

## 1

Find the Euler-Lagrange equation associated with the functional

$$J[u(x, y, z)] = \int_R \sqrt{1 + u_x^2 + u_y^2 + u_z^2} dx dy dz,$$

where  $R$  is a region in three-dimensional space.

**Solution.** We will assume  $u(x, y, z)$  has explicit values on the boundary of  $R$ ,  $dx dy dz$ . By the definition of the action,

$$J[u] = \int_R \mathcal{L} dx dy dz \implies \mathcal{L} = \sqrt{1 + u_x^2 + u_y^2 + u_z^2}.$$

In general, the Euler-Lagrange equation is

$$0 = \frac{\partial \mathcal{L}}{\partial u} - \frac{\partial}{\partial x} \frac{\partial \mathcal{L}}{\partial u_x} - \frac{\partial}{\partial y} \frac{\partial \mathcal{L}}{\partial u_y} - \frac{\partial}{\partial z} \frac{\partial \mathcal{L}}{\partial u_z}. \quad (1)$$

Here,

$$\frac{\partial \mathcal{L}}{\partial u} = 0, \quad \frac{\partial \mathcal{L}}{\partial u_x} = \frac{\partial \mathcal{L}}{\partial u_x^2} \frac{\partial u_x^2}{\partial u_x} = \frac{u_x}{\sqrt{1 + u_x^2 + u_y^2 + u_z^2}} = \frac{u_x}{\mathcal{L}}, \quad \frac{\partial \mathcal{L}}{\partial u_y} = \frac{u_y}{\mathcal{L}}, \quad \frac{\partial \mathcal{L}}{\partial u_z} = \frac{u_z}{\mathcal{L}}.$$

For the  $\partial/\partial x$  term of (1),

$$\frac{\partial}{\partial x} \frac{\partial \mathcal{L}}{\partial u_x} = \frac{\partial}{\partial x} \frac{u_x}{\mathcal{L}} = \frac{\partial u_x}{\partial x} \frac{\partial}{\partial u_x} \frac{u_x}{\mathcal{L}} + \frac{\partial u_y}{\partial x} \frac{\partial}{\partial u_y} \frac{u_x}{\mathcal{L}} + \frac{\partial u_z}{\partial x} \frac{\partial}{\partial u_z} \frac{u_x}{\mathcal{L}}$$

where

$$\frac{\partial}{\partial u_x} \frac{u_x}{\mathcal{L}} = \frac{1}{\mathcal{L}^2} \left( \frac{\partial u_x}{\partial u_x} \mathcal{L} - u_x \frac{\partial \mathcal{L}}{\partial u_x} \right) = \frac{1}{\mathcal{L}^2} \left( \mathcal{L} - u_x \frac{u_x}{\mathcal{L}} \right) = \frac{\mathcal{L}^2 - u_x^2}{\mathcal{L}^3}, \quad (2)$$

$$\frac{\partial}{\partial u_y} \frac{u_x}{\mathcal{L}} = \frac{1}{\mathcal{L}^2} \left( \frac{\partial u_x}{\partial u_y} \mathcal{L} - u_x \frac{\partial \mathcal{L}}{\partial u_y} \right) = -\frac{u_x u_y}{\mathcal{L}^3}, \quad (3)$$

$$\frac{\partial}{\partial u_z} \frac{u_x}{\mathcal{L}} = -\frac{u_x u_z}{\mathcal{L}^3}, \quad (4)$$

