AN13690

Enable More USB Examples on M4 Core for RT1170 or M7 Core for RT1180

Rev. 1 — 20 November 2022

Application note

Document information

Information	Content
'	AN13690, Examples, USB, USB Examples, M4, M7, M4 Core, M7 Core, RT1170, RT1180
	This document describes how to migrate USB examples from M7 to M4 or from M33 to M7 with different toolchains.



Enable More USB Examples on M4 Core for RT1170 or M7 Core for RT1180

1 Introduction

RT1170 works with M7 and M4, on which all USB examples can run. However, all USB examples in the release package are enabled on M7. Only example <code>host_hid_mouse</code> and <code>dev_hid_mouse</code> are enabled on M4. As for RT1180 works with M7 and M33, all USB examples in the release package are enabled on M33. Only example host_hid_mouse and dev_hid_mouse are enabled on M7. Since USB projects on both cores share demo source files but with different project settings, examples can be migrated.

This document describes how to migrate USB examples from M7 to M4 or from M33 to M7 with different toolchains. There are four main steps required:

- 1. Create an RT1170 M4/RT1180 M7 project.
- 2. Rearrange source files.
- 3. Rearrange project files.
- 4. Adjust project settings.

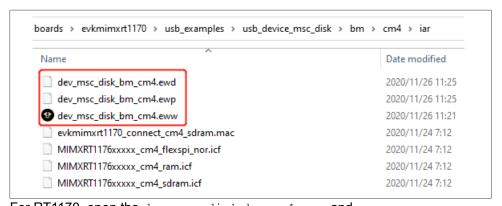
This document takes the <code>dev_msc_disk_bm</code> as an example to show how to enable USB examples on M4 core of RT1170 or on M7 core of RT1180 with IAR, MDK, ARMGCC, and MCUXpresso IDE.

2 IAR

1. Create an RT1170 M4/RT1180 M7 project

- a. For RT1170, copy the *cm4* folder under *<install_dir>/boards/evkmimxrt1170/usb_examples/usb_device_hid_mouse/bm/cm4* to the folder where the example must be enabled.
 - In this case, copy the *cm4* folder to *<install_dir>/boards/evkmimxrt1170/usb_examples/usb_device_msc_disk/bm*.
 - For RT1180, copy the *cm7* folder under *<install_dir>/boards/evkmimxrt1180/usb_examples/usb_device_hid_mouse/bm/cm7* to the folder where the example must be enabled.
 - In this case, copy the *cm7* folder to *<install_dir>/boards/evkmimxrt1180/usb_examples/usb_device_msc_disk/bm*.
- b. For RT1170, open the *iar* folder under *<install_dir>/boards/evkmimxrt1170/usb_examples/usb_device_msc_disk/bm/cm4/iar*. For RT1180, open the *iar* folder under *<install_dir>/boards/evkmimxrt1180/usb_examples/usb_device_msc_disk/bm/cm7/iar*.
- c. For RT1170, change the filename dev_hid_mouse_bm_cm4 to dev_msc_disk_bm_cm4 respectively.
 For RT1180, change the filename dev_hid_mouse_bm_cm7 to dev_msc_disk_bm_cm7 respectively.

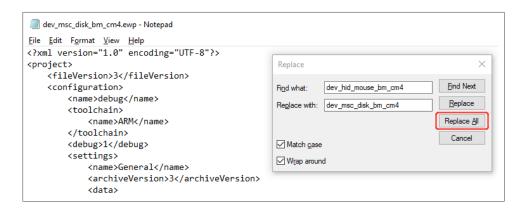
Enable More USB Examples on M4 Core for RT1170 or M7 Core for RT1180



d. For RT1170, open the dev_msc_disk_bm_cm4.eww and dev_msc_disk_bm_cm4.ewp files with a text editor, such as notepad, notepad++, sublime or Visual studio code.
For RT1180, open the dev_msc_disk_bm_cm7.eww and dev_msc_disk_bm_cm7.ewp files with a text editor, such as notepad, notepad++, sublime or Visual studio code.

e. For RT1170, search and replace all <code>dev_hid_mouse_bm_cm4</code> with <code>dev_msc_disk_bm_cm4</code>, and then save the files.





For RT1180, search and replace all ${\tt dev_hid_mouse_bm_cm7}$ with ${\tt dev_msc_disk_bm_cm7}$, and then save the files.

