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Gram-Schmidt Procedure and QR Factorization
 In [1]:
               using DrWatson;
               @quickactivate "MATH361Lectures";
 In [2]:
               import MATH361Lectures
               using LinearAlgebra
             Solving Linear Least Squares with Cholesky
             The following Julia function uses the Cholesky factorization method to solve the problem of least squares, that is, given A and b, we find
             x that solves
                                                                                  \operatorname{argmin}_{v \in \mathbb{R}^n} \|Av - b\|_2
 In [3]:
               function lsqcholesky(A,b)
                 L,U = cholesky(A'*A);
                    w = MATH361Lectures.forwardsub(L,A'*b);
                    x = MATH361Lectures.backsub(U, w);
                    return x
               end
              lsqcholesky (generic function with 1 method)
 Out[3]:
 In [4]:
               A = [1 \ 2 \ -4; \ 3 \ -1 \ 1; \ 1 \ -2 \ 1; \ 3 \ -2 \ -1; \ 4 \ 2 \ -1];
               b = [-1; 2; -2; 1; 3];
               x = lsqcholesky(A,b)
 Out[4]: 3-element Vector{Float64}:
               0.6296350152682856
               0.6441762396393778
               0.5746691871455578
             Compare this with what we obtain using the Julia backslash operator:
 In [5]:
               x bs = A \setminus b
 Out[5]: 3-element Vector{Float64}:
               0.6296350152682856
               0.6441762396393776
               0.5746691871455579
             Additionally, for the solution we have obtained, let's compute ||Ax - b||_2.
 In [6]:
               norm(A*x-b, 2)
              2.2560728637642335
 Out[6]:
 In [7]:
               norm(A*x bs-b, 2)
              2.2560728637642335
 Out[7]:
             Observe what happens if we introduce a small perturbation to x:
 In [8]:
               x_pert = x + [0.00001, -0.00002, 0.00005]
 Out[8]: 3-element Vector{Float64}:
               0.6296450152682855
               0.6441562396393777
               0.5747191871455578
 In [9]:
             norm(A*x_pert - b,2)
 Out[9]: 2.256072880563336
             We see that there is a small increase in the two norm for ||Ax_{pert} - b||_2. To confirm that it is indeed a small perturnation, let's compute
             \|x-x_{\mathrm{pert}}\|_2.
In [10]: norm(x - x_pert,2)
Out[10]: 5.4772255750510576e-5
             Background for QR Factorization
             Orthonormal Vectors
             Recall that the dot product of two column vectors \mathbf{u} = [u_1, u_2, \dots, u_n]^T and \mathbf{v} = [v_1, v_2, \dots, v_n]^T is
                                                                     \mathbf{u} \cdot \mathbf{v} = \mathbf{u}^T \mathbf{v} = u_1 v_1 + u_2 v_2 + \dots + u_n v_n.
             Observe that if {\bf u} is a vector, then \|{\bf u}\|_2^2={\bf u}^T{\bf u}, and also that {\bf u}^T{\bf v}={\bf v}^T{\bf u}.
             Two vectors \mathbf{u} and \mathbf{v} are said to be orthogonal if their dot product is zero, that is, if \mathbf{u} \cdot \mathbf{v} = \mathbf{u}^T \mathbf{v} = 0. We say that a vector is
             normalized (in the 2-norm) if \|\mathbf{u}\|_2 = 1.
             Orthonormal Set of Vectors
             A set of vectors \{\mathbf{q}_1,\mathbf{q}_2,\ldots,\mathbf{q}_n\} is an orthogonal set if \mathbf{q}_i^T\mathbf{q}_j=0 whenever i\neq j. Furthermore, an orthogonal set of vectors is an
             orthonormal set if, in addition \|\mathbf{q}_i\|_2 = 1 for all i.
             Orthogonal Matrices
             A matrix Q is orthogonal if it's columns form a orthogonal set of vectors.
             A matrix Q is ONC if it's columns form an orthonormal set. Equivalently, a matrix Q is ONC if Q^TQ=I.
             As an example, any permutation matrix P is ONC.
