EDtoolbox - Input data structs

geoinputdata

Five alternatives exist for specifying the struct geoinputdata:

- 1. If the field .freefieldcase is given the value 1, then no scattering object will be defined and all other fields are irrelevant.
- 2. An external .cad-file can be specified in the field .geoinputfile.
- 3. If the field .geoinputfile is not specified, then the fields .corners and .planecorners should give the geometry data (but see alt. 4).
- 4. If neither of the two alternatives above apply (e.g., if the entire struct is left empty), then a file opening window will appear, and a .cad-file can be selected.
- 5. If both .geoinputfile, and .corners+.planecorners are specified, priority will be given to the .geoinputfile.

Field name	Description
.geoinputfile	(Optional) This field should be given the
- Pagarahani II	file name (with path) of a .cad-file
.corners	(Optional) A matrix of size [ncorners,3],
	giving the x-, y-, and z-coordinates of each
	corner.
.planecorners	(Optional) A matrix of size
	[nplanes,nmaxcornersperplane]. For
	each plane, the corners should be given
	in the counterclockwise direction when
	looking at the plane from the active side.
	Each row might need extra zeros to give
	all rows the same number of elements.
.planerefltypes	(Optional) Allowed values are 1 $(default =$
	rigid), 0 (ideal total absorption), and -1
	(soft/pressure-release).
.listofedgestoskip	(Optional) Some edges can be deacti-
	vated by using this parameter, which
	can have one or two columns. Single-
	$\operatorname{column} \Rightarrow \operatorname{list}$ of edge numbers will be
	deactivated. Two columns \Rightarrow each row
	has a corner number pair, the edge be-
	tween which will be deactivated. Takes
	precedence over .firstcornertoskip and
	.listofcornerstoskip. Default value []
6:	(empty).
.firstcornertoskip	(Optional) All edges with at least one corner with a number same or larger
	than .firstcornertoskip will be deacti-
	vated. Default value 1e6.
.listofcornerstoskip	(Optional) All edges with at least
.11storcornerstoskip	one corner belonging to the list
	.listofcornerstoskip will be deactivated.
	Default value [] (empty).
.planeseesplanestrategy	(Optional) This parameter is irrelevant for
·pranosospranosoraoog)	convex-shaped scattering objects but is
	preparing for non-convex objects. If this
	parameter is given the value 1, then a
	plane-to-plane visibility check is done by
	checking plane-midpoint to plane-midpoint
	visibility. Default value 0.
.freefieldcase	(Optional) If this parameter is given the
	value 1, then a free-field case will be run
	and no scattering object will be defined.
	Default value 0.

envdata

Field name	Description
.cair	(Optional) Should be the speed of sound in
	m/s. Default value 344.
.rhoair	(Optional) Should be the density of the
	medium, in kg/m ³ . Default value 1.21.

controlparameters

Field name	Description
Maximum one of the three	Chooses which calculation method should
following parameters can be	be used. If none is set to one, then only
set to one:	the geometry part will be run: identify the
	edges of the geometry model.
.docalctf	Determines if transfer functions will be
	computed, with the ESIE method for
	higher-order diffraction.
.docalctf_ESIEBEM	Determines if transfer functions will be
	computed, with the ESIEBEM method.
.docalcir	Determines if impulse responses will be
	computed, with the "separate diffraction
	orders" method.
.frequencies	(Required if .docalctf = 1 or
	.docalctf_ESIEBEM=1). A vector of
	frequency values that computations will
	be made for.
.directsound	(Optional) If this parameter is set to 0, the
	direct sound will not be computed and the
	result variable tfdirect or irdirect will be
	empty. Default value 1.
.skipfirstorder	(Optional) If this parameter is set to 1
. BRIPIII BUOI GCI	the direct sound, specular reflection, and
	first-order diffraction will not be computed
	and their respective output variables will
.	be empty. Default value 0.
.Rstart	(Optional) Determines the phase of the fi-
	nal transfer functions (or the definition of
	the time zero in TD calculations). Default
	value 0.
.difforder	(Optional) Specifies how many orders of
	diffraction should be included. ² Default
	value 10.
.discretizationtype	Determines how the edges will be dis-
	cretized: $0 \Rightarrow a$ uniform discretization
	$2 \Rightarrow$ Gauss-Legendre discretization. The
	value 1 is obsolete/not used. Default value
	2.
.ngauss	Specifies the number of quadrature points
S	along the longest edge, for the ESIE and
	ESIEBEM methods. It will be scaled down
	linearly based on the length of each edge
	with a minimum of 2. Recommended value
	is at least 3 quadrature points per wave-
	length, which has to be converted manually
	to a number of quadrature points. Default
	value 16.
aumfo.compuggo	
.surfacegaussorder	For the ESIEBEM method, this parameter distance in the second state of the second seco
	ter determines how many intermediate re-
	ceivers will be placed across each plane. A
	value of 5 implies 5*5 surface receivers for
	the largest plane, and progressively fewer
	for smaller planes. Default value 5.
.fs	Determines the sampling frequency. De-
	fault value 44100.
.savealldifforders	If this parameter is set to 1, then results are
	stored for each diffraction order. Default value

 $[\]overline{\ }$ To simulate an incoming plane wave with amplitude 1, and phase zero, at the origin, then .Rstart should be set to the distance to the far-away monopole source. See also the description of the input data struct Sinputdata.

source. See also the description of the input data struct Sinputdata. 2 For time-domain (impulse response) calculations, ${\tt difforder}$ can not be higher than 6.

