



# Final Year Project Demo

Edge Compute Camera Trap for Object Detection



# This presentation

- Covers the problem addressed and my solution
- Outlines the approach taken to create the solution
- Demonstrates the final prototype

# Camera traps

- Used in various ecological studies
- Track movement
- Observe behaviour and patterns
- Estimate populations

# Disadvantages

- Time to analyse each manually
- False trigger events

# Application of AI

- Can be used to go through images and detect animals and species in each
- Reduces time taken to analyse pictures
- Saves man hours

# Disadvantages of AI

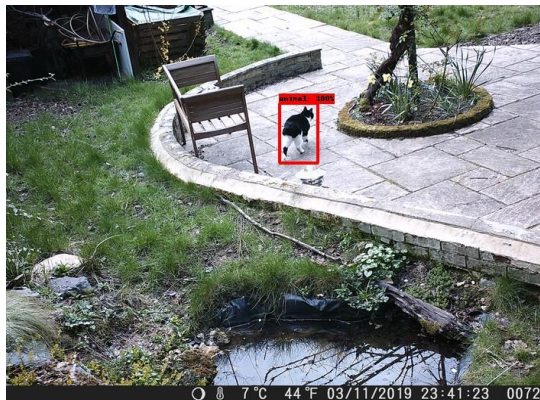
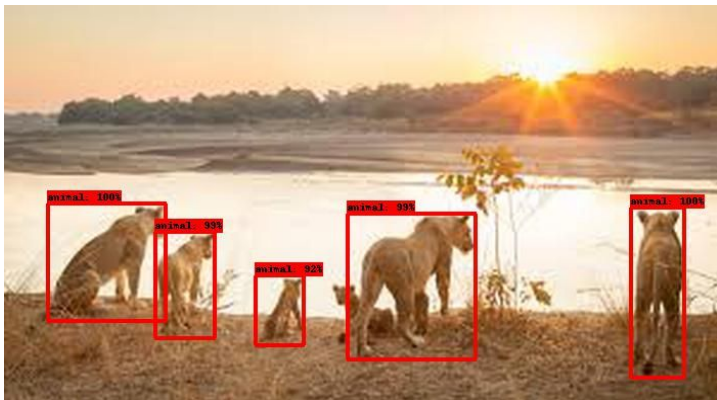
- Often done at offsite data centers
- Large amount of data takes a long time to transfer back and forth
- Sanctuaries often don't have good internet connection for this

# My Solution

- A camera trap that can run AI locally
- Saves man hours for analyzing images
- Saves time spent transferring to data centers
- Uses just one Animal class to help identify wider variety of species

# Approach

- First tested MegaDetector by MicroSoft AI for Earth team
- Was not compatible with Intel Neural Compute Stick 2 (NCS2)





# Neural Network Version 1

- Trained all versions using dataset from LILA BC
- Tensorboard results looked promising
- This version not compatible with NCS2
- Erroneous detection and subject not detected





## Version 2

- Better for correct detections
- False positives as well
- Faster R-CNN not compatible with code that was written for SSD



## Version 3

- Discovered Google Colab and got access to an Nvidia Tesla T4
- Roughly followed a guide for training Tensorflow 1 models
- Manually drew bounding boxes for over 250 images
- After training there were lots of false positive results
- The same occurred for training twice as long