             The Gram Schmidt Procedure
             Given any set of linearly independent vectors, \mathbf{a}_1, \mathbf{a}_2, \dots, \mathbf{a}_n, there is a procedure known as the Gram Schmidt procedure that produces
             an orthonormal set \mathbf{q}_1, \mathbf{q}_2, \dots, \mathbf{q}_n with the same span as the original independent set. The Gram Schmidt procedure works as follows:
             Set
                                                        \mathbf{q}_1 = rac{\mathbf{a}_1}{\|\mathbf{a}_1\|_2},
                                                       \mathbf{q}_2 = rac{\mathbf{a}_2 - (\mathbf{q}_1^T \mathbf{a}_2) \mathbf{q}_1}{\|\mathbf{a}_2 - (\mathbf{q}_1^T \mathbf{a}_2) \mathbf{q}_1\|_2},
                                                        \mathbf{q}_3 = rac{\mathbf{a}_3 - (\mathbf{q}_1^T \mathbf{a}_3) \mathbf{q}_1 - (\mathbf{q}_2^T \mathbf{a}_3) \mathbf{q}_2}{\|\mathbf{a}_3 - (\mathbf{q}_1^T \mathbf{a}_3) \mathbf{q}_1 - (\mathbf{q}_2^T \mathbf{a}_3) \mathbf{q}_2\|_2},
                                                       \mathbf{q}_n = rac{\mathbf{a}_n - (\mathbf{q}_1^T \mathbf{a}_n) \mathbf{q}_1 - (\mathbf{q}_2^T \mathbf{a}_n) \mathbf{q}_2 - \cdots - (\mathbf{q}_{n-1}^T \mathbf{a}_n) \mathbf{q}_{n-1}}{\|\mathbf{a}_n - (\mathbf{q}^T \mathbf{a}_n) \mathbf{q}_n - (\mathbf{q}^T \mathbf{a}_n) \mathbf{q}_n - \cdots - (\mathbf{q}^T \mathbf{a}_n) \mathbf{q}_n},
             Now, note that we can "reverse" the result of the Gram Schmidt procedure by solving for the \mathbf{a}_i vectors as linear combinations of the \mathbf{q}_i
             vectors:
                       \mathbf{a}_1 = \|\mathbf{a}_1\|_2 \mathbf{q}_1,
                       \mathbf{a}_2 = (\mathbf{q}_1^T \mathbf{a}_2) \mathbf{q}_1 + \|\mathbf{a}_2 - (\mathbf{q}_1^T \mathbf{a}_2) \mathbf{q}_1\|_2 \mathbf{q}_2,
                       \mathbf{a}_3 = (\mathbf{q}_1^T \mathbf{a}_3) \mathbf{q}_1 + (\mathbf{q}_2^T \mathbf{a}_3) \mathbf{q}_2 + \|\mathbf{a}_3 - (\mathbf{q}_1^T \mathbf{a}_3) \mathbf{q}_1 - (\mathbf{q}_2^T \mathbf{a}_3) \mathbf{q}_2\|_2 \mathbf{q}_3
                       \mathbf{a}_n = (\mathbf{q}_1^T \mathbf{a}_n) \mathbf{q}_1 + (\mathbf{q}_2^T \mathbf{a}_n) \mathbf{q}_2 + \dots + (\mathbf{q}_{n-1}^T \mathbf{a}_n) \mathbf{q}_{n-1} + \|\mathbf{a}_n - (\mathbf{q}_1^T \mathbf{a}_n) \mathbf{q}_1 - (\mathbf{q}_2^T \mathbf{a}_n) \mathbf{q}_2 - \dots - (\mathbf{q}_{n-1}^T \mathbf{a}_n) \mathbf{q}_{n-1}\|_2 \mathbf{q}_n,
             We can simplify the expressions in the last cell by defining
                                                        egin{aligned} r_{kk} = \|\mathbf{a}_k - (\mathbf{q}_1^T \mathbf{a}_k) \mathbf{q}_1 - (\mathbf{q}_2^T \mathbf{a}_k) \mathbf{q}_k - \dots - (\mathbf{q}_{k-1}^T \mathbf{a}_k) \mathbf{q}_{k-1} \|_2, \end{aligned}
                                                         r_{kl} = \mathbf{q}_k^T \mathbf{a}_l, ~~	ext{for}~ l > k
             Then we obtain:
                                                                 \mathbf{a}_1 = r_{11}\mathbf{q}_1,
                                                                 \mathbf{a}_2 = r_{12}\mathbf{q}_1 + r_{22}\mathbf{q}_2,
                                                                 \mathbf{a}_3 = r_{13}\mathbf{q}_1 + r_{23}\mathbf{q}_2 + r_{33}\mathbf{q}_3,
                                                                 \mathbf{a}_n = r_{1n}\mathbf{q}_1 + r_{2n}\mathbf{q}_2 + \cdots + r_{n-1n}\mathbf{q}_{n-1} + r_{nn}\mathbf{q}_n
