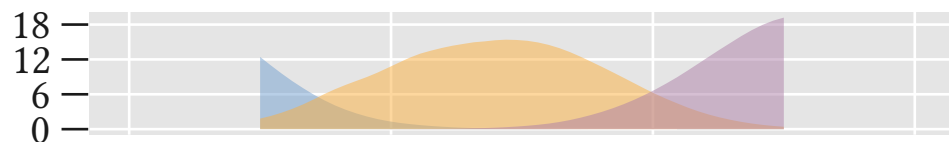


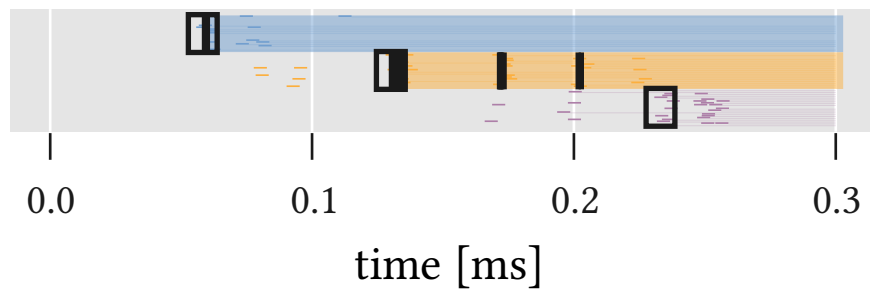
Effective paths



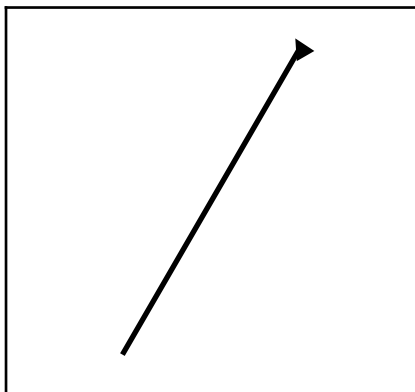
Expected volley sizes for the highlighted path



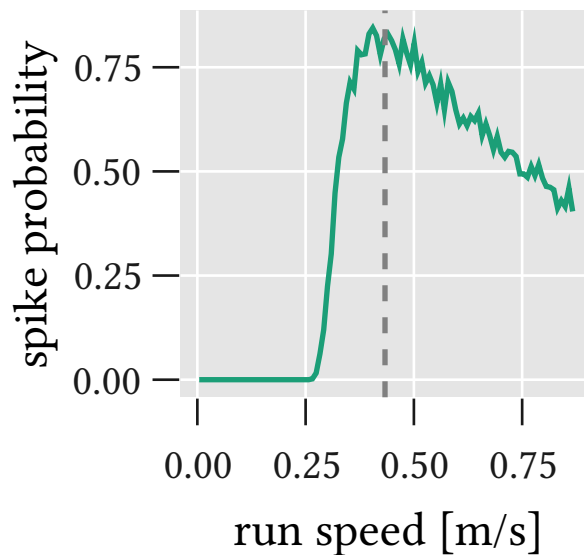
Activity for the highlighted path



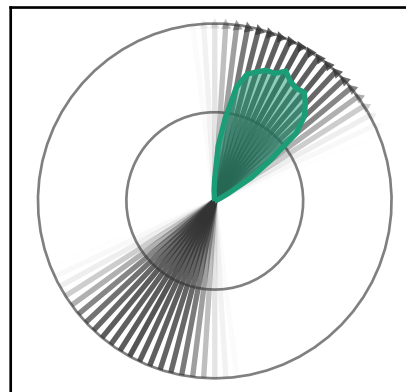
Optimal path



Speed



Orientation



Translation

