### PSEUDOCODE FOR THEORIZED GRAVITATIONAL CLUSTERING

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#### Dataset:

Set of Points Separated by Euclidean Distances

### **Input Parameters:**

- ε, epsilon
- **F**, Force
- **1.** Determine the **Influence** ( $I_{P,\epsilon}$ ), within the reach  $\epsilon$ , of each point in the dataset.

Influence  $(I_{P,\epsilon})$  is defined as

$$I_{P,\varepsilon} = \sum \frac{1}{d_{U,\varepsilon}}$$

where

- ε is the neighbourhood distance or reach of point P where the Influence is to be measured
- is the distance between point P and the  $i_{th}$  neighbour point within reach,  $\epsilon$ , of point P
- **2.** Determine the **Force** ( $F_P$  ) between all pairs of points in the dataset.

Force  $(F_P)$  is defined as

$$F_P = \frac{(l_{P_1,\varepsilon})(l_{P_2,\varepsilon})}{D_{P_1P_2}}$$

where

- $D_{P1P2}$  is the distance between points  $P_1$  and  $P_2$
- **3.** Cluster the points, i.e. a pair of points with sufficient **F** acting between them belong to the same cluster.

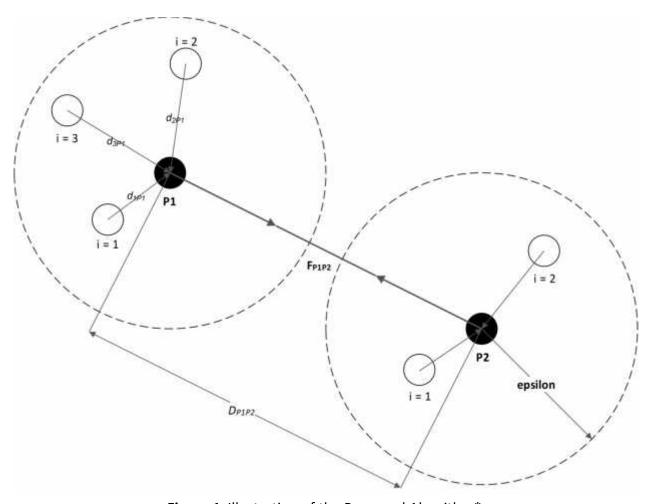


Figure 1: Illustration of the Proposed Algorithm\*

The proposed algorithm primarily draws inspiration from the physical laws of interaction such as Coulomb's law and Newton's law, and from the clustering algorithms DBSCAN and other forms of density-based clustering or attraction-based clustering and Jarvis-Patrick Clustering. The issue of the physical inverse square law, applied in Coulomb's law and Newton's law, may not be exactly relevant to the proposed clustering method but the concept is not ruled out.

<sup>\*</sup>Points with no neighbours within a specified  $\epsilon$  or singletons produced with not enough  $F_P$  are considered as "noise"

The algorithm, although may at some cases result to clustering similar to hierarchical clustering methods, is not hierarchical, either agglomerative or divisive. It does not produce a dendogram in the process of clustering per se.

# **Complexity Analysis**

1. Determination of **Influence** ( $I_{P,E}$ ), Worst Case if  $\epsilon$  encompasses all points

Visit "n" points	O(n)
Through all other "n – 1" points	O(n)
(Computation of I) Arithmetic Operation	O(1)
running in Constant Time	
Big Oh Rule of Products	O(n*n)
Complexity	$O(n^2)$

2. Determination of Force ( $F_P$  ), Worst Case if redundancy is ignored

Complexity	$O(n^2)$
Big Oh Rule of Products	O(n*n)
running in Constant Time	
(Computation of F) Arithmetic Operation	O(1)
Through all other "n – 1" points	O(n)
Visit "n" points	O(n)

3. Clustering

"If" Statement	O(1)
Complexity	0(1)

## The sequence of the clustering algorithm leads to:

Step 1 Complexity	$O(n^2)$
Step 2 Complexity	$O(n^2)$
Step 3 Complexity	O(1)
Big Oh Rule of Sums	$O(n^2) + O(n^2) + O(1) = O(max(n^2, n^2, 1))$
Complexity	O(n <sup>2</sup> )