# JOSEPH RUAN

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## **EDUCATION**

#### **Purdue University - West Lafayette**

Aug 2024 - May 2027

Bachelor's, Mechanical Engineering

- Minors in Computer Science. Economics
- Relevant Coursework: Statics (ME27000), Thermodynamics (ME20000), Linear Circuit Analysis (ECE20001)

#### PROFESSIONAL EXPERIENCE

#### **Collaborative Robotics Lab**

Research Assistant

West Lafayette, IN, USA

Aug 2024 - Present

- Designed, assembled, and programmed robot to measure soil microbiome emissions; presented findings to USDA
- Developed low-cost inertia measuring and position estimation solutions to study animal behavior patterns
- · Created electromechanical assemblies for papers published in IEEE and Journal of Animal Science
- Wrote co-processor transmission layer for real-time SLAM/edge computing in Embedded C to offload data collection

#### **Purdue Electric Racing**

West Lafayette, IN, USA

Aug 2024 - Present

Chassis Team

- · Designed chassis closeouts using NX to isolate cockpit and driver from potentially hazardous road debris
- Validated closeouts and battery mounts using ANSYS to verify compliance with rigidity and deformation targets
- · Utilized composite manufacturing techniques such as wet layups and vacuum infusion to manufacture closeouts
- Manufactured chassis components using multi-axis manufacturing methods and designed jig/tooling for assembly
- Welded chassis tubes together and validated welds using ultrasonic non-destructive testing

## **Global Active Problem Solving (EPICS)**

Barranquilla, AT, Colombia

Aug 2024 - Present

- Designed a wildlife monitoring solution for the Universidad del Norte to monitor the ecosystem around the university
- Utilized design-for-manufacturing techniques to comply with client requirements for additive manufacturing

## Miso Mechanics 9442

Camera Designer

Seattle, WA, USA

Oct 2023 - May 2024

Captain and Lead Programmer

- Founded and led rookie FIRST Robotics team and fundraised over \$30,000 USD for competition and robot costs
- Utilized 3D printing and laser cutting for rapid prototyping and iteration, reducing traditional timelines by half
- Designed multiple subsystems in Onshape on award-winning competition robot which ranked 20th offensively internationally
- Developed computer vision system using PhotonVision and custom camera assemblies to detect game objectives
- Created motion planning system for autonomous routines allowing for real-time decision-making to aid in gameplay

### BSA Troop 647

Mercer Island, WA, USA

Eagle Scout & Patrol Leader

Jun 2018 - Jun 2024

- Planned, designed, and led construction of a new freestanding structure on charter organization property
- Organized outings and service projects for patrol members as well as troop camping trips and conservation projects.

## PROJECTS & OUTSIDE EXPERIENCE

## Soil Microbome Measuring Robot (SoMMR)

Ames, IA, USA

Collaborative Robotics Lab

2024 - Present

- Designed slip ring assembly for reel of robot to allow for easy unspooling as well as sensor array and module mounting system
- · Developed data parsing script to sync timestamps of photos and sensors for more precise research
- Presented findings at the United States Department of Agriculture's Ames National Laboratory

## **Streaming Service**

Self-Employed

Seattle, WA, USA

Jun 2023 - Present

- Utilized various public Docker containers to build a streaming service used by 50K active users
- Implemented user SSO with AniList and Trakt APIs to automatically synchronize user data to service
- Employed reverse proxy and various web technologies to maintain service stability and load-balance

### **SKILLS**

**Skills:** MATLAB, Excel/Numbers/Sheets, Git, Java, Python, Bash, CAD, C/C++, Development Operations (DevOps), Docker, FEM/FEA, Linux/Unix, Netlify, SolidWorks, NX, Ansys, Embedded Programming

Languages: Chinese