(1) 
$$\overline{3Q} = \overline{3Q} + \overline{5Q}$$
 $\overline{3Q} = \overline{3A} + \overline{3Q}$ 
 $\overline{3} = \overline{3A} + \overline{3A} + \overline{3A} + \overline{3A} = \overline{3A} + \overline{3A} = \overline{3A} =$ 

$$d\vec{r} = \partial_1 d\vec{r} + \partial_2 d\vec{r}$$

$$d\vec{r} = \frac{\partial_1}{\partial_1} d\vec{r} + \partial_3 d\vec{r}$$

$$d\vec{r} = (2\vec{r})^2 + (2\vec{r})^$$

- (D'D)2B=

\X

(D'D) = (

$$\frac{\partial \vec{r}}{\partial t} |_{t,\vec{r},\vec{\lambda}} = \frac{\partial \vec{r}}{\partial x} |_{t,\vec{r},\vec{r},\vec{\lambda}} = \frac{\partial \vec{r}}{\partial x} |_{t,\vec{r},\vec{r},\vec{\lambda}} = \frac{\partial \vec{r}}{\partial x} |_{t,\vec{r},\vec{r},\vec{\lambda}} = \frac{2}{4} (t_{t},\vec{r},\vec{r},\vec{\lambda}) |_{t,\vec{r},\vec{\lambda}} = \frac{2}{4} (t_{t},\vec{r},\vec{r},\vec{r},\vec{\lambda}) |_{t,\vec{r},\vec{\lambda}} = \frac{2}{4} (t_{t},\vec{r},\vec{r},\vec{\lambda}) |_{t,\vec{r},\vec{\lambda}} = \frac{2}{4} (t_{t},\vec{r},\vec{r},\vec{\lambda}) |_{t,\vec{r},\vec{\lambda}} = \frac{2}{4} (t_{t},\vec{r},\vec{r},\vec{\lambda}) |_{t,\vec{r},\vec{\lambda}} = \frac{2}{4} (t_{t},\vec{r},\vec{r},\vec{\lambda}$$

7= 2(4,3)

$$\lambda(t_1\sigma_1X) \longrightarrow \lambda(t_1\sigma) \qquad \text{normally bracks} \qquad \frac{2}{3} = \frac{2(t_1\sigma_1)}{2(t_1\sigma_1)} = g_2(\sigma_1\hat{\sigma})$$

$$\lambda(t_1\sigma_1\hat{\sigma}) = \phi(t)f_1(\sigma_1)$$

$$\lambda(t_1\sigma_1\hat{\sigma}) = \phi(t)f_1(\sigma_1\hat{\sigma})$$

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