Flux based finite element methods

JaEun Ku

jku@math.okstate.edu

Mathematics, Oklahoma State University

Joint work with Drs. Young Ju Lee (Texas State University, San Morales), Imbumn Kim, Dongwoo Sheen (Seoul National University), and Lothar Reichel(Kent State University)

Jan 17, 2020

Model problem

$$Lu = -\nabla \cdot \mathcal{A} \nabla u = f \text{ in } \Omega$$
$$u = 0 \text{ on } \partial \Omega.$$

Goal: approximation of the flux $\sigma = -A\nabla u$ (and more)

Finite Element methods

1. Standard Galerkin method.(post-processing for the flux variable)

$$(\mathcal{A}\nabla u\,,\,\nabla v)=(f,v)$$

2. Mixed Galerkin method.(more degrees of freedom) (A. Alonso, C. Carstenson, A. Demlow, M. Fortin, R. Hoppe, R. Raviart, J. Thomas)

$$(\mathcal{A}^{-1}\boldsymbol{\sigma},\boldsymbol{\tau}) - (\nabla \cdot \boldsymbol{\tau}, u) = 0,$$
$$(\nabla \cdot \boldsymbol{\sigma}, v) = (f, v)$$

3. Least-squares Finite Element method.(more degree of freedom) (Z. Cai, G, Carey, R. Lazarov, T. Manteuffel, S. Mc-Cormick, A. Pehlivanov, P. Vassilevski)

Model problem

$$Lu = -\nabla \cdot \mathcal{A} \nabla u = f \text{ in } \Omega$$
$$u = 0 \text{ on } \partial \Omega.$$

First-order system

$$\sigma + A\nabla u = 0 \text{ on } \Omega,$$

$$\nabla \cdot \sigma = f \text{ on } \Omega,$$

$$u = 0 \text{ on } \partial \Omega.$$

Solution spaces

$$u \in V := H_0^1(\Omega),$$

 $\sigma \in W := H(\text{div}) = \{\sigma \in L^2 ; \nabla \cdot \sigma \in L^2\}.$

Let
$$\mathbf{X} = V \times W$$

$$(\nabla \cdot \boldsymbol{\sigma}, \nabla \cdot \boldsymbol{\tau}) + (\mathcal{A}^{-1}(\boldsymbol{\sigma} + \mathcal{A}\nabla u), \boldsymbol{\tau} + \mathcal{A}\nabla v) = (f, \nabla \cdot \boldsymbol{\tau})$$

$$(\nabla \cdot \boldsymbol{\sigma}, \nabla \cdot \boldsymbol{\tau}) + (\mathcal{A}^{-1}(\boldsymbol{\sigma} + \mathcal{A}\nabla u), \boldsymbol{\tau} + \mathcal{A}\nabla v) = (f, \nabla \cdot \boldsymbol{\tau})$$

Introduce a weight δ , (small such as h^2)

$$(\nabla \cdot \boldsymbol{\sigma}, \nabla \cdot \boldsymbol{\tau}) + \boldsymbol{\delta}(\mathcal{A}^{-1}(\boldsymbol{\sigma} + \mathcal{A}\nabla u), \boldsymbol{\tau} + \mathcal{A}\nabla v) = (f, \nabla \cdot \boldsymbol{\tau})$$

$$(\nabla \cdot \boldsymbol{\sigma}, \nabla \cdot \boldsymbol{\tau}) + (\mathcal{A}^{-1}(\boldsymbol{\sigma} + \mathcal{A}\nabla u), \boldsymbol{\tau} + \mathcal{A}\nabla v) = (f, \nabla \cdot \boldsymbol{\tau})$$

Introduce a weight δ , (small such as h^2)

$$(\nabla \cdot \boldsymbol{\sigma}, \nabla \cdot \boldsymbol{\tau}) + \delta(\mathcal{A}^{-1}(\boldsymbol{\sigma} + \mathcal{A}\nabla u), \boldsymbol{\tau} + \mathcal{A}\nabla v) = (f, \nabla \cdot \boldsymbol{\tau})$$