Generalizing (2)–(4) to the  $\partial/\partial y$  and  $\partial/\partial z$  terms,

$$\frac{\partial}{\partial x} \frac{\partial \mathcal{L}}{\partial u_x} = u_{xx} \frac{\mathcal{L}^2 - u_x^2}{\mathcal{L}^3} - u_{yx} \frac{u_x u_y}{\mathcal{L}^3} - u_{zx} \frac{u_x u_z}{\mathcal{L}^3},$$

$$\frac{\partial}{\partial y} \frac{\partial \mathcal{L}}{\partial u_y} = u_{yy} \frac{\mathcal{L}^2 - u_y^2}{\mathcal{L}^3} - u_{xy} \frac{u_x u_y}{\mathcal{L}^3} - u_{zy} \frac{u_y u_z}{\mathcal{L}^3},$$

$$\frac{\partial}{\partial z} \frac{\partial \mathcal{L}}{\partial u_z} = u_{zz} \frac{\mathcal{L}^2 - u_z^2}{\mathcal{L}^3} - u_{xz} \frac{u_x u_z}{\mathcal{L}^3} - u_{yz} \frac{u_y u_z}{\mathcal{L}^3}.$$

Then, assuming  $u_{xy} = u_{yx}$ ,  $u_{yz} = u_{zy}$ , and  $u_{xz} = u_{zx}$ , (1) becomes

$$\begin{aligned} 0 &= u_{xx}(\mathcal{L}^4 - u_x^2) + u_{yy}(\mathcal{L}^4 - u_y^2) + u_{zz}(\mathcal{L}^4 - u_z^2) - 2u_{xy}u_xu_y - 2u_{yz}u_yu_z - 2u_{xz}u_xu_z \\ &= (u_{xx} + u_{yy} + u_{zz})(1 + u_x^2 + u_y^2 + u_z^2) - u_{xx}u_x^2 - u_{yy}u_y^2 - u_{zz}u_z^2 - 2u_{xy}u_xu_y - 2u_{yz}u_yu_z - 2u_{xz}u_xu_z \\ &= u_{xx}(1 + u_y^2 + u_z^2) + u_{yy}(1 + u_x^2 + u_z^2) + u_{zz}(1 + u_x^2 + u_y^2) - 2u_{xy}u_xu_y - 2u_{yz}u_yu_z - 2u_{xz}u_xu_z. \end{aligned}$$

## 2 Plate vibrations (preliminaries)

Start from Green's theorem

$$\int_R \left( \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dx dy = \int_{\partial R} (P dx + Q dy), \quad (5)$$

where  $R$  is the region in the  $xy$  plane spanned by the plate, and  $dx dy dz$  its boundary.

**2.a** Show that

$$\int_R \phi \frac{\partial^2 \psi}{\partial x^2} dx dy = \int_R \psi \frac{\partial^2 \phi}{\partial x^2} dx dy + \int_{\partial R} \left( \phi \frac{\partial \psi}{\partial x} - \psi \frac{\partial \phi}{\partial x} \right) dy. \quad (6)$$

**Solution.** In (5), let

$$Q = \phi \frac{\partial \psi}{\partial x} - \psi \frac{\partial \phi}{\partial x}, \quad P = 0.$$

Then

$$\frac{\partial Q}{\partial x} = \frac{\partial \phi}{\partial x} \frac{\partial \psi}{\partial x} + \phi \frac{\partial^2 \psi}{\partial x^2} - \frac{\partial \psi}{\partial x} \frac{\partial \phi}{\partial x} - \psi \frac{\partial^2 \phi}{\partial x^2} = \phi \frac{\partial^2 \psi}{\partial x^2} - \psi \frac{\partial^2 \phi}{\partial x^2}, \quad \frac{\partial P}{\partial y} = 0.$$

Making these substitutions into (5) gives

$$\begin{aligned} \int_R \left( \phi \frac{\partial^2 \psi}{\partial x^2} - \psi \frac{\partial^2 \phi}{\partial x^2} \right) dx dy &= \int_{\partial R} \left( \phi \frac{\partial \psi}{\partial x} - \psi \frac{\partial \phi}{\partial x} \right) dy \\ \iff \int_R \phi \frac{\partial^2 \psi}{\partial x^2} dx dy &= \int_R \psi \frac{\partial^2 \phi}{\partial x^2} dx dy + \int_{\partial R} \left( \phi \frac{\partial \psi}{\partial x} - \psi \frac{\partial \phi}{\partial x} \right) dy \end{aligned}$$

