## 1 Problem 1

Let's consider coherent states of a one-dimensional quantum particle with mass m confined in a one-dimensional harmonic potential  $V(X) = m\omega^2 X^2/2$ :

$$a |\lambda\rangle = \lambda |\lambda\rangle,$$
  $|\lambda\rangle = \exp\left(-\frac{1}{2}|\lambda|^2\right) \exp\left(\lambda a^{\dagger}\right) |0\rangle.$ 

Here,  $\lambda$  is a complex parameter.

## **1.1** Compute $\langle x|\lambda\rangle$ .

**Solution.** Since  $a|0\rangle = 0|0\rangle$ ,  $\exp(\lambda a)|0\rangle = |0\rangle$  and therefore we can write

$$\langle x|\lambda\rangle = \exp\left(-\frac{1}{2}|\lambda|^2\right)\langle x|\exp\left(\lambda a^{\dagger}\right)\exp(\lambda a)|0\rangle.$$
 (1)

For two operators A and B,  $e^{A+B} = e^{-[A,B]/2}e^Ae^B$  if [A,B] commutes with each A and B. Here, we have

$$\exp\left[\lambda(a^{\dagger}+a)\right] = \exp\left(\frac{\lambda^2}{2}\right) \exp\left(\lambda a^{\dagger}\right) \exp(\lambda a) \implies \exp\left(\lambda a^{\dagger}\right) \exp(\lambda a) = \exp\left(-\frac{\lambda^2}{2}\right) \exp\left[\lambda(a^{\dagger}+a)\right],$$

where we have used  $[a, a^{\dagger}] = 1$ . From (2.3.24) in Sakurai,

$$X = \sqrt{\frac{\hbar}{2m\omega}}(a+a^{\dagger}), \qquad P = i\sqrt{\frac{\hbar m\omega}{2}}(a^{\dagger} - a), \qquad (2)$$

so

$$\exp\left[\lambda(a^{\dagger}+a)\right] = \exp\left(\lambda X \sqrt{\frac{2m\omega}{\hbar}}\right).$$

Making these substitutions into (1) yields

$$\langle x|\lambda\rangle = \exp\left(-\frac{1}{2}|\lambda|^2\right) \exp\left(-\frac{\lambda^2}{2}\right) \langle x| \exp\left(\lambda X \sqrt{\frac{2m\omega}{\hbar}}\right) |0\rangle$$
$$= \exp\left(-\frac{1}{2}|\lambda|^2\right) \exp\left(-\frac{\lambda^2}{2}\right) \exp\left(\lambda x \sqrt{\frac{2m\omega}{\hbar}}\right) \langle x|0\rangle. \tag{3}$$

From (2.3.30) in Sakurai,

$$\langle x|0\rangle = \left(\frac{m\omega}{\pi\hbar}\right)^{1/4} \exp\left(-\frac{m\omega}{2\hbar}x^2\right)$$

so (3) becomes

$$\langle x|\lambda\rangle = \left(\frac{m\omega}{\pi\hbar}\right)^{1/4} \exp\left(-\frac{1}{2}|\lambda|^2 - \frac{\lambda^2}{2} + \lambda x\sqrt{\frac{2m\omega}{\hbar}} - \frac{m\omega}{2\hbar}x^2\right).$$

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**1.2** Compute  $\langle \lambda | X | \lambda \rangle$ ,  $\langle \lambda | P | \lambda \rangle$ ,  $\langle \lambda | X^2 | \lambda \rangle$ , and  $\langle \lambda | P^2 | \lambda \rangle$ . Also, compute  $\langle \lambda | (\Delta X)^2 | \lambda \rangle \langle \lambda | (\Delta P)^2 | \lambda \rangle$  where  $\Delta A = A - \langle A \rangle$ .

**Solution.** For  $\langle \lambda | X | \lambda \rangle$ ,

$$\langle \lambda | X | \lambda \rangle = \frac{1}{|\lambda|^2} \langle \lambda | a^{\dagger} X a | \lambda \rangle$$

$$= \frac{1}{|\lambda|^2} \sqrt{\frac{\hbar}{2m\omega}} \langle \lambda | a^{\dagger} (a + a^{\dagger}) a | \lambda \rangle = \frac{1}{|\lambda|^2} \sqrt{\frac{\hbar}{2m\omega}} \langle \lambda | (a^{\dagger} a^2 + a^{\dagger^2} a) | \lambda \rangle = \frac{|\lambda|^2 (\lambda^* + \lambda)}{|\lambda|^2} \sqrt{\frac{\hbar}{2m\omega}}$$

