

Team Notebook

UPGraded

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1 Aho-Corasick

```
namespace aho{
    vector<string> vs;
    ll val[maxn+1];
    ll smatch[maxn+1];

    ll p[maxn+1];
    ll pchar[maxn+1];
    map<ll,ll> vadj[maxn+1];

    ll nCount=1;
    const long long root=0;

    ll flink[maxn+1];
    ll olink[maxn+1];

    void addString(string& s,ll id){
        ll i=root;
        for(char c: s){
            if(vadj[i].find(c) != vadj[i].end()){
                i = vadj[i][c];
                continue;
            }
            ll node = nCount++;
            p[node]=i;
            pchar[node]=c;
            vadj[i][c]=node;
            i=node;
        }
        smatch[i]=id;
        val[i]++;
    }

    void build(){
        for(int i=0; i<maxn; i++) smatch[i]=-1;
        pchar[root]=-1;
        ll id=0;

        for(string& s: vs) addString(s,id++);
        queue<ll> q; q.push(root);

        while(!q.empty()){
            ll x=q.front(); q.pop();
            for pll yy: vadj[x] q.push(yy.second);

            ll nx = flink[p[x]];
            ll c = pchar[x];

            while(nx != root && vadj[nx].find(c) == vadj[nx].end()) nx = flink[nx];

            if(vadj[nx].find(c) == vadj[nx].end() || vadj[nx][c] == x) flink[x]=root;
            else flink[x]=vadj[nx][c];

            if(smatch[flink[x]] != -1) olink[x] = flink[x];
            else olink[x] = olink[flink[x]];
        }

        void match(ll node, ll pos){
            // match, at T[pos]. If you need the matching P, use vs[smatch[node]]
        }

        void aho(string& T){
            ll x=root;
            for(int c=0; c<(ll)T.size(); c++){
                while(x != root && vadj[x].find(T[c]) == vadj[x].end()) x = flink[x];
                if(vadj[x].find(T[c]) == vadj[x].end()) continue;
                x = vadj[x][T[c]];
                if(smatch[x] != -1) match(x,c);
                ll mx = olink[x];
                while(mx != root){
                    match(mx,c);
                    mx = olink[mx];
                }
            }
        }
    }

    void getKthParent(int x, int k){ // Only if you want to know this
        if(k == 0) return x;
        int nextBit = (k&(-k));
        return getKthParent(lifting[x][__builtin_ctz(k)],k-nextBit);
    }

    bool isAncestor(int x, int y){ // ancestor x of y
        return (in[x] <= in[y] && out[x] >= out[y]);
    }

    int lca(int x, int y){
        if(isAncestor(x,y)) return x;
        if(isAncestor(y,x)) return y;
        //Moving x;
        for(int pow2 = maxPow-1; pow2>=0; pow2--){
            if(!isAncestor(lifting[x][pow2],y)){
                x = lifting[x][pow2];
            }
        }
        return lifting[x][0];
    }
}

double build(int x, int p, vector<vll>& vadj){
    lifting[x][0] = p;
    in[x]=timeTransversal++;
    for(int i=0; i<maxPow-1; i++){
        lifting[x][i+1] = lifting[lifting[x][i]][i];
    }
    for(int y: vadj[x]){
        if(y == p) continue;
        build(y,x,vadj);
    }
    out[x]=timeTransversal++;
}

int getKthParent(int x, int k){ // Only if you want to know this
    if(k == 0) return x;
    int nextBit = (k&(-k));
    return getKthParent(lifting[x][__builtin_ctz(k)],k-nextBit);
}

bool isAncestor(int x, int y){ // ancestor x of y
    return (in[x] <= in[y] && out[x] >= out[y]);
}

int lca(int x, int y){
    if(isAncestor(x,y)) return x;
    if(isAncestor(y,x)) return y;
    //Moving x;
    for(int pow2 = maxPow-1; pow2>=0; pow2--){
        if(!isAncestor(lifting[x][pow2],y)){
            x = lifting[x][pow2];
        }
    }
    return lifting[x][0];
}
}
```