             Which can be simplified even further to A=QR if we think of the vectors \mathbf{a}_1,\mathbf{a}_2,\ldots,\mathbf{a}_n as forming the columns of the matrix A, the
             vectors \mathbf{q}_1, \mathbf{q}_2, \dots, \mathbf{q}_n as forming the columns of a matrix Q, and the scalars r_{ij} as forming the entries of an upper triangular matrix R.
             The following Julia function implements the Gram Schmidt procedure on the columns of an m \times n matrix to produce an ONC matrix Q:
In [11]:
               function gsqr(A)
                   m,n = size(A);
                    Q = Matrix{Float64}(A);
                    R = Matrix{Float64} (I,n,n);
                   R[1,1] = norm(Q[:,1],2);
                    Q[:,1] = (1/R[1,1]) * Q[:,1]; # get first column of Q
                    for j = 2:n # loop through columns
                           for i = 1:j-1
                                 R[i,j] = dot(Q[:,i],Q[:,j]);
                                  Q[:,j] = Q[:,j] .- R[i,j]*Q[:,i];
                           R[j,j] = norm(Q[:,j],2);
                           Q[:,j] = (1/R[j,j])*Q[:,j];
                      end
                      return Q, R
               end
              gsqr (generic function with 1 method)
Out[11]:
             Let's look at an example:
In [12]:
               A = [1 \ 2 \ 3; -1 \ 1 \ -1; \ 0 \ 1 \ 0; 2 \ -1 \ 2]
              4×3 Matrix{Int64}:
Out[12]:
                -1 1 -1
                 2 -1 2
In [13]:
               Q,R = gsqr(A);
In [14]:
              4×3 Matrix{Float64}:
Out[14]:
                0.408248 0.82885
                                                0.382546
                -0.408248 0.318788 -0.255031
                 0.0 0.382546 -0.82885
                 0.816497 -0.255031 -0.318788
In [15]:
Out[15]: 3×3 Matrix{Float64}:
                2.44949 -0.408248
                                              3.26599
               0.0
                               2.61406
                                              1.6577
                0.0
                               0.0
                                              0.765092
             We will check manually that indeed Q is ONC:
In [16]:
               Q[:,1]'*Q[:,1]
              1.00000000000000002
Out[16]:
In [17]:
               Q[:,2]'*Q[:,2]
              0.99999999999998
Out[17]:
In [18]:
               Q[:,3]'*Q[:,3]
              0.99999999999997
Out[18]:
In [19]:
               Q[:,1]'*Q[:,2]
              5.551115123125783e-17
Out[19]:
In [20]:
               Q[:,1]'*Q[:,3]
               -1.3322676295501878e-15
Out[20]:
In [21]:
               Q[:,2]'*Q[:,3]
              3.3306690738754696e-16
Out[21]:
             Here are a few important points:
             1) The Gram Schmidt procedure results in reduce QR factorization. Of course this is all that is needed for solving the linear least squares
             problem.
             2) The Gram Schmidt method is not the most numerically stable method for QR factorization. In the next lecture, we will look at another
             approach that uses so-called Householder reflectors in order to obtain (full) QR factorization. In preparation for the next lecture, please
             watch the video on QR factorization.
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