

Practical Session Report
ADVANCED MACHINE LEARNING:
Kernel Methods

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Contents

1	Kernel-PCA	3
1.1	Implementation	3
1.1.1	PCA	3
1.1.2	K-PCA : kernels definition	3
1.1.3	K-PCA	3
1.2	Moons	5
1.2.1	Sample	5
1.2.2	PCA	5
1.2.3	K-PCA : Linear	5
1.2.4	K-PCA : Gaussian	6
1.2.5	K-PCA : Polynomial	7
1.3	Circles	7
1.3.1	Sample	7
1.3.2	PCA	7
1.3.3	K-PCA : Linear	8
1.3.4	K-PCA : Gaussian	8
1.3.5	K-PCA : Polynomial	9
1.4	IRIS	9
1.4.1	Sample	9
1.4.2	PCA	10
1.4.3	K-PCA : Linear	10
1.4.4	K-PCA : Gaussian	10
1.4.5	K-PCA : Polynomial	11
2	Kernel-KMeans	11
2.1	Regular KMeans implementation	11
2.2	Kernel KMeans	12
3	Logistic Regression	12
4	One class SVM and Maximum Enclosing Ball	12
4.1	A first implementation	12
4.2	Running on IRIS dataset	13

1 Kernel-PCA

Our own implementation of PCA and Kernel-PCA are respectively available in `PCA.py`, `kPCA.py`.

1.1 Implementation

1.1.1 PCA

```
def PCA(X,n_components):
    # data normalization
    X_centered = X - np.mean(X)
    X_normalized = X_centered / np.std(X)

    # covariance matrix
    cov = np.cov(X_normalized.T)

    # eigen values & vectors
    eigen_values, eigen_vectors = np.linalg.eig(cov)

    # ordering the eigen vectors by decreasing values
    eig_vals_order = np.argsort(eigen_values)[::-1]
    eigen_vectors_decr = eigen_vectors[:,eig_vals_order]

    # creating the n_components PCs over X
    PCs = np.dot(X,eigen_vectors_decr[:,0:n_components])

    return(PCs)
```

1.1.2 K-PCA : kernels definition

```
def linear(x,y,sigma):
    return np.dot(x,y)

# gaussian rbf kernel
def gaussian(x,y,sigma):
    n = np.linalg.norm(x-y)
    # return np.exp(- (n * n) / (2 * sigma * sigma))
    return np.exp(-sigma * n * n)

def poly(x,y,sigma):
    d = np.dot(x,y)
    #return np.pow(d,2)
    return (d + 1) * (d + 1)

def kernel(X,function,sigma):
    n = np.size(X,0)
    K = np.zeros([n,n])

    for i in range(n):
        for j in range(n):
            K[i,j] = function(X[i,:],X[j:],sigma)

    # centering K
    Kn = np.ones([n,n])/n
    K = K - Kn * K - K * Kn + Kn * K * Kn

    return(K)
```

1.1.3 K-PCA

```
def k_pca(X,y,function,sigma):

    # data normalization
    X_centered = X - np.mean(X)
    X_normalized = X_centered / np.std(X)
```

```

K = kernel(X_normalized,function,sigma)

# covariance matrix
cov = np.cov(K.T)

# eigen values & vectors
# which are NOT ALWAYS ordered descreasingly
eigen_values, eigen_vectors = np.linalg.eig(cov)
eig_vals_order = np.argsort(eigen_values)[::-1]
eigen_vectors = eigen_vectors[:,eig_vals_order]

# PCA in ONE dimension
X_new = np.dot(K,eigen_vectors[:,0])
plt.scatter(x=X_new[y==0],y=np.ones(len(X_new[y==0])),color='blue',alpha=.5)
plt.scatter(x=X_new[y==1],y=np.ones(len(X_new[y==1])),color='red',alpha=.5)
plt.show()

# PCA in TWO dimensions
X_new = np.dot(K,eigen_vectors[:,0:2])
plt.scatter(x=X_new[y==0,0],y=X_new[y==0,1],color='blue',alpha=.5)
plt.scatter(x=X_new[y==1,0],y=X_new[y==1,1],color='red',alpha=.5)
plt.show()

# PCA in THREE dimensions
X_new = np.dot(K,eigen_vectors[:,0:3])
X_new = X_new.astype('float64')
fig = plt.figure()
asub = fig.add_subplot(111,projection='3d')
ax = X_new[y==0,0]
bx = X_new[y==0,1]
cx = X_new[y==0,2]
ay = X_new[y==1,0]
by = X_new[y==1,1]
cy = X_new[y==1,2]
asub.scatter(ax,bx,cx,c='blue',marker='o',alpha=.5)
asub.scatter(ay,by,cy,c='red',marker='o',alpha=.5)
plt.show()

return K