2 BinaryLifting

```
namespace LCA{
    const int maxPow = 30;
    int lifting[maxn][maxPow];
    int in[maxn];
    int out[maxn];
    int timeTransversal=0;

    void clear(){ // CALL THIS
        timeTransversal=0;
    }
}
```

3 CHT

```
namespace CHT {
    map<ll, ll> mp;
    map<double, ll> qrange;
    double INF = 1e18;

    double Intersect(map<ll, ll>::iterator a, map<ll, ll>::iterator b) {
    }
```

```

    return double(a->second - b->second) / double(b->first - a
->first);
}

bool Check(ll m, ll x) {
    if (mp.find(m) != mp.end()) {
        if (mp[m] >= x) return false;
        return true;
    }

    auto y = mp.upper_bound(m);
    if (y == mp.end() || y == mp.begin()) return true;
    auto u = (--y);
    ++y;
    double sec = Intersect(u, y);
    double cross = double(u->second - x) / double(m - u->first
);
    if (sec < cross) return false;
    return true;
}

void UpdateQRange(map<ll, ll>::iterator it) {
    auto x = ++it;
    --it;
    if (x == mp.end())
        qrange[INF] = it->first;
    else
        qrange[Intersect(it, x)] = it->first;
}

void UpdateRight(ll m) {
    auto it = mp.find(m);
    auto x = ++it;
    --it;
    if (x == mp.end()) return;
    while (1) {
        auto y = ++x;
        --x;
        if (y == mp.end()) return;
        double sec = Intersect(y, x);
        double cross = Intersect(y, it);
        if (sec > cross) return;
        qrange.erase(sec);
        mp.erase(x);
        x = y;
    }
}

void UpdateLeft(ll m) {
    auto it = mp.find(m);

```

```

    if (it == mp.begin()) return;
    auto x = --it;
    ++it;

    auto n = ++it;
    --it;
    if (n == mp.end())
        qrange.erase(INF);
    else
        qrange.erase(Intersect(x, n));

    while (x != mp.begin()) {
        auto y = --x;
        ++x;
        double sec = Intersect(y, x);
        double cross = Intersect(y, it);
        if (sec < cross) return;
        qrange.erase(sec);
        mp.erase(x);
        x = y;
    }
}

// Use this
void Add(ll m, ll x) {
    if (!Check(m, x)) return;
    mp[m] = x;
    UpdateRight(m);
    UpdateLeft(m);
    auto it = mp.find(m);
    UpdateQRange(it);
    if (it == mp.begin()) return;
    UpdateQRange(--it);
}

ll Eval(map<ll, ll>::iterator it, ll x) { return it->first *
x + it->second; }

// Use this
ll GetMax(ll x) {
    auto it = qrange.lower_bound(x);
    return Eval(mp.find(it->second), x);
}
} // namespace CHT

```

4 Congruencias

```
using rp = pair<ll, pll>;
```

```

rp mygcd(ll a, ll b){
    if(a==0) return {b,{0,1}};
    if(b==0) return {a,{1,0}};
    rp prev=mygcd(b%a,a);

    ll ax=prev.second.second-prev.second.first*(b/a);
    ll bx=prev.second.first;

    rp ans={prev.first, {ax,
bx}};
    return ans;
}

rp solve(ll c1, ll c2, ll b){
    rp ans = mygcd(c1,c2);
    if(b%ans.first != 0) return {-1,-1,-1};
    ll bd = b/ans.first;
    ll c2p = c2/ans.first;

    ans.second.first%=c2p;
    bd%=c2p;

    ans.second.first = (__int128(bd)*__int128(ans.second.
first))%c2p;
    ans.second.first = (ans.second.first+c2p)%c2p;

    ans.second.second = (b-ans.second.first*c1)/c2;
    return ans;
}

// Falta checar que el lcm no cause overflow
pll sistema(vll& c, vll& b){
    pll ans(b[0], c[0]);
    for(size_t i=1; i<c.size(); i++){
        ll pc = ans.second;
        ll pb = ans.first;
        rp sol = solve(pc, c[i],b[i]-pb);
        if(sol.first == -1) return {-1,-1};

        ans.second = pc*(c[i]/sol.first);
        ans.first += pc*sol.second.first;
        ans.first %= ans.second;
    }
    return ans;
}

