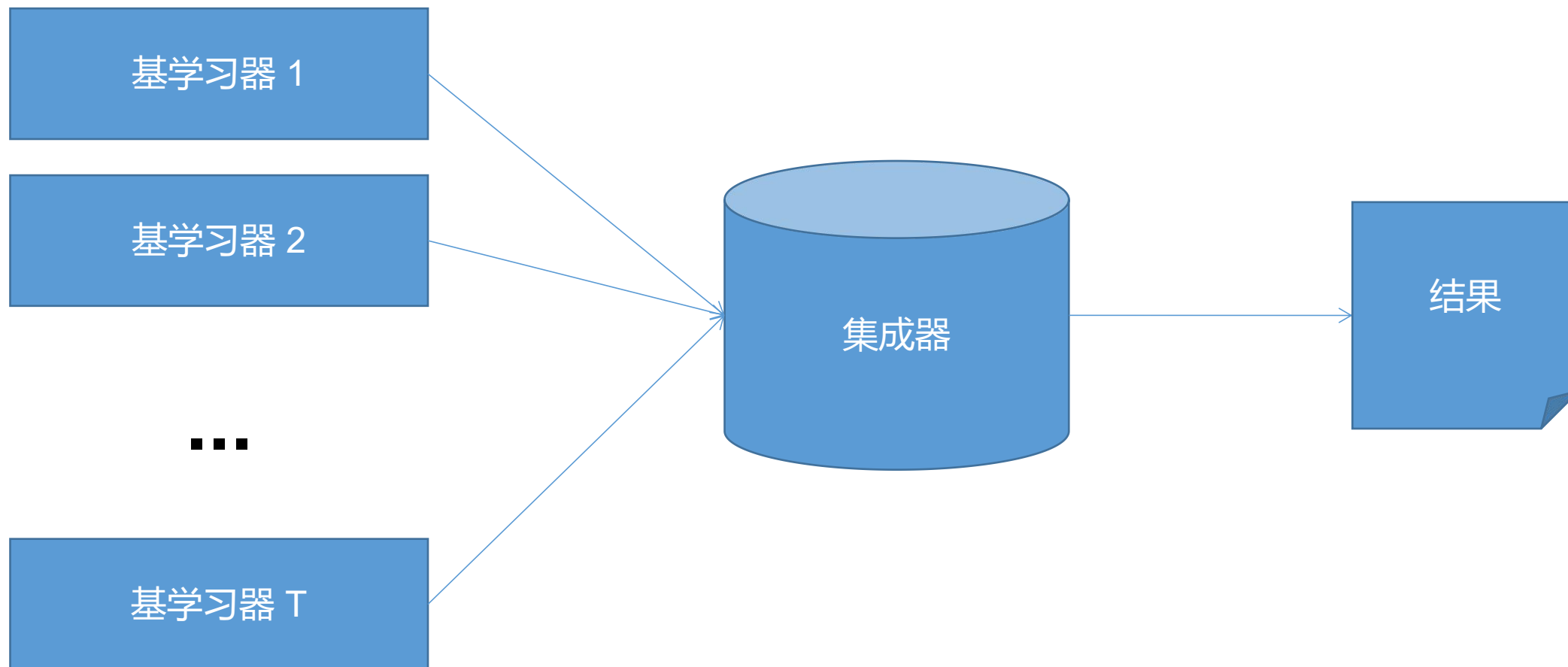


集成学习 (Ensemble Learning)