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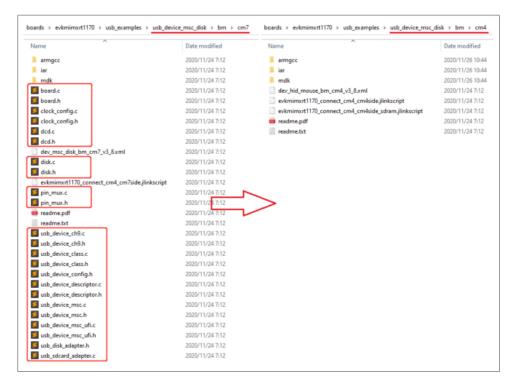




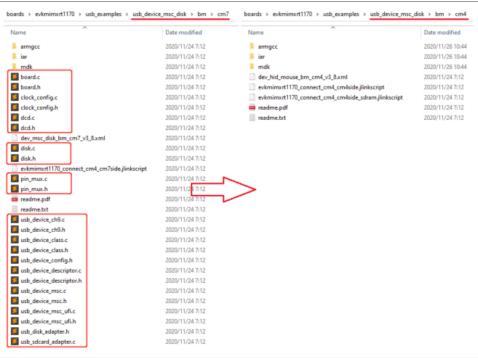
2. Rearrange source files

- a. For RT1170, open the *cm4* folder under *<install_dir>/boards/evkmimxrt1170/usb_examples/usb_device_msc_disk/bm/cm4*, and delete all files with the .c and .h extension.
 - For RT1180, open the *cm7* folder under *<install_dir>/boards/evkmimxrt1180/usb_examples/usb_device_msc_disk/bm/cm7*, and delete all files with the .c and .h extension.
- b. For RT1170, copy files with the .c and .h extension in the cm7 folder under <install_dir>/boards/evkmimxrt1170/usb_examples/usb_device_msc_disk/bm/cm7 to the cm4 folder under <install_dir>/boards/evkmimxrt1170/usb_examples/usb_device_msc_disk/bm/cm4.

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For RT1180, copy files with the .c and .h extension in the *cm33* folder under <install_dir>/boards/evkmimxrt1180/usb_examples/usb_device_msc_disk/bm/cm33 to the cm7 folder under <install_dir>/boards/evkmimxrt1180/usb_examples/usb_device_msc_disk/bm/cm7.



3. Rearrange project files

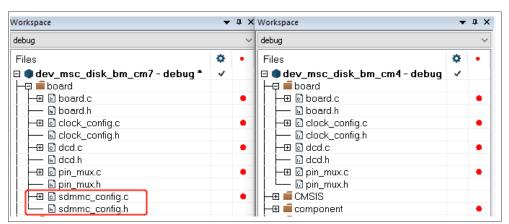
Enable More USB Examples on M4 Core for RT1170 or M7 Core for RT1180

Note: The following steps are described for RT1170. However, these steps are also applicable for RT1180.

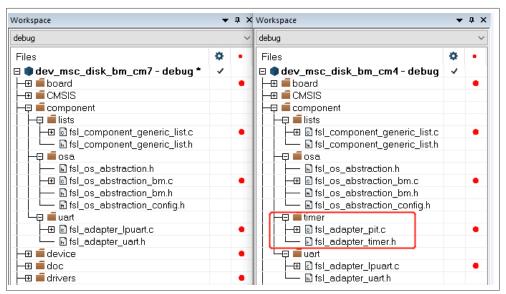
- a. Open dev_msc_disk_bm_cm7 and dev_msc_disk_bm_cm4 IAR project respectively. The two workspaces are respectively located under <install_dir>/boards/evkmimxrt1170/usb_examples/usb_device_msc_disk/bm/cm7/iar and <install_dir>/boards/evkmimxrt1170/usb_examples/usb_device_msc_disk/bm/cm4/iar.
- b. Compare the whole project directory. Find file groups that are in the cm7 project but not cm4 and add them to the cm4 project.
- c. Compare the two groups with the same name. Delete files that are in the cm4 project but not cm7. Find files that are in the cm7 project but not cm4 and add them to the cm4 project.

In this case,

• For the board group, add sdmmc_config source files to board group in the cm4 project.

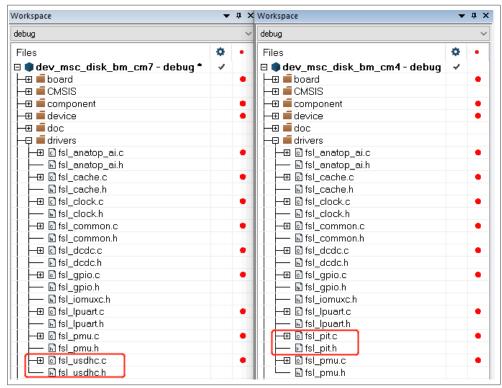


 For the component group, delete files associated with timer from cm4 project and add no files.