```

5 ConvexHull

```
namespace CH {
    struct Point {
        ll x;
        ll y;
        Point() : x(0), y(0) {}
        Point(ll _x, ll _y) : x(_x), y(_y) {}
        ll operator*(const Point& b) const {
            return x * b.y - y * b.x;
        }
        Point operator-(const Point& b) const {
            return {x-b.x, y-b.y};
        }
        bool operator==(const Point& b) const {
            return ((x == b.x) && (y == b.y));
        }

        bool operator<(Point& b) {
            if (x != b.x) return x < b.x;
            return y < b.y;
        }
    };

    // skips colinear
    vector<Point> partialConvex(const vector<Point>& vl) {
        if (vl.size() == 0) return {};
        vector<Point> c(vl.size());
        c[0] = vl[0];
        int j = 1;
        for (size_t i = 1; i < vl.size(); i++) {
            if (vl[i] == c[j-1]) continue;
            if (j == 1) {
                c[j++] = vl[i];
                continue;
            }
            if (vl[i] == c[j-2]) continue;
            if ((c[j-1]-c[j-2]) * (vl[i]-c[j-2]) < 0) {
                c[j++] = vl[i];
                continue;
            }
            j--; i--;
        }
        c.resize(j);
        return c;
    }

    vector<Point> getConvexHull(vector<Point>& vl) {
        if (vl.size() == 0) return {};
        sort(vl.begin(), vl.end());
    }
}
```

```
auto ch1 = partialConvex(vl);
reverse(vl.begin(), vl.end());
auto ch2 = partialConvex(vl);
vector<Point> ch;
for (auto p : ch1) ch.push_back(p);
for (size_t i = 1; i+1 < ch2.size(); i++) ch.
    push_back(ch2[i]);
return ch;
}
```

6 CribaLineal

```
const int maxn = 1e7;
std::vector<int> prime;
bool is_composite[maxn];

void sieve (int n) {
    std::fill (is_composite, is_composite + n, false);
    for (int i = 2; i < n; ++i) {
        if (!is_composite[i]) prime.push_back (i);
        for (int j = 0; j < prime.size () && i * prime[j] < n
            ; ++j) {
            is_composite[i * prime[j]] = true;
            if (i % prime[j] == 0) break;
        }
    }
}
```

7 Dinics

```
const int maxn = 400;

namespace Dinics{
    map<ll,ll> vadj[maxn];
    vpll layered[maxn];
    vpll layeredSum[maxn];
    int level[maxn];
    int index[maxn];
    const long long maxFlow = 1e16;

    void clear(int N){
        for(int i=0; i<N; i++) vadj[i].clear();
    }
}
```

```
void buildLayered(int N, int S){
    for(int i=0; i<N; i++) level[i] = -1;
    queue<int> q;
    queue<int> q2; //0-1 BFS
    int step = 1;
    level[S] = 0;
    q.push(S);
    while(1){
        while(!q.empty()){
            int x = q.front();
            q.pop();
            for(pll yy: vadj[x]){
                int y = yy.first;
                if(level[y] != -1) continue;
                if(yy.second <= 0) continue;
                level[y] = step;
                q2.push(y);
            }
        }
        if(q2.empty()) break;
        step++;
        while(!q2.empty()){
            q.push(q2.front());
            q2.pop();
        }
    }

    for(int i=0; i<N; i++){
        layered[i].clear();
        layeredSum[i].clear();
        for(pll yy:vadj[i]){
            if(level[i]+1 != level[yy.first]) continue;
            layered[i].push_back(yy);
            layeredSum[i].push_back(yy);
        }
    }
}

ll blockFlow(int x, ll flow, int T){
    if(flow == 0) return flow;
    if(x == T) return flow;
    if(index[x] >= (ll)layered[x].size()) return 0;
    for(size_t i=index[x]; i<layered[x].size(); index[x]
        ]++,i=index[x]){
        ll nextFlow = min(flow, layered[x][i].second);
        ll attempt = blockFlow(layered[x][i].first,
            nextFlow, T);
        if(attempt!=0){
            layered[x][i].second-=attempt;
            if(layered[x][i].second == 0) index[x]++;
        }
    }
}
```

```

        return attempt;
    }
}
return 0;
}

ll blockPaths(ll N,ll S,ll T){
    for(int i=0; i<N; i++) index[i]=0;
    ll ans = 0;
    while(1){
        ll flow = blockFlow(S,maxFlow, T);
        ans+=flow;
        if(flow == 0) return ans;
    }
}

ll dinics(ll N, ll S, ll T){
    ll ans = 0;
    while(1){
        buildLayered(N,S);
        ll push = blockPaths(N,S,T);
        ans+=push;
        if(push == 0) return ans;
        // actualizar cambios en residual
        for(int i=0; i<N; i++){
            for(size_t j=0; j<layered[i].size(); j++){
                vadj[i][layered[i][j].first] = layered[i][j].second;
                vadj[layered[i][j].first][i] += layeredSum[i][j].second-layered[i][j].second;
            }
        }
    }
}
}
}
}