$$= 2 \operatorname{Re}(\lambda) \sqrt{\frac{\hbar}{2m\omega}}, \tag{4}$$

where we have again used (2). For  $\langle \lambda | P | \lambda \rangle$ ,

$$\langle \lambda | P | \lambda \rangle = \frac{1}{\lambda^2} \langle \lambda | a^{\dagger} P a | \lambda \rangle$$

$$= \frac{i}{|\lambda|^2} \sqrt{\frac{\hbar m \omega}{2}} \langle \lambda | a^{\dagger} (a^{\dagger} - a) a | \lambda \rangle = \frac{i}{|\lambda|^2} \sqrt{\frac{\hbar m \omega}{2}} \langle \lambda | (a^{\dagger^2} a - a^{\dagger} a^2) | \lambda \rangle = \frac{i |\lambda|^2 (\lambda^* - \lambda)}{|\lambda|^2} \sqrt{\frac{\hbar m \omega}{2}}$$

$$= 2 \operatorname{Im}(\lambda) \sqrt{\frac{\hbar m \omega}{2}}.$$
(5)

From (2), note that

$$X^{2} = \frac{\hbar}{2m\omega}(a^{2} + aa^{\dagger} + a^{\dagger}a + a^{\dagger^{2}}), \qquad P^{2} = -\frac{\hbar m\omega}{2}(a^{\dagger^{2}} - a^{\dagger}a - aa^{\dagger} + a^{2}).$$

Then for  $\langle \lambda | X^2 | \lambda \rangle$ ,

$$\langle \lambda | X^{2} | \lambda \rangle = \frac{1}{|\lambda|^{2}} \langle \lambda | a^{\dagger} X^{2} a | \lambda \rangle = \frac{1}{|\lambda|^{2}} \frac{\hbar}{2m\omega} \langle \lambda | a^{\dagger} (a^{2} + aa^{\dagger} + a^{\dagger} a + a^{\dagger^{2}}) a | \lambda \rangle$$

$$= \frac{1}{|\lambda|^{2}} \frac{\hbar}{2m\omega} \langle \lambda | (a^{\dagger} a^{3} + a^{\dagger} aa^{\dagger} a + a^{\dagger^{2}} a^{2} + a^{\dagger^{3}} a) | \lambda \rangle = \frac{1}{|\lambda|^{2}} \frac{\hbar}{2m\omega} \langle \lambda | (a^{\dagger} a^{3} + a^{\dagger} a + 2a^{\dagger^{2}} a^{2} + a^{\dagger^{3}} a) | \lambda \rangle$$

$$= (\lambda^{2} + 1 + 2|\lambda|^{2} + \lambda^{*2}) \frac{\hbar}{2m\omega} = (1 + 2 \left[ \operatorname{Re}(\lambda)^{2} + \operatorname{Im}(\lambda)^{2} \right] + 2 \left[ \operatorname{Re}(\lambda)^{2} - \operatorname{Im}(\lambda)^{2} \right] ) \frac{\hbar}{2m\omega}$$

$$= [1 + 4 \operatorname{Re}(\lambda)^{2}] \frac{\hbar}{2m\omega}, \tag{6}$$

where we have again used  $[a, a^{\dagger}] = 1$ . For  $\langle \lambda | P^2 | \lambda \rangle$ ,

$$\langle \lambda | P^{2} | \lambda \rangle = \frac{1}{|\lambda|^{2}} \langle \lambda | a^{\dagger} P^{2} a | \lambda \rangle = -\frac{1}{|\lambda|^{2}} \frac{\hbar m \omega}{2} \langle \lambda | a^{\dagger} (a^{\dagger^{2}} - a^{\dagger} a - a a^{\dagger} + a^{2}) a | \lambda \rangle$$

$$= -\frac{1}{|\lambda|^{2}} \frac{\hbar m \omega}{2} \langle \lambda | (a^{\dagger^{2}} a - a^{\dagger^{2}} a^{2} - a^{\dagger} a a^{\dagger} a + a^{\dagger} a^{3}) | \lambda \rangle = -\frac{1}{|\lambda|^{2}} \frac{\hbar m \omega}{2} \langle \lambda \rangle | (a^{\dagger^{3}} a - a^{\dagger} a - 2 a^{\dagger^{2}} a^{2} + a^{\dagger} a^{3} | \lambda \rangle \rangle$$

$$= -(\lambda^{*2} - 1 - 2|\lambda|^{2} + \lambda^{2}) \frac{\hbar m \omega}{2} = \left(1 + 2 \left[ \operatorname{Re}(\lambda)^{2} + \operatorname{Im}(\lambda)^{2} \right] - 2 \left[ \operatorname{Re}(\lambda)^{2} - \operatorname{Im}(\lambda)^{2} \right] \right) \frac{\hbar m \omega}{2}$$

$$= \left[1 + 4 \operatorname{Im}(\lambda)^{2}\right] \frac{\hbar m \omega}{2}. \tag{7}$$