```

1.2 Moons

1.2.1 Sample

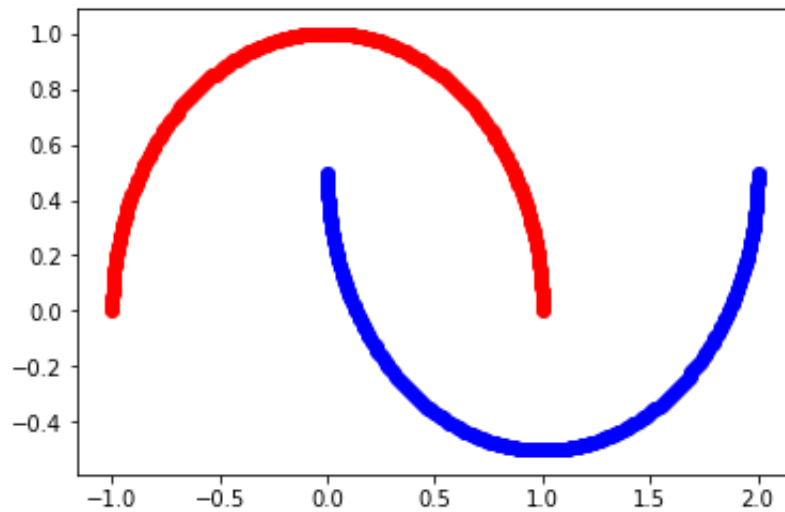


Figure 1: Moons sample

1.2.2 PCA

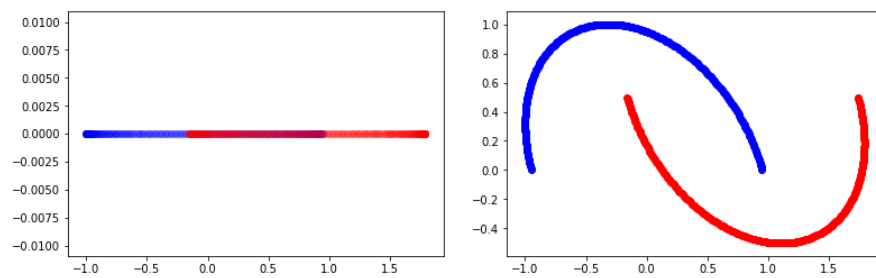


Figure 2: PCA results in one & two dimensions

Processing time for PCA : 0.35378100000000146 seconds

The classic PCA didn't work well on moons.

1.2.3 K-PCA : Linear

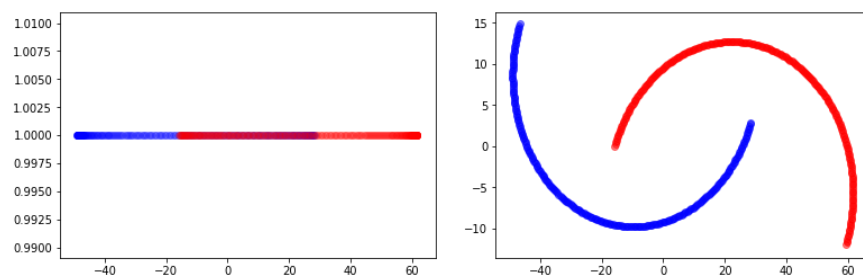


Figure 3: K-PCA results using linear kernel in one & two dimensions

Processing time (moons linear) : 1.903731 seconds

Obviously, the linear kernel didn't work too. But the processing time is considerably higher.

