

```
#include <CapacitiveSensor.h>
```

```
CapacitiveSensor sensor = CapacitiveSensor(7, 6);  
CapacitiveSensor sensor1 = CapacitiveSensor(7, 5);  
CapacitiveSensor sensor2 = CapacitiveSensor(7, 4);  
CapacitiveSensor sensor3 = CapacitiveSensor(7, 3);
```

```
int val0 = 0;  
int lastVal0 = 0;  
int val = 0;  
int lastVal = 0;  
int val1 = 0;  
int lastVal1 = 0;  
int val2 = 0;  
int lastVal2 = 0;  
int val3 = 0;  
int lastVal3 = 0;  
int ldr = 0;  
int lastLdr = 0;
```

```
void setup()  
{  
  Serial.begin(9600);  
}
```

```
void loop()  
{
```

```
//#define MIDIMessage;
```

```
  int lectura = sensor.capacitiveSensor(30);  
  int lectura1 = sensor1.capacitiveSensor(30);  
  int lectura2 = sensor2.capacitiveSensor(30);  
  int lectura3 = sensor3.capacitiveSensor(30);
```

```
//if ((lectura/9) > 127)  
//(lectura/9) == 127;  
// val0 = (lectura/9);  
//   if (val0 != lastVal)  
//   {  
//     MIDIMessage(176,5,val);}  
//   lastVal0 = val0;
```

```
if (lectura > 80)
```

```
val = 127;
else
val = 0;
if (val != lastVal){
    MIDIMessage(176,1,val);}
lastVal = val;
```

```
if (lectura1 > 80)
val1 = 127;
else
val1 = 0;
if (val1 != lastVal1){
    MIDIMessage(176,2,val1);}
lastVal1 = val1;
```

```
if (lectura2 > 80)
val2 = 127;
else
val2 = 0;
if (val2 != lastVal2){
    MIDIMessage(176,3,val2);}
lastVal2 = val2;
```

```
if (lectura3 > 80)
val3 = 127;
else
val3 = 0;
if (val3 != lastVal3){
    MIDIMessage(176,4,val3);}
lastVal3 = val3;
```

```
ldr = (analogRead(1)/8);
if (ldr != lastLdr) {
    MIDIMessage(176,6,ldr);
}
lastLdr = ldr;
```

```
delay(10);
```

```
//      Serial.print(lectura1);
//      Serial.println(";");
//      Serial.print(lectura2);
//      Serial.println(";");
```

```
}  
void MIDIMessage(byte command, byte data1, byte data2) {  
    Serial.write(command);  
    Serial.write(data1);  
    Serial.write(data2);  
}  
//
```