

# NSC200

## *NewStep Single Axis Stepper Motor Controller/Driver*



**Newport®**  
Experience | Solutions

## LabVIEW Drivers

*For Motion, Think Newport™*



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# Preface

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# NSC200

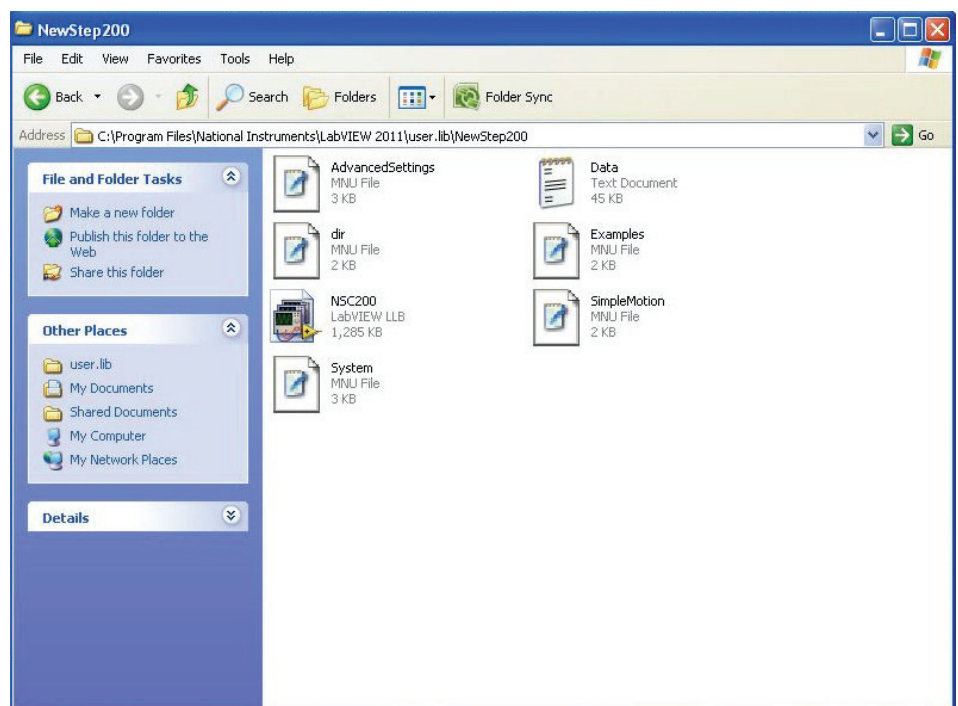
## LabVIEW Drivers

### 1.0 NSC200 LabVIEW Drivers

#### NOTE

You must use at least the [2010](#) of LabVIEW.

Copy the directory NewStep200 under the directory **user.lib** of LabVIEW 20xx.



In each VI, there is a connection cluster that contains the following components:



**error (no error)** The **error in** cluster can accept error information wired from VIs previously called. Use this information to decide if any functionality should be bypassed in the event of errors from other VIs.

The pop-up option **Explain Error** (or Explain Warning) gives more information about the error displayed



**status** The **status** Boolean is either TRUE (X) for an error, or FALSE (checkmark) for no error or a warning.

The pop-up option **Explain Error** (or Explain Warning) gives more information about the error displayed.



**code** The **code** input identifies the error or warning.

The pop-up option **Explain Error** (or Explain Warning) gives more information about the error displayed.



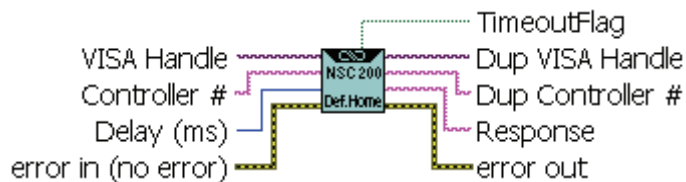
**source** The **source** string describes the origin of the error or warning.








