

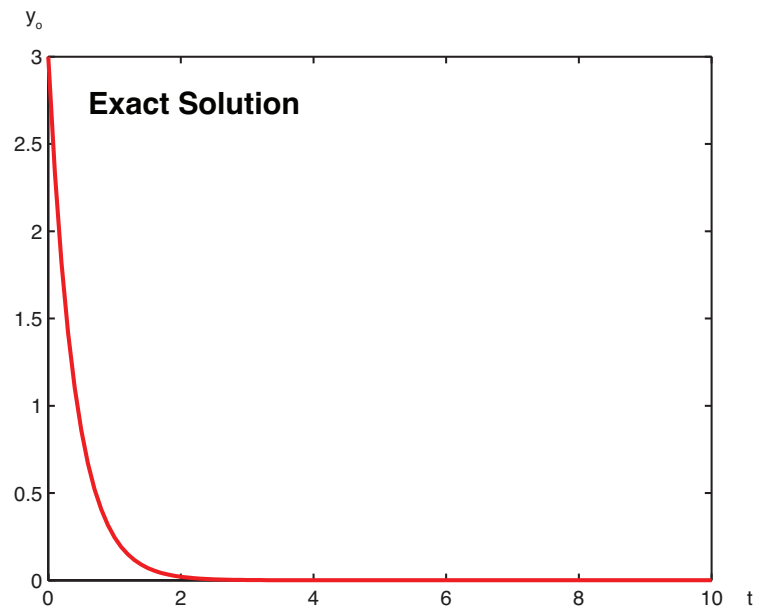
1. For the differential equation

$$(D + 2.5)y_0(t) = 0$$

with the initial condition $y_0(0) = 3$:

- Find and plot the analytical (exact) solution to the differential equation for $0 \leq t \leq 10$.
- Write a program in C++ to plot a numerical solution using (3). You may have to try several values of Δt to get a good enough approximation.
- Compare the exact solution with the approximate solution.

$$\begin{aligned}
 1 \Rightarrow \lambda + 2.5 &= 0 & t & \quad y_0 \\
 2 \Rightarrow \lambda &= -2.5 & 0 & \quad 3.000 \times 10^{-0} \\
 3 \Rightarrow y_0(t) &= C_1 e^{-2.5t} & 1 & \quad 2.462 \times 10^{-1} \\
 4 \Rightarrow 3 &= C_1 & 2 & \quad 2.021 \times 10^{-2} \\
 5 \Rightarrow y_0(t) &= 3e^{-2.5t} & 3 & \quad 1.659 \times 10^{-3} \\
 & & 4 & \quad 1.362 \times 10^{-4} \\
 & & 5 & \quad 1.118 \times 10^{-5} \\
 & & 6 & \quad 0.918 \times 10^{-6} \\
 & & 7 & \quad 0.753 \times 10^{-7} \\
 & & 8 & \quad 0.618 \times 10^{-8} \\
 & & 9 & \quad 0.508 \times 10^{-9} \\
 & & 10 & \quad 0.412 \times 10^{-10}
 \end{aligned}$$



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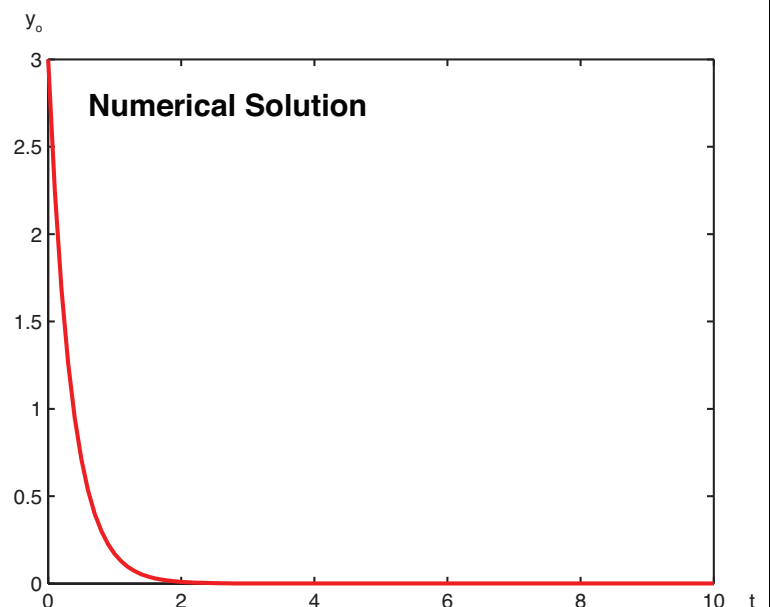
// 10/10/2014 - ECE 3620 - Meine, Joel
// Assignment #1 - Problem 1