1.2.4 K-PCA : Gaussian

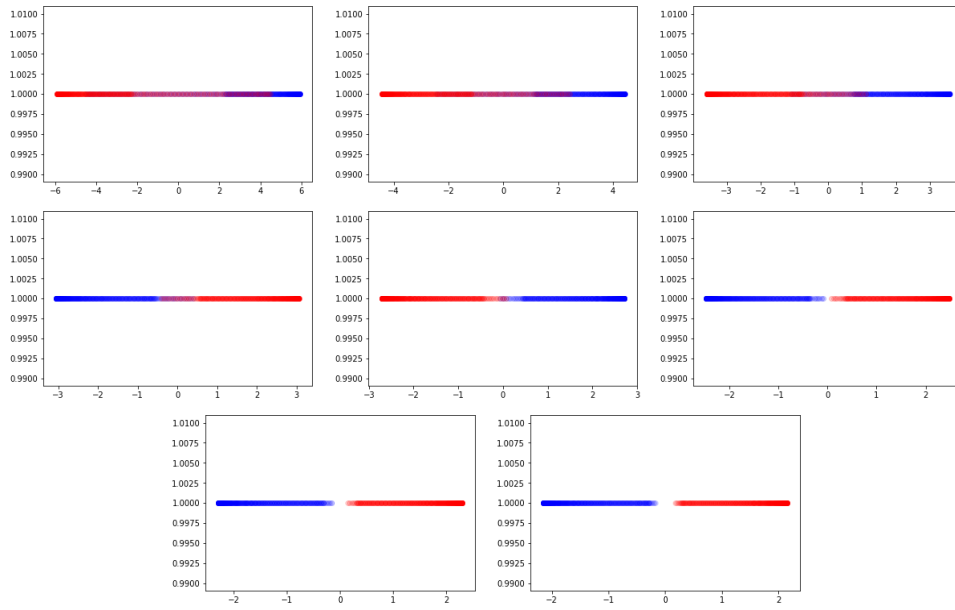


Figure 4: K-PCA results using gaussian kernel in one dimension
We start sigma at 1 and increase it by step of 1.

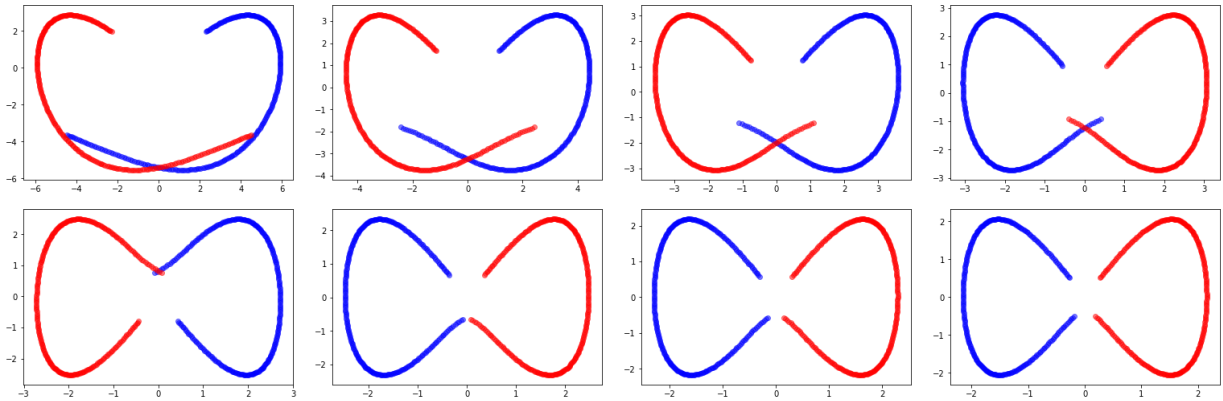


Figure 5: K-PCA results using gaussian kernel in two dimension
We start sigma at 1 and increase it by step of 1.

Processing time (moons gaussian 8) : 5.175716999999999 seconds

The gaussian work pretty well on the moons dataset. The processing time is 10 times the PCA ones.