From (1.4.51) in Sakurai,  $\langle (\Delta A)^2 \rangle = \langle A^2 \rangle - \langle A \rangle^2$ . Then

$$\langle \lambda | (\Delta X)^2 | \lambda \rangle = \langle \lambda | X^2 | \lambda \rangle - \langle \lambda | X | \lambda \rangle^2 = [1 + 4 \operatorname{Re}(\lambda)^2] \frac{\hbar}{2m\omega} - 4 \operatorname{Re}(\lambda)^2 \frac{\hbar}{2m\omega} = \frac{\hbar}{2m\omega},$$

where we have used (4) and (6), and

$$\langle \lambda | (\Delta P)^2 | \lambda \rangle = \langle \lambda | P^2 | \lambda \rangle - \langle \lambda | P | \lambda \rangle^2 = [1 + 4 \operatorname{Im}(\lambda)^2] \frac{\hbar m \omega}{2} - 4 \operatorname{Im}(\lambda)^2 \frac{\hbar m \omega}{2} = \frac{\hbar m \omega}{2},$$

where we have used (5) and (7). Finally,

$$\langle \lambda | (\Delta X)^2 | \lambda \rangle \langle \lambda | (\Delta P)^2 | \lambda \rangle = \frac{\hbar^2}{4},$$

which shows that the coherent state  $|\lambda\rangle$  satisfies the minimum uncertainty relation.

**1.3** Starting from  $|\psi(0)\rangle = |\lambda\rangle$  at t = 0, we let  $|\psi(t)\rangle$  evolve in time. What is the state  $|\psi(t)\rangle$  for t > 0?

**Solution.** The Hamiltonian for the harmonic oscillator,

$$H = \frac{P^2}{2m} + \frac{m\omega^2 X^2}{2},\tag{8}$$

is time independent, so the time evolution operator U(t) for the coherent state in general is given by

$$U(t) = \exp\left(-\frac{iHt}{\hbar}\right),\tag{9}$$

which is (2.1.28) in Sakurai. Rewriting  $|\lambda\rangle$  in the power series representation,

$$|\lambda\rangle = \exp\left(-\frac{|\lambda|^2}{2}\right) \sum_{n=0}^{\infty} \frac{\lambda^n a^{\dagger n}}{n!} |0\rangle = \exp\left(-\frac{|\lambda|^2}{2}\right) \sum_{n=0}^{\infty} \frac{\lambda^n}{n!} |n\rangle.$$
 (10)

The time evolution operator U(t) for an energy eigenket  $|n\rangle$  of the harmonic oscillator is given by

$$U(t)\left|n\right\rangle = \exp\left(-\frac{iE_nt}{\hbar}\right)\left|n\right\rangle = \exp\left[-i\left(n+\frac{1}{2}\right)\omega t\right]\left|n\right\rangle = e^{-in\omega t}e^{-i\omega t/2},$$

where  $E_n$  are given by (2.3.9) in Sakurai. Then, using (10), we have

$$|\psi(t)\rangle = U(t) |\lambda\rangle = \exp\left(-\frac{|\lambda|^2}{2}\right) \sum_{n=0}^{\infty} \frac{\lambda^n}{n!} e^{-in\omega t} e^{-i\omega t/2} |n\rangle = e^{-i\omega t/2} \exp\left(-\frac{|\lambda|^2}{2}\right) \sum_{n=0}^{\infty} \frac{(\lambda e^{-i\omega t})^n}{n!} |n\rangle$$

$$= e^{-i\omega t/2} |\lambda e^{-i\omega t}\rangle, \tag{11}$$

where  $\lambda e^{-i\omega t}$  is a complex number (albeit one that is changing in time). Thus,  $|\lambda e^{-i\omega t}\rangle$  is another coherent state.

**1.4** Compute  $\langle \psi(t)|X|\psi(t)\rangle$  and  $\langle \psi(t)|P|\psi(t)\rangle$ , and their time derivatives  $d\langle X\rangle/dt$  and  $d\langle P\rangle/dt$ .