#include <iostream>
#include <iomanip>
#include <math.h>
#include <vector>
#include <fstream>
using namespace std;

double a = -2.5; // Constant
double yi = 3; // Value - Initial
double dt = 0.1; // Time - Step Size
double tf = 10; // Time - Final
double Dp = 10; // Data Points, No. of

vector<double> ODE(vector<double> t)
{
    double y;
    vector<double> Y;
    y = yi;
    Y.push_back(y);
    for (int i = 0; i < t.size(); i++)
    {

```



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        y = (1 + a*dt)*y;
        Y.push_back(y);
    }
    Y.pop_back();
    return(Y);
}

int main()
{
    std::cout << "Assignment #1 - Problem 1" << std::endl;
    std::cout << "=====" << std::endl;
    std::cout << "For the differential equation..." << std::endl;
    std::cout << "(D + 2.5)yo(t) = 0" << std::endl;
    std::cout << "with initial condition yo(0) = 3:" << std::endl;
    std::cout << "Constant, a = " << a << std::endl;
    std::cout << "Value - Initial, yo(0) = " << yi << std::endl;
    std::cout << "Time - Step Size, dt = " << dt << std::endl;
    std::cout << "Time - Max, tf = " << tf << std::endl;
    std::cout << "-----" << std::endl;
    std::cout << " t      y" << std::endl;
    std::cout << "-----" << std::endl;

    double I;
    I = (tf/dt)/Dp; // Increment Length, I

    vector<double> T,sT; // Time List, T; Time List (Shortened), sT
    for (int j = 0; j <= tf/dt; j++)
    {
        T.push_back(j*dt);
    }
    for (int k = 0; k <= I; k++)
    {
        sT.push_back(T[k*I]);
    }

    vector<double> P,sP; // Print List, P; Print List (Shortened), sP
    P = ODE(T);
    for (int m = 0; m <= I; m++)
    {
        sP.push_back(P[m*I]);
    }
    for (int n = 0; n < sP.size(); n++)
    {
        printf(" %2.1f  %20.18f \n", sT[n], sP[n]);
    }
    ofstream outfile("A1_P1.txt");
    for (int o = 0; o < P.size(); o++)
    {
        outfile << T[o] << " " << P[o] << endl;
    }

    std::cout << "-----" << std::endl;
    system("pause");
    return 0;
}

```

```

Assignment #1 - Problem 1
=====
For the differential equation...
(D + 2.5)yo(t) = 0
with initial condition yo(0) = 3:
Constant, a = -2.5
Value - Initial, yo(0) = 3
Time - Step Size, dt = 0.1
Time - Max, tf = 10
-----
 t      y
-----
0.0    3.0000000000000000
1.0    0.168940544128417970
2.0    0.009513635816801980
3.0    0.000535746270510044
4.0    0.000030169755484912
5.0    0.000001698964969281
6.0    0.000000095674688788
7.0    0.000000005387777994
8.0    0.000000000303404715
9.0    0.000000000017085786
10.0   0.000000000000962161
-----

```

2. For the third-order differential equation

$$(D^3 + 0.6D^2 + 25.1125D + 2.5063)y_0(t) = 0$$

with the initial conditions $y_0(0) = 1.5$, $\dot{y}_0(0) = 2$, $\ddot{y}_0(0) = -1$:

- Find and plot the analytical solution to the differential equation for $0 \leq t \leq 10$. Identify the roots of the characteristic equation and plot them in the complex plane.
- Put the third-order differential equation into state-space form.
- Write a program in C(++) to plot an approximate solution using (8). You may have to try several values of Δt to get a reasonable approximation.
- Compare the exact solution with the approximate solution.

$$^1 \Rightarrow \lambda^3 + 0.6\lambda^2 + 25.1125\lambda + 2.5063 = 0$$

$$^2 \Rightarrow (\lambda + 0.1)(\lambda^2 + 0.5 + 25.0625) = 0$$

$$^3 \Rightarrow \lambda_1 = -0.25 + j5 \quad \lambda_2 = -0.25 - j5 \quad \lambda_3 = -0.1$$

$$^4 \Rightarrow y_0(t) = (C_1 \cos 5t + C_2 \sin 5t)e^{-0.25t} + C_3 e^{-0.1t}$$

$$^5 \Rightarrow \dot{y}_0(t) = (C_1(-0.25 \cos 5t - 5 \sin 5t) + C_2(5 \cos 5t - 0.25 \sin 5t))e^{-0.25t} - 0.1C_3 e^{-0.1t}$$

$$^6 \Rightarrow \ddot{y}_0(t) = (C_1(-24.9375 \cos 5t + 2.5 \sin 5t) + C_2(-2.5 \cos 5t - 24.9375 \sin 5t))e^{-0.25t} + 0.01C_3 e^{-0.1t}$$

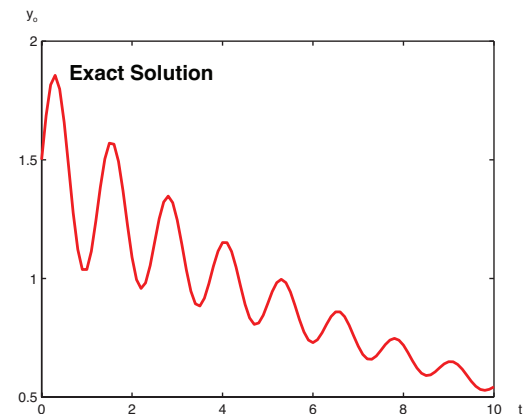
$$1.5 = C_1 + C_3$$

$$^7 \Rightarrow 2 = -0.25C_1 + 5C_2 - 0.1C_3$$

$$-1 = -24.9375C_1 - 2.5C_2 + 0.01C_3$$

$$^8 \Rightarrow C_1 = -0.002398 \quad C_2 = 0.429928 \quad C_3 = 1.5024$$

$$^9 \Rightarrow y_0(t) = (-0.002398 \cos 5t + 0.429928 \sin 5t)e^{-0.25t} + 1.5024e^{-0.1t}$$



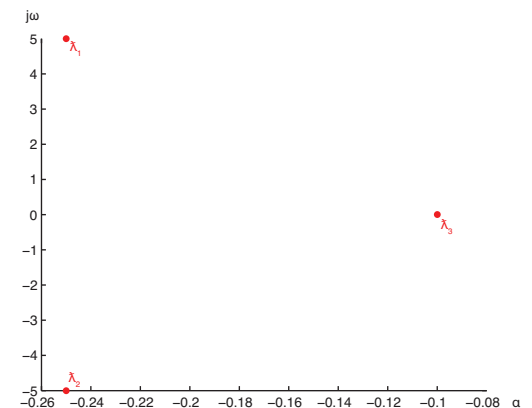
$$^1 \Rightarrow \begin{bmatrix} \dot{x}_1(t) \\ \dot{x}_2(t) \\ \dot{x}_3(t) \end{bmatrix} = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -2.5063 & -25.1125 & -0.6 \end{bmatrix} \begin{bmatrix} x_1(t) \\ x_2(t) \\ x_3(t) \end{bmatrix}$$