1.2.5 K-PCA : Polynomial

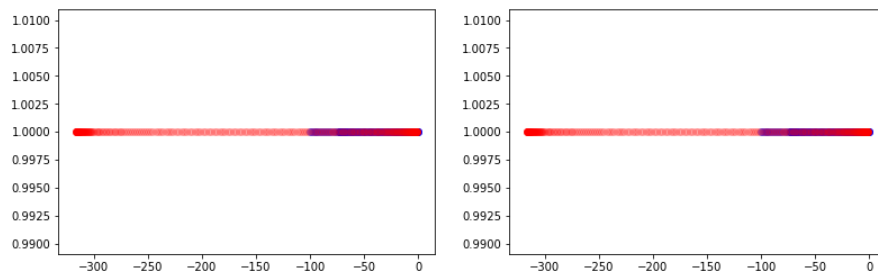


Figure 6: K-PCA results using polynomial kernel in one & two dimensions

Processing time (moons poly) : 2.4073649999999986 seconds

1.3 Circles

1.3.1 Sample

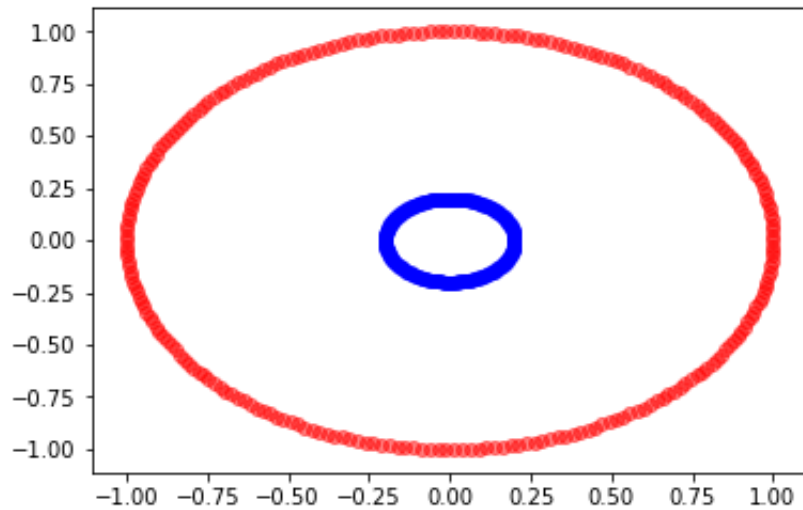


Figure 7: Circles sample

1.3.2 PCA

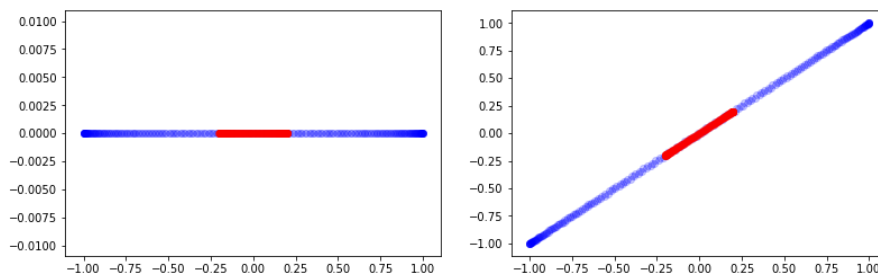


Figure 8: PCA results in one & two dimensions

Processing time for PCA : 0.36244999999999955 seconds

As expected, the classic PCA didn't work well on circles too.

1.3.3 K-PCA : Linear

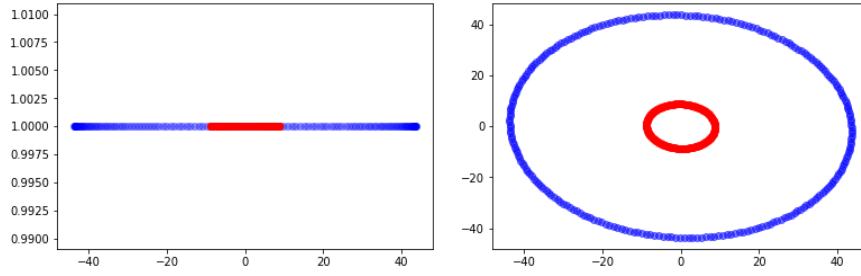


Figure 9: K-PCA results using linear kernel in one & two dimensions

Processing time (moons linear) : 1.9496979999999837 seconds

1.3.4 K-PCA : Gaussian

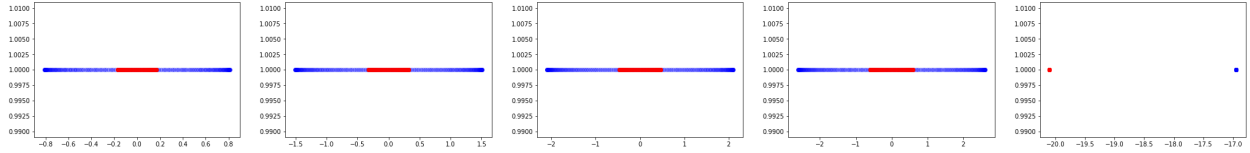


Figure 10: K-PCA results using gaussian kernel in one dimension
We start sigma at 0.1 and increase it by step of 0.01.