Take v=0, then

$$(\nabla \cdot \boldsymbol{\sigma}, \nabla \cdot \boldsymbol{\tau}) + \delta(\mathcal{A}^{-1}(\boldsymbol{\sigma} + \mathcal{A}\nabla u), \boldsymbol{\tau}) = (f, \nabla \cdot \boldsymbol{\tau})$$

$$(\nabla \cdot \boldsymbol{\sigma}, \nabla \cdot \boldsymbol{\tau}) + (\mathcal{A}^{-1}(\boldsymbol{\sigma} + \mathcal{A}\nabla u), \boldsymbol{\tau} + \mathcal{A}\nabla v) = (f, \nabla \cdot \boldsymbol{\tau})$$

Introduce a weight δ , (small such as h^2)

$$(\nabla \cdot \boldsymbol{\sigma}, \nabla \cdot \boldsymbol{\tau}) + \boldsymbol{\delta}(\mathcal{A}^{-1}(\boldsymbol{\sigma} + \mathcal{A}\nabla u), \boldsymbol{\tau} + \mathcal{A}\nabla v) = (f, \nabla \cdot \boldsymbol{\tau})$$

Take v=0, then

$$(\nabla \cdot \boldsymbol{\sigma}, \nabla \cdot \boldsymbol{\tau}) + \delta(\mathcal{A}^{-1}(\boldsymbol{\sigma} + \mathcal{A}\nabla u), \boldsymbol{\tau}) = (f, \nabla \cdot \boldsymbol{\tau})$$

Move $\delta(\nabla u, \tau)$ to the right and use integration by parts,

$$(\nabla \cdot \boldsymbol{\sigma}, \nabla \cdot \boldsymbol{\tau}) + \delta(\mathcal{A}^{-1}\boldsymbol{\sigma}, \boldsymbol{\tau}) = (f, \nabla \cdot \boldsymbol{\tau}) + \delta(\boldsymbol{u}, \nabla \cdot \boldsymbol{\tau}).$$

Reduced (Hybrid) Finite Element Method

Step 1 (Coarse-grid solution) On a coarse mesh \mathcal{T}_H , obtain the standard Galerkin solution u_H^G satisfying

$$(\mathcal{A}\nabla u_H^G, \nabla v_H) = (f, v_H) \quad \text{for all } v_H \in V_H^r. \tag{1}$$

Step 2 (Fine-grid solution) On a finer mesh \mathcal{T}_h , find the H(div) projection $\sigma_h \in W_h$ for the given data $f + u_H^G$, i.e.

$$(\nabla \cdot \boldsymbol{\sigma}_h, \nabla \cdot \boldsymbol{\tau}_h) + \boldsymbol{\delta}(\mathcal{A}^{-1}\boldsymbol{\sigma}_h, \boldsymbol{\tau}_h) = (f + \boldsymbol{\delta}u_H^G, \nabla \cdot \boldsymbol{\tau}_h) \quad \text{for all } \boldsymbol{\tau}_h \in W_h^k.$$
(2)

Quasi-Orthogonality

$$(\nabla \cdot (\boldsymbol{\sigma} - \boldsymbol{\sigma}_h), \nabla \cdot \boldsymbol{\tau}_h) + \delta(\mathcal{A}^{-1}(\boldsymbol{\sigma} - \boldsymbol{\sigma}_h), \boldsymbol{\tau}_h) = (\delta(u - u_H^G), \nabla \cdot \boldsymbol{\tau}_h), \tag{3}$$
 for all $\boldsymbol{\tau}_h \in W_h^k$.

Some of the advantages of New method

 Well-developed fast solver on fine grid (D. Arnold, R. Ralk, R. Winther and R. Hiptmair, J. Xu)

Smaller problem size.

• elimination of the need for artificial stabilization techniques (no *inf-suf* condition.)

• a practical and sharp a posteriori error estimator

Mixed methods

$$(\mathcal{A}^{-1}\boldsymbol{\sigma}_h^m, \boldsymbol{\tau}_h) - (\nabla \cdot \boldsymbol{\tau}_h, u_h^m) = 0,$$

$$(\nabla \cdot \boldsymbol{\sigma}_h^m, v_h) = (f, v_h)$$

$$\frac{\delta(\mathcal{A}^{-1}\boldsymbol{\sigma}_h^m,\boldsymbol{\tau}_h) - \delta(\nabla \cdot \boldsymbol{\tau}_h, u_h^m)}{(\nabla \cdot \boldsymbol{\sigma}_h^m, v_h)} = 0,$$

$$(\nabla \cdot \boldsymbol{\sigma}_h^m, v_h) = (f, v_h)$$

Taking $v_h = \nabla \cdot \boldsymbol{\tau}_h$,

$$(\nabla \cdot \boldsymbol{\sigma}_h^m, \nabla \cdot \boldsymbol{\tau}_h) + \delta(\mathcal{A}^{-1} \boldsymbol{\sigma}_h^m, \boldsymbol{\tau}_h) = (f + \delta u_h^m, \nabla \cdot \boldsymbol{\tau}_h).$$

