

# Animated Skeleton in a Coffin for Halloween

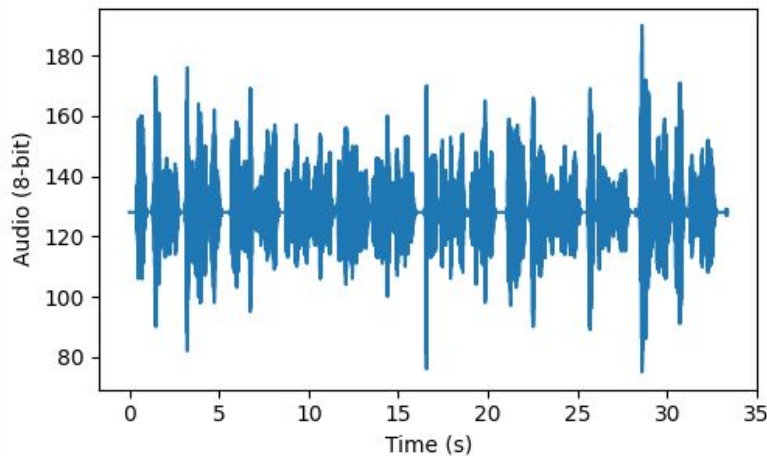


<https://github.com/jmoonware/jaws>

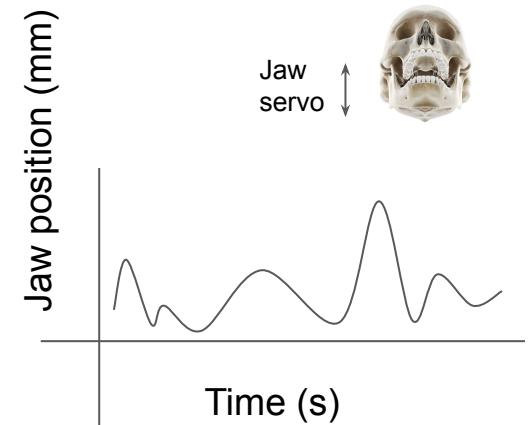
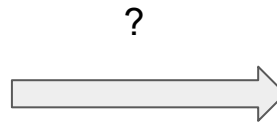
The basic issue: How do you animate the jaw motion of a plastic skull, given an audio input?

Possible solutions:

- (1) Feed audio into low-pass circuit and use amplitude to drive motor
  - A simple solution that doesn't work very well... ❌
- (2) Get a pile of videos, detect jaw motion, and feed results (with audio) into a neural net
  - Allows arbitrary audio input, but is a lot of work! ❌
- (3) **"In between" solution:**
  - Record video of desired speech, detect jaw motion, and use synchronized jaw motion and audio as playback on a microprocessor ←