**Solution.** Proceeding similarly to 1.2 and using (11), we have

$$\begin{split} \langle \psi(t)|X|\psi(t)\rangle &= \left\langle \lambda e^{-i\omega t} \right| e^{i\omega t/2} X e^{-i\omega t/2} \left| \lambda e^{-i\omega t} \right\rangle = \left\langle \lambda e^{-i\omega t} \middle| X \middle| \lambda e^{-i\omega t} \right\rangle \\ &= \frac{1}{|\lambda e^{-i\omega t}|^2} \sqrt{\frac{\hbar}{2m\omega}} \left\langle \lambda e^{-i\omega t} \middle| (a^\dagger a^2 + a^{\dagger^2} a) \middle| \lambda e^{-i\omega t} \right\rangle = \frac{|\lambda|^2 (\lambda^* e^{i\omega t} + \lambda e^{-i\omega t} e^{-i\omega t})}{|\lambda|^2} \sqrt{\frac{\hbar}{2m\omega}} \end{split}$$

$$= \left\{ [\operatorname{Re}(\lambda) - i\operatorname{Im}(\lambda)]e^{i\omega t} + [\operatorname{Re}(\lambda) + i\operatorname{Im}(\lambda)]e^{-i\omega t} \right\} \sqrt{\frac{\hbar}{2m\omega}}$$

$$= \left[ \operatorname{Re}(\lambda)(e^{i\omega t} + e^{-i\omega t}) - \frac{\operatorname{Im}(\lambda)}{i}(e^{i\omega t} - e^{-i\omega t}) \right] \sqrt{\frac{\hbar}{2m\omega}}$$

$$= 2[\operatorname{Re}(\lambda)\cos(\omega t) + \operatorname{Im}(\lambda)\sin(\omega t)] \sqrt{\frac{\hbar}{2m\omega}}.$$
(12)

Likewise,

$$\langle \psi(t)|P|\psi(t)\rangle = \langle \lambda e^{-i\omega t} | e^{i\omega t/2} P e^{-i\omega t/2} | \lambda e^{-i\omega t} \rangle = \langle \lambda e^{-i\omega t} | P | \lambda e^{-i\omega t} \rangle$$

$$= \frac{i}{|\lambda e^{-i\omega t}|^2} \sqrt{\frac{\hbar m \omega}{2}} \langle \lambda e^{-i\omega t} | (a^{\dagger 2} a - a^{\dagger} a^2) | \lambda e^{-i\omega t} \rangle = i \frac{|\lambda|^2 (\lambda^* e^{i\omega t} - \lambda e^{-i\omega t} e^{-i\omega t})}{|\lambda|^2} \sqrt{\frac{\hbar m \omega}{2}}$$

$$= i \left\{ [\text{Re}(\lambda) - i \text{Im}(\lambda)] e^{i\omega t} - [\text{Re}(\lambda) + i \text{Im}(\lambda)] e^{-i\omega t} \right\} \sqrt{\frac{\hbar m \omega}{2}}$$

$$= \left[ \text{Im}(\lambda) (e^{i\omega t} + e^{-i\omega t}) - \frac{\text{Re}(\lambda)}{i} (e^{i\omega t} - e^{-i\omega t}) \right] \sqrt{\frac{\hbar m \omega}{2}}$$

$$= 2[\text{Im}(\lambda) \cos(\omega t) - \text{Re}(\lambda) \sin(\omega t)] \sqrt{\frac{\hbar m \omega}{2}}.$$
(13)

For the time derivatives, the harmonic oscillator Hamiltonian is given by (8). Note that

$$[X, H] = i\hbar \frac{P}{m},$$
  $[X, P] = -i\hbar m\omega^2 X,$ 

where we have used the results of problem 2.1 on the previous homework. Then, using the Ehrenfest theorem,

$$\frac{d\langle X\rangle}{dt} = -\frac{i}{\hbar} \langle \psi(t)|[X,H]|\psi(t)\rangle = \frac{1}{m} \langle \psi(t)|P|\psi(t)\rangle = \frac{2}{m} [\operatorname{Im}(\lambda)\cos(\omega t) - \operatorname{Re}(\lambda)\sin(\omega t)]\sqrt{\frac{\hbar\omega}{2}},$$

$$= 2\omega [\operatorname{Im}(\lambda)\cos(\omega t) - \operatorname{Re}(\lambda)\sin(\omega t)]\sqrt{\frac{\hbar}{2m\omega}}$$