Mixed method

$$(\nabla \cdot \boldsymbol{\sigma}_h^m, \nabla \cdot \boldsymbol{\tau}_h) + \delta(\mathcal{A}^{-1} \boldsymbol{\sigma}_h^m, \boldsymbol{\tau}_h) = (f + \delta u_h^m, \nabla \cdot \boldsymbol{\tau}_h).$$

Reduce method (Hybrid method)

$$(\nabla \cdot \boldsymbol{\sigma}_h, \nabla \cdot \boldsymbol{\tau}_h) + \boldsymbol{\delta}(\mathcal{A}^{-1}\boldsymbol{\sigma}_h, \boldsymbol{\tau}_h) = (f + \boldsymbol{\delta}u_H^G, \nabla \cdot \boldsymbol{\tau}_h).$$

$$(\nabla \cdot (\boldsymbol{\sigma}_h^m - \boldsymbol{\sigma}_h), \nabla \cdot \boldsymbol{\tau}_h) + \delta(\mathcal{A}^{-1}(\boldsymbol{\sigma}_h^m - \boldsymbol{\sigma}_h), \boldsymbol{\tau}_h) = \delta(u_h^m - u_H^G, \nabla \cdot \boldsymbol{\tau}_h).$$

Supercloseness property 1.

$$\|\boldsymbol{\sigma}_h - \boldsymbol{\sigma}_h^m\|_{H(\mathsf{div})} \le C\sqrt{\delta} \Big(H\|u - u_H^G\|_{W_2^1(\Omega)} + Ch\|\boldsymbol{\sigma} - \Pi_h\boldsymbol{\sigma}\|_{H(\mathsf{div})} \Big).$$

Basic Error Estimate (2017, Ku, Lee, Sheen)

$$\|\boldsymbol{\sigma} - \boldsymbol{\sigma}_h\|_{L_2(\Omega)} \le C\|\boldsymbol{\sigma} - \Pi_h \boldsymbol{\sigma}\|_0 + \sqrt{\delta}(h\|\boldsymbol{\sigma} - \Pi_h \boldsymbol{\sigma}\|_{H(\text{div})} + CH\|u - u_H^G\|_{W_2^1(\Omega)}).$$

Basic Error Estimate (RT space of order 0)

$$\|\boldsymbol{\sigma} - \boldsymbol{\sigma}_h\|_{L_2(\Omega)} \leq C\|\boldsymbol{\sigma} - \Pi_h \boldsymbol{\sigma}\|_{L_2(\Omega)}$$

$$+ \sqrt{\delta}h\|\boldsymbol{\sigma} - \Pi_h \boldsymbol{\sigma}\|_{H(\text{div})} + C\sqrt{\delta}H\|\boldsymbol{u} - \boldsymbol{u}_H^G\|_{W_2^1(\Omega)}$$

$$\leq Ch\|\boldsymbol{\sigma}\|_1 + Ch^2\|\nabla \cdot \boldsymbol{\sigma}\|_1 + C\sqrt{\delta}H^2\|\boldsymbol{u}\|_2.$$

Relation between H and h

$$h = \sqrt{\delta}H^2.$$

Numerical example

$$-\triangle u = f \quad \text{in } \Omega,$$

$$u = 0 \quad \text{on } \partial \Omega,$$
 where $\Omega = [0,1] \times [0,1]$ and $u = (x^2 - x)(y^2 - y).$

Results with fixed coarse mesh with $h=H^2$ and $\delta=1$

1/H	$ u-u_H^G _1$	1/h	$ u-u_h _1$	$\ oldsymbol{\sigma} - oldsymbol{\sigma}_h\ _0$	Rate	$\ oldsymbol{\sigma}_h + abla u_H^G \ _0$	$egin{array}{c c} \ oldsymbol{\sigma}_h + abla u_H^G \ _0 \ \hline \ u - u_H^G \ _1 \end{array}$
4	0.549D-01	16	0.143D-01	0.931D-02	×	0.551D-01	1.00
8	0.285D-01	64	0.358D-02	0.234D-02	1.00	0.285D-01	1.00
16	0.143D-01	256	0.895D-03	0.585D-03	1.00	0.143D-01	1.00
32	0.716D-02	1024	0.224D-03	0.146D-03	1.00	0.716D-02	1.00