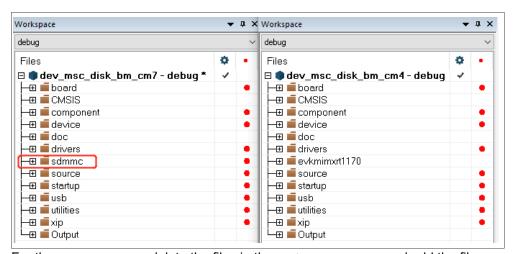


• For the drivers group, delete fsl_pit source files from the cm4 project and add fsl_usdhc source files to the cm4 project.

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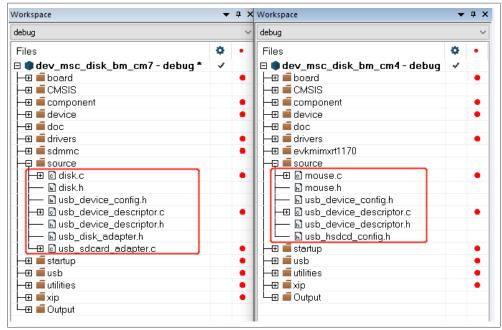


• For the sdmmc group, there is not sdmmc group in the cm4 project. Add sdmmc group and its children to the cm4 project.

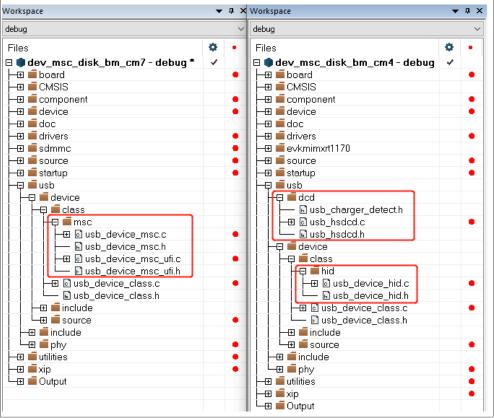


• For the source group, delete the files in the cm4 source group and add the files under <install_dir>/boards/evkmimxrt1170/usb_examples/usb_device_msc_disk/bm/cm4 with the same name as in the cm7 project.

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• For the usb group, replace the hid group and its children in the cm4 project with msc group in the cm7 project and delete the dcd group.



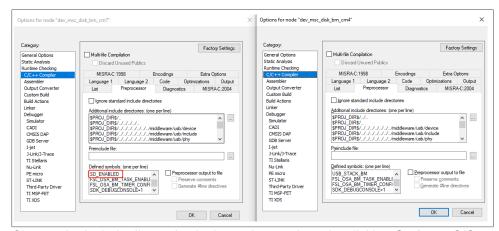
4. Adjust project settings

Enable More USB Examples on M4 Core for RT1170 or M7 Core for RT1180

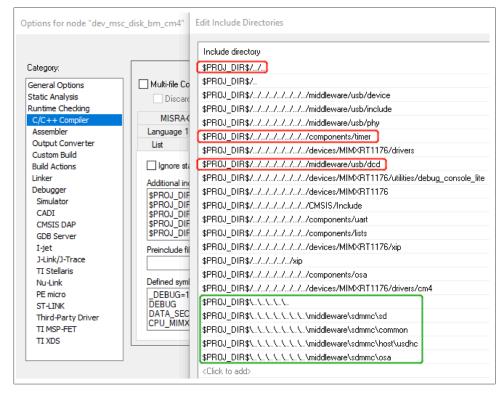
Note: The following steps are described for RT1170. However, these steps are also applicable for RT1180.

a. Compare the macro in the project settings: Option - C/C++ compiler > Preprocessor. Add the macro that is in the cm7 project but not cm4 to the cm4 project.

In this case, add the SD ENABLED macro to the cm4 project.



b. Change the include directories in the project settings, by clicking Option > C/C++
compiler > Preprocessor, according to the changes of project files.
 In this case, delete the directories framed in red and add the directories in green.



With all above steps done, the RT1170 M7 project successfully changes to an M4 project and the M4 example USB project is available for downloading and debugging. The RT1180 M33 project successfully changes to an M7 project and the M7 example USB project is downloading and debugging.

Enable More USB Examples on M4 Core for RT1170 or M7 Core for RT1180

3 MDK

1. Create an RT1170 M4/RT1180 M7 project

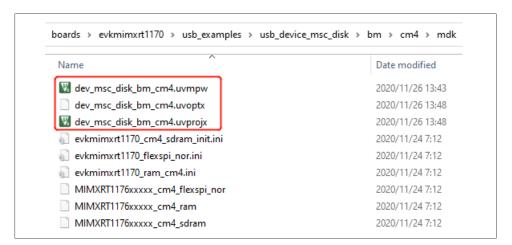
a. For RT1170, copy the *cm4* folder under *<install_dir>/boards/evkmimxrt1170/usb_examples/usb_device_hid_mouse/bm/cm4* to the folder where the example must be enabled.