Sinputdata

D ' ' '
Description (Required) A matrix of size [nsources,3], giving
(Neglinear) A matrix of size [insolices,5], giving the x-, y-, and z- coordinates of each source. (Optional) If this value is set to 1, the contributions from all sources will be added and saved in a single transfer function or impulse response, after being multiplied by the values
in the matrix .sourceamplitudes. Default value 0. (Optional) A matrix of amplitudes, size [nsources,nfreq], that each source is multiplied with. Using this, together with .doaddsources=1, a vibration pattern on a surface can be simulated. ² Default value
ones(nsources,nfreq). (Optional) If n sources and n receivers are specified, one can choose to compute the response only for source 1 to receiver 1, source 2 to receiver 2, etc by setting this parameter to 0. This is relevant for computing monostatic
backscattering. Default value 1. (Optional) Can be either monopole (default) or polygonpiston.
(Optional) but (Required) if .sourcetype is polygonpiston. Format as for geoinputdata.corners, that is, x, y, z of all npistoncorners piston corners, stored in a matrix of size [npistoncorners,3]. Please note that these coordinates must be given values that fulfill the plane equation of the plane specified in the field .pistonplanes. The EDtoolbox does not (as of version 0.501) check this for you.
(Optional) but (Required) if .sourcetype is polygonpiston. Matrix of size [npistons,maxncornersperpiston], where each row contains the 3,4,5, corner numbers for each piston. The order must follow the same right-hand rule as the planecorners: if you put your right hand to point in the direction of the plane and piston normal vector, then your curved fingers should point in the direction of the corner order. This can also be expressed as counterclockwise order when one is looking at the piston from the outside of the scattering object. Please note that if the pistons have different numbers of corners, the matrix in .pistoncornernumbers must get zeros at the end of each row which has fewer than
maxncornersperpiston values. (Optional) but (Required) if .sourcetype is polygonpiston. List of size [npistons,1], which gives the plane number (defined in the list geoinputdata.planecorners) that each piston belongs to.
(Optional); only relevant if .sourcetype is polygonpiston. A number which will have slightly different meanings for different piston types. The default value is 3. · For a rectangular piston: the number of gauss quadrature points along one dimension of each piston. The total number of gauss quadrature points is thus .pistongaussorder ² . · For a triangular piston: .pistongaussorder with values [1, 2, 3, 4, 5, 6, 7, 8] gives, respectively, [1, 3, 4, 6, 7, 12, 16, 16] quadrature points. · For a regular polygon (approximating a circle), quadrature points will be distributed in .pistongaussorder concentric circles with linearly distributed radii. For each radius, the number of quadrature points is [1, 8, 16, 24, 32,] so that for .pistongaussorder = [1, 2, 3, 4, 5,], the total number of points is, respectively, [1, 9, 25,49, 81,].

Rinputdata

Field name	Description
.coordinates	(Required) A matrix of size [nreceivers,3],
	giving the x-, y-, and z- coordinates of each
	receiver.1

 $^{^{1}}$ If a receiver is placed at a surface, it needs to be placed a tiny distance away from the surface, say $10^{-5}\,$ m.

Filehandlingparameters

Field name	Description
.outputdirectory	(Optional) but (Required) if geometry is defined as .corners and planecorners. All result files will be saved in this directory. If not spec-
.filestem	ified, a folder named "results" will be made in the folder of the cad-file. (Optional) but (Required) if geometry is de- fined as .corners and planecorners. All result files will start with this text string. If not spec- ified, this field will be given the name of the cad-file.
.suppressresultrecycling	(Optional) $0 \Rightarrow$ all result files will be inspected for possible recycling. Default value 0.
.savecadgeofile	(Optional) $1 \Rightarrow$ the contents of the .cad-file will be saved in a _cadgeo.mat file. Default value 0.
.saveSRdatafiles	(Optional) $1 \Rightarrow$ the visibility of planes and edges, as seen from sources and receivers, is stored in _Sdata.mat and _Rdata.mat files. Default value 1.
.saveeddatafile	(Optional) $1 \Rightarrow$ the edgedata struct is saved in an _eddata.mat file. Default value 1.
.saveed2datafile	(Optional) 1 \Rightarrow the edgetoedgedata struct is saved in an _ed2data.mat file. Default value 1.
$. { t save submatrix} { t data}$	(Optional) 1 \Rightarrow the submatrixdata struct is saved in a _submatrixdata.mat file. Default value 1.
.saveinteqsousigs	(Optional) 1 \Rightarrow the edge source signals are saved in a _sousigs.mat file. Default value 0.
.loadinteqsousigs	(Optional) $1 \Rightarrow$ previously calculated, and saved, edge source signals are loaded and reused. Default value 0.
$. {\tt savepathsfile}$	(Optional) 1 ⇒ the lists of possible direct sound, specular reflections, and first-order diffractions, are saved in a _paths.mat file. Default value 1.
.savehodpaths	(Optional) 1 ⇒ the lists of possible higer- order diffractions are saved in a _hodpaths.mat file. Used only by EDmain_convex_time. Default value 0.
.savelogfile	(Optional) $1 \Rightarrow$ a log text-file is saved, see Section ??. Default value 1.
.savediff2result	(Optional) $1 \Rightarrow$ the results for second- order diffraction are saved sepa- rately, in the form of the variable extraoutputdata.tfinteqdiff_nodiff2. De- fault value 0.
.showtext	(Optional) $1\Rightarrow$ some progression text is printed out on screen. If the value is set to 0, no text is printed out on the screen. If values higher than 1 are set, then even more detailed information is printed out on screen.

If a source is placed at a surface, it needs to be placed a tiny distance away from the surface, say 10^{-5} m. 2 To simulate an incoming plane wave with amplitude 1 at the origin, then .sourceamplitudes should be given the value "distance", where "distance" is the distance to the far-away monopole source. See also the description for the input data struct controlparameters. It is also possible to implement this by scaling the resulting transfer functions/impulse response accordingly.