

Supplementary Information for “Is the Tea Party Libertarian, Authoritarian, or Something Else?”

Contents

1. Additional information on Factor Analysis
2. Scree plot for factor model
3. Numerical factor loadings
4. Including Party ID as a covariate
5. Estimated effects of misarchism on Party ID and Conservatism
6. Additional information on Bayesian Model Averaging
7. Inclusion probabilities and expected value of coefficients from Bayesian Model Averaging
8. Additional information on Multiple Imputation
9. Pooled regression results after Multiple Imputation
10. Multiple Imputation diagnostics
11. Additional information on matching estimates and sensitivity bounds
12. References

Additional information on Factor Analysis

We used an oblique rotation which allows for factors to be correlated. This is appropriate here because, while we argue that moral statism and anti-governmentalism are unique and distinct, they are likely to be correlated. We use maximum likelihood as the factoring method because it has a more formal statistical basis than other methods and is widely seen as one of the optimal methods. See Fabrigar et al. (1999). We estimate two factors, which a scree plot (below) suggests to be the optimal number.

For N equal to 5914, a chi-square test of the hypothesis that two factors is sufficient is equal to 900.727 with a p-value of 0, suggesting that two factors are not sufficient, as we would expect. That said, the root mean square of the residuals is 0.044 and the Tucker-Lewis Index for factor reliability score is 0.869, both of which are near the conventional cutoffs of .05 and .9, respectively.

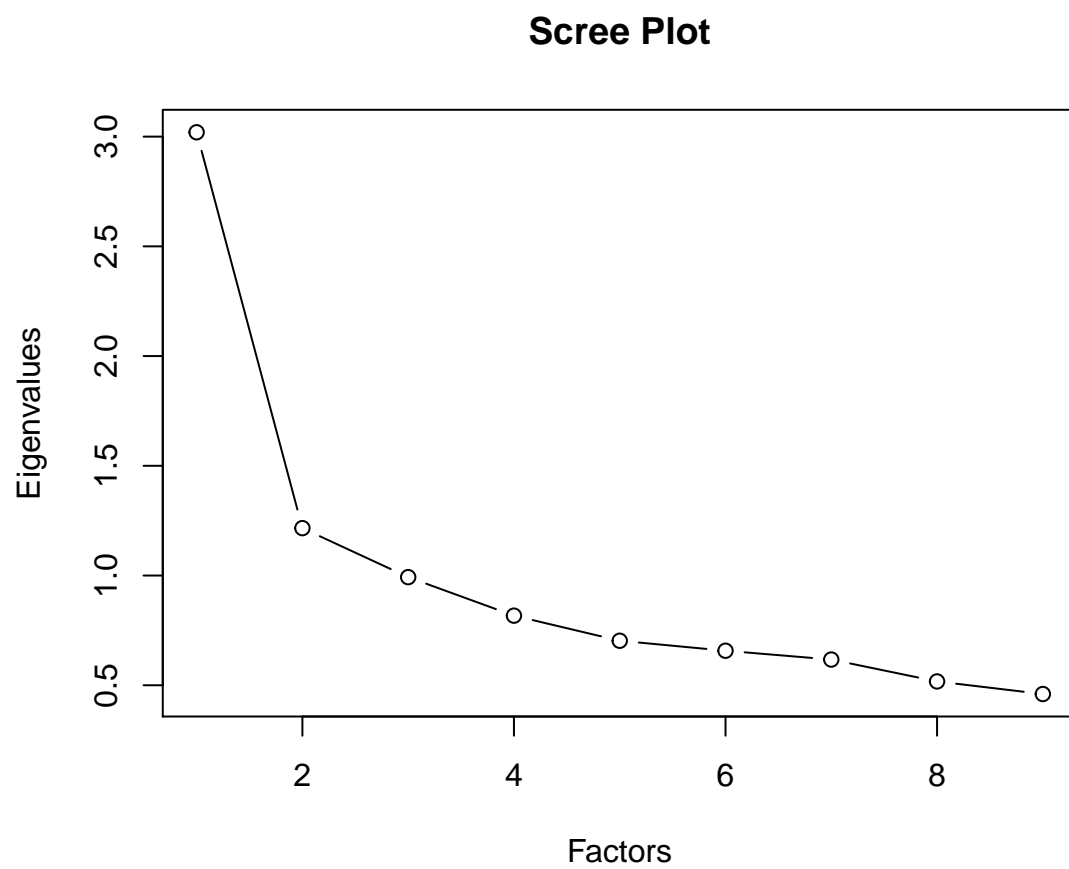


Figure 1: Scree plot shows elbow at two factors

	ML1	ML2
Family	0.03	0.59
Guns	0.40	-0.05
Intolerant	-0.12	0.44
Morals	-0.22	0.36
Wiretapping	0.21	0.35
Defense	0.04	0.49
Services	0.78	0.01
Immigration	-0.24	0.38
Jobs	0.61	-0.04