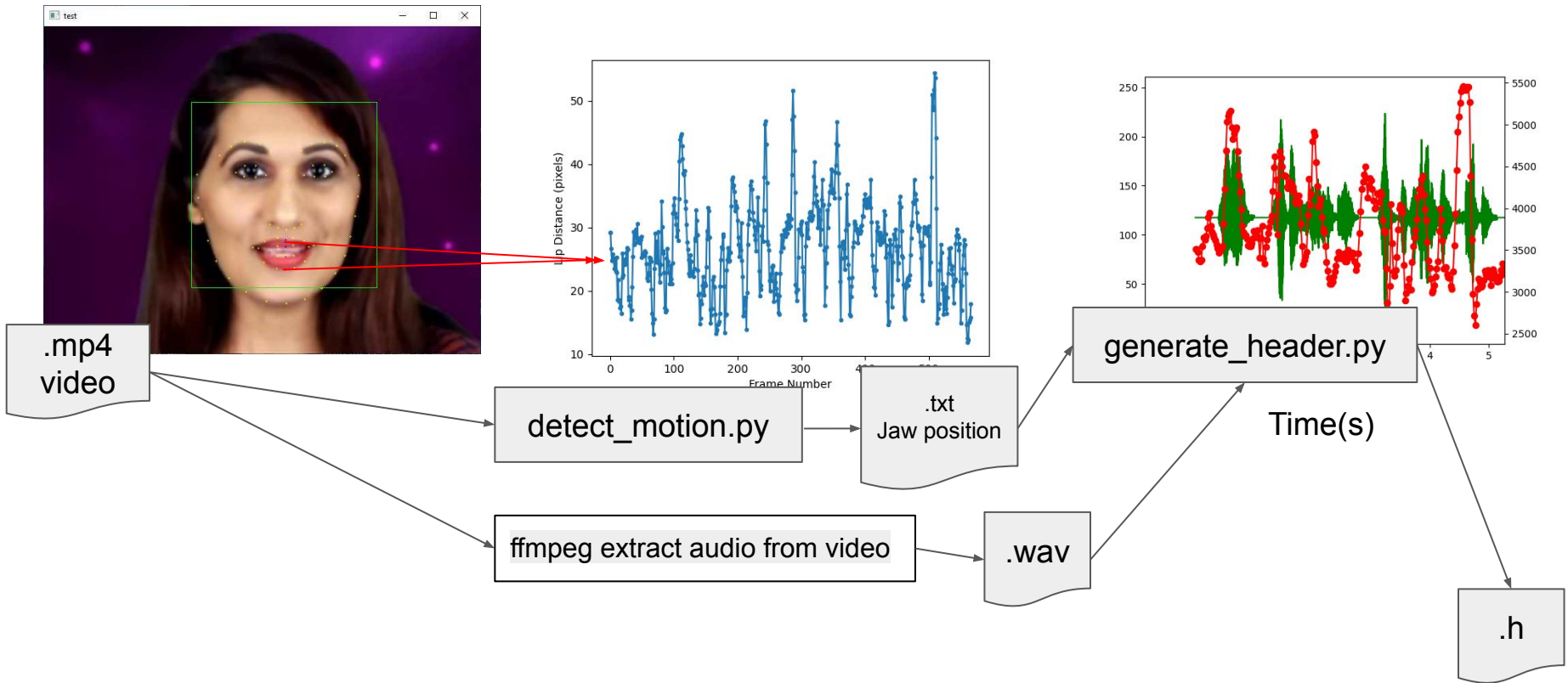
Audio signal



Jaw motion

Also, want to turn other things on/off, open/close lids, etc. so some DIO is needed

