[1] Azlan, N.Z.; Zainudin, F.; Yusuf, H.M.; Toha, S.F.; Yusoff, S.Z.S.; Osman, N.H., "Fuzzy Logic Controlled Miniature LEGO Robot for Undergraduate Training System," Industrial Electronics and Applications, 2007. ICIEA 2007. 2nd IEEE Conference on, vol., no., pp.2184, 2188, 23-25 May 2007

[2] Gijeong Jang; Sungho Lee; Inso Kweon, "Color landmark based self-localization for indoor mobile robots," Robotics and Automation, 2002. Proceedings. ICRA '02. IEEE International Conference on, vol.1, no.

[7] Tripathy, H. K., Tripathy, B. K., & Das, P. K. (2008). A Prospective Fuzzy Logic approach to Knowledge-based Navigation of Mobile LEGO-Robot. Journal of Convergence Information Technology, 3(1), 64-70.

[4] Want, R., "An introduction to RFID technology," Pervasive Computing, IEEE , vol.5, no.1, pp.25,33, Jan.-March 2006

[5] Klaus Finkenzeller. RFID Handboook: Radio-Frequency Identification Fundamentals and Applications. Wiley, New York, 2000.

[6][4] Hahnel, D.; Burgard, W.; Fox, D.; Fishkin, K.; Philipose, M., "Mapping and localization with RFID technology," Robotics and Automation, 2004. Proceedings. ICRA '04. 2004 IEEE International Conference on, vol.1, no., pp.1015, 1020 Vol.1, 26 April-1 May 2004

[7][5] Gueaieb, W.; Miah, Md.S., "An Intelligent Mobile Robot Navigation Technique Using RFID Technology," Instrumentation and Measurement, IEEE Transactions on , vol.57, no.9, pp.1908,1917, Sept. 2008

[8][6] I. Hallmann and B. Siemiatkowska, “Artificial landmark navigation system,” in Proc. Int. Symp. Intell. Robot. Syst., Jul. 2001, pp. 219–228.