Table 1: Factor Loadings

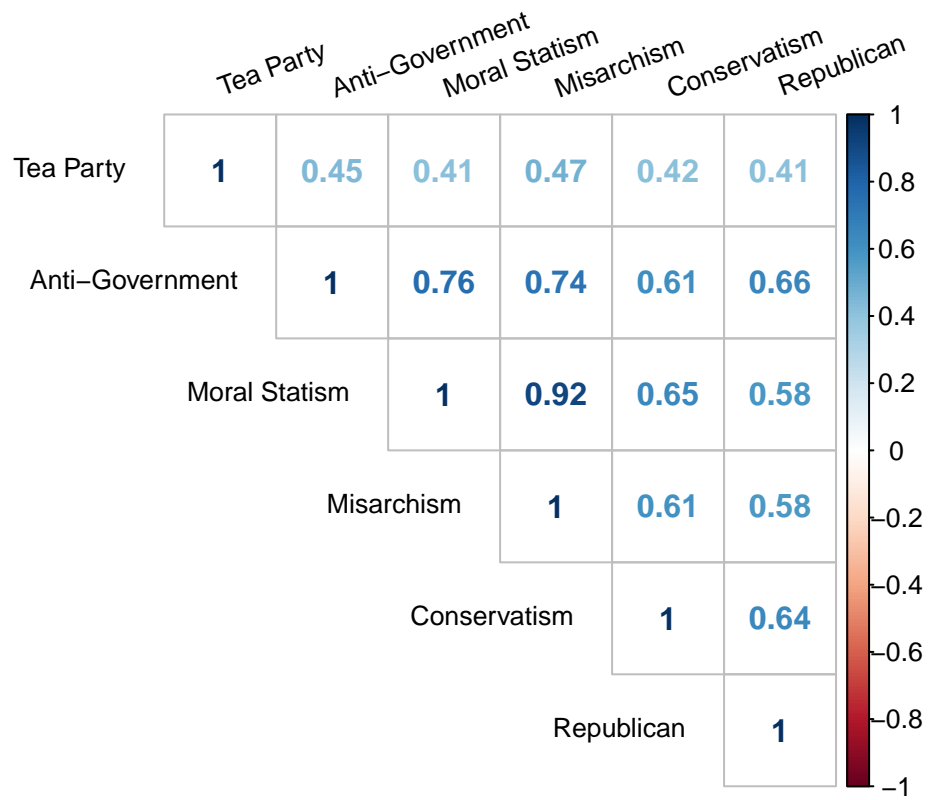


Figure 2: Correlation plot for different dimensions of right-wing attitudes

Table 2: Alternative Dependent Variables for Model 2

	<i>Dependent variable:</i>	
	PartyID (Republican)	Conservatism
	(1)	(2)
Gender (Male)	-0.006 (0.013)	0.008 (0.014)
Income	0.032** (0.015)	-0.003 (0.016)
Age	-0.057*** (0.014)	0.025 (0.016)
Race (White)	0.076*** (0.015)	-0.058*** (0.017)
Education	0.044*** (0.015)	-0.024 (0.017)
Obama	-0.545*** (0.020)	-0.103*** (0.025)
Authoritarianism	-0.029** (0.015)	0.039** (0.016)
BornAgain	0.016 (0.014)	0.030* (0.015)
Religion	0.001 (0.015)	0.038** (0.017)
PartyID (Republican)		0.321*** (0.022)
FoxNews	0.039** (0.015)	0.059*** (0.017)
Conservatism	0.256*** (0.018)	
MoralStatism	-0.001 (0.024)	0.259*** (0.026)
Government	-0.103*** (0.023)	-0.100*** (0.026)
MoralStatism*Government	0.025 (0.026)	0.044 (0.029)
Constant	-0.051*** (0.019)	-0.009 (0.022)
Observations	2,406	2,406
R ²	0.674	0.523
Adjusted R ²	0.673	0.521
Residual Std. Error (df = 2391)	0.305	0.342
F Statistic (df = 14; 2391)	354.000***	187.000***

Note:

*p<0.1; **p<0.05; ***p<0.01

Individuals characterized by the highest observed levels of moral statism also in the 90th percentile of anti-governmentalism (below a value of -.7 on the governmentalism factor) have a probability of supporting the Tea Party around 40%. To be more precise, moving from minimum to maximum moral statism while in the 10th percentile of governmentalism increases the probability of supporting the Tea Party by .39 (sd=.07) more than it would in the 90th percentile of governmentalism, from .01 (sd=.00) to .42, (sd=.07) rather than .05 (sd=.02) to

Table 3: Including ideology in factor model and removing from regression model

	<i>Dependent variable:</i>
	Tea Party Support
Gender (Male)	0.116 (0.128)
Income	−0.301** (0.148)
Age	−0.343** (0.144)
Race (White)	−0.404** (0.169)
Education	0.066 (0.158)
Obama	−1.250*** (0.222)
Authoritarianism	0.035 (0.148)
BornAgain	0.298** (0.135)
Religion	−0.013 (0.155)
PartyID (Republican)	0.512** (0.199)
FoxNews	0.707*** (0.133)
MoralStatism	−0.556** (0.261)
Government	0.923*** (0.276)
MoralStatism*Government	1.380*** (0.268)
Constant	−2.700*** (0.214)
Observations	2,406
Log Likelihood	−830.000
Akaike Inf. Crit.	1,690.000
<i>Note:</i>	*p<0.1; **p<0.05; ***p<0.01

.03 (sd=.02).