In this case, copy the *cm4* folder under *<install_dir>/boards/evkmimxrt1170/usb_examples/usb_device_hid_mouse/bm/cm4* to the *bm* folder under *<install_dir>/boards/evkmimxrt1170/usb_examples/usb_device_msc_disk/bm.*

For RT1180, copy the *cm7*folder under *<install_dir>/boards/evkmimxrt1180/usb_examples/usb_device_hid_mouse/bm/cm7* to the folder where the example must be enabled.

In this case, copy the *cm7* folder under *<install_dir>/boards/evkmimxrt1180/usb_examples/usb_device_hid_mouse/bm/cm7* to the *bm* folder under *<install_dir>/boards/evkmimxrt1180/usb_examples/usb_device_msc_disk/bm*.

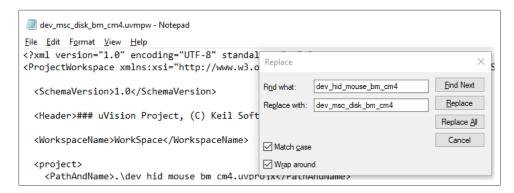
- b. For RT1170, open the *mdk* folder under *<install_dir>/boards/evkmimxrt1170/usb_examples/usb_device_msc_disk/bm/cm4/mdk*. For RT1180, open the *mdk* folder under *<install_dir>/boards/evkmimxrt1180/usb_examples/usb_device_msc_disk/bm/cm7/mdk*.
- c. For RT1170, change the filename dev_hid_mouse_bm_cm4 to dev_msc_disk_bm_cm4 respectively.



For RT1180, change the filename dev_hid_mouse_bm_cm7 to dev_msc_disk_bm_cm7 respectively.

- d. For RT1170, open the <code>dev_msc_disk_bm_cm4.uvmpw</code>, <code>dev_msc_disk_bm_cm4.uvoptx</code>, and <code>dev_msc_disk_bm_cm4.uvoptx</code> files with a text editor, such as notepad, notepad++, sublime or Visual studio code. For RT1180, open the <code>dev_msc_disk_bm_cm4.uvmpw</code>, <code>dev_msc_disk_bm_cm7.uvoptx</code>, and <code>dev_msc_disk_bm_cm7.uvoptx</code> files with a text editor, such as notepad, notepad++, sublime or Visual studio code.
- e. For RT1170, search and replace all dev_hid_mouse_bm_cm4 with dev msc disk bm cm4, and then save the files.

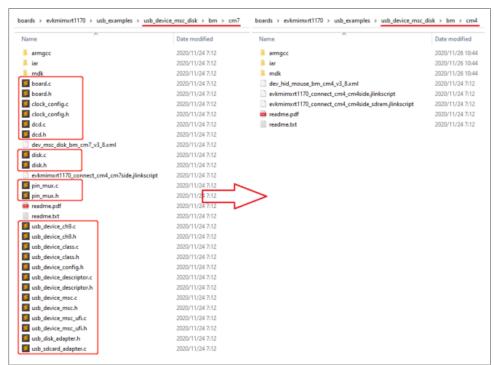
Enable More USB Examples on M4 Core for RT1170 or M7 Core for RT1180



For RT1180, search and replace all dev_hid_mouse_bm_cm7 with dev msc disk bm cm7, and then save the files.

2. Rearrange source files

- a. For RT1170, open the *cm4* folder under *<install_dir>/boards/evkmimxrt1170/usb_examples/usb_device_msc_disk/bm/cm4*, and delete all files with the .c and .h extension.
 - For RT1180, open the *cm7* folder under *<install_dir>/boards/evkmimxrt1180/usb_examples/usb_device_msc_disk/bm/cm7*, and delete all files with the .c and .h extension.
- b. For RT1170, copy files with the .c and .h extension in the cm7 folder under <install_dir>/boards/evkmimxrt1170/usb_examples/usb_device_msc_disk/bm/cm7 to the cm4 folder under <install_dir>/boards/evkmimxrt1170/usb_examples/usb_device_msc_disk/bm/cm4.



For RT1180, copy files with the .c and .h extension in the *cm33* folder under <install dir>/boards/evkmimxrt1180/usb examples/usb device msc disk/bm/cm33

Enable More USB Examples on M4 Core for RT1170 or M7 Core for RT1180

to the *cm7* folder under *<install_dir>/boards/evkmimxrt1180/usb_examples/usb_device_msc_disk/bm/cm7*.

