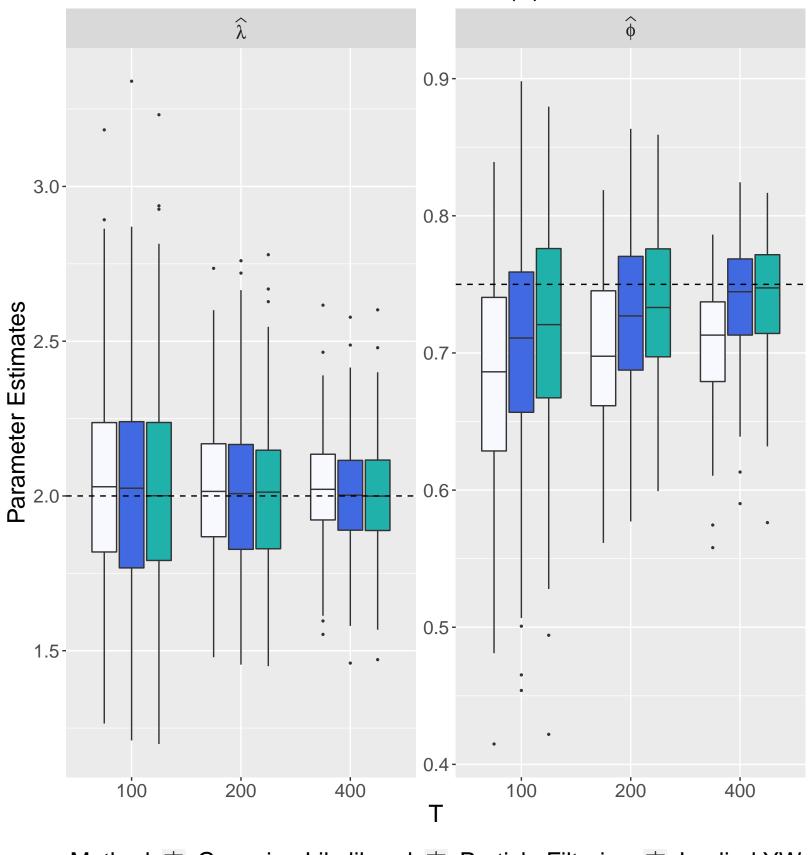
Poisson – AR(1)



Method 

Gaussian Likelihood 

Particle Filtering 

Implied YW