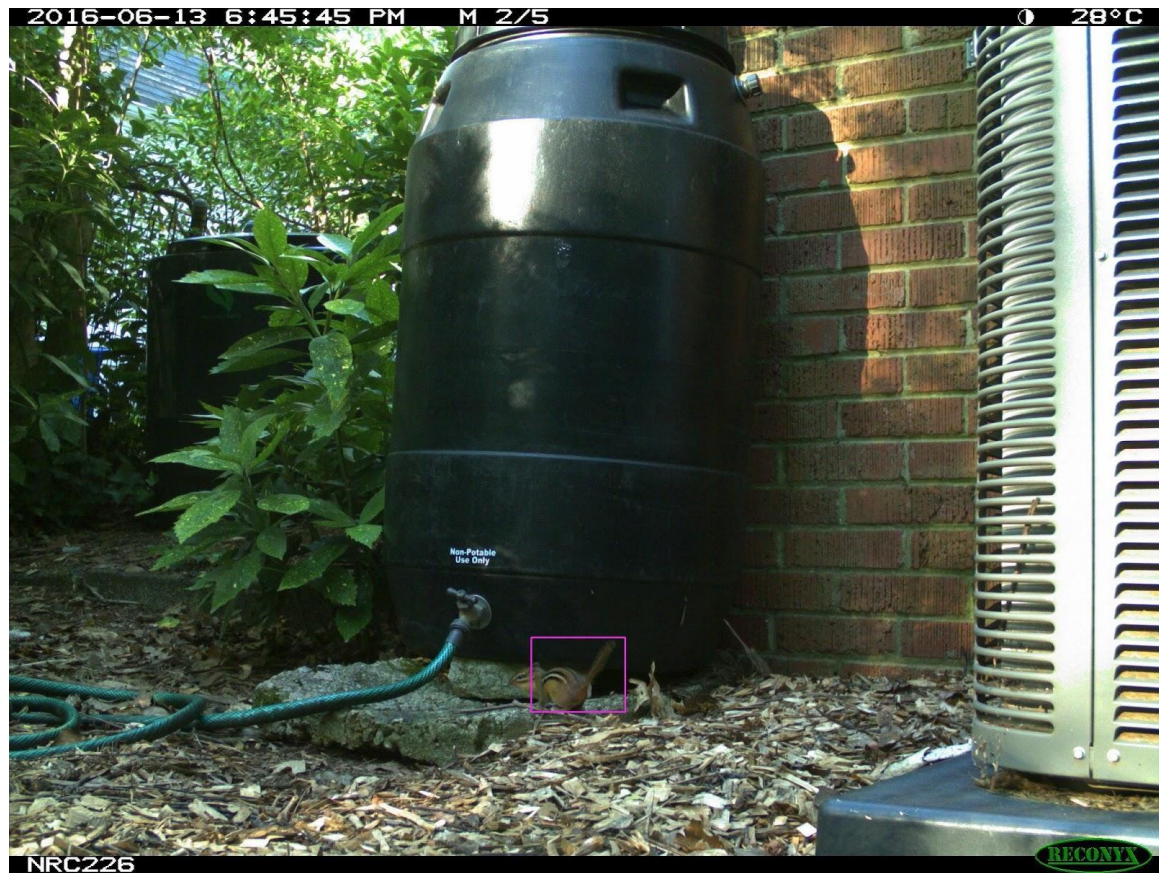




## Version 4

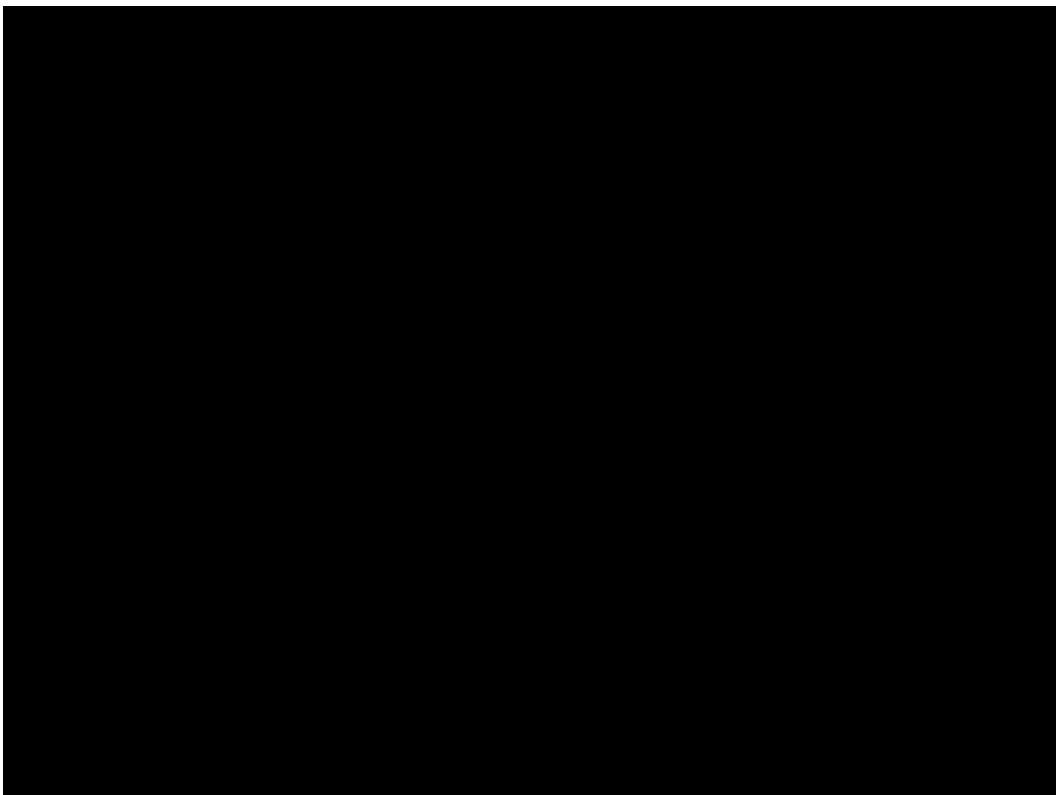
- Changed parameters to make SSD Inception V2 model similar to Faster R-CNN Inception V2 model
- Score converter changes to SOFTMAX
- Learning rate changed from momentum based to manual step with much lower values
- Model training and testing was a success











# To Conclude

- A working Neural Network was created that can detect a variety of species
- This was successfully incorporated with software and hardware to create a working system
- The camera trap can capture images, run inference on them and sort them based on detection