and

$$\frac{d\langle P\rangle}{dt} = -\frac{i}{\hbar} \langle \psi(t)|[P,H]|\psi(t)\rangle = -m\omega^2 \langle \psi(t)|X|\psi(t)\rangle = -2m\omega^2 [\text{Re}(\lambda)\cos(\omega t) + \text{Im}(\lambda)\sin(\omega t)]\sqrt{\frac{\hbar}{2m\omega}}$$
$$= -2\omega [\text{Re}(\lambda)\cos(\omega t) + \text{Im}(\lambda)\sin(\omega t)]\sqrt{\frac{\hbar m\omega}{2}},$$

which are what we would get by differentiating (12) and (13), respectively.

**1.5** Compute  $\langle \lambda'' | \exp(-iHt/\hbar) | \lambda' \rangle$ .

**Solution.** From (9), we are looking for  $\langle \lambda'' | U(t) | \lambda' \rangle$ . From (11),

$$U(t)\left|\lambda\right> = e^{-i\omega t/2}\left|\lambda e^{-i\omega t}\right> \implies U(t)\left|\lambda'\right> = e^{-i\omega t/2}\left|\lambda' e^{-i\omega t}\right>,$$

so

$$\langle \lambda'' | U(t) | \lambda' \rangle = e^{-i\omega t/2} \langle \lambda'' | \lambda' e^{-i\omega t} \rangle.$$

Using the power series representation as in (10),

$$\left|\lambda' e^{-i\omega t}\right\rangle = \exp\left(-\frac{|\lambda'|^2}{2}\right) \sum_{n=0}^{\infty} \frac{(\lambda' e^{-i\omega t})^n}{n!} \left|n\right\rangle,$$

SO

$$\left\langle \lambda'' \middle| \lambda' e^{-i\omega t} \right\rangle = \exp\left(-\frac{|\lambda''|^2}{2}\right) \exp\left(-\frac{|\lambda'|^2}{2}\right) \sum_{n=0}^{\infty} \frac{(\lambda''^* \lambda' e^{-i\omega t})^n}{n!} \left\langle n \middle| n \right\rangle = \exp\left(-\frac{|\lambda''|^2}{2} + \lambda''^* \lambda' e^{-i\omega t} - \frac{|\lambda'|^2}{2}\right).$$

Finally, we have

$$\langle \lambda'' | \exp\left(-\frac{iHt}{\hbar}\right) | \lambda' \rangle = \exp\left(-\frac{i\omega t}{2} - \frac{|\lambda''|^2}{2} + {\lambda''}^* \lambda' e^{-i\omega t} - \frac{|\lambda'|^2}{2}\right).$$

## 2 Problem 2

Consider a quantum system which has coordinate  $X_1$  and momentum  $P_1$ , and another system which has coordinate  $X_2$  and momentum  $P_2$ . (An operator from the first system always commutes with an operator of the second system.) We think of the second system as a "probe" which we can use to detect the properties of the first system. For a short time T, the two systems are coupled by a coupling Hamiltonian  $H_c$ , given by

$$H_c = \frac{X_1 P_2}{T}.$$

The coupling between the two systems disturbs the momentum of the first system. The disturbance operator is defined to be

$$D \equiv P_1(T) - P_1(0). \tag{14}$$

The probe introduces measurement error or "noise" into the system. The noise operator is defined by

$$N \equiv X_2(T) - X_1(0).$$

The stste of the system at t=0 is  $|\Psi(0)\rangle = |\phi_1(0)\phi_2(0)\rangle$ , and all expectation values are taken in this state.

**2.1** With  $H_c$  as the Hamiltonian, find the Heisenberg operators  $X_1(t)$ ,  $P_1(t)$ ,  $X_2(t)$ , and  $P_2(t)$  in terms of  $X_1(0)$ ,  $P_1(0)$ ,  $X_2(0)$ , and  $P_2(0)$ . Time is restricted to the range  $t \in [0, T]$ .