Bayesian Model Averaging

A version of the R package *BMA* modified by Montgomery and Nyhan was used to search over the entire model space of Model 2. The analysis was conducted using the *bic.glmMN()* function, which is a version of the *bic.glm()* function in the R package *BMA*. See Raftery et al. (2015) and Montgomery and Nyhan (2010). The analysis uses uniform priors for all independent variables and the only restriction is that the interaction term and its two component variables are required to enter or not enter models together. Options were set to be least restrictive. No Occam's Window was used to narrow the models selected by the initial leap algorithm run over the entire model space and, following Montgomery and Nyhan (pp. 21), the number of best models of each size returned by the leaps algorithm was set to 100,000. In the end, 4,096 models were selected.

Regression results such as those presented above are sometimes sensitive to minor differences in model specification, such as including or excluding one variable. Because we do not know the true model, an idiosyncratic search for optimal model specifications can lead to bias. One risk is publication bias, if researchers prefer models that confirm their hypotheses. Another is loss of efficiency if too many unnecessary variables are included. Finally, an *ad hoc* approach leads to incomplete representations of model uncertainty (J. M. Montgomery and Nyhan 2010, 4). An increasingly widespread solution in political science is Bayesian Model Averaging (BMA), which estimates all possible models from a set of variables provides posterior probabilities for all possible coefficients and models.

In particular, a version of the R package *BMA* modified by Montgomery and Nyhan was used to search over the entire model space of Model 2.¹ The analysis uses uniform priors for all independent variables and the only restriction is that the interaction term and its two component variables are required to enter or not enter models together.² In the end, 4,096 models were selected.

The results show that the misarchist terms are highly robust to model selection, with a posterior probability of inclusion equal to 100% (one minus the cumulative posterior probability of all models excluding them). The expected value of the coefficient for *MoralStatism* is .78 (sd=.29), for *Government* it is -.71 (sd=.26), and for the interaction term it is -1.43 (sd=.31). *Obama* and *FoxNews* also had probabilities of inclusion equal to 100% with expected values not dissimilar to those estimated in Model 2. *Age* and *Race* had probabilities of inclusion greater than 50% but with unstable signs, as indicated by expected values hardly distinguishable from zero. All other variables had probabilities of inclusion less than 50%. More detailed graphical information is reported in Supplementary Information.

In the main models reported above, we have consciously chosen to include a large number of control variables because we are presently most concerned with testing our hypotheses and ruling out rival hypotheses. BMA provides further evidence that the models presented above likely contain superfluous independent variables. Though we believe it is best to rely primarily

¹The analysis was conducted using the *bic.glmMN()* function, which is a version of the *bic.glm()* function in the R package *BMA*. See (Raftery et al. 2015) and (J. M. Montgomery and Nyhan 2010)

²Options were set to be least restrictive. No Occam's Window was used to narrow the models selected by the initial leap algorithm run over the entire model space and, following Montgomery and Nyhan (pp. 21), the number of best models of each size returned by the leaps algorithm was set to 100,000

on the conservative estimates reported above, we briefly report how our coefficients of interest would change under different specifications suggested by the BMA. In a model with just those variables found to be the most robust to model selection (*Fox News*, *Obama*, *MoralStatism*, and *Government*), moving from 10th percentile of *MoralStatism* to 90th within the 90th of *Government*, is associated with the probability of supporting the Tea Party increasing from .01 (sd=.00) to .50 (sd=.06). Thus, the results from Bayesian Model Averaging suggest the main results reported above are highly robust and, if anything, conservative estimates of the partial correlation between misarchism and Tea Party support.