基础概念

集成学习



集成的效果

	测试例1	测试例2	测试例3
h_1	✓	✓	×
h_2	×	✓	✓
h_3	✓	×	✓
集成	✓	✓	✓

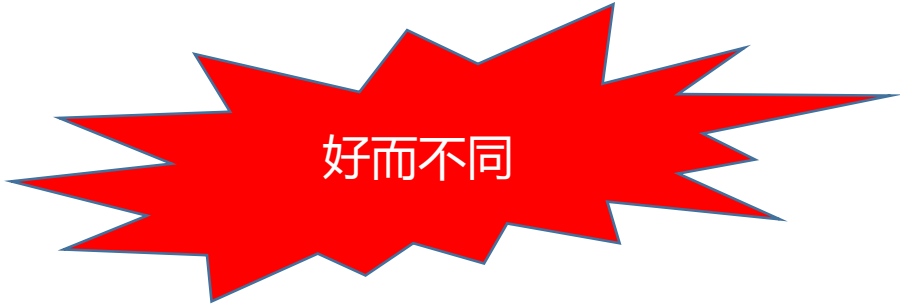
(a) 集成提升性能

	测试例1	测试例2	测试例3
h_1	✓	✓	×
h_2	✓	✓	×
h_3	✓	✓	×
集成	✓	✓	×

(b) 集成不起作用

	测试例1	测试例2	测试例3