Results with fixed coarse mesh with H=1/4 and $\delta=h^2$

	1/H	$ u-u_H^G _1$	1/h	$ u-u_h _1$	$\ oldsymbol{\sigma}-oldsymbol{\sigma}_h\ _0$	Rate	$\ \boldsymbol{\sigma}_h + \nabla u_H^G\ _0$	$rac{\ oldsymbol{\sigma}_h + abla u_H^G\ _0}{ u - u_H^G _1}$
	4	0.549D-01	16	0.143D-01	0.932D-02	×	0.551D-01	1.00
	4	0.549D-01	64	0.358D-02	0.233D-02	1.00	0.549D-01	1.00
	4	0.549D-01	256	0.895D-03	0.582D-03	1.00	0.549D-01	1.00
Ī	4	0.549D-01	1024	0.224D-03	0.146D-03	1.00	0.549D-01	1.00

Comparison with mixed method

1/H	$\ u-u_H^G\ _{0}$	1/h	$\ oldsymbol{\sigma} - oldsymbol{\sigma}_h\ _0$	DOF	$\ u-u_h^M\ _0$	$\parallel oldsymbol{\sigma} - oldsymbol{\sigma}_h^M \parallel_{0}$	DOF
4	0.501D-02	16	0.931D-02	841	0.219D-02	0.928D-02	1312
8	0.132D-02	64	0.234D-02	12705	0.549D-03	0.233D-02	20608
16	0.332D-03	256	0.585D-03	198577	0.137E-03	0.582D-03	328192

From two-grids to one-grid

Basic Error Estimate (RT space of order 0)

$$\|\boldsymbol{\sigma} - \boldsymbol{\sigma}_h\|_{L_2(\Omega)} \le Ch\|\boldsymbol{\sigma}\|_1 + Ch^2\|\nabla \cdot \boldsymbol{\sigma}\|_1 + C\sqrt{\delta}H\|u - u_H^G\|_1.$$

Relation between H and h

$$h = \sqrt{\delta}H^2.$$

take
$$u_H^G = 0$$
 and $\delta = h^2$

$$\|\boldsymbol{\sigma} - \boldsymbol{\sigma}_h\|_{L_2(\Omega)} \le Ch\|\boldsymbol{\sigma}\|_1 + Ch^2\|\nabla \cdot \boldsymbol{\sigma}\|_1 + C\sqrt{\delta}\|u\|_1.$$

Find σ^0 defied by

$$\begin{split} (\nabla \cdot \boldsymbol{\sigma}_h^0, \nabla \cdot \boldsymbol{\tau}_h) + \delta(\mathcal{A}^{-1} \boldsymbol{\sigma}_h^0, \boldsymbol{\tau}_h) &= (f, \nabla \cdot \boldsymbol{\tau}_h), \text{ (no } \delta(\boldsymbol{u}_G^H, \nabla \cdot \boldsymbol{\tau}_h)) \\ \text{then, for } n = 1, 2, \dots \text{ find } \boldsymbol{\sigma}_h^n \text{ defined by} \\ (\nabla \cdot \boldsymbol{\sigma}_h^n, \nabla \cdot \boldsymbol{\tau}_h) + \delta(\mathcal{A}^{-1} \boldsymbol{\sigma}_h^n, \boldsymbol{\tau}_h) &= (f, \nabla \cdot \boldsymbol{\tau}_h) + \delta(\mathcal{A}^{-1} \boldsymbol{\sigma}_h^{n-1}, \boldsymbol{\tau}_h). \\ \boldsymbol{\sigma}_h^n &\to \boldsymbol{\sigma}_h^m, \text{ as } n \to \infty. \end{split}$$

 u_h can be recovered by

$$(u_h, \nabla \cdot \boldsymbol{\tau}) = (\mathcal{A}^{-1} \boldsymbol{\sigma}_h, \boldsymbol{\tau}_h)$$