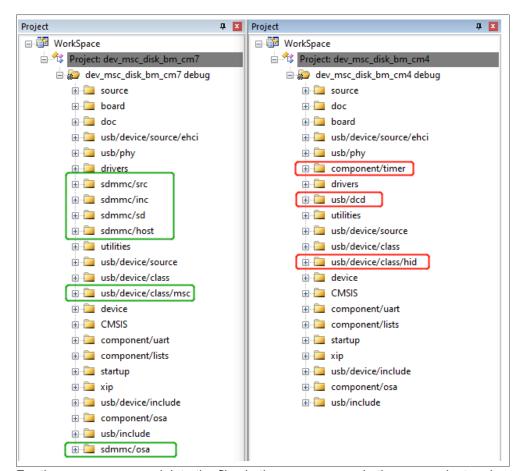
3. Rearrange project files

Note: The following steps are described for RT1170. However, these steps are also applicable for RT1180.

- a. Open dev_msc_disk_bm_cm7 and dev_msc_disk_bm_cm4 MDK project respectively. The two workspaces are respectively located in <install_dir>/boards/evkmimxrt1170/usb_examples/usb_device_msc_disk/bm/cm7/mdk and <install_dir>/boards/evkmimxrt1170/usb_examples/usb_device_msc_disk/bm/cm4/ mdk.
- b. Compare the whole project directory, delete groups that are in the cm4 project but not cm7. In the cm4 project, add groups that are in the cm7 project but not cm4.
- c. Compare the two groups with the same name. Delete files that are in the $\mathtt{cm4}$ project but not $\mathtt{cm7}$. Add files that are in the $\mathtt{cm7}$ project but not $\mathtt{cm4}$.

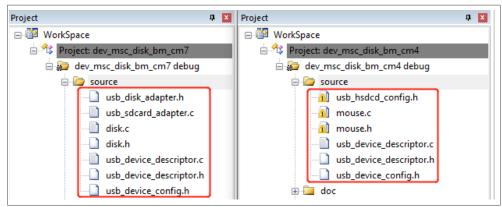
In this case

• Delete the groups framed in the red box in the cm4 project and add the directories framed in the green box to the cm4 project.

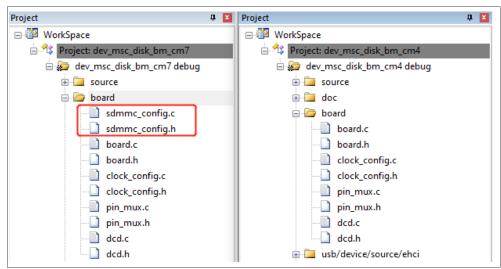


• For the source group, delete the files in the source group in the cm4 project and add files under <install_dir>boards/evkmimxrt1170/usb_examples/usb_device_msc_disk/bm/cm4 with the same name as in cm7 project.

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For the board group, add sdmmc_config source files to the board group in the cm4 project.

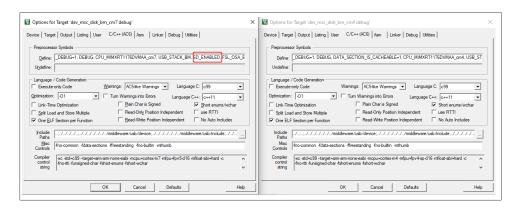


• For the drivers group, delete fsl_pit source files in the cm4 project and add fsl usdhc source files to the cm4 project.

4. Adjust project settings

Note: The following steps are described for RT1170. However, these steps are also applicable for RT1180.

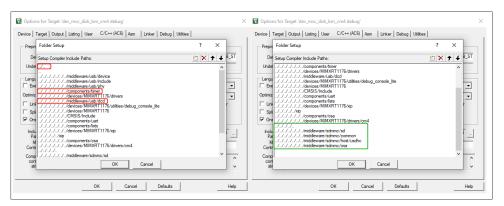
a. Compare the macro in the project settings by clicking Option -> C/C++. Add a macro that is in the cm7 project but not cm4.
 In this case, add the SD ENABLED macro to the cm4 project.



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b. Change the include paths in the project settings, by clicking **Option** > **C/C++**, according to the changes of project files.

In this case, delete the paths framed in the red box and add the paths framed in the green box.



With all above steps done, the RT1170 M7 project successfully changes to an M4 project and the M4 example USB project is available for downloading and debugging. The RT1180 M33 project successfully changes to an M7 project and the M7 example USB project is downloading and debugging.

