

**Submit on Crowdmark by Tuesday, June 22, 2021, 11:59pm**

## Instruction

Upload a PDF file with two parts. Part one should include your typed report (your discussions, data and figures). Part two should list your code. You will receive a Crowdmark link for uploading your results.

## Perturbations in linear systems

This computing assignment is an exploration of condition numbers, perturbations, and the numerical behavior of random and not-so-random matrices. You will need to load `Data.mat` from the folder to get all the data for the assignment, including the matrices  $E$ ,  $H$ ,  $HI$ ,  $H8$ , and  $HI8$  referred to below. For all your computations use  $\epsilon = 10^{-6}$ , a variable `epsilon` with the proper value is included in the data.

1. For  $A = E$ ,  $A = H$ , compare the 1-condition number  $\kappa_1(A)$  (in Matlab simply `cond(A, 1)`) to the observed amplification in perturbations as well as to the Matlab estimate `rcond(A)`. Note, that `rcond(A)` estimates the reciprocal  $1/\kappa_1(A)$ .

### a). Perturbations in the right-hand side

For each of these two matrices ( $A = E$  and  $A = H$ ) you will solve a total of 100 systems. You pair each right side  $b = B(:, j)$  with each perturbation direction  $d = D(:, k)$ ; note, that all column vectors in your data have length 1 in the  $\|\cdot\|_1$  norm. Compute (simply use the Matlab “\” backslash command) the solution of

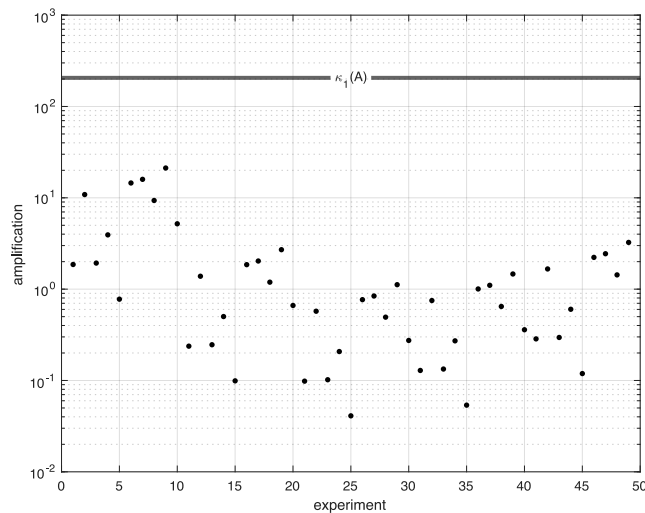
$$Ax = b, \quad \text{and} \quad Ay = b + \epsilon d,$$

and compare the amplification of the relative errors

$$e = \frac{\frac{\|y-x\|_1}{\|x\|_1}}{\frac{\|\epsilon d\|_1}{\|b\|_1}} = \frac{\|y-x\|_1}{\epsilon \|x\|_1}$$

to the upper bound  $\kappa_1(A)$ .

Look at the average, median, and maximum of the amplification factors. Describe your observations (supported by a plot), and comment on your results. See the sample below for a possible visualization.



b). Perturbations of the matrix

For each of the two matrices  $E$  and  $H$ , solve a total of 60 linear systems to compute amplification factors. You use the same 10 right hand sides  $b$  from the first part; to get your perturbation matrices, type  $C = \text{BIGC}(:, :, k)$ , for  $k = 1, \dots, 6$ . All the data matrices have  $\|C\|_1 = 1$ .

Compute (simply use the Matlab “\” backslash command) the solution of

$$Ax = b, \quad \text{and} \quad (A + \epsilon C)z = b,$$

and compare the amplification of the relative errors

$$e = \frac{\frac{\|z-x\|_1}{\|x\|_1}}{\frac{\|\epsilon C\|_1}{\|A\|_1}} = \|A\|_1 \frac{\|z-x\|_1}{\epsilon \|x\|_1}$$

to the upper bound  $\kappa_1(A)$  and the Matlab estimate  $1/\text{rcond}(A)$ .

Look at averages, median, and maxima of amplification factors. Plot your results, and comment on your observations.

2. Use the Matlab command  $\text{AINV} = \text{inv}(A)$  to find the inverse of a matrix  $A$ , and compute the inverse of this inverse,  $\text{AC} = \text{inv}(\text{AINV})$ , which mathematically equals  $A = (A^{-1})^{-1}$ . The matrix  $I$  is the identity matrix.

a). For  $A = E$ , compute  $\|A * \text{AINV} - I\|_1$ , and  $\|\text{AC} - A\|_1$ .

b). For  $A = H$ , compute  $\|A * \text{AINV} - I\|_1$ , and  $\|\text{AC} - A\|_1$ . For this matrix, also compare the computed inverse to the exact inverse  $HI$  provided in the data, i.e., compute  $\|\text{AINV} - HI\|_1$ .

c). Repeat b) for the matrix  $A = H8$  with exact inverse  $HI8$ . Compute  $\kappa_1(H8)$ .

Summarize your observations and highlight anything that might seem surprising.