# On Deciding $\beta'$ from an $\mathcal{H}$ Machine Through a Self Validating Process

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February 27, 2015

#### Abstract

This paper contains a description for the configuration of a self-validating Turing Machine. This description allows such a machine to solve for  $\beta'$ .

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### 1.1 Introduction

This paper contains a description for the configuration of a self-validating Turing Machine. Solving for  $\beta'$  is the equivalent to finding an exception to diagonalization.

#### 1.2 Preliminaries

The terms  $Circular\ Machine$  and  $Circle-free\ Machine$  are no longer used by convention. However, it is convenient to note here that a  $Circular\ Machine$  is unsatisfactory due to it's inability to continue based on the rules of a Universal Turing Machine,  $\mathscr{U}$ , set forth in Turing's Paper on the Entscheidungsproblem. In addition, a  $Circle-free\ Machine$  is satisfactory based on those same rules and an ability to continue enumerating a calculation set. [1]

A Standard Description or S.D. is the rule set for any given Turing Machine  $\mathcal{M}$  in a standard form. By creating a standard, the rule sets themselves can be used to create a Description Number or D.N. which itself is readable by a Universal Turing Machine,  $\mathcal{U}$ , as an instruction set. [1]

From Turing's paper: "Let  $\mathscr{D}$  be the Turing Machine which when supplied with the Standard Description (S.D.) of any computing machine  $\mathscr{M}$  will test this S.D. and if  $\mathscr{M}$  is circular will mark the S.D. with the symbol "u" and if it is circle free, will mark it with 's' for 'unsatisfactory' and 'satisfactory' respectively. By combining machines  $\mathscr{D}$  and  $\mathscr{U}$ , we could construct a machine  $\mathscr{H}$  to compute the sequence of  $\beta$ '" [1]  $\mathscr{H}$  is circle free by construction since each section after the Turing machine moves to the next section, is itself finite and the calculations should take a finite number of steps. [1]

It is not in the scope of this paper to provide an in depth description of computable numbers and their processing. The only additional preliminary is that one accepts the Church-Turing thesis that says every function which is calculable, is a computable function. For an in depth understanding of Turing Machines,

the Universal Turing Machine and the history behind it's development, please read *The Annotated Turing* by Charles Petzold. [1]

## 1.3 Turing's Claim

In the eighth section of Turing's paper on the Entscheidungsproblem, Turing claims that  $\beta'$  can not be determined vis a vis the following reason:

"The instructions for calculating the R(K)-th [figure] would amount to 'calculate the first R(K)-th figures computed by  $\mathscr{H}$  and write down the R(K)-th'. This R(K)-th would never be found. I.e.  $\mathscr{H}$  is circular..." [1]

This is because, since  $\mathscr{H}$  relies on subroutines, when it reaches and tries to evaluate K, it must call itself, which provides instructions on reading inputs from 1 to K-1 in order to call the R(K)-th figure, but it can never get there, because it keeps repeating it's own instruction loop. [1] The question is, however, is there a Turing Machine which can recognize itself arbitrarily when it reaches it's own Description Number (D.N.), such that  $\mathscr{H}$  prints  $\beta'$ ?

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#### 2.1 Supermachine

Now, let us determine that  $\mathscr{H}'$  is a controller machine with a D.N. of K'. It controls two different  $\mathscr{H}$  machines:  $\mathscr{H}_0$  and  $\mathscr{H}_1$ .  $\mathscr{H}_0$  and  $\mathscr{H}_1$  have the same ability to determine "u" or "s", except  $\mathscr{H}_0$  tests as Turing describes, from 1 counting upwards and  $\mathscr{H}_1$  tests tests from the twos complement of whatever number is being tested by  $\mathscr{H}_0$  and subtracts one instead of adding one to find the next number. They take each input simultaneously until the controller machine finds a redundancy. They each have a unique D.N. of  $K_0$  or  $K_1$  through an identifier string which differentiates the two  $\mathscr{H}$  machines from each other. The key requirements for  $\mathscr{H}'$  include storing output value pairs from the two connected  $\mathscr{H}$  machines, recognizing redundancies and recognizing when a redundancy is met with an existing nil key value on the input.

Let  $\mathscr{H}_s$  be the supermachine that is the combination of all three  $\mathscr{H}$  Machines and  $K_s$  is the D.S. for the supermachine.

Initialize the identifier strings such that  $K_1 < K_0$ .

Let the number of bits in the two complement be determined by n number of bits in  $K_0$ .

Let the twos complement be the number  $c=2^n-1$ , If  $c-K_0>K_1$ , then re-initialize the identifier string in either  $K_0$  or  $K_1$  such that  $c-K_0< K_1$ . This guarantees that  $\mathscr{H}_0$  will read  $K_1$  before  $\mathscr{H}_1$  reads  $K_1$  and also guarantees  $\mathscr{H}_1$  will read  $K_0$  before  $\mathscr{H}_0$  reads  $K_0$ . When the machines have determined the field, let the controller  $\mathscr{H}^*$  contain a controller function which stores the value pairs of  $\mathscr{H}_0$  and  $\mathscr{H}_1$ , checks for a redundancy on the input and proceeds to utilize machine  $\mathscr{H}_0$  to proceed upwards from c+1.

<sup>&</sup>lt;sup>1</sup>by recognizing itself arbitrarily, we mean that it can recognize itself even if K is dynamic and changes as the program continues to run, or there is no initializer that feeds a static K to be recognized by a sngle read instruction that skips K and just rubber stamps apportal.

At this point it should be noted that the  $\mathscr{H}'$  controller takes it's instructions from  $\mathscr{H}_0$  and  $\mathscr{H}_1$  .

## 2.2 $\beta'$ is Decidable

*Proof.* At the point K' is received as an input, it is determined satisfactory by either  $\mathcal{H}_0$  or  $\mathcal{H}_1$  without calling either machine.

Finally,  $K_s$ , which describes the super machine  $\mathscr{H}$  is read by  $\mathscr{H}'$  and like all other strings, is stored with a value of nil until  $\mathscr{H}_0$  or  $\mathscr{H}_1$  returns a value for  $\beta'$  at that location.  $K_s$  is sent to be verified by  $\mathscr{H}_0$ , which when  $\mathscr{H}'$  calls  $K_s$  under the iteration, is recognized as redundant by  $\mathscr{H}'$  in the data store, but because th value is already written as null, the controller stores the fact this process occurred, sends the same  $K_s$  to  $\mathscr{H}_1$ , which verifies the redundancy and nil value.  $\mathscr{H}'$  now self-verifies the input  $K_s$  as it's current operating D.N., provides a value of "s" and moves to evaluate section  $K_s + 1$ .

Therefore,  $\beta'$  is decidable for any Description Number given some  $\mathscr{H}$  Machine.

## References

[1] Charles Petzold *The Annotated Turing* 2008: Wiley Publishing, Indianapolis, IN.