```

8 GCD

```
using rp = pair<ll,pll>;

rp mygcd(ll a, ll b){
    if(a==0) return {b,{0,1}};
    if(b==0) return {a,{1,0}};
    rp prev=mygcd(b%a,a);

    ll bd = b/prev.first;
    ll ax=prev.second.second-prev.second.first*(b/a);
    ax = (ax%bd+ bd)%bd;
```

```

    ll bx=(prev.first-a*ax)/b;

    rp ans={prev.first, {ax,
        bx}};
    return ans;
}
// sea  $c = \max(a,b)$ , la solución  $|x| \leq c$ 

// Soluciones de  $ax + by = 0$ .
//  $d = \gcd(a,b)$ ;  $\rightarrow x=(b/d)*t, y=-1*(a/d)*t$ ;

```

9 Gaussian Elimination

```

namespace Gauss {
    const int maxn = 1<<6;
    double mat[maxn][maxn+1];
    double ans[maxn];

    void Gauss(int N) {
        for (int i = 0; i < N-1; i++) {
            int l = i;
            for (int j = i+1; j < N; j++) {
                if (fabs(mat[j][i]) > fabs(mat[l][i])) l = j;
            }

            for (int k = i; k <= N; k++) swap(mat[i][k], mat[l][k]);

            for (int j = i+1; j < N; j++) {
                for (int k = N; k >= i; k--) {
                    mat[j][k] -= mat[i][k] * mat[j][i] / mat[i][i];
                }
            }
        }

        for (int i = N-1; i >= 0; i--) {
            double t = 0;
            for (int k = i+1; k < N; k++) {
                t += mat[i][k] * ans[k];
            }
            ans[i] = (mat[i][N] - t) / mat[i][i];
        }
    }
}

```

| 10 KMP

```
vector<int> kmp(string& s){
    int n = s.size();
    vector<int> vs(n);
    //vs[i] = kmp que acaba en la posicion i
    for(int i=1; i<n; i++){
        int j = vs[i-1]; // j = aproximacion anterior
        while( j!=0 && s[i] != s[j]){
            j = vs[j-1];
        }
        if(s[i] == s[j]) j++;
        vs[i] = j;
    }
    return vs;
}
```

11 KnapsackBalance

```

11 knapsack(vll& ww, ll C) {
    vll w;
    for (ll x : ww) {
        if (x > C) continue;
        if (x == 0) continue;
        w.push_back(x);
    }
    if (w.empty()) return 0;

    ll maxw = w[0];
    for (size_t i = 0; i < w.size(); i++) maxw = max(maxw, w[i]);
    vll dp(maxw*2 + 1, -1);
    vll prev(maxw*2 + 1, -1);
    auto xy = [=](ll x) {
        return (x-C+maxw);
    };

    size_t b = 0; ll sum = 0;
    for (size_t i = 0; i < w.size(); i++) {
        if (sum + w[i] > C) break;
        sum+=w[i]; b = i;
    }

    prev[xy(sum)] = b+1;
    for (size_t i = b+1; i < w.size(); i++) {
        for (ll j = C-maxw; j <= C + maxw; j++) dp[xy(j)] =
            prev[xy(i)];
    }
}

