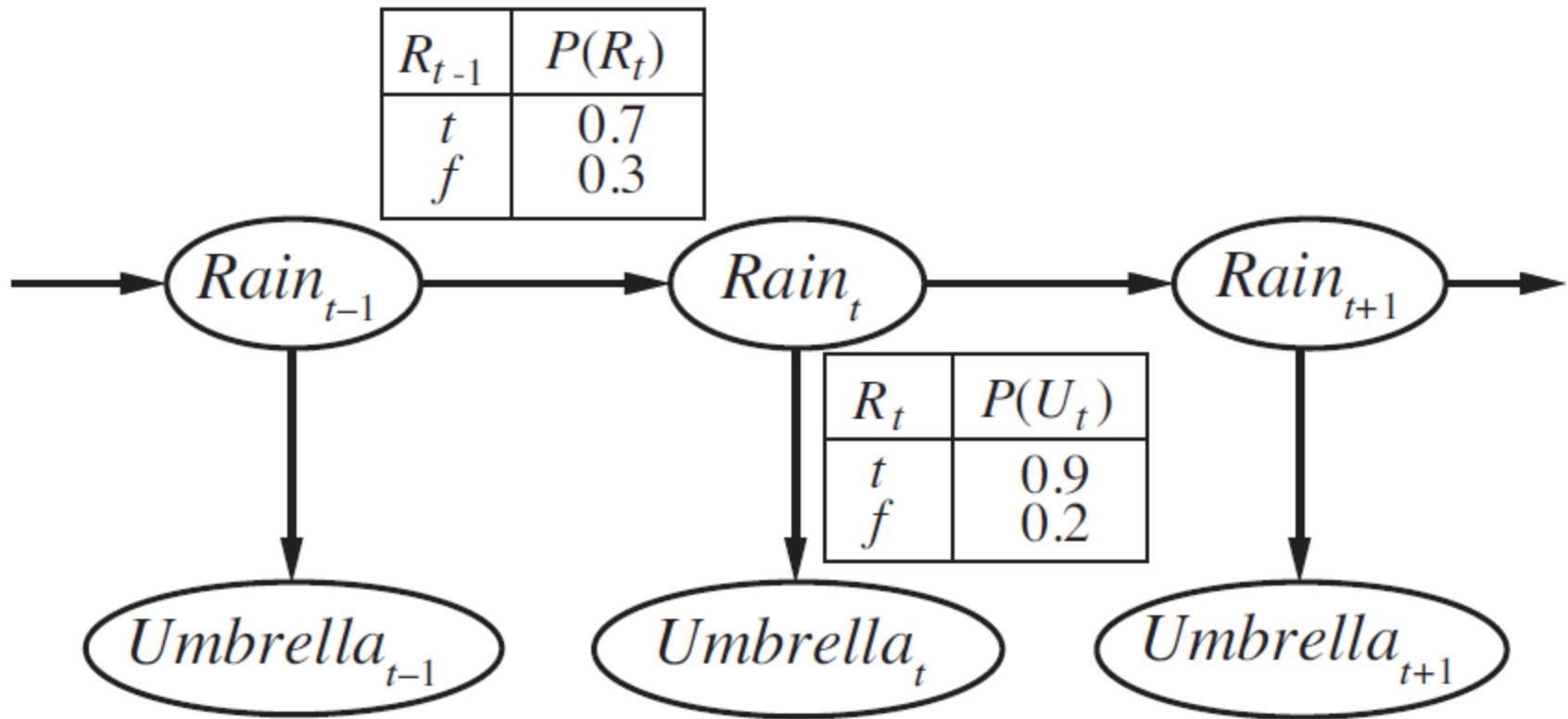
# Markov Blanket



# Example Network



# Markov Chains and Hidden Markov Models



# Inference by Enumeration

# Factors Multiplication

$A$	$B$	$\mathbf{f}_1(A, B)$
T	T	.3
T	F	.7
F	T	.9
F	F	.1

**X**

$B$	$C$	$\mathbf{f}_2(B, C)$
T	T	.2
T	F	.8
F	T	.6
F	F	.4

**=**

$A$	$B$	$C$	$\mathbf{f}_3(A, B, C)$
T	T	T	$.3 \times .2 = .06$
T	T	F	$.3 \times .8 = .24$
T	F	T	$.7 \times .6 = .42$
T	F	F	$.7 \times .4 = .28$
F	T	T	$.9 \times .2 = .18$
F	T	F	$.9 \times .8 = .72$
F	F	T	$.1 \times .6 = .06$
F	F	F	$.1 \times .4 = .04$

# Summing out Variable from Factor

$A$	$B$	$C$	$\mathbf{f}_3(A, B, C)$
T	T	T	$.3 \times .2 = .06$
T	T	F	$.3 \times .8 = .24$
T	F	T	$.7 \times .6 = .42$
T	F	F	$.7 \times .4 = .28$
F	T	T	$.9 \times .2 = .18$
F	T	F	$.9 \times .8 = .72$
F	F	T	$.1 \times .6 = .06$
F	F	F	$.1 \times .4 = .04$

$$\begin{aligned}\mathbf{f}(B, C) &= \sum_a \mathbf{f}_3(A, B, C) = \mathbf{f}_3(a, B, C) + \mathbf{f}_3(\neg a, B, C) \\ &= \begin{pmatrix} .06 & .24 \\ .42 & .28 \end{pmatrix} + \begin{pmatrix} .18 & .72 \\ .06 & .04 \end{pmatrix} = \begin{pmatrix} .24 & .96 \\ .48 & .32 \end{pmatrix} .\end{aligned}$$

# Variable Elimination