as desired.  $\square$

**2.b** Work out analogous expressions for

$$\int_R \phi \frac{\partial^2 \psi}{\partial y^2} dx dy, \quad (7)$$

$$\int_R \phi \frac{\partial^2 \psi}{\partial x \partial y} dx dy. \quad (8)$$

**Solution.** For (7), let

$$Q = 0, \quad P = \psi \frac{\partial \phi}{\partial y} - \phi \frac{\partial \psi}{\partial y},$$

in (5). Then, similarly to the proof for (6),

$$\frac{\partial Q}{\partial x} = 0, \quad \frac{\partial P}{\partial y} = \psi \frac{\partial^2 \phi}{\partial y^2} - \phi \frac{\partial^2 \psi}{\partial y^2}.$$

Substituting into (5),

$$\begin{aligned} \int_R \left( \phi \frac{\partial^2 \psi}{\partial y^2} - \psi \frac{\partial^2 \phi}{\partial y^2} \right) dx dy &= \int_{\partial R} \left( \psi \frac{\partial \phi}{\partial y} - \phi \frac{\partial \psi}{\partial y} \right) dx \\ \iff \int_R \phi \frac{\partial^2 \psi}{\partial y^2} dx dy &= \int_R \psi \frac{\partial^2 \phi}{\partial y^2} dx dy + \int_{\partial R} \left( \psi \frac{\partial \phi}{\partial y} - \phi \frac{\partial \psi}{\partial y} \right) dy. \end{aligned} \quad (9)$$

For (8), let

$$2Q = \phi \frac{\partial \psi}{\partial y} - \psi \frac{\partial \phi}{\partial y}, \quad 2P = \psi \frac{\partial \phi}{\partial x} - \phi \frac{\partial \psi}{\partial x}.$$

Then

$$\begin{aligned} 2 \frac{\partial Q}{\partial x} &= \frac{\partial \phi}{\partial x} \frac{\partial \psi}{\partial y} + \phi \frac{\partial^2 \psi}{\partial x \partial y} - \frac{\partial \psi}{\partial x} \frac{\partial \phi}{\partial y} - \psi \frac{\partial^2 \phi}{\partial x \partial y} = \phi \frac{\partial^2 \psi}{\partial x \partial y} - \psi \frac{\partial^2 \phi}{\partial x \partial y}, \\ 2 \frac{\partial P}{\partial y} &= \frac{\partial \psi}{\partial y} \frac{\partial \phi}{\partial x} + \psi \frac{\partial^2 \phi}{\partial x \partial y} - \frac{\partial \phi}{\partial y} \frac{\partial \psi}{\partial x} - \phi \frac{\partial^2 \psi}{\partial x \partial y} = \psi \frac{\partial^2 \phi}{\partial x \partial y} - \phi \frac{\partial^2 \psi}{\partial x \partial y}. \end{aligned}$$

Substituting into (5), we have

$$\begin{aligned} \frac{1}{2} \int_R \left( \phi \frac{\partial^2 \psi}{\partial x \partial y} - \psi \frac{\partial^2 \phi}{\partial x \partial y} - \psi \frac{\partial^2 \phi}{\partial x \partial y} + \phi \frac{\partial^2 \psi}{\partial x \partial y} \right) dx dy &= \frac{1}{2} \int_{\partial R} \left( \psi \frac{\partial \phi}{\partial x} - \phi \frac{\partial \psi}{\partial x} \right) dx + \frac{1}{2} \int_{\partial R} \left( \phi \frac{\partial \psi}{\partial y} - \psi \frac{\partial \phi}{\partial y} \right) dy \\ \iff \int_R \phi \frac{\partial^2 \psi}{\partial x \partial y} dx dy &= \int_R \psi \frac{\partial^2 \phi}{\partial x \partial y} dx dy + \frac{1}{2} \int_{\partial R} \left( \psi \frac{\partial \phi}{\partial x} - \phi \frac{\partial \psi}{\partial x} \right) dx + \frac{1}{2} \int_{\partial R} \left( \phi \frac{\partial \psi}{\partial y} - \psi \frac{\partial \phi}{\partial y} \right) dy. \end{aligned} \quad (10)$$