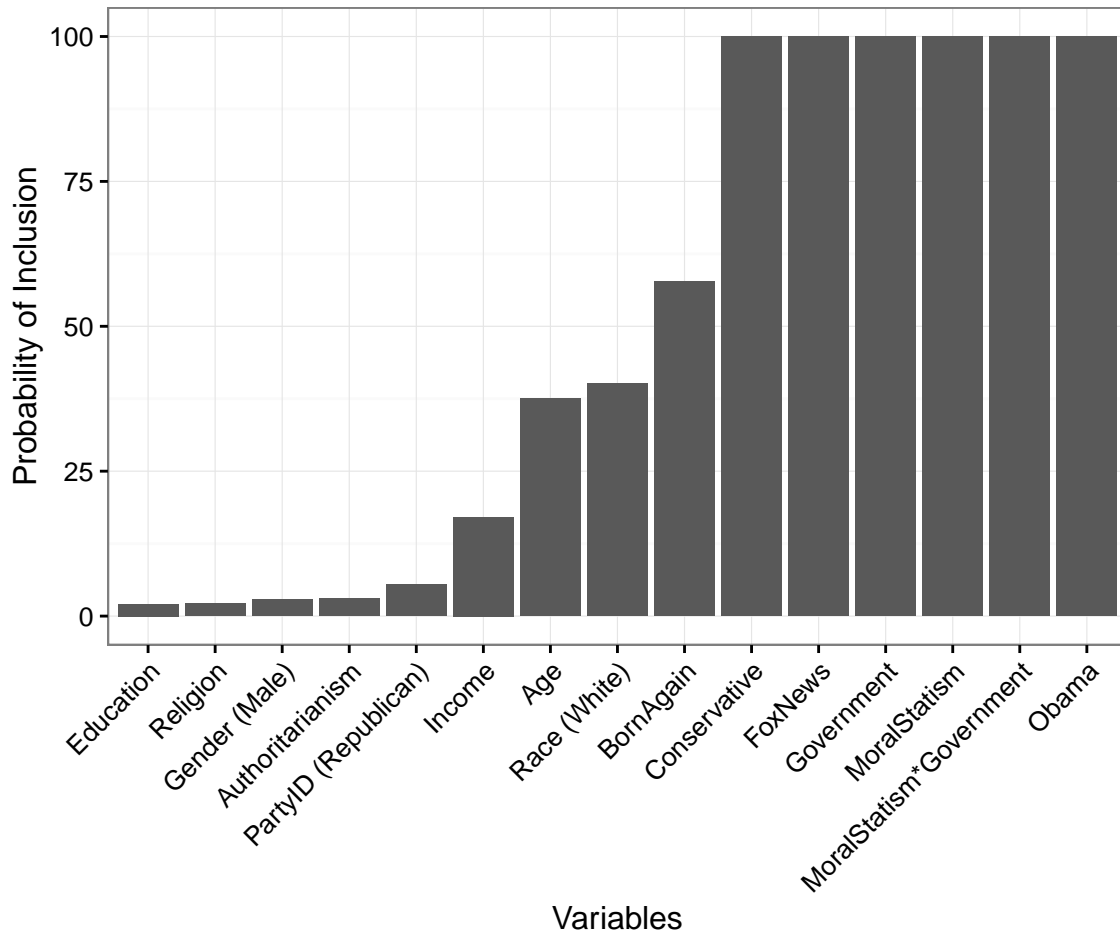


Figure 3: Inclusion Probabilites from Bayesian Model Averaging

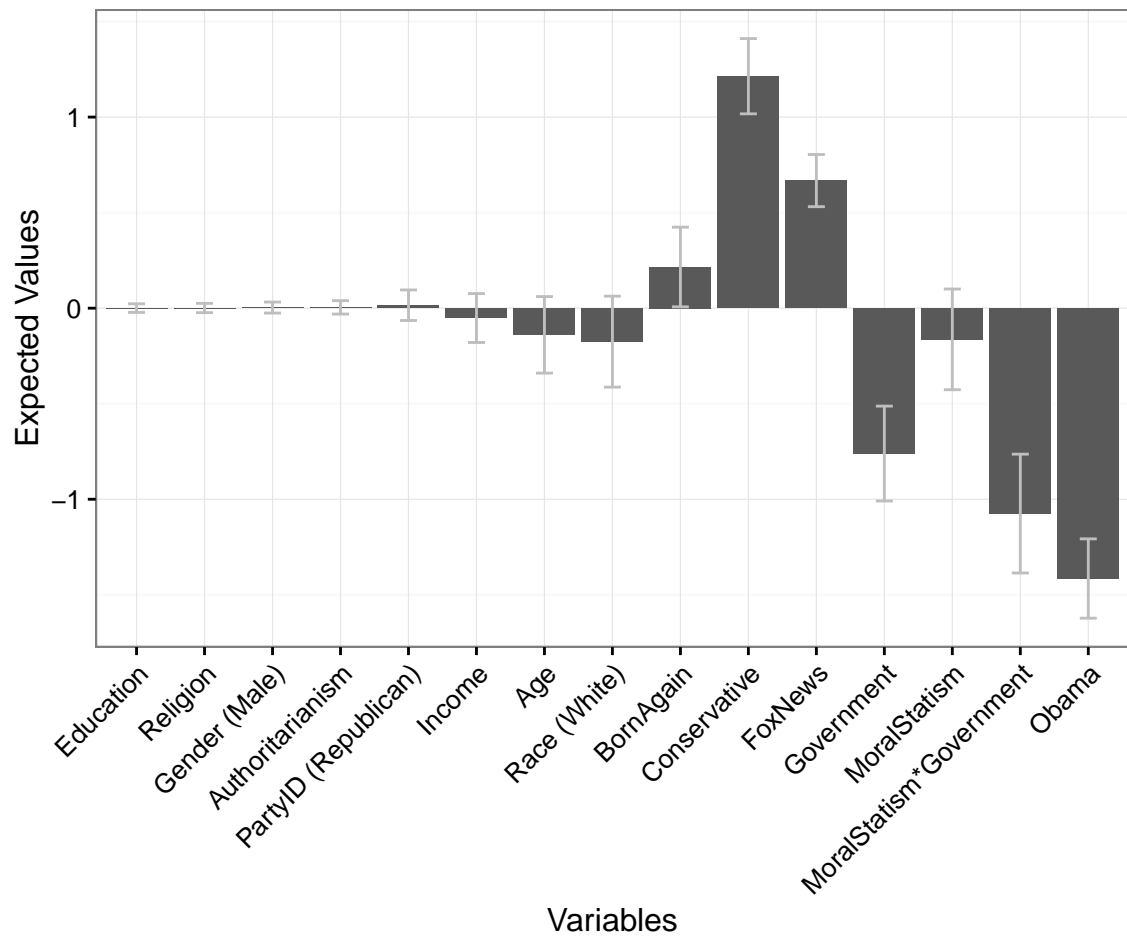


Figure 4: Expected Values from Bayesian Model Averaging

Multiple Imputation

We use the R package *Amelia* (Honaker, King, and Blackwell 2008) to generate 10 versions of the ANES dataset with missing values imputed and *Zelig* (Imai, King, and Lau 2009) to obtain pooled regression results via “Rubin’s rules.” The multiple imputation algorithm only assumes that missing values are “missing at random,” not necessarily “missing completely at random.” In this context, “missing at random” only means that missingness is dependent on the observed variables. Full numerical results are provided below. Graphical diagnostics for overimputation, dispersion, and comparing pre- and post-imputation densities for our main variables suggest no problems or anomalies in the imputation procedures (see below the numerical results).