4 ARMGCC

1. Create an RT1170 M4/RT1180 M7 project

- a. For RT1170, copy the *cm4* folder under *<install_dir>*/boards/evkmimxrt1170/usb_examples/usb_device_hid_mouse/bm/cm4 to the
 - folder where the example must be enabled.
 - In this case, copy <install_dir>/boards/evkmimxrt1170/usb_examples/usb_device_hid_mouse/bm/cm4 to <install_dir>/boards/evkmimxrt1170/usb_examples/usb_device_msc_disk/bm.
 - For RT1180, copy the *cm7* folder under *<install_dir>/boards/evkmimxrt1180/usb_examples/usb_device_hid_mouse/bm/cm7* to the folder where the example must be enabled.
 - In this case, copy <install_dir>/boards/evkmimxrt1180/usb_examples/usb_device_hid_mouse/bm/cm7 to <install_dir>/boards/evkmimxrt1180/usb_examples/usb_device_msc_disk/bm.
- b. For RT1170, open the *CMakeLists.txt* of the example. The file is located under <install_dir>/boards/evkmimxrt1170/usb_examples/usb_device_msc_disk/bm/cm4/armgcc.
 - For RT1180, open the *CMakeLists.txt* of the example. The file is located under <install_dir>/boards/evkmimxrt1180/usb_examples/usb_device_msc_disk/bm/cm7/ armgcc.
- c. For RT1170, search and replace all dev_hid_mouse_bm_cm4 with dev_msc_disk_bm_cm4, and then save the files.
 For RT1180, search and replace all dev_hid_mouse_bm_cm7 with dev_msc_disk_bm_cm7, and then save the files.

2. Rearrange source files

a. For RT1170, open the *cm4* folder under *<install_dir>/boards/evkmimxrt1170/usb_examples/usb_device_msc_disk/bm/cm4* folder and delete all files with the .c and .h extension.

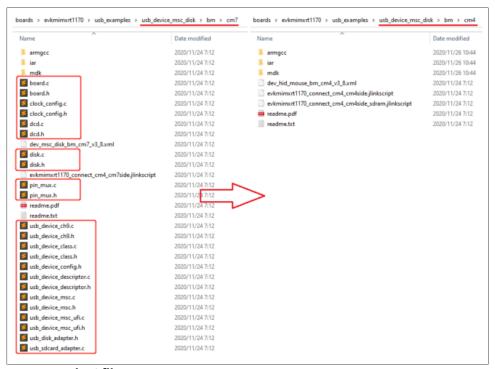
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For RT1180, open the *cm7* folder under *<install_dir>/boards/evkmimxrt1180/usb_examples/usb_device_msc_disk/bm/cm7* folder and delete all files with the .c and .h extension.

b. For RT1170, copy files with the .c and .h extension in the *cm7* folder under <install_dir>/boards/evkmimxrt1170/usb_examples/usb_device_msc_disk/bm/cm7 to the *cm4* folder under <install_dir>/boards/evkmimxrt1170/usb_examples/usb_device_msc_disk/bm/cm4.

For RT1180, copy files with the .c and .h extension in the *cm33* folder under <install_dir>/boards/evkmimxrt1180/usb_examples/usb_device_msc_disk/bm/cm33 to the cm7 folder under <install_dir>/boards/evkmimxrt1180/usb_examples/usb_device_msc_disk/bm/cm7.

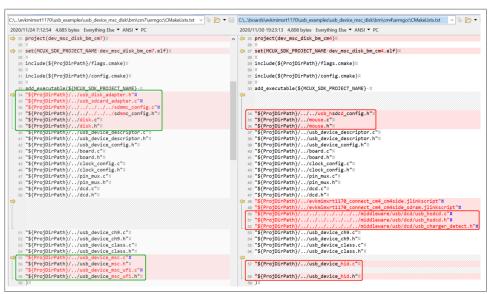


3. Rearrange project files

Note: The following steps are described for RT1170. However, these steps are also applicable for RT1180.

- a. Open the CMakeLists.txt of the two examples respectively. The two files are respectively located under <install_dir>/boards/evkmimxrt1170/usb_examples/usb_device_msc_disk/bm/cm7/armgcc and <install_dir>/boards/evkmimxrt1170/usb_examples/usb_device_msc_disk/bm/cm4/ armgcc.
- b. Search the **add_executable** section in the *cm7* and *cm4* projects. Delete files that are in the cm4 project but not cm7. Add files that are in the cm7 project but not cm4 to the cm4 project.
 - In this case, delete the files in red box and add the directories in the green box to the $\mbox{cm4}$ project.

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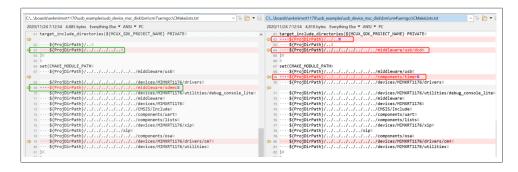
4. Adjust project settings

Note: The following steps are described for RT1170. However, these steps are also applicable for RT1180.