### 3 Plate vibrations

Start with the action for a vibrating plate whose potential energy is dominated by bending,

$$S[u(x, y, t)] = \frac{1}{2} \int_{t_0}^{t_1} \int_R \left\{ \rho u_t^2 - \kappa_1 [(u_{xx}^2 + u_{yy}^2) - 2(1 - \mu)(u_{xx}u_{yy} - u_{xy}^2)] \right\} dx dy dt, \quad (11)$$

where  $\rho$  is the mass density per unit area,  $\kappa_1$  has the dimension of energy and is sometimes called flexural rigidity, and  $\mu$  is a dimensionless material constant called Poisson's ratio. For isotropic material,  $\mu = 1/4$ . Notice that there is *no* external bending moment applied to the plate boundary. There is also *no* external forcing.

**3.a** Using the results of problem 2, show that the variation generated by going from a solution  $u^0$  to  $u^0 + \epsilon \psi$  has the form

$$\delta S = \epsilon \int_{t_0}^{t_1} \int_R (-\rho u_{tt} - \kappa_1 \nabla^4 u) \psi dx dy dt + \epsilon \int_{t_0}^{t_1} \int_{\partial R} \left( P(u) \psi + M(u) \frac{\partial \psi}{\partial n} \right) d\ell dt. \quad (12)$$

Specify  $P(u)$  and  $M(u)$ .

**Solution.** Making the substitution  $u \mapsto u + \epsilon\psi$  into (11),

$$\begin{aligned}
 S[u + \epsilon\psi] &= \int_{t_0}^{t_1} \int_R \left\{ \frac{\rho}{2} (u_t + \epsilon\psi_t)^2 - \frac{\kappa_1}{2} [(u_{xx} + \epsilon\psi_{xx})^2 + (u_{yy} + \epsilon\psi_{yy})^2] \right\} dx dy dt \\
 &\quad + \kappa_1(1 - \mu) \int_{t_0}^{t_1} \int_R [(u_{xx} + \epsilon\psi_{xx})(u_{yy} + \epsilon\psi_{yy}) - (u_{xy} + \epsilon\psi_{xy})^2] dx dy dt \\
 &= \int_{t_0}^{t_1} \int_R \left[ \frac{\rho}{2} (u_t^2 + 2\epsilon u_t \psi_t + \epsilon^2 \psi_t^2) - \frac{\kappa_1}{2} (u_{xx}^2 + 2\epsilon u_{xx} \psi_{xx} + \epsilon^2 \psi_{xx}^2 + u_{yy}^2 + 2\epsilon u_{yy} \psi_{yy} + \epsilon^2 \psi_{yy}^2) \right] dx dy dt \\
 &\quad + \kappa_1(1 - \mu) \int_{t_0}^{t_1} \int_R (u_{xx} u_{yy} + \epsilon u_{xx} \psi_{yy} + \epsilon u_{yy} \psi_{xx} + \epsilon^2 \psi_{xx} \psi_{yy} - u_{xy}^2 - 2\epsilon u_{xy} \psi_{xy} - \epsilon^2 \psi_{xy}^2) dx dy dt.
 \end{aligned}$$

