

# JONATHAN M. BOSNICH

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## EDUCATION

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### Northwestern University

Ph.D. in Mechanical Engineering  
Advisor: Professor Todd Murphey  
GPA: 3.63/4.00

Evanston, IL  
2021 - Present

### University of Colorado, Boulder

B.S. in Mechanical Engineering, *Summa Cum Laude*  
B.A. in Mathematics, *With Distinction*  
GPA: 3.91/4.00

Boulder, CO  
2016 - 2020  
2016 - 2020

### Coursework

(*Pure Math*) Point-Set Topology, Real Analysis, Abstract Algebra, Lie Theory (Independent Study)  
(*Applied Math*) Data-Driven Dynamical Systems\*, Applied Dynamical Systems\*, Nonlinear Optimization\*, Distributed Optimization\*, Linear Systems\*, Active Learning\*, Stochastic Processes\*, Numerical Analysis  
(\*graduate course)

### Programming

Python, MATLAB, Julia, ROS

## PAPERS IN PREPARATION

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J. M. Bosnich, G. Mamakoukas, T. D. Murphey, "Data-Driven Minimal-Norm Stabilization of Nonlinear Systems Using the Koopman Operator"

## RESEARCH EXPERIENCE

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### Interactive & Emergent Autonomy Lab, Northwestern University

Graduate Research Assistant  
Advisor: Professor Todd Murphey

Evanston, IL  
2021 - Present

- Developing a minimal-norm data-driven controller that guarantees stabilization of nonlinear systems
- Learned model from data using the Koopman operator/residual dynamic mode decomposition (ResDMD)
- Derived explicit error bounds on model eigenvalues by extending ResDMD to control-affine systems
- Applied matrix nearness optimization to develop minimal-norm feedback gains that guarantee stability

### Bio-Inspired Perception and Robotics Lab, University of Colorado

Undergraduate Research Assistant  
Advisor: Professor Sean Humbert

Boulder, CO  
2018 - 2020

- Extracted state information from a system of distributed sensors by projecting data onto basis functions
- Developed a data-driven method for choosing optimal basis functions by solving integral operator equations
- Used a Galerkin approximation of the singular value expansion to solve integral operator equations
- Investigated analytic and data-driven methods for modeling and controlling an array of soft actuators

### Mathematics Department, University of Colorado

Independent Research in Lie Theory  
Advisor: Professor Keith Kearnes

Boulder, CO  
Spring 2020

- Worked on the unsolved classification of 10-dimensional simple Lie algebras over the two-element field
- Used the adjoint representation and spectral graph theory to study the only known Lie algebra of this type
- Formulated and programmed criteria for admissible Lie algebras, reducing 2048 possibilities to at most 85

**Collective Dynamics and Control Lab, University of Maryland**

Research Intern, Bio-Inspired Robotics REU

Advisor: Professor Derek Paley

College Park, MD

Summer 2019

- Created a soft-robotic gripper that adapts the force it applies to an object via sensory feedback control
- Implemented PID control law in MATLAB, fabricated the soft gripper, and integrated the system
- Delivered final presentation to the REU cohort, lab members, and PIs, and was awarded best presentation

**Mathematics Department, University of Colorado**

Research Intern, Mathematics REU

Advisor: Professor Nathaniel Thiem

Boulder, CO

Summer 2018

- Sought an algebraic relationship relating the partitions of an integer  $n$  and of a set with  $n$  elements
- Employed techniques from algebraic combinatorics and graph theory to search for this relationship

**ENGINEERING EXPERIENCE**

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**Spectra Logic Corporation**

Systems Engineer Intern

Boulder, CO

2020 - 2021

- Wrote a Python program that queried and analyzed CAN communication metrics stored in a SQL database
- Identified performance degradation by visualizing data from different sources in a single multi-plot chart
- Conducted tests, collected data, and performed statistical analysis to investigate robot positioning issues

**Mechanical Engineering Capstone Project**

Systems Engineer

Boulder, CO

2019 - 2020

Client: National Oceanic and Atmospheric Administration (NOAA)

- Designed hardware and software for aircraft-mounted atmospheric LiDAR scanner to track wildfires
- Implemented feedback controller in LabVIEW that ensured a steady scan in the presence of aircraft motion

**TEACHING EXPERIENCE**

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**Mechanical Engineering 314 - Machine Dynamics, Northwestern University**

Teaching Assistant

Grader

Evanston, IL

Spring 2023

Fall 2023

- Taught total of 17 lectures, and received high praise from the students and instructor (Todd Murphey)
- Topics I covered: Euler-Lagrange equations, constraints, external forces, Noether's theorem, impacts

**Math Academic Resource Center, University of Colorado**

Tutor

Boulder, CO

2018 - 2020

**Applied Mathematics Department, University of Colorado**

Learning Assistant for Calculus I &amp; II

Boulder, CO

2017 - 2018

**TEAMS Elementary School Engineering Program**

Group Leader

Longmont, CO

2015 - 2017

**HONORS**

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Ted Belytschko Fellowship (one of two recipients; Northwestern Mechanical Engineering)	2021
Walter P. Murphy Fellowship (Northwestern Mechanical Engineering)	2021
NSF GRFP Honorable Mention	2021
Outstanding Undergraduate of the College of Engineering (CU, Boulder)	2020
Outstanding Undergraduate of the Mechanical Engineering Department (CU, Boulder)	2020
College of Engineering Dean's list (CU, Boulder)	2016 - 2020
Engineering Honors Program (CU, Boulder)	2016 - 2020
Phi Beta Kappa (academic fraternity; CU, Boulder)	2018 - 2020
Pi Mu Epsilon (math honor society; CU, Boulder)	2018 - 2020
Valedictorian (Berthoud High School)	2016