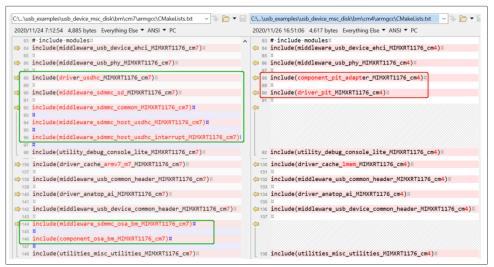
a. Search the target_include_directories, CMAKE_MODULE_PATH, and # include modules section one by one. Add macros that are in the cm7 project but not cm4 to the cm4 project.

In this case, remove the paths framed in the red box from the cm4 project and add the directories framed in the green box.

Note: Modify the include modules with the cm7 suffix to cm4. For example, modify driver_usdhc_MIMXRT1176_cm7 to driver usdhc MIMXRT1176 cm4.

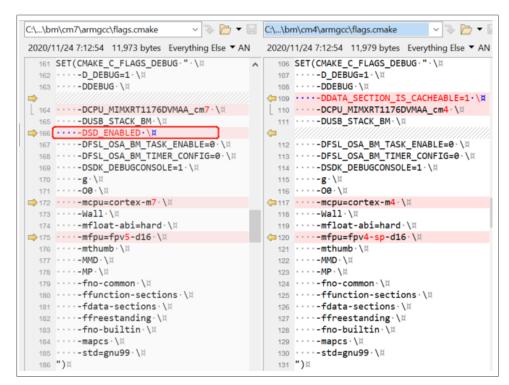


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- b. Open the flags.cmake of the two examples respectively. The two files are respectively located in <install_dir>/boards/evkmimxrt1170/usb_examples/usb_device_msc_disk/bm/cm7/armgcc and <install_dir>/boards/evkmimxrt1170/usb_examples/usb_device_msc_disk/bm/cm4/ armgcc.
- c. Search the CMAKE_C_FLAGS_DEBUG section in the cm4 and cm7 projects. Compare the macros and add the macro that is in the cm7 project but not cm4 to the cm4 project.

In this case, add the SD ENABLED macro to the cm4 project.



With all above steps done, the RT1170 M7 project successfully changes to an M4 project and the M4 example USB project is available for downloading and debugging. The RT1180 M33 project successfully changes to an M7 project and the M7 example USB project is downloading and debugging.

Enable More USB Examples on M4 Core for RT1170 or M7 Core for RT1180

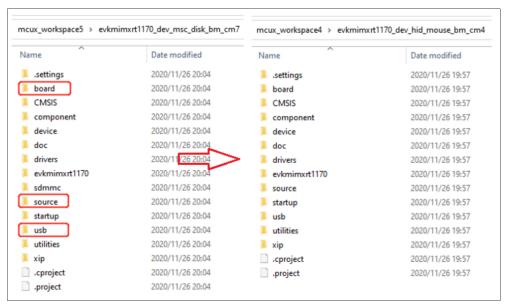
5 MCUXpresso IDE

1. Rearrange source files

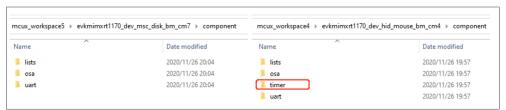
- a. For RT1170, import dev_msc_disk_bm_cm7 and dev_hid_mouse_bm_cm4 example. For RT1180, import dev_msc_disk_bm_cm33 and dev_hid_mouse_bm_cm4 example.
- b. Open the directory of the two examples in the file explorer.
- c. For RT1170, compare the whole project directory and add the folders that are in the cm7 project but not cm4 to the cm4 project. For RT1180, compare the whole project directory and add the folders that are in the cm33 project but not cm7 to the cm7 project.
- d. Compare the two folders. For RT1170, delete the files that are in the cm4 project but not cm7 and add the files that are in the cm7 project but not cm4 to the cm4 project. For RT1180, delete the files that are in the cm7 project but not cm33 and add the files that are in the cm33 project but not cm7 to the cm7 project.

In the RT1170 case.

• For the board, source, and usb folders, replace them in the cm4 project with the ones in the cm7 directory.

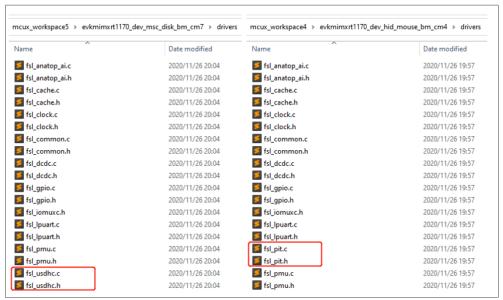


• For the component folder, delete the timer folder in the cm4 directory.