with error estimate

$$||u - u_h||_0 \le Ch||u||_2 + \sqrt{\delta}||u_h^m||_0.$$

with $u_H^G = 0$ and $\delta = h^2$

DOFs	h	$\ oldsymbol{\sigma} - oldsymbol{\sigma}_h\ $	Rate	$\ u-u_h\ $	Rate
56	2.50e-01	6.37378e-01	X	1.50786e-01	Х
208	1.25e-01	3.24488e-01	0.9740	7.82612e-02	0.9461
800	6.25e-02	1.63279e-01	0.9908	3.94786e-02	0.9872
3136	3.12e-02	8.18073e-02	0.9970	1.97822e-02	0.9969
12416	1.56e-02	4.09294e-02	0.9991	9.89644e-03	0.9992
49408	7.81e-03	2.04685e-02	0.9997	4.94889e-03	0.9998

A posteriori error estimators

Take A = Identity for simplicity.

Assume

$$\|\boldsymbol{\sigma} - \boldsymbol{\sigma}_h\|_{L_2(\Omega)} \le m\|\nabla(u - u_H^G)\|_{L_2(\Omega)},\tag{4}$$

where $0 \le m < 1$.

 $\| \boldsymbol{\sigma}_h + \nabla u_H^G \|$ as an estimator for $\| \nabla (u - u_H^G) \|_0$

$$\|\boldsymbol{\sigma}_h + \nabla u_H^G\|_0 = \|(\boldsymbol{\sigma}_h - \boldsymbol{\sigma} - \nabla u + \nabla u_H^G)\|_0$$

$$\leq \|\boldsymbol{\sigma} - \boldsymbol{\sigma}_h\|_0 + \|\nabla u - \nabla u_H^G\|_0$$

$$\leq (1+m)\|\nabla u - \nabla u_H^G\|_0$$

Thus,

$$\frac{1}{1+m} \|\boldsymbol{\sigma}_h + \nabla u_H^G\|_0 \le \|\nabla u - \nabla u_H^G\|_0.$$

$$\|\nabla u - \nabla u_H^G\|_0 \leq \|\boldsymbol{\sigma} - \boldsymbol{\sigma}_h + \nabla u - \nabla u_H^G\|_0$$
$$+\|\boldsymbol{\sigma} - \boldsymbol{\sigma}_h\|_0$$
$$\leq \|\boldsymbol{\sigma}_h + \nabla u_H^G\|_0 + m\|\nabla u - \nabla u_H^G\|_0.$$

Thus,

$$\|\nabla u - \nabla u_H^G\|_0 \le \frac{1}{1-m} \|\sigma_h + \nabla u_H^G\|_0.$$

Equivalent a posteriori error estimator

$$\frac{1}{1+m} \|\boldsymbol{\sigma}_h + \nabla u_H^G\|_0 \le \|\nabla u - \nabla u_h\|_0 \le \frac{1}{1-m} \|\boldsymbol{\sigma}_h + \nabla u_H^G\|_0.$$

A posteriori error estimates for the flux

$$J_l = \begin{cases} [[\boldsymbol{\sigma}_h \cdot t]] & \text{if } l \not\subset \partial \Omega, \\ 2(\boldsymbol{\sigma}_h \cdot t) & \text{if } l \subset \partial \Omega. \end{cases}$$

Then, for any $T \in \mathcal{T}_H$, we define

$$\eta^{2}(T) = |T| \| \operatorname{rot} \boldsymbol{\sigma}_{h} \|_{0,T}^{2} + \frac{1}{2} \sum_{l \subset \partial T} |l| \|J_{l}\|_{0,l}^{2},$$

where |T| and |l| are the area of T and the length of l, respectively, and let

$$\eta = (\sum_{T \in \mathcal{T}_h} \eta_T^2)^{1/2}.$$

$$c \eta(T) \leq \|\boldsymbol{\sigma} - \boldsymbol{\sigma}_h\|_{0,N(T)},$$

 $\|\boldsymbol{\sigma} - \boldsymbol{\sigma}_h\|_0 \leq C \left(\sum_{T \in \mathcal{T}_h} \eta_T^2 + h^2 \|f - P_h f\|_0^2 + \delta^2 \|\boldsymbol{\sigma}_h - \boldsymbol{\sigma}_H\|_0^2 \right)^{1/2}.$