Then

$$\begin{aligned}
 \Delta S &= S[u + \epsilon\psi] - S[u] \\
 &= \int_{t_0}^{t_1} \int_R \left[ \frac{\rho}{2} (2\epsilon u_t \psi_t + \epsilon^2 \psi_t^2) - \frac{\kappa_1}{2} (2\epsilon u_{xx} \psi_{xx} + \epsilon^2 \psi_{xx}^2 + 2\epsilon u_{yy} \psi_{yy} + \epsilon^2 \psi_{yy}^2) \right] dx dy dt \\
 &\quad + \kappa_1(1 - \mu) \int_{t_0}^{t_1} \int_R (\epsilon u_{xx} \psi_{yy} + \epsilon u_{yy} \psi_{xx} + \epsilon^2 \psi_{xx} \psi_{yy} - 2\epsilon u_{xy} \psi_{xy} - \epsilon^2 \psi_{xy}^2) dx dy dt,
 \end{aligned}$$

and so, dropping terms of  $\mathcal{O}(\epsilon^2)$ ,

$$\delta S = \epsilon \int_{t_0}^{t_1} \int_R \{ \rho u_t \psi_t - \kappa_1 [(u_{xx} \psi_{xx} + u_{yy} \psi_{yy}) - (1 - \mu)(u_{xx} \psi_{yy} + u_{yy} \psi_{xx} - 2u_{xy} \psi_{xy})] \} dx dy dt. \quad (13)$$

For the first term in the integrand of (13), using the product rule of differentiation yields

$$u_t \psi_t = \frac{\partial}{\partial t} (u_t \psi) - u_{tt} \psi.$$

For the second two terms, we may apply what was proven in problem 2. Letting  $\phi \mapsto u_{xx}$  and  $\psi \mapsto \psi$  in (6) and (9), we have

$$\begin{aligned}
 \int_{t_0}^{t_1} \int_R u_{xx} \psi_{xx} dx dy dt &= \int_{t_0}^{t_1} \int_R \psi u_{xxxx} dx dy dt + \int_{t_0}^{t_1} \int_{\partial R} (u_{xx} \psi_x - \psi u_{xxx}) dy dt, \\
 \int_{t_0}^{t_1} \int_R u_{xx} \psi_{yy} dx dy dt &= \int_{t_0}^{t_1} \int_R \psi u_{xxyy} dx dy dt - \int_{t_0}^{t_1} \int_{\partial R} (u_{xx} \psi_y - \psi u_{xxy}) dx dt.
 \end{aligned}$$

Now with  $\phi \mapsto u_{yy}$ ,

$$\begin{aligned}
 \int_{t_0}^{t_1} \int_R u_{yy} \psi_{xx} dx dy dt &= \int_{t_0}^{t_1} \int_R \psi u_{xyxy} dx dy dt + \int_{t_0}^{t_1} \int_{\partial R} (u_{yy} \psi_x - \psi u_{xyy}) dy dt, \\
 \int_{t_0}^{t_1} \int_R u_{yy} \psi_{yy} dx dy dt &= \int_{t_0}^{t_1} \int_R \psi u_{yyyy} dx dy dt - \int_{t_0}^{t_1} \int_{\partial R} (u_{yy} \psi_y - \psi u_{yyy}) dx dt.
 \end{aligned}$$

Finally, with  $\phi \mapsto u_{xy}$  and  $\psi \mapsto \psi$  in (10), we have

$$\begin{aligned}
 \int_{t_0}^{t_1} \int_R u_{xy} \psi_{xy} dx dy dt &= \int_{t_0}^{t_1} \int_R \psi u_{xxyy} dx dy dt - \frac{1}{2} \int_{t_0}^{t_1} \int_{\partial R} (u_{xy} \psi_x - \psi u_{xxy}) dx dt \\
 &\quad + \frac{1}{2} \int_{t_0}^{t_1} \int_{\partial R} (u_{xy} \psi_y - \psi u_{xyy}) dy dt.
 \end{aligned}$$

