Scheduling and Analys of Limited-Preemptive Modable Gang Tasks

Joan Marcè i Igual Geoffrey Nelissen Mitra Nasri Paris Panagiotou

24th of February, 2020



- Parallel threads executed together as a "gang"
- Execution does not start until there are enough free cores



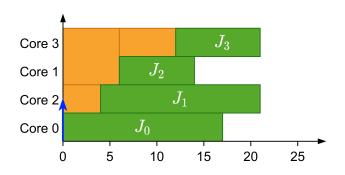
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First of all, let's explain what gang scheduling is.

It's the execution of multiple parallel threads together as a "gang". In these threads the execution does not start until there are enough cores to execute them together.

- 1.We have these jobs assigned to different cores.
- 2.If we release them as a gang job then we should pack them like a single task. Obtaining the following group. <click>
- 3. Then, < click > we have obtained the gang task result of merging the jobs

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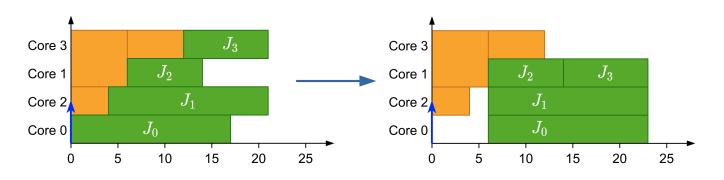
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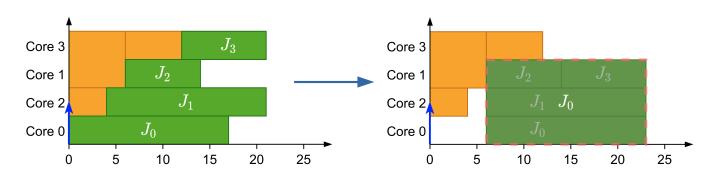
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Avoids overhead when loading initial data



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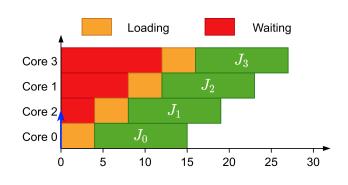
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In this example all these threads have been scheduled at the same time but have to wait until the previous one have finished loading.

On the contrary<click>, if we know that all these threads are starting at the same time we can load the data once for all the threads at the same time which is what we would do with gang scheduling.

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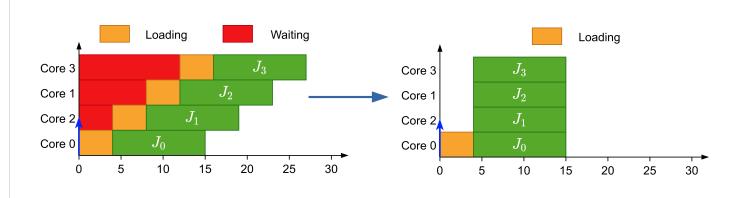
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- Avoids overhead when loading initial data
- Allows synchronization



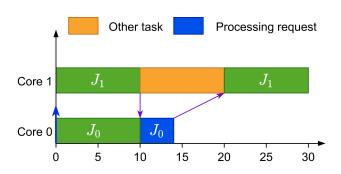
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Additionally it helps in synchronization situations, like in the following example<click>

Here there are two jobs and job 1 sends some data to job 0 that is processed and sent back. In this case another task has been scheduled after job 1 sent the data and after the other task finishes then job 1 can continue its execution

On the other hand if we use gang<click> the job would wait for job 0 to finish the processing part and return the results as no other task would be allowed to execute while job 1 is waiting.

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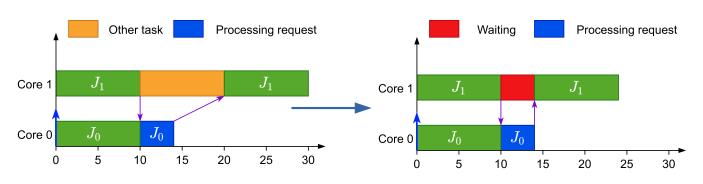
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- <click>Moldable gang, where the number of cores can be in a range of values and the actual chosen value is decided when scheduling the task
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Previous work

- Introduced in the context of high-performance computing[1]
- In real-time:
 - For rigid tasks:
 - Job-Level Fixed Priority is not predictable[2]
 - An optimal scheduler (DP-Fair) exists for preemptive tasks[3]
 - For moldable tasks
 - Global EDF has been adapted[4]
 - Scheduler that chooses cores to meet the deadline



^[1]Ousterhout, 1982 ^[2]Goossens et al., 2010 [3]Goossens et al., 2016 [4]Kato et al.,2009 ^[5]Berten et al., 2011

Previous work

- In real-time:
 - For malleable tasks:
 - An optimal algorithm, in terms of processors, has been proposed[6]
 - Bundled task-model[7]:



^[6]Collette et al., 2008 ^[7]Wasly et al., 2017

Schedulability analysis



Our work



LPMRGS