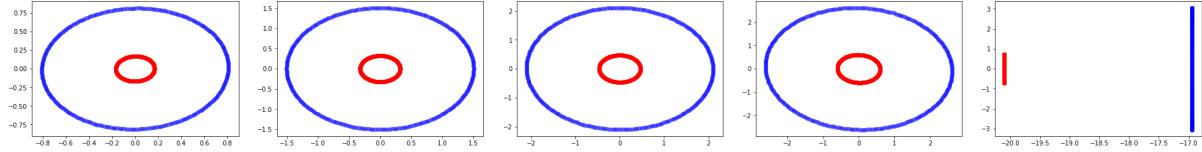


Figure 11: K-PCA results using gaussian kernel in two dimension
We start sigma at 0.1 and increase it by step of 0.01.

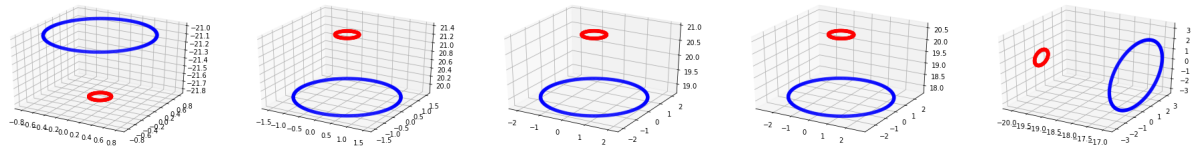


Figure 12: K-PCA results using gaussian kernel in three dimension
We start sigma at 0.1 and increase it by step of 0.01.

Processing time (moons gaussian 0.05) : 4.970557999999983 seconds

The gaussian work pretty well on the circles dataset.