Making these substitutions into (13),

$$\begin{aligned}
 \frac{\delta S}{\epsilon} &= \int_{t_0}^{t_1} \int_R \psi \{ -\rho u_{tt} - \kappa_1 [(u_{xxx} + u_{yyy}) - (1 - \mu)(u_{xxy} + u_{xyx} - 2u_{xyy})] \} dx dy dt \\
 &\quad + \rho \int_{t_0}^{t_1} \int_R \frac{\partial}{\partial t} (u_t \psi) dx dy dt - \kappa_1 \int_{t_0}^{t_1} \int_{\partial R} [(u_{xx} \psi_x - \psi u_{xxx}) + (1 - \mu)(u_{xx} \psi_y - \psi u_{xxy} - u_{xy} + \psi u_{xyy})] dx dt \\
 &\quad + \kappa_1 \int_{t_0}^{t_1} \int_{\partial R} [(u_{yy} \psi_y - \psi u_{yy}) + (1 - \mu)(u_{yy} \psi_x - \psi u_{xyy} - u_{xy} \psi_y + \psi u_{xyy})] dy dt \\
 &= \int_{t_0}^{t_1} \int_R \psi [-\rho u_{tt} - \kappa_1 (u_{xxx} + u_{yyy})] dx dy dt + \rho \int_R u_t \psi dx dy \\
 &\quad - \kappa_1 \int_{t_0}^{t_1} \int_{\partial R} [(u_{xx} \psi_x - \psi u_{xxx}) + (1 - \mu)(u_{xx} \psi_y - u_{xy} \psi_x)] dx dt \\
 &\quad + \kappa_1 \int_{t_0}^{t_1} \int_{\partial R} [(u_{yy} \psi_y - \psi u_{yy}) + (1 - \mu)(u_{yy} \psi_x - u_{xy} \psi_y)] dy dt.
 \end{aligned}$$

Note that

$$\nabla^4 u = \frac{\partial^4 u}{\partial x^4} + 2 \frac{\partial^4 u}{\partial x^2 \partial y^2} + \frac{\partial^4 u}{\partial y^4},$$

so

$$\begin{aligned}
 \frac{\delta S}{\epsilon} &= \int_{t_0}^{t_1} \int_R \psi (-\rho u_{tt} - \kappa_1 \nabla^4 u) dx dy dt + 2\kappa_1 \int_{t_0}^{t_1} \int_R \psi u_{xxyy} dx dy dt + \rho \int_R u_t \psi dx dy \\
 &\quad - \kappa_1 \int_{t_0}^{t_1} \int_{\partial R} [(u_{xx} \psi_x - \psi u_{xxx}) + (1 - \mu)(u_{xx} \psi_y - u_{xy} \psi_x)] dx dt \\
 &\quad + \kappa_1 \int_{t_0}^{t_1} \int_{\partial R} [(u_{yy} \psi_y - \psi u_{yy}) + (1 - \mu)(u_{yy} \psi_x - u_{xy} \psi_y)] dy dt
 \end{aligned}$$

Define  $\hat{\mathbf{n}}$  as the unit vector normal to the surface and  $\hat{\ell}$  as the unit vector tangent to the surface. Then we have the directional derivatives

$$\frac{\partial}{\partial n} = \hat{\mathbf{n}} \cdot \nabla = x_n \frac{\partial}{\partial x} + y_n \frac{\partial}{\partial y}, \quad \frac{\partial}{\partial \ell} = \hat{\ell} \cdot \nabla = x_\ell \frac{\partial}{\partial x} + y_\ell \frac{\partial}{\partial y}.$$

Eventually, we find

$$\delta S = -\epsilon \int_{t_0}^{t_1} \int_R (\rho u_{tt} + \kappa_1 \nabla^4 u) \psi dx dy dt + \epsilon \int_{t_0}^{t_1} \int_{\partial R} \left( P(u) \psi + M(u) \frac{\partial \psi}{\partial n} \right) d\ell dt$$

where

$$\begin{aligned}
 P(u) &= \kappa_1 \left\{ \frac{\partial}{\partial n} \nabla^2 u + (1 - \mu) \frac{\partial}{\partial \ell} [u_{xx} x_n x_\ell + u_{xy} (x_n y_\ell + x_\ell y_n) + u_{yy} y_n y_\ell] \right\}, \\
 M(u) &= -\kappa_1 [\mu \nabla^2 u + (1 - \mu)(u_{xx} x_n^2 + 2u_{xy} x_n y_n + u_{yy} y_n^2)].
 \end{aligned}$$