$$\dot{x}_1(t) = x_2(t)$$

$$^2 \Rightarrow \dot{x}_2(t) = x_3(t)$$

$$\dot{x}_3(t) = -2.5063x_1(t) - 25.1125x_2(t) - 0.6x_3(t)$$

$$^3 \Rightarrow \dot{x}_3(t) + 0.6x_3(t) + 25.1125x_2(t) + 2.5063x_1(t) = 0$$



```

// 10/10/2014 - ECE 3620 - Meine, Joel
// Assignment #1 - Problem 2

#include <iostream>
#include <iomanip>
#include <math.h>
#include <vector>
#include <fstream>
using namespace std;

vector<double> a = {2.5063,25.1125,0.6}; // Constants
vector<double> yi = {1.5,2,-1}; // Values - Initial
int O = a.size(); // Order of Differential Equation
double dt = 0.001; // Time - Step Size
double tf = 10; // Time - Final
double Dp = 10; // Data Points, No. of

// NOTE: The number of items in a and yi "must" be equal.

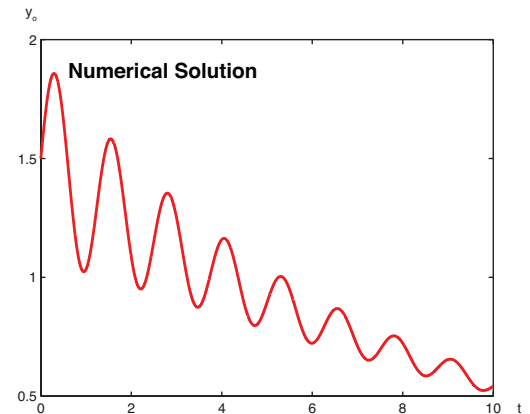
vector<double> matrixOP_vecmul(vector<vector<double>> M, vector<double> u)
{ // Calculates v(n) = M(nxm) * u(m)
    vector<double> v;
    for (int k = 0; k < O; k++)
        v.push_back(0);
    int i, j;
    for (i = 0; i < O; i++){
        v[i] = 0;
        for (j = 0; j < O; j++){
            v[i] = v[i] + M[i][j] * u[j];
        }
    }
    return(v);
}

vector<vector<double>> ODE_m(vector<double> t)
{
    vector<double> y;
    vector<vector<double>> Y;
    y = yi;
    Y.push_back(y);

    // Z = w + A*dt
    vector<double> z;
    int r, s;
    for (r = 0; r < O; r++) // Column Size, Initialize
        z.push_back(0);
    vector<vector<double>> Z, w, A;
    for (s = 0; s < O; s++) // Row Size, Initialize
    {
        Z.push_back(z);
        w.push_back(z);
        A.push_back(z);
    }
    int i, j;
    for (i = 0; i < O; i++) // w
        for (j = 0; j < O; j++)
            if (i == j)
                w[i][j] = 1;
            else
                w[i][j] = 0;

    int m, n;
    for (m = 0; m < O; m++) // A
        for (n = 0; n < O; n++)
            if (n == m + 1 && m != O - 1)
                A[m][n] = 1;
            else if (m == O - 1)
                A[m][n] = -a[n];
}