1.3.5 K-PCA : Polynomial

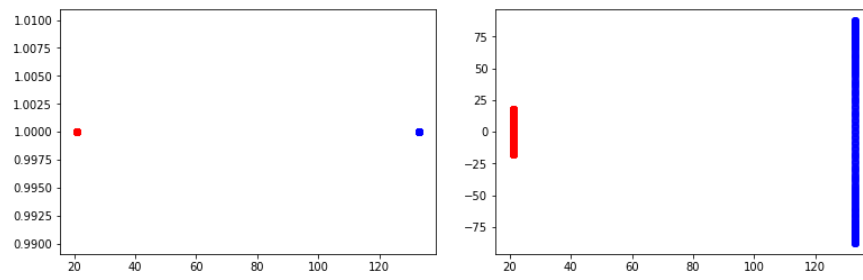


Figure 13: K-PCA results using polynomial kernel in one & two dimensions

Processing time (moons poly) : 2.4073649999999986 seconds

1.4 IRIS

1.4.1 Sample

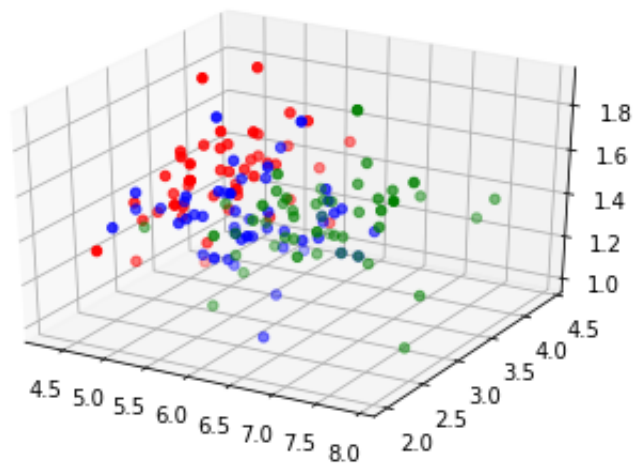


Figure 14: IRIS sample, plot with the 3 first components

1.4.2 PCA

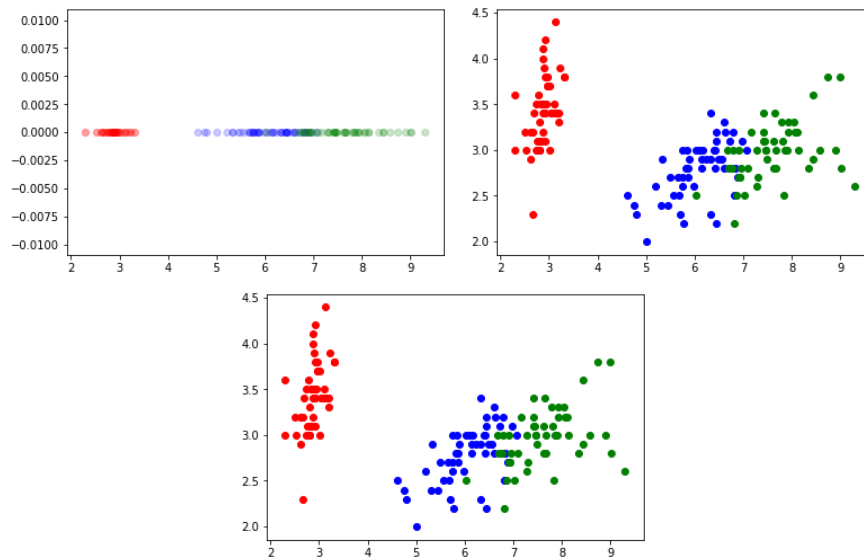


Figure 15: PCA results in one, two & three dimensions

Processing time for PCA : 0.5740129999999999 seconds

1.4.3 K-PCA : Linear

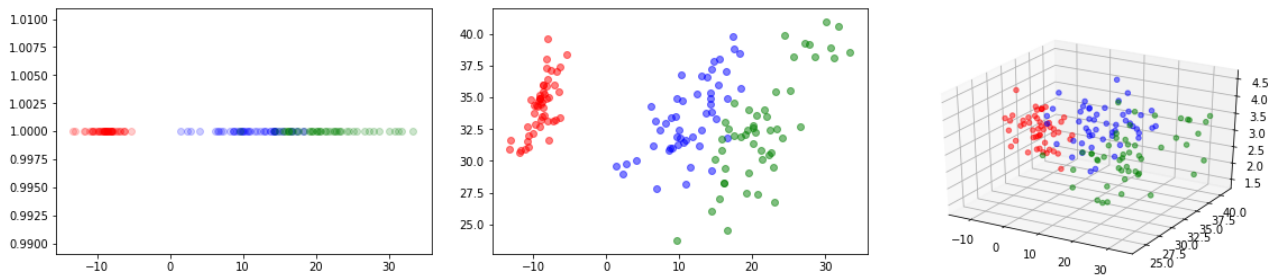


Figure 16: K-PCA results using linear kernel in one, two & three dimensions

Processing time (IRIS linear) : 0.6345670000000001 seconds

1.4.4 K-PCA : Gaussian

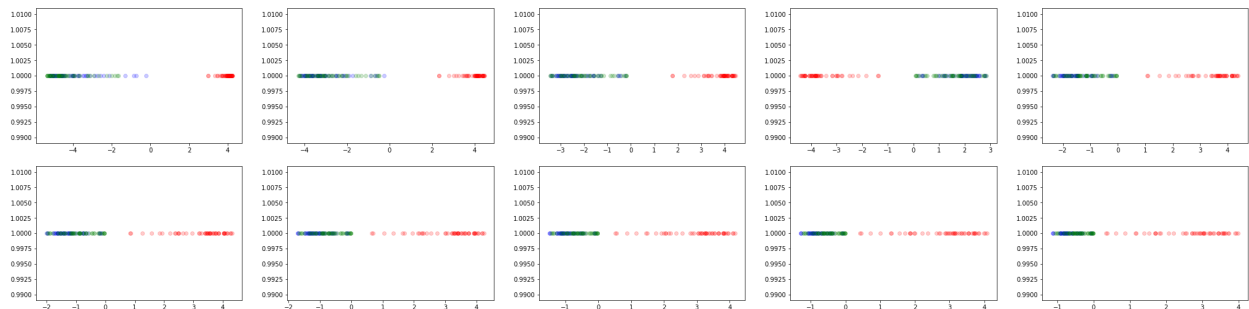


Figure 17: K-PCA results using gaussian kernel in one dimension
We start sigma at 1 and increase it by step of 1.