```

```

    for (ll j = C-maxw; j <= C; j++) dp[xy(j+w[i])] = max
        (prev[xy(j)], dp[xy(j+w[i])]);
    for (ll j = C + maxw; j > C; j--) {
        for (ll k = dp[xy(j)]-1; k > prev[xy(j)]; k--) dp
            [xy(j-w[k])] = max(dp[xy(j-w[k])], k);
    }
    swap(prev, dp);
}
for (int i = C; i >= 0; i--) if (prev[xy(i)] != -1)
    return i;
return -1;
}

```

12 MinCostMaxFlow

```

const int maxn = 50 * 101 + 2;
namespace MCMF {
    typedef struct edge {
        ll f;
        ll cost;
        ll cap;
        ll v;
        struct edge* back;
        edge(ll _cost, ll _cap, ll _v) :
            f(0), cost(_cost), cap(_cap), v(_v) {}
    } edge;
    const long long INF = 1e16;

    vector<edge*> vadj[maxn];

    void addEdge(ll u, ll v, ll cost, ll cap) {
        edge* a = new edge(cost, cap, v);
        edge* b = new edge(cost*-1, 0, u);
        a->back = b;
        b->back = a;
        vadj[u].push_back(a);
        vadj[v].push_back(b);
    }

    pll sendFlow(ll S, ll T, ll N) {
        vll vl(N, INF);
        vector<edge*> prev(N, NULL);
        queue<ll> q; q.push(S);
        vl[S] = 0;

        vll inQueue(N);
        inQueue[S] = 1;
        while (!q.empty()) {

```

```

            int k = q.front(); q.pop();
            inQueue[k] = 0;
            for (edge* e : vadj[k]) {
                if (e->f == e->cap) continue;
                if (e->cost + vl[k] >= vl[e->v]) continue;
                vl[e->v] = e->cost + vl[k];
                prev[e->v] = e;
                if (inQueue[e->v]) continue;
                q.push(e->v);
                inQueue[e->v]=1;
            }
        }

        if (vl[T] == INF) return {0,0};
        ll f = INF;
        ll x = T;
        while (x != S) {
            f = min(prev[x]->cap - prev[x]->f, f);
            x = prev[x]->back->v;
        }
        x = T;
        while (x != S) {
            prev[x]->f += f;
            prev[x]->back->f -= f;
            x = prev[x]->back->v;
        }
        return {f, vl[T]};
    }

    pll maxFlow(ll S, ll T, ll N) {
        pll ans {0,0};
        while (1) {
            pll x = sendFlow(S, T, N);
            if (x.first == 0) return ans;
            ans.first += x.first;
            ans.second += x.second * x.first;
        }
    }
}

```

13 OrderStatisticsTree

```

//Order Statistics Tree
#include<ext/pb_ds/assoc_container.hpp>
#include<ext/pb_ds/tree_policy.hpp>

using namespace __gnu_pbds;

```

```

using map_t = tree<ll,null_type,
    less<ll>, rb_tree_tag,
    tree_order_statistics_node_update>;

// No inserta duplicados.
// tiene mismas funciones que set o map (dependiendo de que
    uses);

int main(){
    map_t mp;
    mp.insert(3);
    mp.insert(5);
    mp.order_of_key(3); // devuelve 0;
    mp.order_of_key(4); // devolveria 1;
    mp.order_of_key(0); // devolveria 0;
    mp.find_by_order(2); // devolveria el iterador al 5 (es
        un puntero);
    mp.find_by_order(1); // devuelve el iterador al 5. (osea
        es 0 ordering);
}

```

14 SCC

```

const int maxn = // add maxn

namespace Tarjan{
    int scc=0; // Number of resulting scc;
    bool inStack[maxn];
    int lo[maxn];
    int hi[maxn];
    int vis[maxn];
    stack<int> st;
    int step=0;
    int sz[maxn]; //Size of each component. Components are 0
        indexed
    vector<vll> comps; // Each component
    int myComp[maxn]; // Maps each node to each component
    unordered_set<ll> compVadj[maxn]; // New graph.
        Components are 0 indexed

    void clear(int N){
        scc=0;
        step = 0;
        for(int i=0; i<N; i++){
            vis[i] =0;
            inStack[i] =0;
            sz[i] = 0;
            myComp[i] =0;