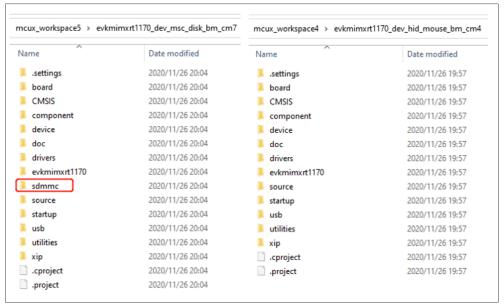


• For the drivers folder, delete fsl_pit source files in the cm4 project and add fsl usdhc source files to the cm4 directory.

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• For the sdmmc folder, copy it to the cm4 project.

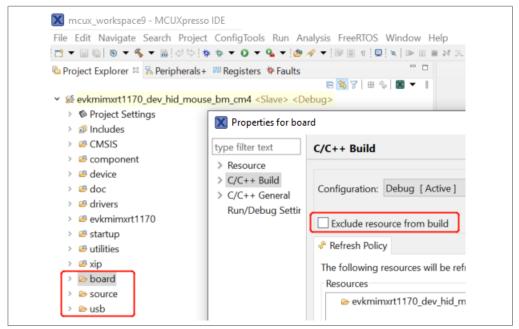


2. Rearrange project files

After the source files are updated, the project files are loaded to the ${\tt cm4}$ project of RT1170 or the ${\tt cm7}$ project of RT1180 automatically. No manual updates to the project files are required.

Due to the deletion in Rearrange source files, for the board, source and usb folders, an option must be deleted in the properties. Right click board -> properties -> C/C++build and uncheck Exclude resource from build. Perform the same operation in the source and usb folders. Take RT1170 as an example:

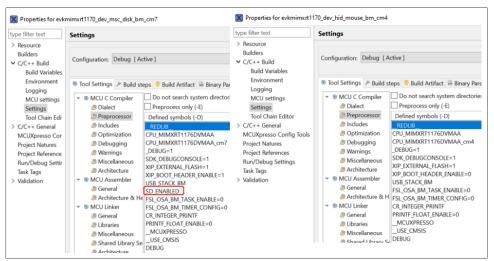
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3. Adjust project settings

Note: The following steps are described for RT1170. However, these steps are also applicable for RT1180.

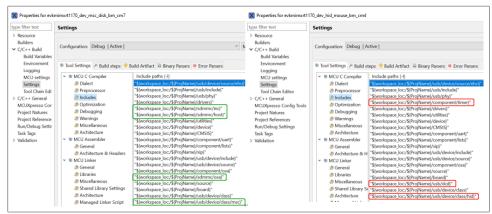
a. Compare the macro in the project settings, by clicking Properties -> C/C++ Build -> Setting -> MCU C Compiler -> Preprocessor. Add the macro that is in the cm7 project but not in cm4 to the cm4 project.
 In this case, the macro is SD_ENABLED.



b. Change the include paths in the project settings, by clicking Properties -> C/C+
 + Build -> Setting -> MCU C Compiler -> Includes, according to the changes of project files.

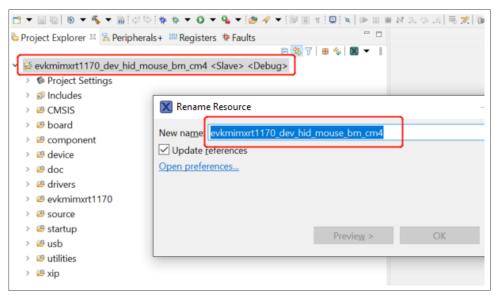
In this case, delete the paths framed in the red box and add the paths in the green box.

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4. Change project name

a. Right-click project name > rename, change the filename dev_hid_mouse_bm_cm4 to dev_msc_disk_bm_cm4, and then click OK.



With all above steps done, the RT1170 M7 project successfully changes to an M4 project and the M4 example USB project is available for downloading and debugging. The RT1180 M33 project successfully changes to an M7 project and the M7 example USB project is downloading and debugging.

6 Note

- 1. The above steps provide the method based on the dev_hid_mouse_bm example to enable the dev_msc_disk_bm example on the M4 core of RT1170 or on the M7 core of RT1180. For other examples of RT1170, similar way applies to change an M7 project to an M4 project. For other examples of RT1180, similar way applies to change an M33 project to an M7 project.
- 2. To enable FreeRTOS examples, refer to dev hid mouse freertos.
- 3. To enable USB host examples, refer to *host_hid_mouse_bm* or *host_hid_mouse_freertos*.

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7 Revision history

This table summarizes revisions to this document.

Table 1. Revision history

Revision number	Date	Substantive changes
0	10 July 2022	Initial release
1	20 November 2022	Editorial and layout update.

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