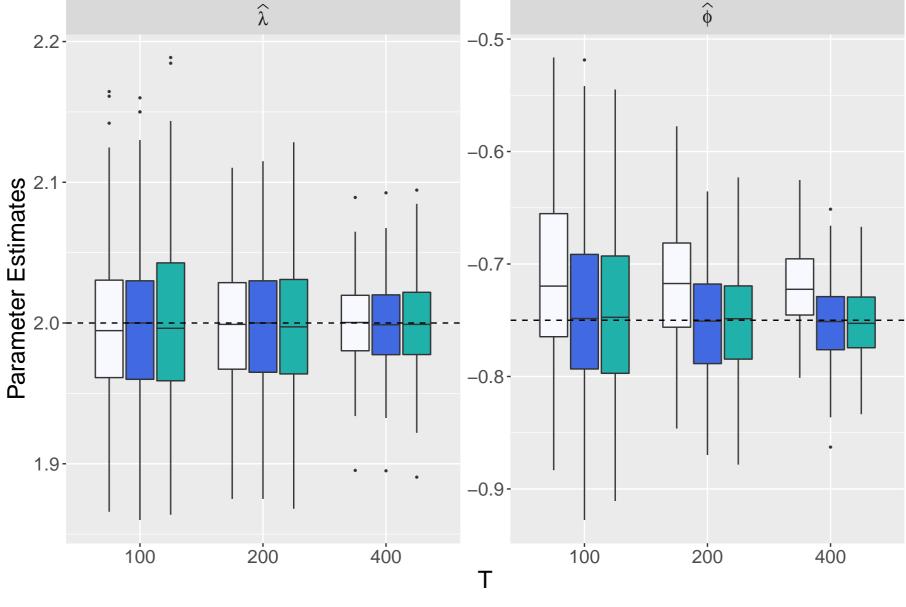
Poisson – AR(1) -0.5-0.6 --0.7-



Method

Gaussian Likelihood

Particle Filtering

Implied YW