h_1	✓	×	×
h_2	×	✓	×
h_3	×	×	✓
集成	×	×	×

(c) 集成起负作用



集成方法



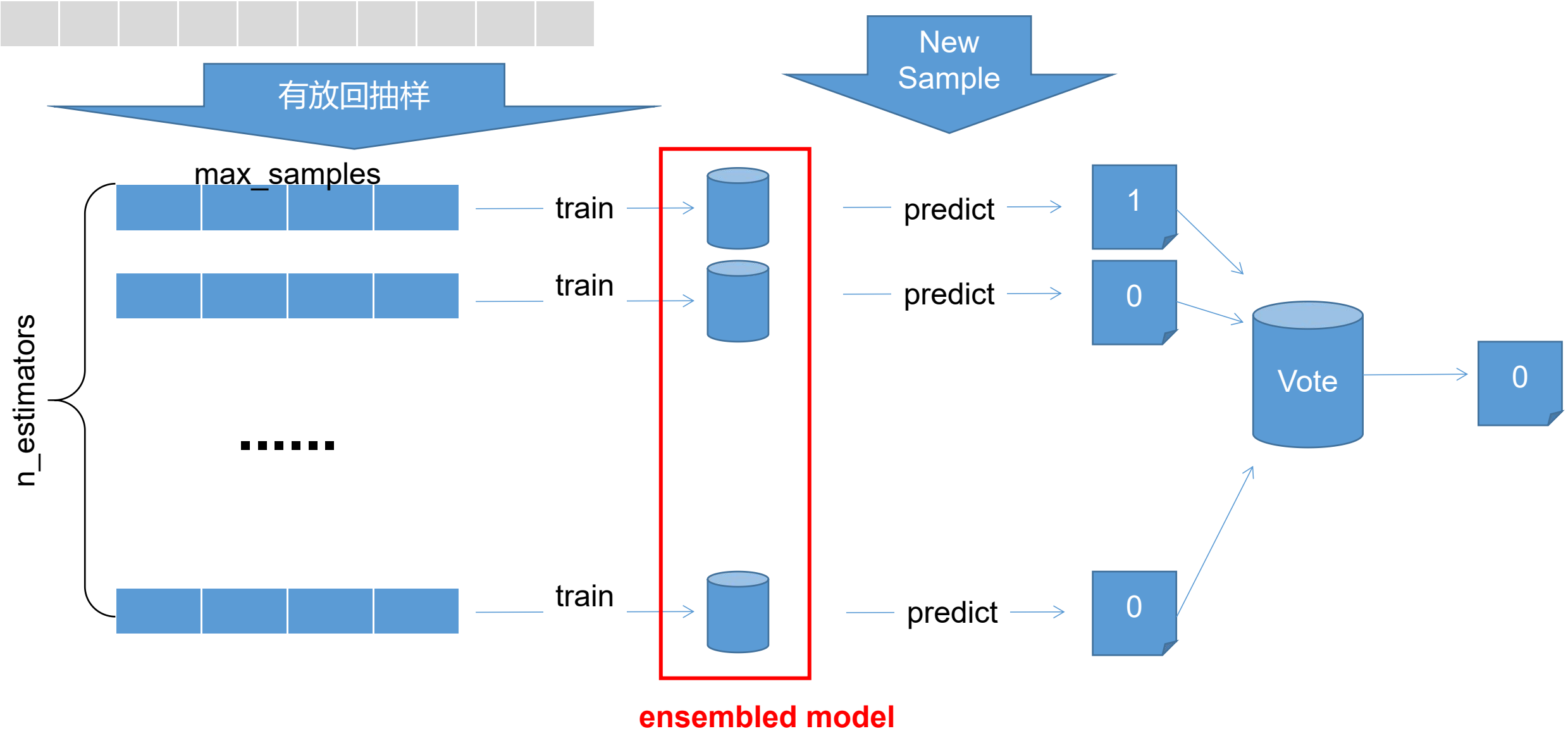
Bagging

Stacking

Boosting

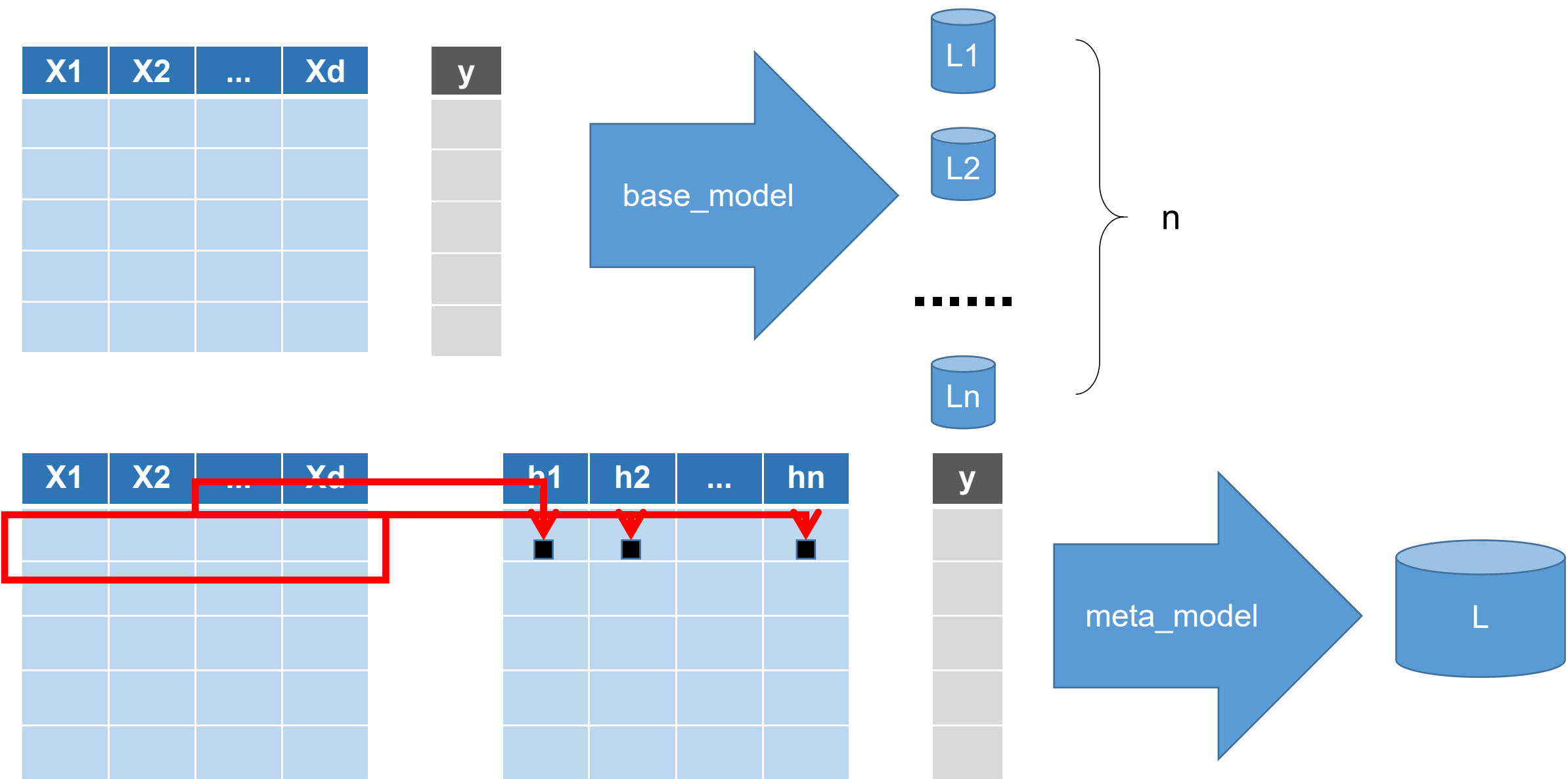
Bagging (Bootstrap Aggregating)

