

Chapter 1

Computational Modeling of Antennas

1.1 Introduction

The finite-difference time-domain (FDTD) method is a computational procedure for solving Maxwell's equations that is based on a clever algorithm first proposed by Kane S. Yee in 1966 [1]. When Yee proposed his algorithm, the method was computationally intensive in terms of both storage and run time, and only problems of very modest size could be solved using the best computational facilities (mainframe computers). Since then the power of computers has steadily increased, as has the popularity of the FDTD method. The first comprehensive analyses of practical antennas using the method were performed during the early 1990's, and today such computations are routinely performed on personal computers [2]-[6].

The purpose of this article is to introduce the reader to the rudiments of the FDTD method as applied to practical antennas. It is hoped that after viewing the article, the reader will understand the power and limitations of the method and be in a position to decide whether or not the FDTD method is suitable for analyzing his/her antenna problem. Because of the limited space, we cannot provide the details for implementing the method in a computer program. Readers interested in writing their own program are referred to reference [7] for the details; others may wish to use one of the commercially available FDTD computer codes.

1.2 The Basic FDTD Algorithm

In the Yee algorithm, both space and time are discretized, with the increments in space for rectangular coordinates being $\Delta x, \Delta y, \Delta z$ and the increment in time being Δt [8], [9].

Figure 1.1: Schematic drawing showing the computational volume, FDTD spatial lattice, and unit cell.

Figure 1 is a schematic drawing showing a typical volume in which Maxwell's equations are to be solved. The volume is divided into unit cells each of volume. The electromagnetic constitutive parameters ($\epsilon = \epsilon_r \epsilon_0$, $\mu = \mu_r \mu_0$, σ) can vary from cell to cell, and they are used to define different objects within the volume¹. The six components of the electromagnetic field ($E_x, E_y, E_z; H_x, H_y, H_z$) are distributed over a unit cell (Yee cell) as shown in the inset. Notice that all of the components are located at different points within the cell, and the components of H are displaced from those of E by one half of a spatial increment, e.g., $\Delta x/2$. Although not shown in the figure, the components of H are also evaluated at points displaced by one half of a time increment, viz, $\Delta t/2$, from those of E .

The partial derivatives in Maxwell's equations are approximated by ratios of differences, for example,

$$\frac{\partial E_x}{\partial z} \approx \frac{\Delta E_x}{\Delta z}, \quad \frac{\partial H_y}{\partial t} \approx \frac{\Delta H_y}{\Delta t} \quad (1.1)$$

¹Here we mention only simple materials with constant permittivity, permeability, and electrical conductivity. In the FDTD method there are techniques to handle more complicated materials, such as those with dispersive and anisotropic properties [9].

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