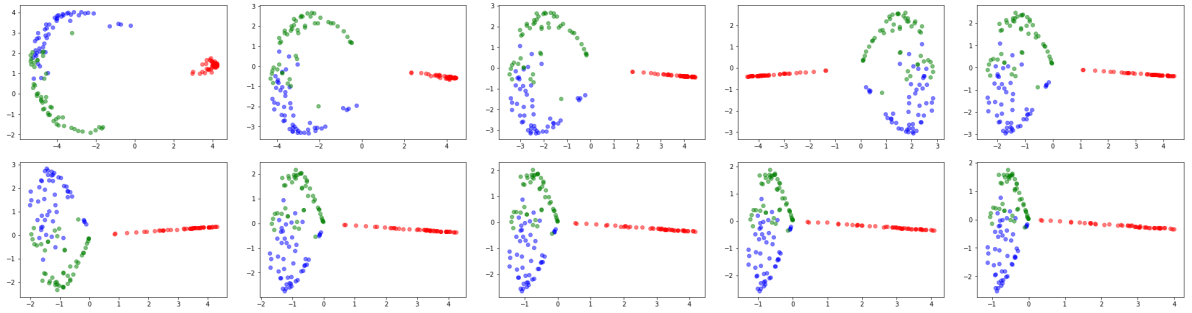


Figure 18: K-PCA results using gaussian kernel in two dimension
We start sigma at 1 and increase it by step of 1.

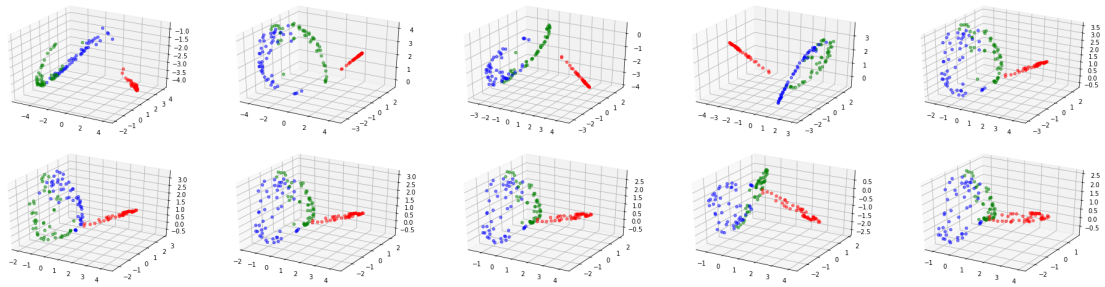


Figure 19: K-PCA results using gaussian kernel in three dimension
We start sigma at 1 and increase it by step of 1.

PProcessing time (IRIS gaussian 10) : 0.9170499999999997 seconds

The result are not so bad. The red class is well separated, the green and blue ones are quasi well separated.

1.4.5 K-PCA : Polynomial

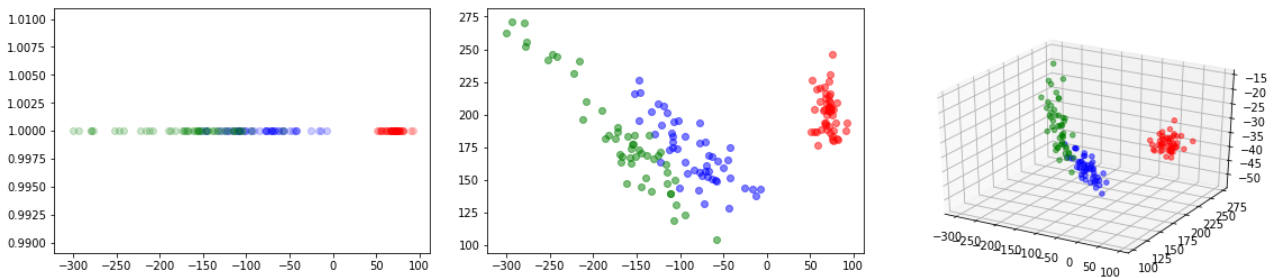


Figure 20: K-PCA results using polynomial kernel in one, two & three dimensions

Processing time (IRIS poly) : 0.73237799999999971 seconds

As the gaussian, the polynomial work pretty well.