Bagging



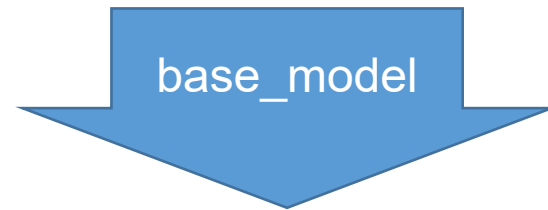
Stacking

Stacking

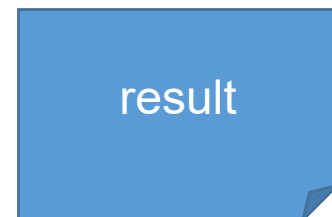
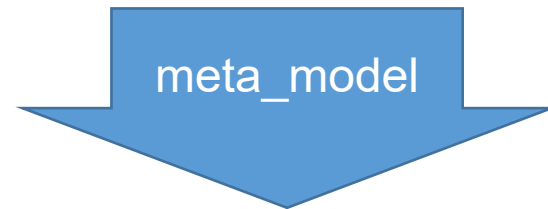


Stacking

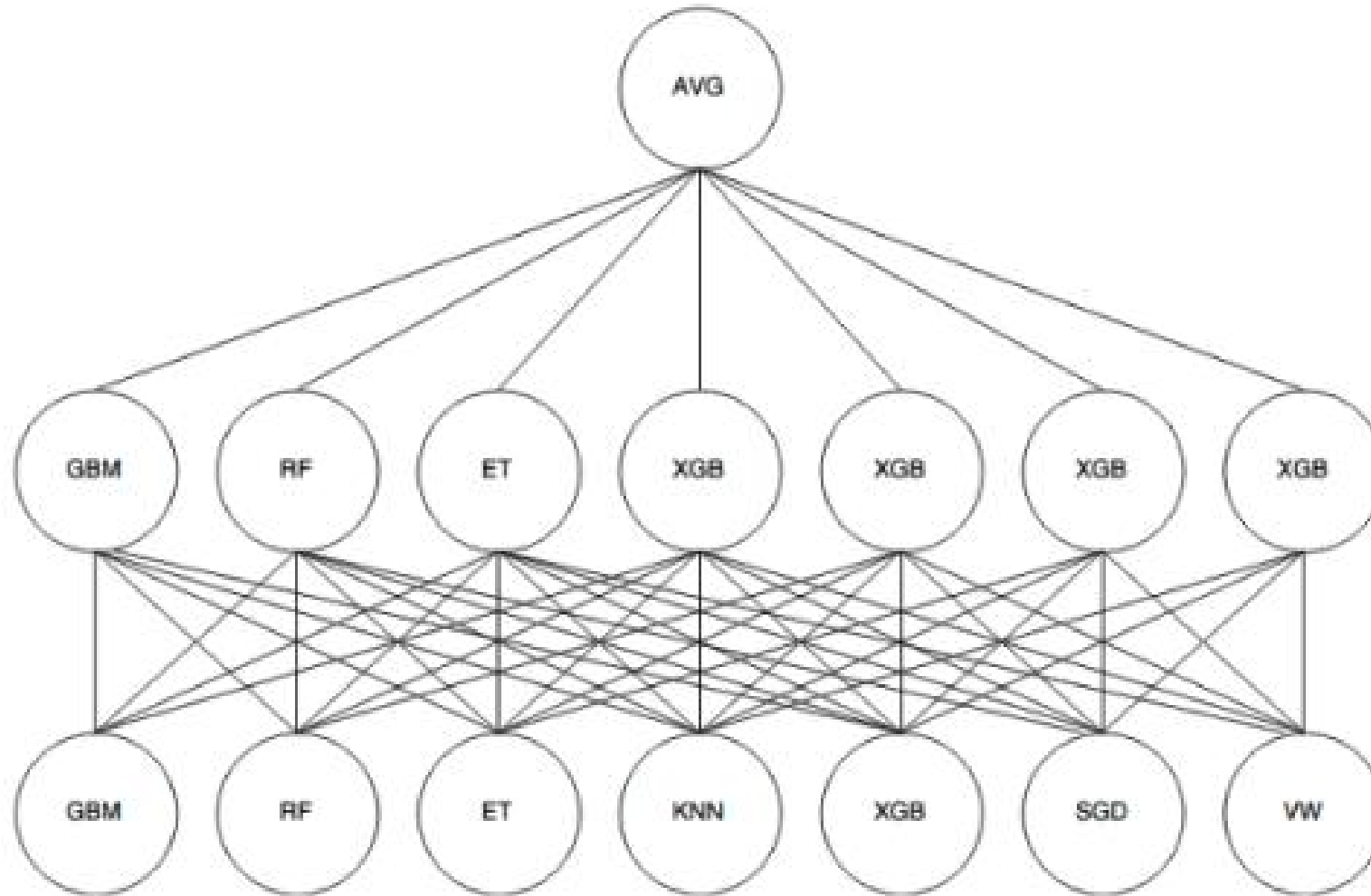
X1	X2	...	Xd



h1	h2	...	hn

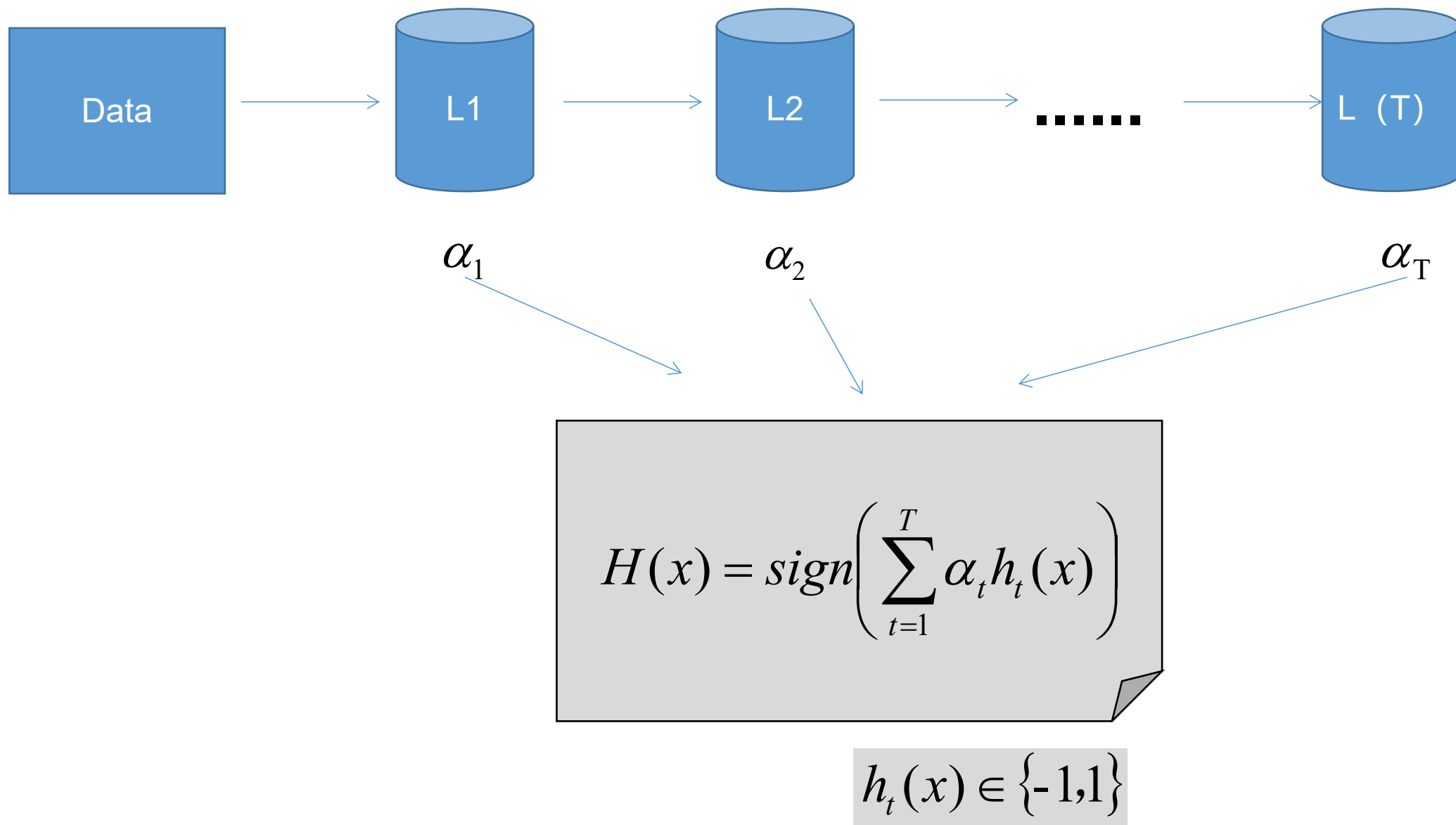


Stacking



Boosting

Boosting



AdaBoost

D	X1	X2	...	Xd	y	D1	D2	D3
(x1,y1)						0.2	0.5	0.28
(x2,y2)						0.2	0.125	0.07
...						0.2	0.125	0.07