```

```

        compVadj[i].clear();
    }
    comps.clear();
}

int tarjan(int x, vector<vll>& vadj){
    if(vis[x]) return maxn+2;
    vis[x] = 1;
    inStack[x] = 1;
    st.push(x);
    lo[x] = hi[x] = step++;
    for(int y : vadj[x]){
        if(inStack[y]){
            lo[x] = min(lo[x], hi[y]);
            continue;
        }
        lo[x] = min(lo[x], tarjan(y, vadj));
    }

    if(lo[x] == hi[x]){
        int currSz = 0;
        vll thisComp;
        while(st.top() != x){
            thisComp.push_back(st.top());
            inStack[st.top()] = 0;
            myComp[st.top()] = scc;
            int y = st.top();
            for(int z : vadj[y]){
                if(inStack[z]) continue;
                z = myComp[z];
                if(z == scc) continue;
                compVadj[scc].insert(z);
            }
            currSz++;
            st.pop();
        }
        thisComp.push_back(x);
        inStack[st.top()] = 0;
        myComp[st.top()] = scc;
        int y = st.top();
        for(int z : vadj[y]){
            if(inStack[z]) continue;
            z = myComp[z];
            if(z == scc) continue;
            compVadj[scc].insert(z);
        }
        st.pop();
        currSz++;
        comps.push_back(thisComp);
        sz[scc] = currSz;
    }
}

```

```

        scc++;
    }
    return lo[x];
}

void tarjanMain(int N, vector<vll>& vadj){ // Use this.
    clear(N); // Modify this if you use a range [1,N]
    for(int i=0; i<N; i++){ //Modify this if your nodes
        start from 1
        if(vis[i] == 0) tarjan(i, vadj);
    }
}

```

15 SegmentTree

```

struct segmentTree{
    struct str{
        ll first;
        ll second;
        str() : first(0), second(0) {}
        str(ll a, ll b) : first(a), second(b) {}
    };

    str func(str a, str b){
        //merge function
    }

    str st[2*maxn];
    ll n;

    void build(vll& vl, int sizn){
        n = sizn;
        for(int i=0; i<n; i++) st[i+n] = {vl[i], i};
        for(int i=n-1; i>0; i--) st[i] = func(st[i*2], st[i
            *2+1]);
    }

    // 0-indexed
    // Value is replaced
    void update(int pos, str x){
        for(pos+=n, st[pos]=x, pos/=2; pos; pos/=2){
            st[pos] = func(st[pos*2], st[pos*2+1]);
        }
    }

    // [L,R] 0-indexed
    str query(int l, int r){

```

```

        str ans1={0,0};
        str ansr={0,0};
        for(l+=n, r+=n; l<r; l/=2, r/=2){
            if(l%2) ans1=func(ans1, st[l++]);
            if(r%2) ansr=func(st[--r], ansr);
        }
        return func(ans1, ansr);
    }
};

```

16 SegmentTreeLazy

```

struct segmentTree{
    struct str{
        ll hash;
        ll sz;
        str() : hash(0), sz(0) {}
        str(ll h, ll s) : hash(h), sz(s) {}
    };

    str st[2*maxn];
    ll n;
    ll h;
    ll d[2*maxn];
    str merge(str& a, str& b){
        // combine a,b
    }

    str ifPropagated(ll idx){
        if(d[idx] == 0) return st[idx];
        // value of st[idx] if you had propagated d[idx]
        // If propagated is always asked after st[idx] = merge
        // (st[idx*2], st[idx*2+1]);
    }

    void apply(ll i, ll x){
        // apply lazy x. Remember to update d[i], flag not
        // propagated to children
        // apply directly to st[i], that is the value used in
        // queries
    }

    void build(vll& vl, ll sz){
        n=sz;
        h=64-__builtin_clzll(n);
        for(int i=0; i<n; i++) st[i+n] = {};
        for(int i=n-1; i>0; i--) st[i]=merge(st[i*2], st[i
            *2+1]);
    }
}

