

APPENDIX B: C CODE FOR INTERSECTION AND SURFACE NORMAL

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#define VEC_SUB(a,b,c) {(c)->x = (a).x-(b).x; \
                        (c)->y = (a).y-(b).y; \
                        (c)->z = (a).z-(b).z;}
#define CROSS(a,b,c)  {(c)->x = (a.y * b.z) - (a.z * b.y); \
                        (c)->y = (a.z * b.x) - (a.x * b.z); \
                        (c)->z = (a.x * b.y) - (a.y * b.x);}
/* assigns ray-surface intersection and surface normal */
void
Intersect_Surface( double z_near, double z_far, double epsilon, double distance,
                  Vector position, Vector prev_position, Ray *ray, HitData *hit )
{
    Vector p_r,          /* point to the right, relative to ray dir and "up" */
          v_d,          /* vector from prev_position to position */
          v_l,          /* vector from prev_position to p_r */
          n;            /* surface normal */

    /* first construct three points that lie on the surface */
    prev_position.z = z_near;
    position.z = z_far;
    /* construct a point one error width to right */
    p_r.x = prev_position.x + epsilon*camera.right_dir.x;
    p_r.y = prev_position.y + epsilon*camera.right_dir.y;
    p_r.z = prev_position.z + epsilon*camera.right_dir.z;
    p_r.z = Displacement( p_r, distance );

    /* get two vectors in the surface plane; cross for surface normal */
    VEC_SUB( position, prev_position, &v_d );
    Normalize( &v_d );
    VEC_SUB( p_r, prev_position, &v_l );
    Normalize( &v_l );
    CROSS( v_l, v_d, &n );
    Normalize( &n );

    /* assign the various hit data */
    hit->distance = distance;
    hit->intersect = prev_position;
    hit->normal = n;
} /* Intersect_Surface() */

```