Another possible problem is that listwise deletion of all observations containing missing values may have led to biased estimates, as well as the simple inefficiency of lost information. In particular, if relative misarchists were more (or less) likely to respond to certain questions than other respondents, we may have over-estimated (or under-estimated) the true partial correlation between our misarchist terms and Tea Party support. One solution to this problem is multiple imputation of missing values, which refers to the process of using the information from observed variables to infer the most likely values for all missing cells. The process finishes by producing a set of new datasets each of which samples from the predictive distribution to assign most likely values to each missing cell. After multiple imputation, the models discussed above are re-estimated on each imputed dataset and the results are combined using “Rubin’s rules.” Specifically, we use the R package *Amelia* (Honaker, King, and Blackwell 2008) to generate 10 versions of the ANES dataset with missing values imputed and *Zelig* to obtain pooled regression results. The multiple imputation algorithm only assumes that missing values are “missing at random,” not necessarily “missing completely at random.” In this context, “missing at random” only means that missingness is dependent on the observed variables.

After pooling the results, the estimates remain substantially the same. *MoralStatism*, *Government*, and the interaction term remain signed as in Model 2 with high statistical significance (.98, $p < .00$; -.68, $p < .00$; -1.35, $p < .00$, respectively). *FoxNews* and *BornAgain* also remain substantially the same. Graphical diagnostics for overimputation, dispersion, and comparing pre- and post-imputation densities for our main variables suggest no problems or anomalies in the imputation procedures. For the sake of brevity we have placed the full results table and further diagnostic information in Supplementary Information.

	Value	Std. Error	t-stat	p-value
(Intercept)	-2.08	0.12	-18.04	0.00
Gender (Female)	-0.10	0.09	-1.12	0.26
Income	-0.33	0.10	-3.33	0.00
Age	-0.30	0.09	-3.38	0.00
Race (White)	-0.30	0.11	-2.68	0.01
Education	-0.04	0.10	-0.43	0.66
Obama	-0.99	0.14	-7.04	0.00
Authoritarianism	0.06	0.11	0.60	0.55
BornAgain	-0.21	0.12	-1.77	0.08
Religion	0.02	0.09	0.19	0.85
PartyID (Republican)	0.23	0.13	1.75	0.08
FoxNews	0.66	0.10	6.90	0.00
MoralStatism	0.98	0.18	5.35	0.00
Government	-0.67	0.17	-4.03	0.00
MoralStatism*Government	-1.34	0.20	-6.76	0.00