Adaptive procedure

 $\mathsf{SOLVE} \to \mathsf{ESTIMATE} \to \mathsf{MARK} \to \mathsf{REFINE}.$

$$(\nabla \cdot \boldsymbol{\sigma}_h, \nabla \cdot \boldsymbol{\tau}_h) + \delta(\mathcal{A}^{-1}\boldsymbol{\sigma}_h, \boldsymbol{\tau}_h) = (f, \nabla \cdot \boldsymbol{\tau}_h) + \delta(A^{-1}\boldsymbol{\sigma}_H, \boldsymbol{\tau}_h).$$

With mild conditions (small δ and initial mesh size), we have $\rho+\gamma<1$ such that

$$\|\boldsymbol{\sigma} - \boldsymbol{\sigma}_h\|^2 \le \rho \|\boldsymbol{\sigma} - \boldsymbol{\sigma}_H\|^2 + \gamma \|\boldsymbol{\sigma} - \boldsymbol{\sigma}_{HH}\|^2 + \operatorname{osc}(H),$$

where

$$osc(H) = ||H(f - P_H f)||^2.$$

Efficient solver

The Raviart-Thomas space of index r is given by

$$\mathbf{V}_h = \{ \mathbf{v} \in H(\text{div}) : \mathbf{v}|_T \in P_r(T) + (x,y)P_r(T) \text{ for all } T \in \mathcal{T}_h \}.$$

Here $P_r(T)$ denotes the set of polynomial functions of degree at most r on T.

Decomposition of V_h .

$$W_h = \{ s \in H^1 : s | T \in P_{r+1}(T) \}, \quad S_h = \{ q \in L_2 : q | T \in P_r(T) \}$$

Discrete gradient operator $\operatorname{grad}_h:S_h\to \mathbf{V}_h$ defined by

$$(\operatorname{grad}_h q, \mathbf{v}) = -(q, \nabla \cdot \mathbf{v}) \text{ for all } \mathbf{v} \in \mathbf{V}_h.$$

(discrete) Helmholtz decomposition

$$V_h = \operatorname{grad}_h S_h \oplus \operatorname{curl} W_h$$
.

This decomposition is orthogonal with respect to both the L_2 and H(div) inner products. Using the orthogonality, one can easily show that the two summand spaces $\operatorname{grad}_h S_h$ and $\operatorname{curl} W_h$ are invariant under A and A_δ , where

$$(A\boldsymbol{\sigma}, \boldsymbol{\tau}) = (\nabla \cdot \boldsymbol{\sigma}, \nabla \cdot \boldsymbol{\tau}) + (\boldsymbol{\sigma}, \boldsymbol{\tau}),$$

$$(A_{\delta}\boldsymbol{\sigma}, \boldsymbol{\tau}) = (\nabla \cdot \boldsymbol{\sigma}, \nabla \cdot \boldsymbol{\tau}) + \delta(\boldsymbol{\sigma}, \boldsymbol{\tau}).$$

Note that

$$A_{\delta} = A + (\delta - 1)I.$$

Iterative solver (submitted, Ku and Reichel)

$$(A + (\delta - 1))\boldsymbol{\sigma}_h = A_{\delta}\boldsymbol{\sigma}_h = -\operatorname{grad}_h(f + \delta u_H^G),$$

i.e.

$$\sigma_h = (1 - \delta)A^{-1}\sigma_h - A^{-1}\operatorname{grad}_h(f + \delta u_H^G).$$

Hence, we define iterative method as

$$\sigma_{n+1} = (1 - \delta)A^{-1}\sigma_n - A^{-1}\operatorname{grad}_h(f + \delta u_H^G).$$

Note that $\sigma_h \in \operatorname{grad}_h S_h$ and $||A^{-1}|| \leq 1$. Moreover, $||A^{-1}||_{\operatorname{grad}_h S_h}|| << 1$.

Performance for different δ values with $h = \frac{1}{128}$.

δ	h^2	h^4	h^6	h^8	h^{10}
$\ oldsymbol{\sigma} - oldsymbol{\sigma}_h^D\ $	0.0012	0.0012	4.0891	4.3579	4.3579
$\ oldsymbol{\sigma} - oldsymbol{\sigma}_h^I\ $	0.0012	0.0012	0.0012	0.0012	0.0012
# of iterations	8	8	8	8	8

The New reduced method provides a good alternative for efficient and accurate approximation of the flux variables .

Thank you