```



```

        else
            A[m][n] = 0;

    int p, q;
    for (p = 0; p < 0; p++) // Z
        for (q = 0; q < 0; q++)
            Z[p][q] = w[p][q] + A[p][q]*dt;

    // y = Z*y
    for (int r = 0; r < t.size(); r++)
    {
        y = matrixOP_vecmul(Z, y);
        Y.push_back(y);
    }
    Y.pop_back();
    return(Y);
}

int main()
{
    std::cout << "Assignment #1 - Problem 2" << std::endl;
    std::cout << "===== " << std::endl;
    std::cout << "For the differential equation..." << std::endl;
    std::cout << "(D^3 + 0.6D^2 + 25.1125D + 2.5063)yo(t) = 0" << std::endl;
    std::cout << "with initial conditions yo(0) = 1.5, Dyo(0) = 2, D^2yo(0) = -1:" << std::endl;
    std::cout << "Constant, a0 = " << a[0] << std::endl;
    std::cout << "Constant, a1 = " << a[1] << std::endl;
    std::cout << "Constant, a2 = " << a[2] << std::endl;
    std::cout << "Value - Initial, yo(0) = " << yi[0] << std::endl;
    std::cout << "Value - Initial, Dyo(0) = " << yi[1] << std::endl;
    std::cout << "Value - Initial, D^2yo(0) = " << yi[2] << std::endl;
    std::cout << "Time - Step Size, dt = " << dt << std::endl;
    std::cout << "Time - Max, tf = " << tf << std::endl;
    std::cout << "-----" << std::endl;
    std::cout << " t      y" << std::endl;
    std::cout << "-----" << std::endl;

    double I;
    I = (tf/dt)/Dp; // Increment Length, I

    vector<double> T, sT; // Time List, T; Time List (Shortened), sT
    for (int j = 0; j <= tf / dt; j++)
    {
        T.push_back(j*dt);
    }
    for (int k = 0; k <= Dp; k++)
    {
        sT.push_back(T[k*I]);
    }

    vector<double> P, sP; // Print List, P; Print List (Shortened), sP

    vector<vector<double>> Q;
    Q = ODE_m(T);
    int f, g;
    for (f = 0; f < T.size(); f++)
        for (g = 0; g < T.size(); g++)
            if (g == 0)
                P.push_back(Q[f][g]); // Retrieves Only the Results of yo(t).

    for (int m = 0; m <= Dp; m++)
    {
        sP.push_back(P[m*I]);
    }
    for (int n = 0; n < sP.size(); n++)
    {
        printf(" %2.1f %12.15f \n", sT[n], sP[n]);
    }
    ofstream outfile("A1_P2.txt");

```

```

Assignment #1 - Problem 2
=====
For the differential equation...
(D^3 + 0.6D^2 + 25.1125D + 2.5063)yo(t) = 0
with initial conditions yo(0) = 1.5, Dyo(0) = 2, D^2yo(0) = -1:
Constant, a0 = 2.5063
Constant, a1 = 25.1125
Constant, a2 = 0.6
Value - Initial, yo(0) = 1.5
Value - Initial, Dyo(0) = 2
Value - Initial, D^2yo(0) = -1
Time - Step Size, dt = 0.001
Time - Max, tf = 10
-----
 t      y
-----
0.0  1.500000000000000
1.0  1.033887852715961
2.0  1.085303450029545
3.0  1.250394073720806
4.0  1.158792742574219
5.0  0.893926695480015
6.0  0.722374852128171
7.0  0.710910246564919
8.0  0.722762280593640
9.0  0.654071852139619
10.0 0.542423987041104
-----

```

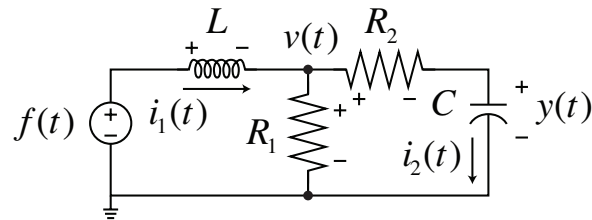
```

for (int o = 0; o < P.size(); o++)
{
    outfile << T[o] << " " << P[o] << endl;
}

std::cout << "-----" << std::endl;
system("pause");
return 0;
}

```

3. For the circuit shown here:



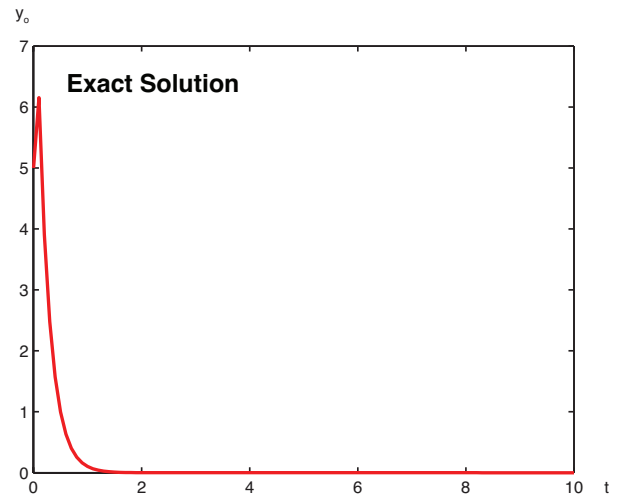
where $R_1 = 1 \text{ k}\Omega$, $R_2 = 22 \text{ k}\Omega$, $C = 10 \text{ }\mu\text{F}$, and $L = 5 \text{ H}$.

