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#!/usr/bin/env python3
# -*- coding: utf-8 -*-
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@author: jimmy
# Import relevant modules/packages
import numpy as np
from astropy import units as u
from astropy import constants as const
import matplotlib.pyplot as plt
# Function to make a list of a descending geometric series
def DescendingGeometric(length):
    # Make list of coefficients that are all 1
    c = np.ones(length)
    # Multiply each component by another factor of 1/2
    for i in range(1,len(c)):
        c[i] *= .5/i
    return(c)
# Function to numerically solve differentiable equation
# Resource that helped me: https://www.math.ubc.ca/~pwalls/math-python/roots-optimization/newton
def NewtonRaphson(f,df,x0,precision,numSteps):
    # Inputs:
    #
         f: function to evaluate
    #
         df: derivative of function
         x0: initial guess at solution
    #
         precision: answer won't exactly be 0, so set a tolerance
    #
         numSteps: maximum number of times to iterate
    # Establish first guess at solution
    x = x0
    # Iterate over number of steps
    for i in range(0,numSteps):
        # Evaluate function
        func = f(x)
        \# If f(x) is within precision, declare that value of x as the solution
        if abs(func) <= precision:</pre>
            \#print('A solution of \{0:.2e\} was found in \{1\} iterations'.format(x,i))
            break
        # If f(x) is not within precision, continue searching for solution
        elif abs(func) > precision:
            # Evaluate derivative
            deriv = df(x)
            # Adjust guess of solution by subtracting quotient of function and derivative from t
            x -= func/deriv
    return(x)
# Function to compute Chi Squared and reduced Chi Squared to compare models to obserations
def ChiSquared(model,observation,error,free):
    # Inputs:
    #
          model = list of values from model
    #
          observation = list of values from actual observations
          error = list of errors (sigma) for each observation
    #
    #
          free = number of free parameters in the model
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# Returns:
          Chi Squared and reduced Chi squared to indicate goodness of fit for the model
    # Initialize Chi Squared as 0
    ChiSq = 0.0
    # Calculate number of degrees of freedom (# of data points - free)
    nu = len(model) - free
    # For each data point:
    for i in range(len(model)):
        # Calculate the difference between the obsrevation and model (residual)
        residual = observation[i] - model[i]
        # Calculate square of quotient of residual and error value for particular data point
        term = (residual/error[i])**2
        # Add this term to the overall Chi Squared value
        ChiSq += term
    # Calculate reduced Chi Squared (just Chi Squared / # of DoF)
    RedChiSq = ChiSq/nu
    return(ChiSq,RedChiSq,nu)
# Function to calculate Gaussian
def Gaussian(x,offset,amplitude,mean,stddev,wavelength=5000.0):
    # Inputs:
        x: point at which to calculate Gaussian (can be a list of values)
    #
        offset: set continuum level of Gaussian
        amplitude: peak depth of function
    #
        mean: center of Gaussian
        stddev: width of Gaussian
        wavelength: reference wavelength for spectrum
    # Returns:
        Value of Gaussian function at x
    # Define exponent
    exponent = (-1.0*(x-mean-wavelength)**2)/(2*stddev)
    # Calculate function value
    function = offset-(amplitude*np.exp(exponent))
    return(function)
# Function to calculate non-relativistic doppler shift
def NonRelDoppler(new value, rest=5000.0):
    # Convert speed of light to km/s
    c = const.c.to(u.km/u.s).value
    # Calculate new velocity
    velocity = ((new value/rest)-1)*c
    return(velocity)
"""wavelength = 5000.0
offset = 1.0
P = 0.5
mean = 0.0
sigma = 1.0
sample = 0.5
# Generate list of wavelengths to draw spectrum over
x = wavelength+np.arange(mean-5.0, mean+5.0+sample, sample)
y = Gaussian(x,offset,P,mean,sigma)
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plt.scatter(x,y)"""