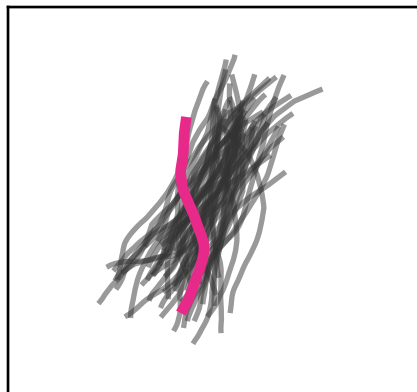
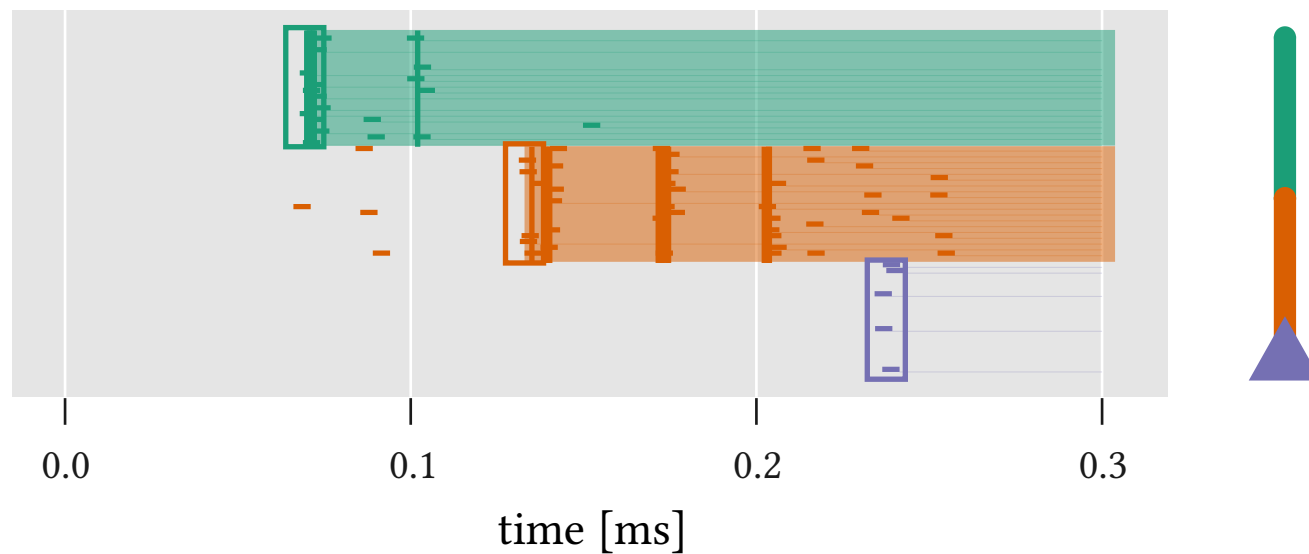


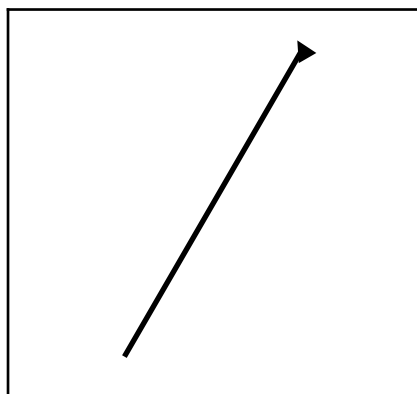
Effective paths



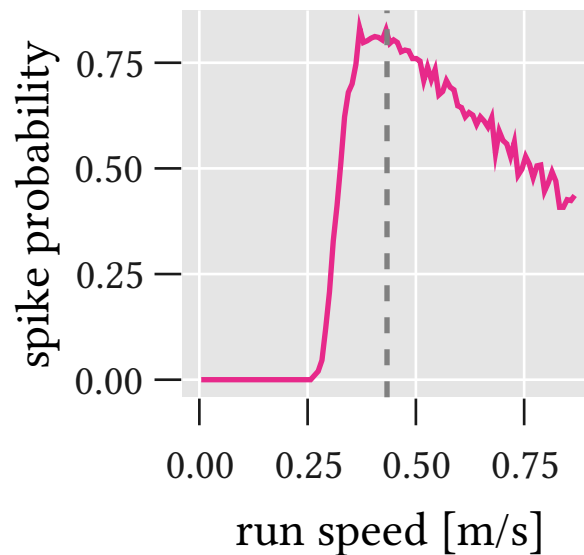
Activity for the highlighted path



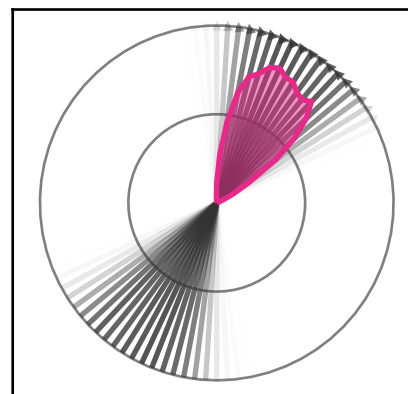
Optimal path



Speed



Orientation



Translation