Table 4: Pooled Logistic Regression Results From 10 Multiple Imputations

Observed and Imputed values of MoralStatism

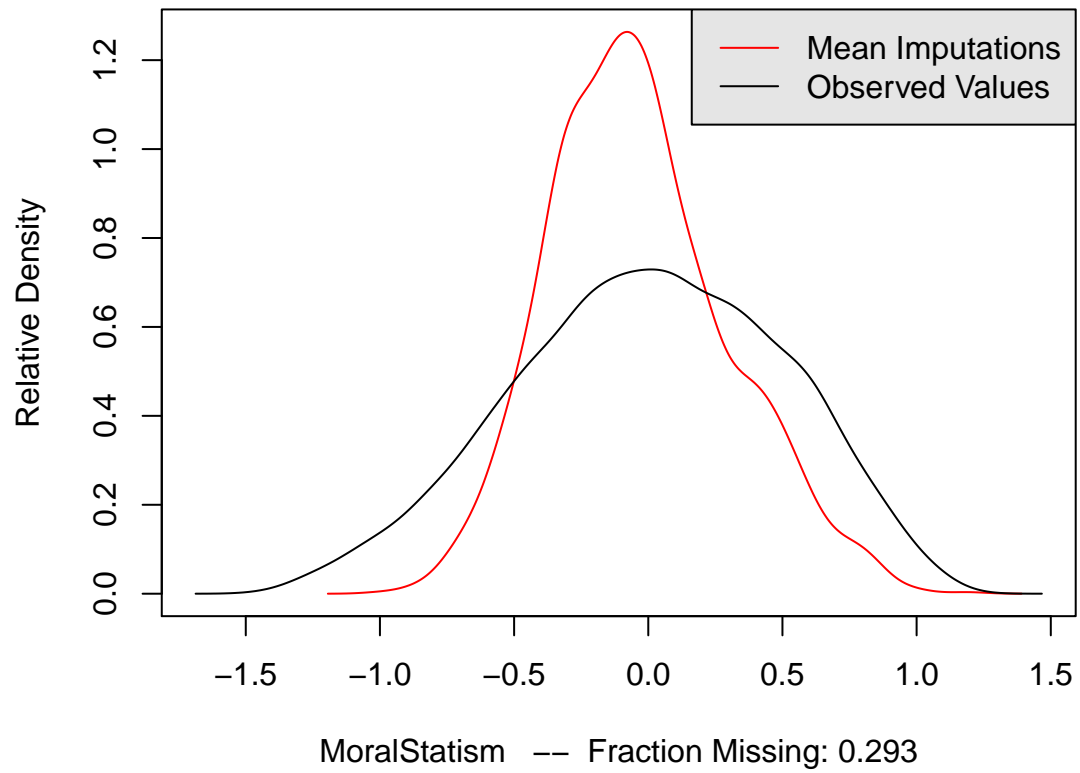


Figure 5: Distributions before and after multiple imputation

Observed and Imputed values of Government

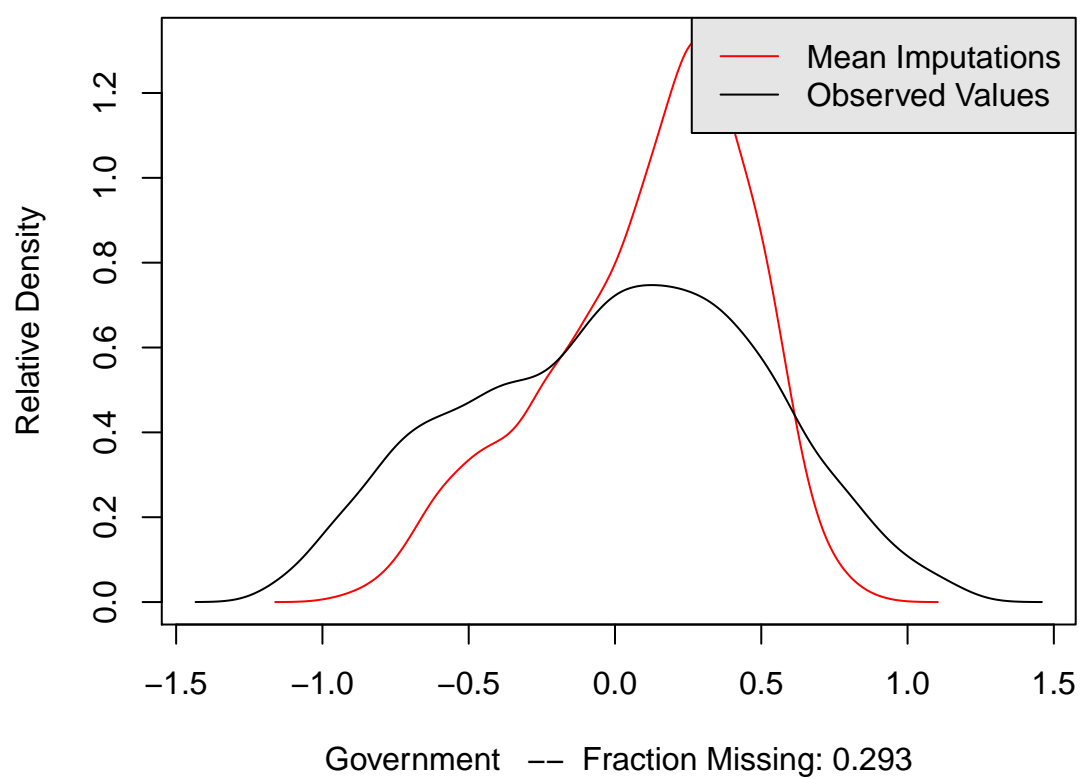