**3.b** Finally, derive the Euler-Lagrange equation and the associated boundary conditions.

**Solution.** We begin by making the strong assumption that the boundary of the plate remains fixed. Mathematically, we assume that the solution  $u^0$  does not vary on the boundary of the plate, denoted by  $\ell \in \partial R$ . We further assume that the edges of the plate cannot move; that is, the first derivative of  $u^0$  normal to the plate does not vary either. These assumptions constrain  $\psi = \psi(\ell, t)$ :

$$u^0(\ell, t) = 0 \implies \psi(\ell, t) = 0, \quad \frac{\partial u^0(\ell, t)}{\partial n} = 0 \implies \frac{\partial \psi(\ell, t)}{\partial n} = 0.$$

Making these assumptions, the entire surface integral of (12) vanishes, and we are left with

$$\delta S = -\epsilon \int_{t_0}^{t_1} \int_R (\rho u_{tt} + \kappa_1 \nabla^4 u) \psi \, dx \, dy \, dt.$$

By Hamilton's principle, this gives us

$$0 = \rho u_{tt} + \kappa_1 \nabla^4 u$$

as the Euler-Lagrange equation.

Now we use (3) as our assumption and return to (12), which becomes

$$\delta S = \epsilon \int_{t_0}^{t_1} \int_{\partial R} \left( P(u) \psi + M(u) \frac{\partial \psi}{\partial n} \right) d\ell \, dt.$$

Once again invoking Hamilton's principle, we find the boundary conditions

$$M(u) = 0, \quad P(u) = 0. \quad (14)$$

## 4 Vibrations of a circular disk

The only scenario in which plate vibrations can be described analytically in terms of known functions is a circular disk. Work with polar coordinates  $(r, \theta)$ , the Euler-Lagrange equation

$$u_{tt} - \lambda \nabla^4 u = 0, \quad (15)$$

and the boundary conditions

$$u = 0, \quad \frac{\partial u}{\partial n} = 0. \quad (16)$$

**4.a** Show that this problem reduces to an eigenvalue problem if we assume that  $u(r, \theta, t)$  is separable:

$$u = v(r, \theta) g(t). \quad (17)$$

Write down the general form of  $g(t)$ .

**Solution.** Substituting the ansatz (17) into (15), we have

$$v \frac{\partial^2 g}{\partial t^2} - \lambda g \nabla^4 v = 0 \implies \frac{1}{g} \frac{\partial^2 g}{\partial t^2} = \lambda \frac{1}{v} \nabla^4 v \equiv -\mu \quad (18)$$

where we have defined some constant  $\mu$ . We may then separate (18) into two differential equations,

$$\lambda \nabla^4 v + \mu v = 0, \quad (19)$$

$$\frac{\partial^2 g}{\partial t^2} + \mu g = 0. \quad (20)$$

The eigenvalue problem is (19), which we may solve for the eigenvalues  $\mu_n$  and obtain the eigenfunctions  $v_n(r, \theta)$ . Then we simply feed  $\mu_n$  into (20) to obtain  $g_n(t)$ , which have the general form

$$g(t) = C_1 e^{\sqrt{\mu}x} + C_2 e^{-\sqrt{\mu}x}, \quad (21)$$

where we note that  $\sqrt{\mu}$  may be imaginary. If so, (21) may be written in terms of sines and cosines. Finally, the solutions to (15) are  $u_n(r, \theta, t) = v_n(r, \theta) g_n(t)$ .