- Determine a differential equation relating the input $f(t)$ to the output $y(t)$.
- Determine the initial conditions on $y(t)$ if $i_1(0) = 0.2 \text{ A}$ and $y(0) = 5 \text{ V}$.
- Determine the analytical solution for the zero-input response of the system with these initial conditions.
- Represent the differential equation for the circuit in state variable form.
- Using your program, determine a numerical solution to the differential equation for the zero-input response.
- Plot and compare the analytical and the numerical solution. Comment on your results.
- Suppose that the circuit had a nonlinear element in it, such as dependent source. Describe how the analytical solution and numerical solution would change.

$$\begin{aligned}
 1 \Rightarrow & \frac{v}{R_1} + \frac{1}{L} \int v - f \, dt + \frac{v-y}{R_2} = 0 & 1 \Rightarrow & R_1(i_2(t) - i_1(t)) + R_2 i_2 + y(t) = 0 \\
 & \frac{y-v}{R_2} + C \frac{dy}{dt} = 0 & 2 \Rightarrow & (1 \times 10^3)(i_2(0) - 0.2) + (22 \times 10^3)i_2(0) + 5 = 0 \\
 2 \Rightarrow & v = y + R_2 C \frac{dy}{dt} & 3 \Rightarrow & i_2(0) = 8.478261 \text{ mA} \\
 & & 4 \Rightarrow & \frac{i_2(0)}{C} = \frac{dy}{dt}(0) \\
 3 \Rightarrow & \frac{y}{R_1} + \frac{R_2}{R_1} C \frac{dy}{dt} + C \frac{dy}{dt} + \frac{1}{L} \int y + R_2 C \frac{dy}{dt} - f \, dt = 0 & 5 \Rightarrow & \frac{dy}{dt}(0) = 847.826 \text{ V/s} \\
 4 \Rightarrow & (1.0 \times 10^{-3}) \frac{dy}{dt} + (2.2 \times 10^{-4}) \frac{d^2 y}{dt^2} + (10 \times 10^{-6}) \frac{d^2 y}{dt^2} + 0.2 \left(y + 0.22 \frac{dy}{dt} - f \right) = 0 \\
 5 \Rightarrow & (1.0 \times 10^{-3}) D y(t) + (2.2 \times 10^{-4}) D^2 y(t) + (10 \times 10^{-6}) D^2 y(t) + 0.2 y(t) + (44 \times 10^{-3}) D y(t) - 0.2 f(t) = 0 \\
 6 \Rightarrow & (2.3 \times 10^{-4}) D^2 y(t) + (45 \times 10^{-3}) D y(t) + 0.2 y(t) = 0.2 f(t) \\
 7 \Rightarrow & (D^2 + 195.652 D + 869.565) y(t) = 869.565 f(t)
 \end{aligned}$$

$$\begin{aligned}
 1 \Rightarrow & \lambda^2 + 195.652 \lambda + 869.565 = 0 \\
 2 \Rightarrow & (\lambda + 4.55027)(\lambda + 191.102) = 0 \\
 3 \Rightarrow & \lambda_1 = -4.55027 \quad \lambda_2 = -191.102 \\
 4 \Rightarrow & y_o(t) = C_1 e^{-4.55027t} + C_2 e^{-191.102t} \\
 5 \Rightarrow & \dot{y}_o(t) = -4.55027 C_1 e^{-4.55027t} - 191.102 C_2 e^{-191.102t} \\
 6 \Rightarrow & y_o(0) = C_1 + C_2 \\
 & \dot{y}_o(0) = -4.55027 C_1 - 191.102 C_2 \\
 7 \Rightarrow & 5 = C_1 + C_2 \\
 & 847.826 = -4.55027 C_1 - 191.102 C_2 \\
 8 \Rightarrow & C_1 = 9.7 \quad C_2 = -4.7 \\
 9 \Rightarrow & y_o(t) = 9.7 e^{-4.55027t} - 4.7 e^{-191.102t}
 \end{aligned}$$