...						0.2	0.125	0.08
(xm,ym)						0.2	0.125	0.5

$$h_t = L(D, D_t)$$
$$\varepsilon_t = E_{x \sim D_t} [h_t(X) \neq y]$$
$$\alpha_t = \frac{1}{2} \ln \left(\frac{1 - \varepsilon_t}{\varepsilon_t} \right)$$
$$D_{t+1}(i) = \frac{D_t(i)}{Z_t} \times \begin{cases} \exp(-\alpha_t), & h_t(x_i) = y_i \\ \exp(\alpha_t), & h_t(x_i) \neq y_i \end{cases}$$

权重 / 分布 (Optional)

$$D_{t+1}(i) = \frac{D_t(i)}{Z_t} \times \begin{cases} \exp(-\alpha_t), & h_t(x_i) = y_i \\ \exp(\alpha_t), & h_t(x_i) \neq y_i \end{cases}$$
$$= \frac{D_t(i) \exp(-\alpha_t y_i h_t(x_i))}{Z_t}$$



$$D_{T+1}(i)$$
$$= \frac{1}{m} \frac{\exp(-\alpha_1 y_i h_1(x_i))}{Z_1} \dots \frac{\exp(-\alpha_T y_i h_T(x_i))}{Z_T}$$
$$= \frac{\exp\left(-y_i \sum_{t=1}^T \alpha_t h_t(x_i)\right)}{m \prod_{t=1}^T Z_t}$$

$$Z_t = \sum_{i=1}^m D_t(i) \exp(-\alpha_t y_i h_t(x_i))$$

损失函数 (Optional)