**Solution.** In general, a Heisenberg operator O(t) is defined by

$$O(t) = U^{\dagger}(t) O(0) U(t),$$

where U(t) is the time evolution operator. For  $H_c$ , it is given by

$$U(t) = \exp\left(-\frac{iH_c t}{\hbar}\right) = \exp\left(-\frac{it}{\hbar T}X_1(0)P_2(0)\right).$$

(2.2.23) in Sakurai gives the commutation relations

$$[X_i, F(\mathbf{P})] = i\hbar \frac{\partial F}{\partial P_i} \qquad [P_i, G(\mathbf{X})] = -i\hbar \frac{\partial G}{\partial X_i}.$$

Using these, we have

$$\begin{split} [X_1(0),U(t)] &= 0, \\ [X_2(0),U(t)] &= i\hbar \left( -\frac{it}{\hbar T} X_1(0) \right) U(t) = \frac{t}{T} X_1(0) U(t) = \frac{t}{T} U(t) X_1(0), \\ [P_1(0),U(t)] &= -i\hbar \left( -\frac{it}{\hbar T} P_2(0) \right) U(t) = -\frac{t}{T} P_2(0) U(t) = -\frac{t}{T} U(t) P_2(0), \\ [P_2(0),U(t)] &= 0. \end{split}$$

Then

$$X_1(t) = U^{\dagger}(t) X_1(0) U(t) = X_1(0), \tag{15}$$

$$P_1(t) = U^{\dagger}(t) P_1(0) U(t) = U^{\dagger}(t) \left( U(t) P_1(0) - \frac{t}{T} U(t) P_2(0) \right) = P_1(0) - \frac{t}{T} P_2(0), \tag{16}$$

$$X_2(t) = U^{\dagger}(t) X_2(0) U(t) = U^{\dagger}(t) \left( U(t) X_2(0) + \frac{t}{T} U(t) X_1(0) \right) = X_2(0) + \frac{t}{T} X_1(0), \tag{17}$$

$$P_2(t) = U^{\dagger}(t) P_2(0) U(t) = P_2(0). \tag{18}$$

**2.2** Derive an expression for  $\sigma(D)$  which involves only the standard deviations of  $X_1(0)$ ,  $P_1(0)$ ,  $X_2(0)$ , and  $P_2(0)$ . Here, we denote the standard deviation of an operator O as  $\sigma(O) = \sqrt{\langle (O - \langle O \rangle)^2 \rangle}$ .

**Solution.** Substituting (18) into (14),

$$D = P_1(0) - \frac{T}{T}P_2(0) - P_1(0) = -P_2(0).$$

Note that for an operator O,

$$\sigma(-O) = \sqrt{\langle (-O - \langle -O \rangle)^2 \rangle} = \sqrt{\langle (\langle O \rangle - O)^2 \rangle} = \sigma(O),$$

SO

$$\sigma(D) = \sigma(P_2(0)). \tag{19}$$

**2.3** Derive an expression for  $\sigma(N)$  which involves only the standard deviations of  $X_1(0)$ ,  $P_1(0)$ ,  $X_2(0)$ , and  $P_2(0)$ .

**Solution.** Substituting (17) into (14),

$$N = X_2(0) + \frac{T}{T}X_1(0) - X_1(0) = X_2(0).$$

which implies

$$\sigma(N) = \sigma(X_2(0)). \tag{20}$$

**2.4** Now consider the product  $\sigma(N) \sigma(D)$ . Assume

$$\sigma(X_1(0)) \sigma(P_1(0)) \ge \frac{\hbar}{2},$$
  $\sigma(X_2(0)) \sigma(P_2(0)) \ge \frac{\hbar}{2}$ 

both hold. Is  $\sigma(N) \sigma(D) \ge \hbar/2$  satisfied? What conditions are required for equality?

**Solution.** From (19) and (20),

$$\sigma(N) \, \sigma(D) = \sigma(P_2(0)) \, \sigma(X_2(0)) \ge \frac{\hbar}{2},$$

where the final inequality is satisfied by assumption. For equality, we would need

$$\sigma(X_2(0)) \sigma(P_2(0)) = \frac{\hbar}{2},$$

which is satisfied if the "probe" system is a Gaussian wave packet.

## 3 Problem 3

Answer the following questions about the angular momentum operator  $L_i$ .