```

```

}

void bi(ll x){
    for(x/=2; x; x/=2){
        st[x] = merge(st[x*2],st[x*2+1]);
        st[x]=ifPropagated(x);
    }
}

void push(ll x){
    for(int s=h; s>0; s--){
        int i=x>>s;
        if(d[i] != 0){
            apply(i*2, d[i]);
            apply(i*2+1,d[i]);
        }
        d[i]=0;
    }
}

//[l,r) 0-indexed
void update(ll l, ll r, ll x){
    ll l0 = l+n;
    ll r0 = r+n-1;
    push(l0);
    push(r0);

    for(l+=n,r+=n; l<r; l/=2,r/=2){
        if(l%2) apply(l++,x);
        if(r%2) apply(--r,x);
    }
    bi(l0);
    bi(r0);
}

//[l,r) 0-indexed
str query(ll l, ll r){
    push(l+n);
    push(r+n-1);
    str ans1(0,0);
    str ansr(0,0);
    for(l+=n,r+=n; l<r; l/=2,r/=2){
        if(l%2) ans1 = merge(ans1,st[l++]);
        if(r%2) ansr = merge(st[--r],ansr);
    }
    return merge(ans1,ansr);
}
};

```

17 SparseTableLCA

```

const int maxn=1e5+7;

namespace SparseLCA{
    const int maxPow = 30;
    ll f1[maxn];
    ll depth[2*maxn];
    ll depthAns[2*maxn];
    ll cc=0;
    ll dpVal[2*maxn][maxPow];
    ll dpAns[2*maxn][maxPow];

    void build(int x, int p, int d, vll vadj[maxn]){
        f1[x]=cc;
        depth[cc]=d;
        depthAns[cc]=x;
        cc++;
        for(ll y: vadj[x]){
            if(y==p) continue;
            build(y,x,d+1,vadj);
            depth[cc]=d;
            depthAns[cc]=x;
            cc++;
        }
    }

    void buildPow(ll N){
        for(int i=0; i<(2*N-1); i++){
            dpAns[i][0]=depthAns[i];
            dpVal[i][0]=depth[i];
        }
        for(int j=1; j<maxPow; j++){
            for(int i=0; i<(2*N-1); i++){
                dpAns[i][j]=dpAns[i][j-1];
                dpVal[i][j]=dpVal[i][j-1];
                int nex = i+(1<<(j-1));
                if(nex >= 2*N-1) continue;
                if(dpVal[nex][j-1] < dpVal[i][j-1]){
                    dpVal[i][j]=dpVal[nex][j-1];
                    dpAns[i][j]=dpAns[nex][j-1];
                }
            }
        }
    }

    ll query(ll a, ll b){
        ll pa = f1[a];
        ll pb = f1[b];
        ll fa = min(pa,pb); ll fb = max(pa,pb);

```

```

        ll dis = fb-fa+1;
        ll pp = 63-__builtin_clzll(dis);
        ll nex = fb-(1<<pp)+1;
        ll ans = dpAns[fa][pp];

        if(dpVal[nex][pp] < dpVal[fa][pp]) return dpAns[nex][pp];
        return ans;
    }

    void preprocess(ll x, ll N, vll vadj[maxn]){
        cc=0;
        build(x,x,0,vadj);
        buildPow(N);
    }
}

```

18 SuffixTree

```

namespace suffix_tree{
    // nodes from [0, sz); //root is 0
    // maxn = maxn+1 if string has special character
    const long long inf = 1e9;
    char s[maxn];
    int to[2*maxn][40];
    int len[2*maxn], fpos[2*maxn], link[2*maxn];
    int node=0, pos=0;
    int sz=1, n=0;

    int lid=0;
    int leaves[2*maxn];

    void match(ll node, string& c, ll mc){
        // match what now
    }

    int make_node(int _pos, int _len){
        fpos[sz] = _pos;
        len[sz] = _len;
        return sz++;
    }

    void go_edge(){
        while(pos>len[to[node][ (int)s[n-pos] ]]){
            node = to[node][ (int)s[n-pos] ];
            pos -= len[node];
        }
    }
}