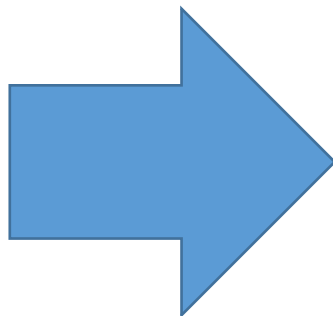
$$H(x_i) \neq y_i$$

$$\text{sign}\left(\sum_{t=1}^T \alpha_t h_t(x_i)\right) \neq y_i$$

$$y_i \times \text{sign}\left(\sum_{t=1}^T \alpha_t h_t(x_i)\right) \leq 0$$

$$y_i \left(\sum_{t=1}^T \alpha_t h_t(x_i)\right) \leq 0$$

$$\exp\left(-y_i \left(\sum_{t=1}^T \alpha_t h_t(x_i)\right)\right) \geq 1$$



$$I\{H(x_i) \neq y_i\} \leq \exp\left(-y_i \left(\sum_{t=1}^T \alpha_t h_t(x_i)\right)\right)$$

$$\frac{1}{m} \sum_{i=1}^m I\{H(x_i) \neq y_i\}$$

$$\leq \frac{1}{m} \sum_{i=1}^m \exp\left(-y_i \left(\sum_{t=1}^T \alpha_t h_t(x_i)\right)\right)$$

$$= \sum_{i=1}^m \left(\left(\prod_{t=1}^T Z_t \right) D_{T+1}(i) \right)$$

$$= \prod_{t=1}^T Z_t$$

求解 alpha (Optional)

$$\min \prod_{t=1}^T Z_t \quad \xrightarrow{\text{greedy}} \quad \min Z_t$$

$$\begin{aligned} Z_t &= \sum_{i=1}^m D_t(i) \exp(-\alpha_t y_i h_t(x_i)) \\ &= E_{x \sim D_t} [\exp(-\alpha_t y_i h_t(x))] \\ &= \exp(-\alpha_t) P(y_i = h_t(x)) + \exp(\alpha_t) P(y_i \neq h_t(x)) \\ &= \exp(-\alpha_t) (1 - \varepsilon_t) + \exp(\alpha_t) \varepsilon_t \end{aligned}$$

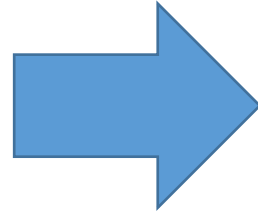
$$\frac{\partial Z_t}{\partial \alpha_t} = 0$$

$$\alpha_t = \frac{1}{2} \ln \left(\frac{1 - \varepsilon_t}{\varepsilon_t} \right)$$

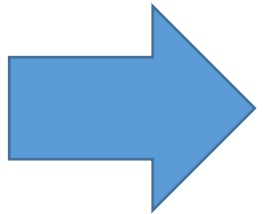
Error Bound (Optional)

$$\begin{aligned} Z_t &= \exp(-\alpha_t)(1-\varepsilon_t) + \exp(\alpha_t)\varepsilon_t \\ &= \sqrt{\frac{\varepsilon_t}{1-\varepsilon_t}}(1-\varepsilon_t) + \sqrt{\frac{1-\varepsilon_t}{\varepsilon_t}}\varepsilon_t \\ &= 2\sqrt{\varepsilon_t(1-\varepsilon_t)} \end{aligned}$$

$$\alpha_t = \frac{1}{2} \ln \left(\frac{1-\varepsilon_t}{\varepsilon_t} \right)$$



$$\begin{aligned} r_t &= \sum_{i=1}^m D_t(i) y_i h_t(x_i) \\ &= E[y_i h_t(x)] \\ &= 1 \bullet P(y_i = h_t(x)) + (-1) \bullet P(y_i \neq h_t(x)) \\ &= 1 - 2\varepsilon_t \\ &\rightarrow \varepsilon_t = \frac{1-r_t}{2} \end{aligned}$$



$$\frac{1}{m} I\{H(x_i) \neq y_i\} \leq \prod_{t=1}^T Z_t = \prod_{t=1}^T \sqrt{1-r_t^2}$$

AdaBoost 的优缺点

优点	缺点
容易实现 不容易出现过拟合 参数不多 理论基础好	alpha 是局部最优 对噪音敏感 base model 不能为线性模型 (logistic regression)