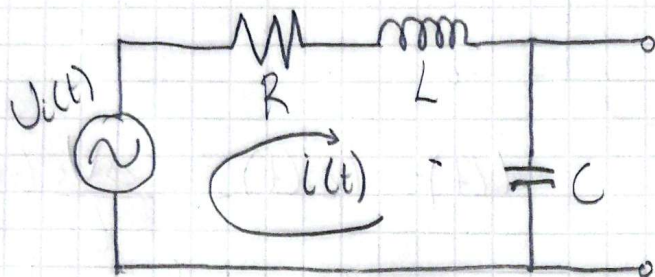


EJERCICIO 2º Parcial - Bonificación

Circuito RLC

Demostar
que RLC en
serie es lineal.



$$\text{Sea } U_i(t) = LC \frac{d^2}{dt^2} V_C(t) + RC \frac{d}{dt} V_C(t) + V_C(t)$$

$$V_C(t) = f(U_i(t), R, L, C)$$

$$\hat{y}(t) =$$

$$U_i(t) = a_{i1} V_1(t) + a_{i2} V_2(t)$$

$$\hat{y}(t)$$

① Para $X_i(t) = V_{C1}(t)$ (I)

$$X_i(t) = LC \frac{d^2}{dt^2} V_{C1}(t) + RC \frac{d}{dt} V_{C1}(t) + V_{C1}(t)$$

② Cuando $X_{ii}(t) = V_{C2}(t)$ (II)

$$X_{ii}(t) = LC \frac{d^2}{dt^2} V_{C2}(t) + RC \frac{d}{dt} V_{C2}(t) + V_{C2}(t)$$

$$\therefore a_{i1} X_i(t) + a_{ii} X_{ii}(t)$$

$$a_{i1} V_{C1}(t) + a_{ii} V_{C2}(t)$$

$$a_{i1} X_i(t) + a_{ii} X_{ii}(t) = LC \frac{d^2}{dt^2} (a_{i1} V_{C1}(t) + a_{ii} V_{C2}(t))$$

$$+ RC (a_{i1} V_{C1}(t) + a_{ii} V_{C2}(t)) + (a_{i1} V_{C1}(t) + a_{ii} V_{C2}(t))$$

• Propiedad de linealidad de la derivada

$$= a_{i1} LC \frac{d^2}{dt^2} V_{C1}(t) + a_{ii} LC \frac{d^2}{dt^2} V_{C2}(t) + a_{i1} RC \frac{d}{dt} V_{C1}(t)$$

$$+ a_{ii} R C \frac{d}{dt} V_{c2}(t) + a_{i1} V_{c1}(t) + a_{i2} V_{c2}(t)$$

• Ahora aplicando factorización tenemos:

$$= a_{i1} \left(L C \frac{d^2}{dt^2} V_{c1}(t) + R C \frac{d}{dt} V_{c1}(t) + a_{i1} V_{c1}(t) \right) +$$

$$+ a_{i2} \left(L C \frac{d^2}{dt^2} V_{c2}(t) + R C \frac{d}{dt} V_{c2}(t) + a_{i2} V_{c2}(t) \right)$$

$$= a_{i1} x_i(t) + a_{i2} x_{ii}(t)$$

$$\therefore \boxed{a_{i1} x_i(t) + a_{i2} x_{ii}(t) = a_{i1} V_{c1}(t) + a_{i2} x_{ii}(t)}$$

El sistema cumple con la prop. de linealidad

$$f(t) =$$

$$\hat{f}(t)$$

$$\text{Si } V_{i1}(t) = x_i(t) \rightarrow V_c(t) = V_{c1}(t)$$

$$V_{i2}(t) = x_{ii}(t) \rightarrow V_c(t) = V_{c2}(t)$$

Por lo tanto el circuito RLC es lineal de modo que:

$$\boxed{V_i(t) = a_{i1} x_i(t) + a_{i2} x_{ii}(t) \quad | \quad V_c(t) = a_{i1} V_{c1}(t) + a_{i2} V_{c2}(t)}$$