Figure 6: Distributions before and after multiple imputation

Observed versus Imputed Values of MoralStatism

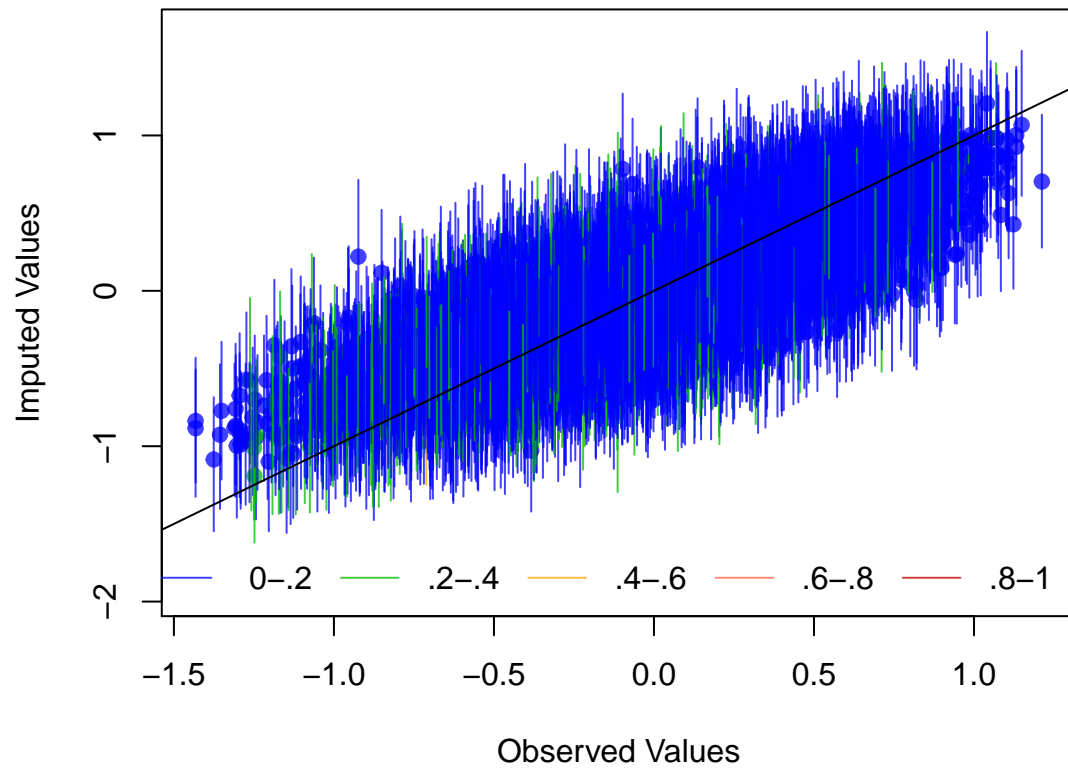


Figure 7: Diagnostic Plot for Overimputation (1)

Observed versus Imputed Values of Government

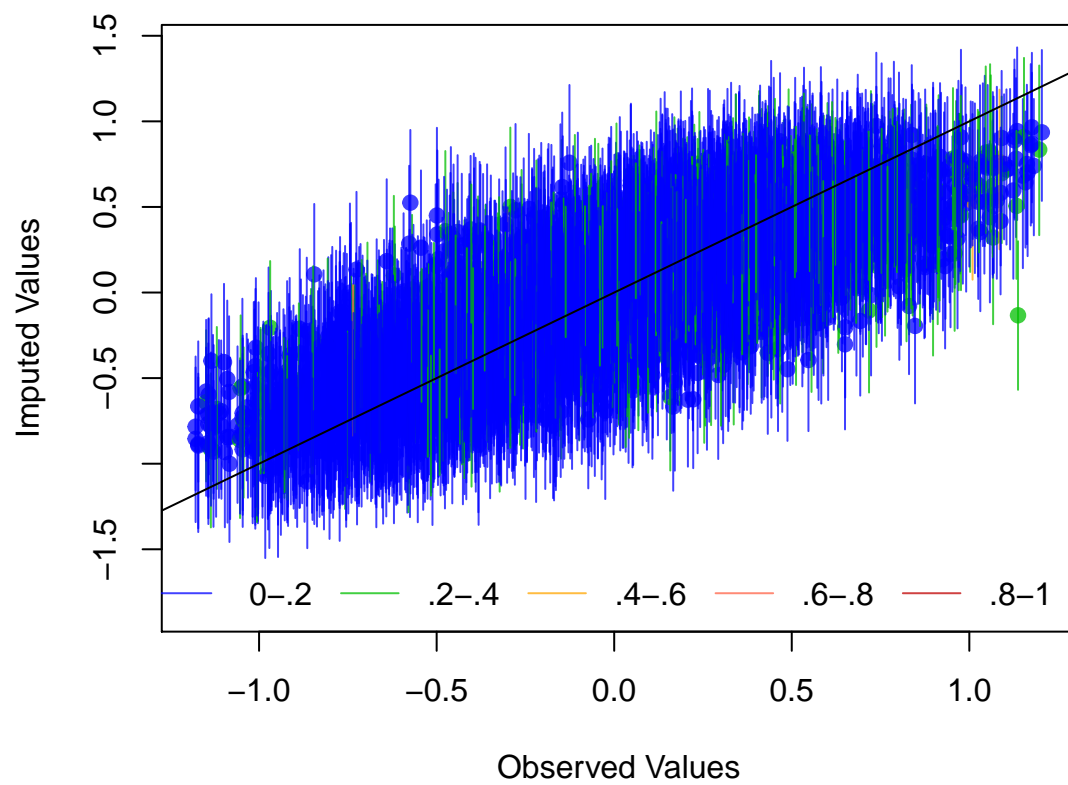


Figure 8: Diagnostic Plot for Overimputation (2)

