Team Lead: Adam

Description Paragraph:

Our goal is to learn how to use ROS to interact with the physical world and people. We want the arm to reach for a point designated by the user by touching the point. It will also respond to voice commands (turn left or right, up or down, etc.). We will be learning Open CV and speech recognition to utilize the commands mentioned earlier.

Tech Needed:

* ROS
  + Create and import packages
* Open CV
* Raspberry Pi (maybe)
* Speech (pocket sphinx + espeak)