**3.1** Calculate  $[L_i, \mathbf{r}]$  where i = x, y, z.

**Solution.** Firstly, note that

$$L_x = YP_z - ZP_y,$$
  $L_y = ZP_x - XP_z,$   $L_z = XP_y - YP_x,$ 

where the expression for  $L_z$  was given in problem 2 of Homework 1, and  $L_x$  and  $L_y$  are cyclic permutations. Then

$$\begin{split} [L_x, X] &= (YP_z - ZP_y)X - X(YP_z - ZP_y) = 0, \\ [L_x, Y] &= (YP_z - ZP_y)Y - Y(YP_z - ZP_y) = YP_zY - ZP_yY - YYP_z + YZP_y = [Y, P_y]Z = i\hbar Z, \\ [L_x, Z] &= (YP_z - ZP_y)Z - Z(YP_z - ZP_y) = YP_zZ - ZP_yZ - ZYP_z + ZZP_y = -[Z, P_z]Y = -i\hbar Y. \end{split}$$

Generalizing these results to  $L_y$  and  $L_z$ ,

$$[L_x, \mathbf{r}] = i\hbar \begin{bmatrix} 0 \\ Z \\ -Y \end{bmatrix}, \qquad [L_y, \mathbf{r}] = i\hbar \begin{bmatrix} -Z \\ 0 \\ X \end{bmatrix}, \qquad [L_z, \mathbf{r}] = i\hbar \begin{bmatrix} Y \\ -X \\ 0 \end{bmatrix}, \qquad (21)$$

where  $\mathbf{r} = \begin{bmatrix} X & Y & Z \end{bmatrix}^T$ .

**3.2** Let us now compare the above results with classical mechanics. Rotations around the x, y, and z axes by an angle  $\theta$  in three-dimensional Cartesian space are represented by the following matrices:

$$R_x(\theta) = \begin{bmatrix} 1 & 0 & 0 \\ 0 & \cos \theta & -\sin \theta \\ 0 & \sin \theta & \cos \theta \end{bmatrix}, \qquad R_y(\theta) = \begin{bmatrix} \cos \theta & 0 & \sin \theta \\ 0 & 1 & 0 \\ -\sin \theta & 0 & \cos \theta \end{bmatrix}, \qquad R_z(\theta) = \begin{bmatrix} \cos \theta & -\sin \theta & 0 \\ \sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{bmatrix}.$$

Calculate  $R_i(\theta)$  **r**. Then expand  $R_i(\theta)$  **r** for a small angle  $\theta$  and consider  $\mathbf{r} - R_i(\theta)$  **r** to first order in  $\theta$ ,

$$\mathbf{r} - R_i(\theta) \mathbf{r} = \theta M_i \mathbf{r} + \mathcal{O}(\theta^2).$$

Calculate the matrices  $M_i$ .

**Solution.** For  $R_i(\theta)$  **r**, we have

$$R_x(\theta) \mathbf{r} = \begin{bmatrix} X \\ \cos \theta Y - \sin \theta Z \\ \sin \theta Y + \cos \theta Z \end{bmatrix}, \qquad R_y(\theta) \mathbf{r} = \begin{bmatrix} \cos \theta X + \sin \theta Z \\ Y \\ \cos \theta Z - \sin \theta X \end{bmatrix}, \qquad R_z(\theta) \mathbf{r} = \begin{bmatrix} \cos \theta X - \sin \theta Y \\ \sin \theta X + \cos \theta Y \\ Z \end{bmatrix},$$

In the small angle approximation, to first order  $\cos \theta \approx 1$  and  $\sin \theta \approx \theta$ . In this approximation,

$$R_x(\theta) \mathbf{r} pprox egin{bmatrix} X \\ Y - \theta Z \\ \theta Y + Z \end{bmatrix}, \qquad R_y(\theta) \mathbf{r} pprox egin{bmatrix} X + \theta Z \\ Y \\ Z - \theta X \end{bmatrix}, \qquad R_z(\theta) \mathbf{r} pprox egin{bmatrix} X - \theta Y \\ \theta X + Y \\ Z \end{bmatrix},$$

and so

$$\mathbf{r} - R_x(\theta) \mathbf{r} \approx \theta \begin{bmatrix} 0 \\ Z \\ -Y \end{bmatrix}, \qquad \mathbf{r} - R_y(\theta) \mathbf{r} \approx \theta \begin{bmatrix} -Z \\ 0 \\ X \end{bmatrix}, \qquad \mathbf{r} - R_z(\theta) \mathbf{r} \approx \theta \begin{bmatrix} Y \\ -X \\ 0 \end{bmatrix},$$

which look similar to (21). These results suggest the matrices

$$M_x = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & -1 & 0 \end{bmatrix}, \qquad M_y = \begin{bmatrix} 0 & 0 & -1 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{bmatrix}, \qquad M_z = \begin{bmatrix} 0 & 1 & 0 \\ -1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}.$$

**3.3** Calculate the matrix elements of the angular momentum operator  $L_i$  in the basis ket  $|l, m\rangle$  when l = 1 and l = 2. Here,  $|l, m\rangle$  is the simultaneous eigenket of  $L^2$  and  $L_z$  with the eigenvalues  $\hbar^2 l(l+1)$  and  $\hbar m$ , respectively.