# How the servo/speech audio is synchronized

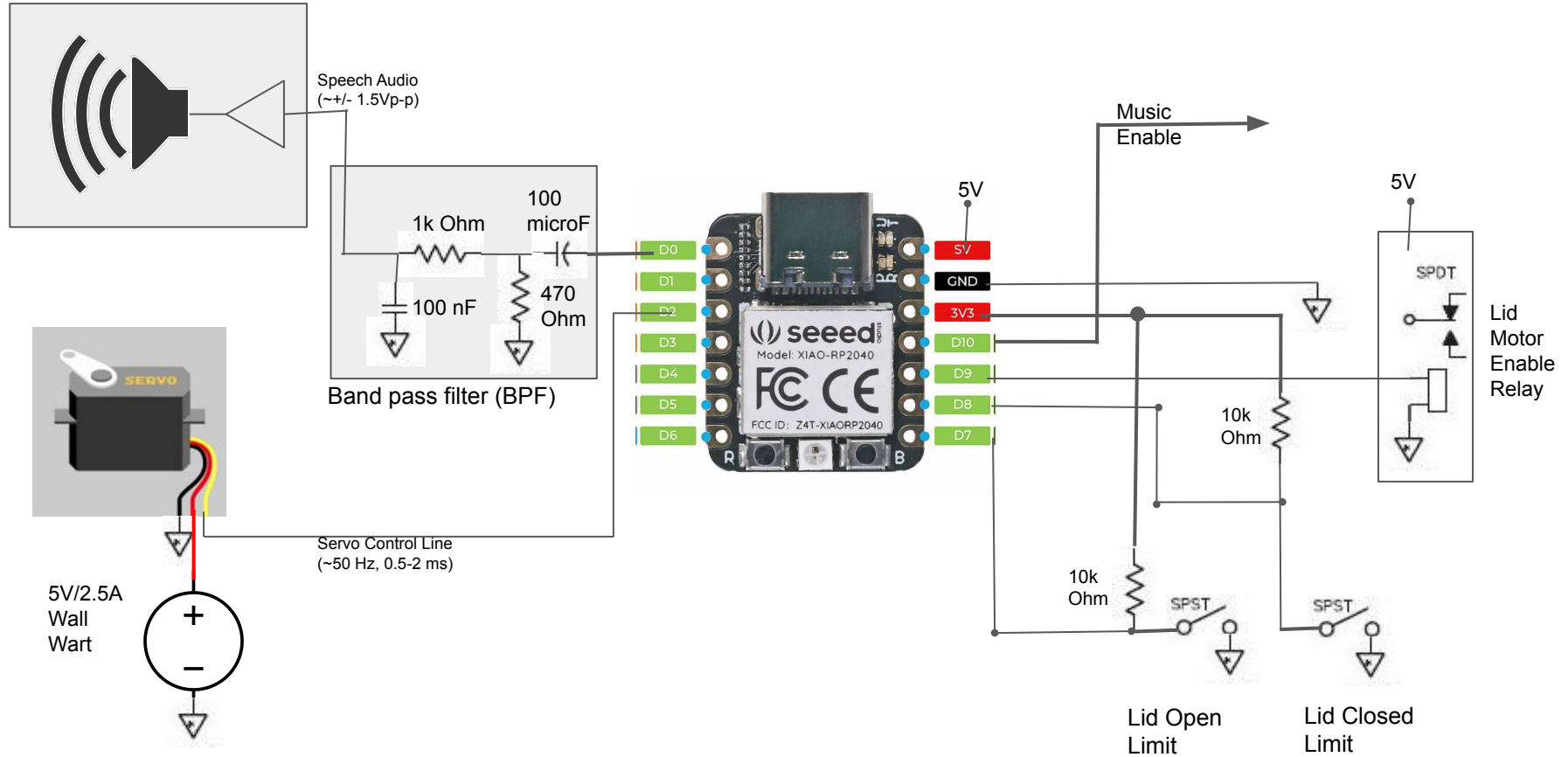


The generated **.h** file has const buffers of audio, motion PWM set values. This is included in the Arduino project, compiled, then loaded onto the Seeeduino Xiao chip

See <https://github.com/jmoonware/jaws>

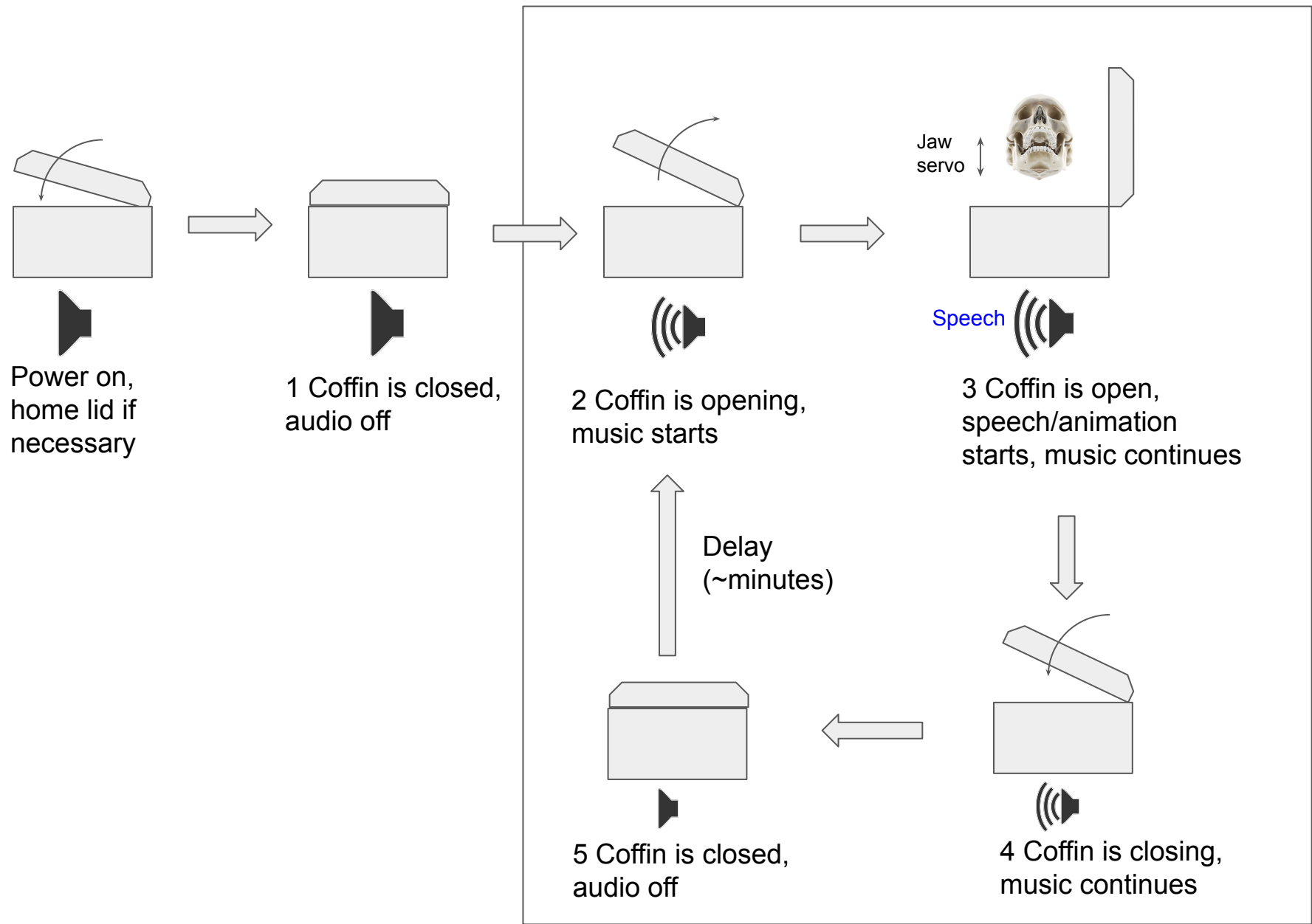
# Circuit diagram for overall system: RP2040-based microcontroller