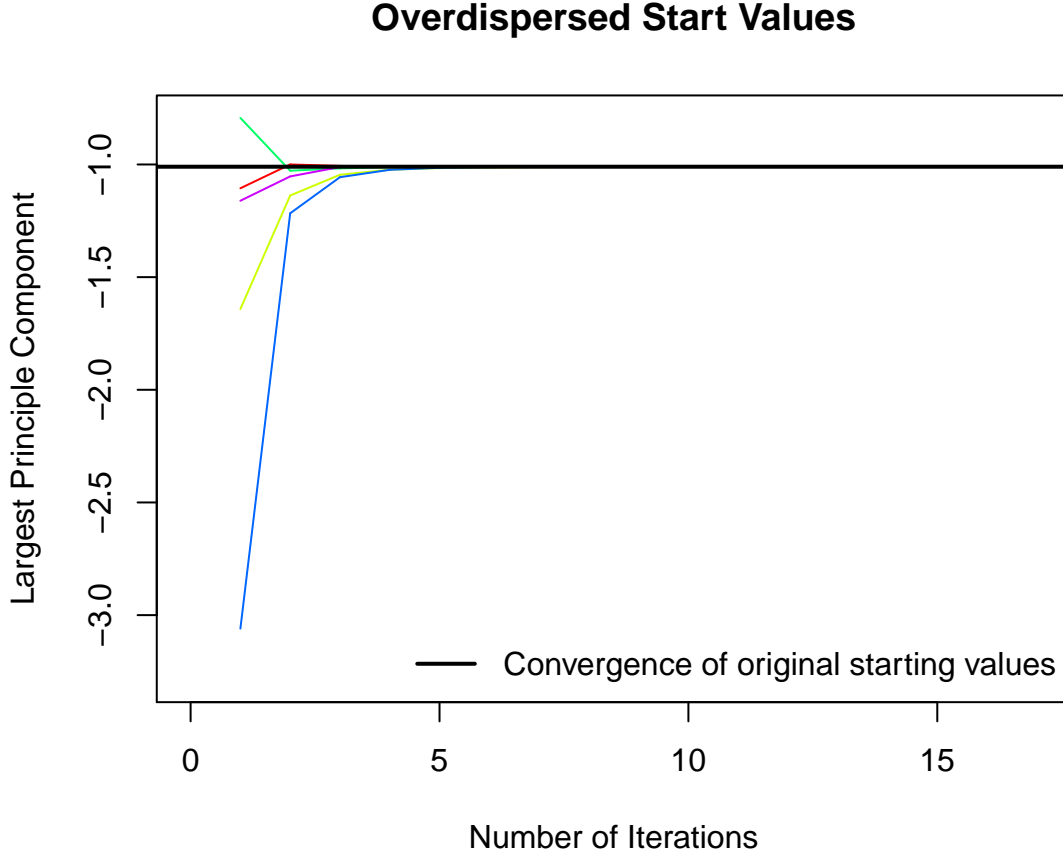


Figure 9: Diagnostic Plot for Dispersion

Matching estimates and sensitivity bounds

Rosenbaum bounds (1988) for a binary dependent variable are calculated using the *binarysens()* function in the R package *rbounds*. See Keele (2014). We generate matching estimates for each of our three independent variables of interest, one at a time, using one-to-one genetic matching with replacement. In each case, “treatment” is defined as having a value above the sample mean of the variable of interest. For each estimate, we balance on all covariates in Model 2 except the two components of the interaction term and including the treatment variable’s propensity scores with respect to those covariates.

To mitigate the risk of bias from non-random assignment into misarchism and guard against parametric model dependence, we employ matching to estimate the effect of misarchism from a subset of highly similar individuals. We use a genetic matching algorithm to identify that subset of the original dataset for which the distribution of each covariate is optimally balanced across both treatment and control groups (Diamond and Sekhon 2012; Sekhon 2011). In other words, the algorithm obtains the matched pairs of those “treated” and not treated to governmentalism and moral statism which are otherwise optimally balanced in the propensity to be treated. The average treatment effect for the treated obtained from this subset will approximate that which we would obtain from a randomized experiment, unless some unobserved factor shapes the propensity to be treated. Although the possibility of omitted variables can never be ruled out, we can quantify the sensitivity of these matching

estimates to some potential unobserved source of bias. Thus, we also report sensitivity bounds as developed by Rosenbaum (Rosenbaum 1988).

We generate matching estimates for each of our three independent variables of interest, one at a time, using one-to-one genetic matching with replacement. In each case, “treatment” is defined as having a value above the sample mean of the variable of interest. For each estimate, we balance on all covariates in Model 2 except the two components of the interaction term and including the treatment variable’s propensity scores with respect to those covariates. We do not balance on the components of the interaction term, or the interaction term itself, because this would remove the covariation of governmentalism and moral statism the effect of which we wish to test, but we do include the components and the interaction term as covariates.

The average treatment effect on those “treated” with greater than the mean level of moral statism is 0.094, with a standard error of 0.057 and a p-value of 0.01. The Rosenbaum bounds for this effect suggest that for it to become statistically insignificant at the 95% confidence level, the odds of differential assignment to treatment due to an unobserved factor would have to be about 2.03.³ Thus, the partial correlation between moral statism and Tea Party support when *Governmentalism* is set at its mean, as obtained in Model 2, does not appear to be an artifact of covariate imbalance or parametric modeling assumptions, and would require a fairly large unobserved source of bias to become insignificant.

The average treatment effect on those “treated” with greater than the mean level of governmentalism is 0.002, with a standard error of 0.028 and a p-value of 0.88. Therefore the partial correlation previously estimated between governmentalism and Tea Party support at mean levels of moral statism appears to have been a spurious result of those with high values of governmentalism having significantly different values of some covariate relative to those with low values of governmentalism.

The average treatment effect on those “treated” with greater than the mean level of the interaction term is -0.048, with a standard error of 0.019 and a p-value of 0.01. The Rosenbaum bounds for this effect suggest that for it to become statistically insignificant at the 95% confidence level, the odds of differential assignment to treatment due to an unobserved factor would have to be about 1.43. Our key relationship of interest estimated in Model 2 therefore does not appear generated by systematic assignment into treatment due to any of the observed covariates and, as with the estimated effect of moral statism, would require a fairly large unobserved source of bias to become insignificant.

³Rosenbaum bounds for a binary dependent variable reported in this section are calculated using the *binarysens()* function in the R package *rbounds*. See (Keele 2014)

References

- Fabrigar, Leandre R, Duane T Wegener, Robert C MacCallum, and Erin J Strahan. 1999. “Evaluating the use of exploratory factor analysis in psychological research.” *Psychological Methods* 4(3): 272–99.
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