**Solution.** The ladder operators are defined by (3.5.5) in Sakurai:

$$J_{\pm} = L_x \pm iL_y.$$

Clearly,

$$L_x = \frac{J_+ + J_-}{2},$$
  $L_y = \frac{J_+ - J_-}{2i}.$ 

From (3.5.39) and (3.5.40),

$$J_{+}|l,m\rangle = \sqrt{(l-m)(l+m+1)}\hbar |l,m+1\rangle, \qquad J_{-}|l,m\rangle = \sqrt{(l+m)(l-m+1)}\hbar |l,m-1\rangle.$$

Then the matrix elements of  $L_x$  are given by

$$\langle 1, m' | L_x | 1, m \rangle = \langle 1, m' | \frac{J_+ + J_-}{2} | 1, m \rangle = \frac{\hbar}{2} \left( \delta_{m+1, m'} \sqrt{2 - m - m^2} + \delta_{m-1, m'} \sqrt{2 + m - m^2} \right),$$

$$\langle 1, m' | L_x | 2, m \rangle = 0,$$

$$\langle 2, m' | L_x | 1, m \rangle = 0,$$

$$\langle 2, m' | L_x | 2, m \rangle = \langle 1, m' | \frac{J_+ + J_-}{2} | 1, m \rangle = \frac{\hbar}{2} \left( \delta_{m+1, m'} \sqrt{6 - m - m^2} + \delta_{m-1, m'} \sqrt{6 + m - m^2} \right),$$

where the integers  $m, m' \in [-l, l]$ .

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The matrix elements of  $L_y$  are given by

$$\langle 1, m' | L_y | 1, m \rangle = \langle 1, m' | \frac{J_+ - J_-}{2i} | 1, m \rangle = -\frac{i\hbar}{2} \left( \delta_{m+1, m'} \sqrt{2 - m - m^2} - \delta_{m-1, m'} \sqrt{2 + m - m^2} \right),$$

$$\langle 1, m' | L_y | 2, m \rangle = 0,$$

$$\langle 2, m' | L_y | 1, m \rangle = 0,$$

$$\langle 2, m' | L_y | 2, m \rangle = \langle 1, m' | \frac{J_+ - J_-}{2i} | 1, m \rangle = -\frac{i\hbar}{2} \left( \delta_{m+1, m'} \sqrt{6 - m - m^2} - \delta_{m-1, m'} \sqrt{6 + m - m^2} \right),$$

where again  $m, m' \in [-l, l]$ .

Since  $|l,m\rangle$  are eigenkets of  $L_z$ , it is diagonal in this basis. Its matrix elements are given by

$$\langle l', m' | L_y | l, m \rangle = \hbar m \, \delta_{m,m'} \, \delta_{l,l'},$$

where  $l, l' \in \{1, 2\}$  and  $m, m' \in [-l, l]$ .

Explicitly, let

$$R = \begin{pmatrix} (1,-1) & (1,0) & (1,1) & (2,-2) & (2,-1) & (2,0) & (2,1) & (2,2) \\ (1,0) & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ (1,1) & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ (2,-2) & 0 & 0 & 0 & \sqrt{2} & 0 & 0 & 0 \\ (2,0) & (2,0) & 0 & 0 & \sqrt{3} & 0 & \sqrt{3} & 0 \\ (2,1) & 0 & 0 & 0 & 0 & 0 & \sqrt{2} & 0 \end{pmatrix},$$

where the row labels represent (l', m') and the column labels represent (l, m). Then

$$L_x = \frac{\hbar}{\sqrt{2}}R, \qquad L_y = -\frac{i\hbar}{\sqrt{2}}R,$$

and

$$L_z = \hbar \begin{array}{c} (1,-1) & (1,0) & (1,1) & (2,-2) & (2,-1) & (2,0) & (2,1) & (2,2) \\ (1,-1) & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ (1,0) & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ (1,1) & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ (2,-2) & 0 & 0 & 0 & -2 & 0 & 0 & 0 \\ (2,0) & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ (2,1) & (2,2) & 0 & 0 & 0 & 0 & 0 & 0 & 2 \end{array} \right].$$

In writing up these solutions, I consulted Sakurai's *Modern Quantum Mechanics* and Shankar's *Principles of Quantum Mechanics*.