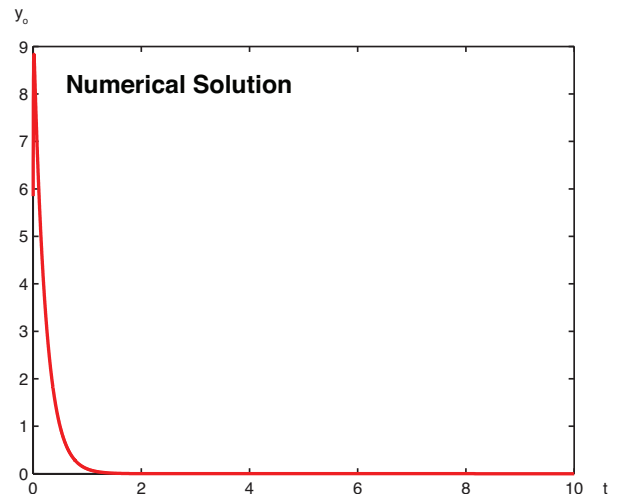
t	y _o
0	5.000 × 10 ⁻⁰
1	1.025 × 10 ⁻¹
2	1.083 × 10 ⁻³
3	1.144 × 10 ⁻⁵
4	1.208 × 10 ⁻⁷
5	1.276 × 10 ⁻⁹
6	1.348 × 10 ⁻¹¹
7	1.425 × 10 ⁻¹³
8	1.505 × 10 ⁻¹⁵
9	1.590 × 10 ⁻¹⁷
10	1.680 × 10 ⁻¹⁹