**4.b** Now consider the eigenvalue problem

$$(\nabla^4 - k^4)v(r, \theta) = 0, \quad (22)$$

with  $\lambda$  set to be  $k^4$ . Notice that it factors into

$$(\nabla^2 - k^2)(\nabla^2 + k^2)v(r, \theta) = 0, \quad (23)$$

with

$$\nabla^2 = \frac{\partial^2}{\partial r^2} + \frac{1}{r} \frac{\partial}{\partial r} + \frac{1}{r^2} \frac{\partial^2}{\partial \theta^2}.$$

Since the disk is circular, we expect the vibration modes to be periodic in  $\theta$ . This suggests the ansatz

$$v = \sum_{n=-\infty}^{\infty} f_n(r) e^{in\theta}. \quad (24)$$

Obtain the ODE governing  $f_n(r)$ .

**Solution.** Firstly, note that

$$\nabla^4 = \left( \frac{\partial^2}{\partial r^2} + \frac{1}{r} \frac{\partial}{\partial r} + \frac{1}{r^2} \frac{\partial^2}{\partial \theta^2} \right)^2 = \frac{\partial^4}{\partial r^4} + \frac{2}{r} \frac{\partial^3}{\partial r^3} + \frac{1}{r^2} \frac{\partial^2}{\partial r^2} + \frac{2}{r^2} \frac{\partial^2}{\partial r^2} \frac{\partial^2}{\partial \theta^2} + \frac{2}{r^3} \frac{\partial}{\partial r} \frac{\partial^2}{\partial \theta^2} + \frac{1}{r^4} \frac{\partial^4}{\partial \theta^4}.$$

Substituting the ansatz of (24) into (22) yields

$$\begin{aligned} k^4 f_n(r) e^{in\theta} &= -\nabla^4 f_n(r) e^{in\theta} \\ &= \left( \frac{\partial^4}{\partial r^4} + \frac{2}{r} \frac{\partial^3}{\partial r^3} + \frac{1}{r^2} \frac{\partial^2}{\partial r^2} + \frac{2}{r^2} \frac{\partial^2}{\partial r^2} \frac{\partial^2}{\partial \theta^2} + \frac{2}{r^3} \frac{\partial}{\partial r} \frac{\partial^2}{\partial \theta^2} + \frac{1}{r^4} \frac{\partial^4}{\partial \theta^4} \right) f_n(r) e^{in\theta} \\ &= e^{in\theta} \left( \frac{\partial^4}{\partial r^4} + \frac{2}{r} \frac{\partial^3}{\partial r^3} + \frac{1}{r^2} \frac{\partial^2}{\partial r^2} - \frac{2n^2}{r^2} \frac{\partial^2}{\partial r^2} - \frac{2n^2}{r^3} \frac{\partial}{\partial r} + \frac{n^4}{r^4} \right) f_n(r). \end{aligned}$$

Dividing out  $e^{in\theta}$ , we have

$$k^4 f_n(r) = \frac{\partial^4 f_n(r)}{\partial r^4} + \frac{2}{r} \frac{\partial^3 f_n(r)}{\partial r^3} + \frac{1 - 2n^2}{r^2} \frac{\partial^2 f_n(r)}{\partial r^2} - \frac{2n^2}{r^3} \frac{\partial f_n(r)}{\partial r} + \frac{n^4}{r^4} f_n(r)$$

as the ODE governing  $f_n(r)$ .

**4.c** What are the appropriate boundary conditions on  $f_n(r)$ ?

**Solution.** From (17) and (24), the solution  $u$  is defined

$$u = v(r, \theta) g(t) = g(t) \sum_{n=-\infty}^{\infty} f_n(r) e^{in\theta}.$$

From (16),

$$u = 0 \implies v = 0 \implies \sum_{n=-\infty}^{\infty} f_n(r) = 0, \quad (25)$$

$$\frac{\partial u}{\partial n} = 0 \implies \frac{\partial v}{\partial n} = 0 \implies \sum_{n=-\infty}^{\infty} \frac{\partial f_n(r)}{\partial r} = 0. \quad (26)$$

on the boundry  $\partial R$  of the plate. Note that  $\partial/\partial n$  is the normal derivative.

In writing these solutions, I consulted Gelfand and Fomin's *Calculus of Variations*, and Olmstead and Volpert's *Differential Equations in Applied Mathematics*.