```



```

void add_letter(int c){
    s[n++] = c;
    pos++;
    int last=0;
    while(pos>0){
        go_edge();
        int edge = s[n-pos];
        int &v = to[node][edge];
        int t = s[fpos[v] + pos - 1];
        if(v == 0){
            v = make_node(n-pos, inf);
            link[last]=node;
            leaves[lid++]=v;
            last=0;
        }
        else if(t == c){
            link[last]=node;
            return;
        }
        else{
            int u = make_node(fpos[v],pos-1);
            to[u][c] = make_node(n-1,inf);
            leaves[lid++]=to[u][c];

            to[u][t] = v;
            fpos[v] += pos-1;
            len[v] -= pos-1;
            v=u;
            link[last] = u;
            last = u;
        }
        if(node == 0) pos--;
        else node=link[node];
    }
}

void add_string(string& x){
    ll i = n;
    node=0; pos=0;
    len[0]=inf;
    for(char c: x) add_letter(c);
    for(int j=i; j<n; j++) len[leaves[j]] = n-fpos[leaves[j]];
    // from [i, n) are leaves
    len[0]=0;
}

void search(string& c){
    ll node=0;

```

```

    ll sz=0;
    for(size_t i=0; i<c.size(); i++){
        sz++;
        if(len[node] < sz){
            node = to[node][(int)c[i]];
            sz=1;
        }
        ll t = s[fpos[node]+sz-1];
        if(node == 0 || t != c[i]) return;
    }
    match(node,c,c.size());
}

```

19 Z-Function

```

vector<int> z_func(string a) {
    // z[i] = max x such that [0, 1, ..., x) = [i, i+1, ..., i+x)
    // z[i] is the length
    vector<int> z(a.size(),0);
    for(int i = 1, l = 0, r = 0; i < (int)a.size(); ++i){
        if(i <= r) z[i] = min(r-i+1, z[i-l]);
        while(z[i] + i < (int)a.size() && a[z[i]] == a[z[i]+i]) z[i]++;
        if(i+z[i]-1 > r) l = i, r = z[i]+i-1;
    }
    // optional: z[0] = a.size();
    return z;
}

```

20 bashrc

```

## Compilation and testing ###
function gc {
    if g++ $1.cpp -o $1.exe -Wall -Werror --std=c++20 2> log.txt; then
        echo "Compiled Succesfully!"
    else
        less log.txt;
    fi
}

function tn {
    for (( i=1; i<=$2; i++))

```

```

do
    if ./$1.exe < $i.in > $i.out; then echo "Ran Test $i"
    else
        echo "Exploded Test $i"
    fi
done
}

function dn {
    for (( i=1; i<=$1; i++))
    do
        if cmp $i.out $i.ans -s; then
            echo "Passed test $i"
        else
            echo "Failed test $i"
        fi
    done
}

export -f gc
export -f tn
export -f dn

```

21 randomForumlas

```

// Primos menores a 1e9
999999191
999999193
999999197
999999223
999999229
999999323
999999337
999999353
999999391
999999433

// Calcular Area de un triangulo dados sus lados
((a+b+c)(a+b-c)(a-b+c)(-a+b+c))^(1/2) / 4

// Calcular Angulos de triangulos Rectangulos

| \      Angulo AB=90 degrees
|  \ C   Angulo BC=acos(B/C) // in radians in c++
A|  \    Convertir Radianes in Degrees= Ans*(360)/(2*PI)
|___\    PI en C++ = const double pi = std::acos(-1);
  B

```

22 vimrc

```
# Create .vimrc file in home
set nu
set rnu
set nowrap
```

```
set expandtab
set shiftwidth=4
set softtabstop=4
filetype indent on
syntax on
```

```
inoremap hnh <esc>
onoremap hnh <esc>
vnoremap hnh <esc>
tnoremap hnh <C-\><C-n>
nnoremap hnh :Ex<cr>
```