2 Kernel-KMeans

2.1 Regular KMeans implementation

Here is our implementation of KMeans in python :

```

def kmeans_centroids(X, n, eps):
    # n centroids initialization (just once)
    np.random.seed(0)
    r = [np.random.randint(0, len(X)) for i in range(n)]

    #todo check r for doubles
    centroids_before = X[r]

    while True:
        #
        y_c = kmeans_fit(X, centroids_before)

        centroids_after = np.zeros((n, len(X[0])))
        sum_moove = 0
        for c in range(n):
            for d in range(np.size(X, axis=1)):
                centroids_after[c, d] = np.mean(X[y_c==c, d])
            # adding the distance from the old centroid to the new one
            sum_moove += np.linalg.norm(centroids_before[c] - centroids_after[c])

        if (sum_moove <= eps): break

        centroids_before = centroids_after

    return centroids_after

def kmeans_fit(X, centroids):
    y = np.zeros(len(X))
    dist = np.zeros(len(centroids))
    for i in range(len(X)):
        # computing the argmin distance to each centroid
        for c in range(len(centroids)):
            dist[c] = np.linalg.norm(X[i] - centroids[c])
        y[i] = np.argmin(dist)

    return y

```

2.2 Kernel KMeans

We just kernelize our data before doing the KMeans :

```

X_centered = X - np.mean(X)
X_normalized = X_centered / np.std(X)
X_normalized = kernel(X_normalized, gaussian, sigma=1)

centers = kmeans_centroids(X_normalized, n=2, eps=0.1)
y_c = kmeans_fit(X_normalized, centers)

```

3 Logistic Regression

Unfortunately, we haven't done anything for this part, we preferred to do the next one before by lack of time.

4 One class SVM and Maximum Enclosing Ball

4.1 A first implementation

The first step is to write a simple 2D problem with a few data: a set X of points in D dimensions. We want to minimize the radius r of a ball $D = \{r, c\}$ with a center c such that :

$$\forall x \in X, \sum_{d=1}^D (X[i, d] - c[d])^2 \leq r^2$$

The first result that we get with $X = \{(0,0), (2,0), (0,2), (1,1)\}$ is $C = [1, 1]$ and $r = 1.41 = \sqrt{2}$. Which is correct.

Here is how we implemented this problem:

```
reset;
option solver loqo;

# data
param n_feat;
param dim;
param X {1..n_feat, 1..dim};

# variables
var r >= 0;
var C {1..dim};

minimize ball: r;
subject to c1 {i in 1..n_feat}: (sum{d in 1..dim} ((X[i,d] - C[d]) ^ 2)) <= (r * r);

data;
param n_feat = 4;
param dim = 2;
param X: 1 2 :=
1 0 0
2 2 0
3 0 2
4 1 1 ;

solve;
display C;
display r;
```

4.2 Running on IRIS dataset

Then, we ran the MEB problem with single classes of the IRIS dataset using a program to convert the data that we get in python into a module for AMPL.

Here is the obtained maximum enclosing balls :

```
# CLASS 0 :
C [*] :=
1 5.1
2 3.35
3 1.4
4 0.35
;
r = 1.2145

# CLASS 1 :
C [*] :=
1 5.98135
2 2.75136
3 3.98539
4 1.28878
;
r = 1.35889

# CLASS 2 :
C [*] :=
1 6.33049
2 2.98564
3 5.65369
4 1.97031
;
```

List of Figures

1	Moons sample	5
2	PCA results in one & two dimensions	5
3	K-PCA results using linear kernel in one & two dimensions	5
4	K-PCA results using gaussian kernel in one dimension	6
5	K-PCA results using gaussian kernel in two dimension	6
6	K-PCA results using polynomial kernel in one & two dimensions	7
7	Circles sample	7
8	PCA results in one & two dimensions	7
9	K-PCA results using linear kernel in one & two dimensions	8
10	K-PCA results using gaussian kernel in one dimension	8
11	K-PCA results using gaussian kernel in two dimension	8
12	K-PCA results using gaussian kernel in three dimension	8
13	K-PCA results using polynomial kernel in one & two dimensions	9
14	IRIS sample, plot with the 3 first components	9
15	PCA results in one, two & three dimensions	10
16	K-PCA results using linear kernel in one, two & three dimensions	10
17	K-PCA results using gaussian kernel in one dimension	10
18	K-PCA results using gaussian kernel in two dimension	11
19	K-PCA results using gaussian kernel in three dimension	11
20	K-PCA results using polynomial kernel in one, two & three dimensions	11