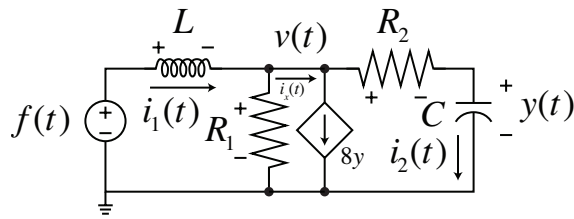
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Assignment #1 - Problem 3
=====
For the differential equation...
(D^2 + 195.652D + 869.565)y_o(t) = 869.565*f(t)
with initial conditions y_o(0) = 5, Dyo(0) = 847.826:
Constant, a0 = 869.565
Constant, a1 = 195.652
Value - Initial, y_o(0) = 5
Value - Initial, Dyo(0) = 847.826
Time - Step Size, dt = 0.001
Time - Max, tf = 10
=====
t      y
-----
0.0    5.000000000000000
1.0    0.101067312486863
2.0    0.001056681139482
3.0    0.000011047835379
4.0    0.000000115507566
5.0    0.000000001207657
6.0    0.00000000012626
7.0    0.00000000000132
8.0    0.000000000000001
9.0    0.000000000000000
10.0   0.000000000000000
=====

```



We see that with the increased precision of the numerical solution, it is revealed that from the starting initial condition of $y_o(0) = 5$ V, the voltage rises just short of 9 V very quickly, but then decays towards stability also within a very short amount of time.



$$1 \Rightarrow \frac{v}{R_1} + \frac{1}{L} \int v - f dt + \frac{v-y}{R_2} + 8y = 0$$

$$\frac{y-v}{R_2} + C \frac{dy}{dt} = 0$$

$$2 \Rightarrow v = y + R_2 C \frac{dy}{dt}$$

$$3 \Rightarrow \frac{y}{R_1} + \frac{R_2}{R_1} C \frac{dy}{dt} + C \frac{dy}{dt} + \frac{1}{L} \int y + R_2 C \frac{dy}{dt} - f dt + 8y = 0$$

$$4 \Rightarrow (1.0 \times 10^{-3}) \frac{dy}{dt} + (2.2 \times 10^{-4}) \frac{d^2 y}{dt^2} + (10 \times 10^{-6}) \frac{d^2 y}{dt^2} + 0.2 \left(y + 0.22 \frac{dy}{dt} - f \right) + 8 \frac{dy}{dt} = 0$$

$$5 \Rightarrow (1.0 \times 10^{-3}) D y(t) + (2.2 \times 10^{-4}) D^2 y(t) + (10 \times 10^{-6}) D^2 y(t) + 0.2 y(t) + (44 \times 10^{-3}) D y(t) - 0.2 f(t) + 8 D y(t) = 0$$

$$6 \Rightarrow (2.3 \times 10^{-4}) D^2 y(t) + 8.045 D y(t) + 0.2 y(t) = 0.2 f(t)$$

$$7 \Rightarrow (D^2 + 34978.3D + 869.565) y(t) = 869.565 f(t)$$

$$1 \Rightarrow \lambda^2 + 34978.3\lambda + 869.565 = 0$$

$$2 \Rightarrow (\lambda + 34978.2)(\lambda + 0.02486) = 0$$

$$3 \Rightarrow \lambda_1 = -34978.2 \quad \lambda_2 = -0.02486$$

$$4 \Rightarrow y_o(t) = C_1 e^{-34978.2t} + C_2 e^{-0.02486t}$$

$$5 \Rightarrow \dot{y}_o(t) = -34978.2 C_1 e^{-34978.2t} - 0.02486 C_2 e^{-0.02486t}$$

$$6 \Rightarrow y_o(0) = C_1 + C_2$$

$$\dot{y}_o(0) = -34978.2 C_1 - 0.02486 C_2$$

$$7 \Rightarrow 5 = C_1 + C_2$$

$$-174804 = -34978.2 C_1 - 0.02486 C_2$$

$$8 \Rightarrow C_1 = 4.99752 \quad C_2 = 0.002482$$

$$9 \Rightarrow y_o(t) = 4.99752 e^{-34978.2t} + 0.002482 e^{-0.02486t}$$

$$1 \Rightarrow i_1(0) - i_x(0) + 8y(0) + i_2(0) = 0 \quad i_x = \frac{v(0)}{R_1}$$

$$R_2 i_2(0) + y(0) + v(0) = 0$$

$$2 \Rightarrow v(0) = -R_2 i_2(0) - y$$

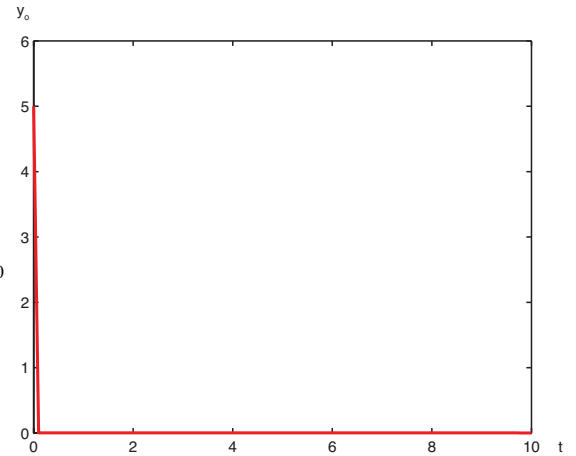
$$3 \Rightarrow i_1(0) + 8y(0) + \frac{y(0)}{R_1} + \frac{R_2}{R_1} i_2(0) + i_2(0) = 0$$

$$4 \Rightarrow 23 i_2(0) + 40.205 = 0$$

$$5 \Rightarrow i_2(0) = -1.74804 \text{ A}$$

$$6 \Rightarrow \frac{i_2(0)}{C} = \frac{dy}{dt}(0)$$

$$7 \Rightarrow \frac{dy}{dt}(0) = -174804 \text{ V/s}$$



As with the earlier comparisons between the analytical solution and the numerical solution computed from the program, the differences are exceedingly marginal. In comparing the circuit against the same circuit with a dependent source in it, we see that the graph of the circuit with the dependent source shows a rate of decay that is much quicker which therefore approaches stability faster.