E.g external amplified computer speakers

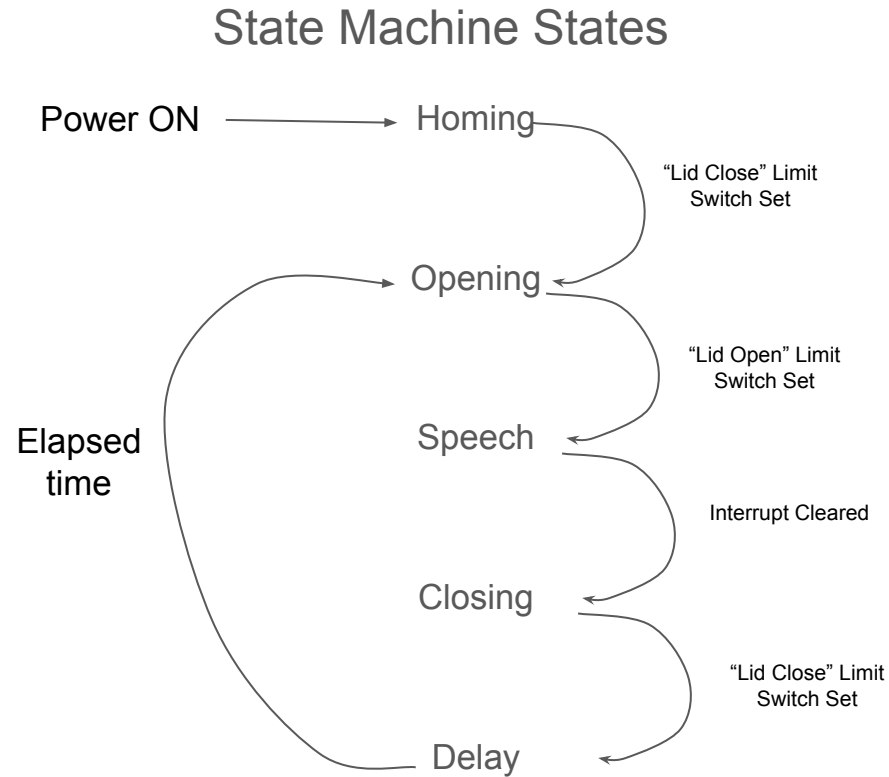


Note: could easily add second, independent stereo channel (and BPF) on D1

Overview of performance - animated skeleton in coffin



# Arduino Software State Machine



See [https://github.com/jmoonware/jaws\\_arduino](https://github.com/jmoonware/jaws_arduino)

# Extracting audio from video: ffmpeg usage

Example:

```
ffmpeg.exe -i test_raw.mp4 -map 0:a -ar 20000 -c:a pcm_u8 -ac 1 output20_u8_1.wav
```

Options explanations:

-i ⇒ input mp4 video file

-map 0:a ⇒ Select input 0, map all ('a') audio streams

-ar 20000 ⇒ audio sampling frequency (here, 20,000 Hz)

-c:a pcm\_u8 ⇒ set codec to 8 bits, unsigned (so audio value is 0-255)

-ac 1 ⇒ Set to (here, 1) output audio channels (i.e. mono)

# How the Pulse Width Modulation (PWM) Counters are set

“IRQ PWM” - generates an interrupt on each audio sample ( $\sim 20\text{kHz}$ )

“Motor PWM” - generates ( $\sim 50\text{ Hz}$  update,  $\sim 0.5\text{-}2\text{ ms}$  width) servo control pulses

“Audio PWM” - generates PWM signal ( $\sim 500\text{ kHz}$ ), then band-pass filtered into  $\sim 20\text{-}10\text{kHz}$  analog signal