## MODELING STRAKES AND FOIL SECTIONS IN VIVA

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#### 1 Effectiveness of Strakes and Modeling of Forces

Scrutton & Walshe (1957) and Woodgate & Maybree (1959) proposed and studied the effect of helical strakes as means for suppressing the wind-excited vibrations of stacks. They considered triple sharp-edged helical strakes with pitch P to diameter D ratio of P/D = 15 and various strake heights h. Starting with h/D = 0.029, they found that vibrations are reduced; further improvement was found as they increased the height to h/D = 0.029, h/D = 0.059, h/D = 0.088, and h/D = 0.118. They provided graphs showing the unstable regime over which vibrations occur, as function of the reduced velocity  $U^* = \frac{U}{f_n D}$  and

the mass-damping ratio  $\xi$ , where  $\xi = \frac{2M\delta}{\rho D^2}$ . The region of unstable response reduces as function of h/D and the reduced velocity of peak response moves to higher values:

- for a bare cylinder they find peak response at about  $U^* = 5.0$ ;
- for  $h/\not = 0.029$  at  $U^* = 5.1$ ;
- for  $h/\cancel{B}$  0.059 at  $U^* = 6.7$ ,
- for  $h/\cancel{B}$  0.088 at  $U^* = 7.1$ ,
- for h/D = 0.118 at  $U^* = 8.4$ .

The basic finding is that beyond h/I0f 0.10, the response is reduced substantially, while the peak response occurs at  $U^*$  above 8.0.

Woodgate & Maybree (1959) found that the optimal pitch to diameter ratio is close to a value of P/D = 5, away from the originally proposed value of P/D = 15. However, the optimal reduction is rather weak, and the pitch to diameter ratio is not a strong parameter of the problem.

### 2 Modeling of Faired Sections

Foil sections have small oscillatory lift coefficient, and smaller drag coefficient than smooth circular cylinder sections. When there is a misalignment between the direction of the current and the orientation of the foil, there is a steady lift coefficient as well; this is not modeled herein.

The fairing drag coefficient depends on:

- the Reynolds number based on the chord length c
- the chord to thickness ratio c/t

The fairing drag coefficient  $c_D$ , based on the projected front area, is given as:

$$c_D = c_f \left( 4 + 2\frac{c}{t} + 120(\frac{t}{c})^3 \right) \tag{1}$$

For  $c_f$  we use either the laminar value, for Re  $< 10^6$ :

$$c_f = \frac{1.328}{\sqrt{\text{Re}}} \tag{2}$$

or the turbulent value, for  $Re > 10^6$ :

$$\frac{1}{\sqrt{c_f}} = 3.46 \log(\text{Re}) - 5.6 \tag{3}$$

The drag per unit riser length,  $F_D$  is found as:

$$F_D = \frac{1}{2} \rho c_D t U^2 \tag{4}$$

## 3 Definition of Symbols

D = cylinder diameter (m)

c =chord length (m) for fairings

 $c_f$  = frictional coefficient (per wetted surface)

 $c_D$  = drag coefficient (per frontal area)

 $f_n$  = natural frequency of oscillation of a compliantly mounted cylinder (Hz)

 $F_D$  = Drag force on fairings (N)

h = height of the helix (m)

M = mass of the cylinder per unit length (kg/m)

P = Pitch of the helix (m)

Re = Reynolds number = UD/v

t =thickness (m) for fairings

U =Velocity of the steady stream (m/s)

 $\delta$  = damping ratio

 $\nu$  = kinematic viscosity of water (m s<sup>2</sup>)

 $\xi$  = mass-damping ratio

 $\rho$  = density of water (kg/m<sup>3</sup>)

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