The pop-up option **Explain Error** (or Explain Warning) gives more information about the error displayed



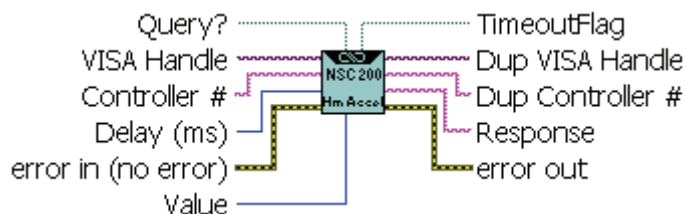
## 2.0 VI'S Description










### 2.1 Define Home.vi



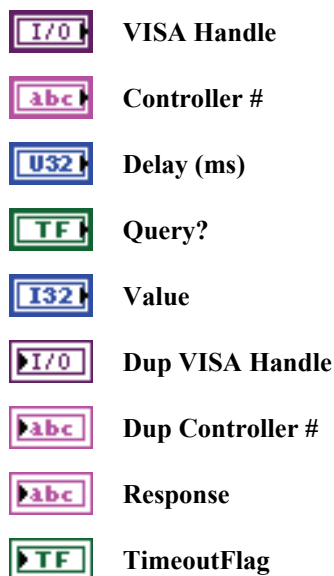
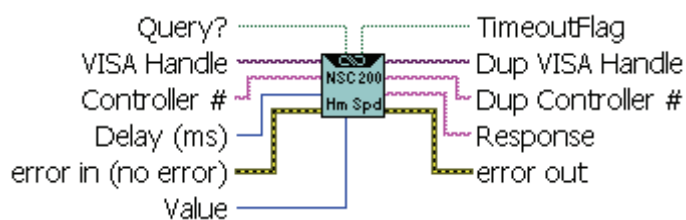
-  VISA Handle
-  Controller #
-  Delay (ms)
-  Dup VISA Handle
-  Dup Controller #
-  Response
-  TimeoutFlag

### 2.2 Homing Acceleration.vi

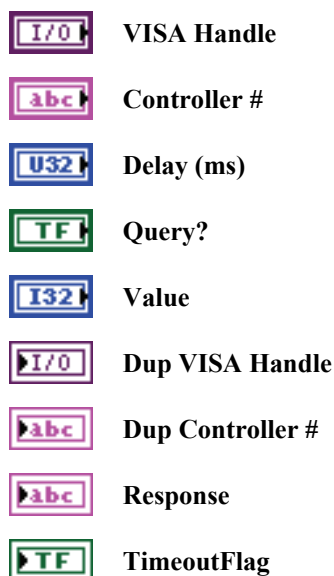
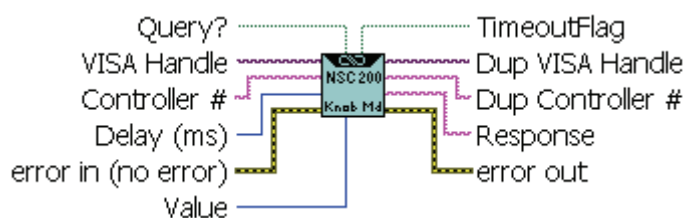


-  VISA Handle
-  Controller #
-  Delay (ms)
-  Query?
-  Value
-  Dup VISA Handle
-  Dup Controller #
-  Response
-  TimeoutFlag

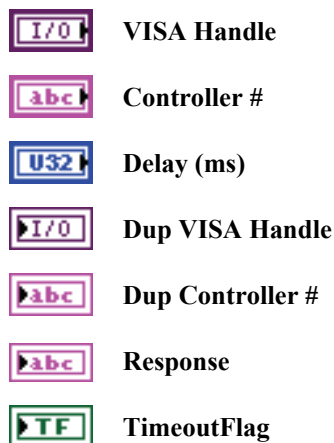
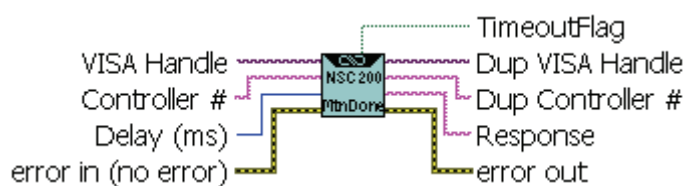
### 2.3 Homing Speed.vi



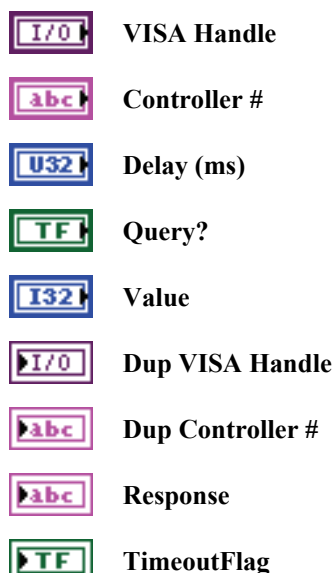
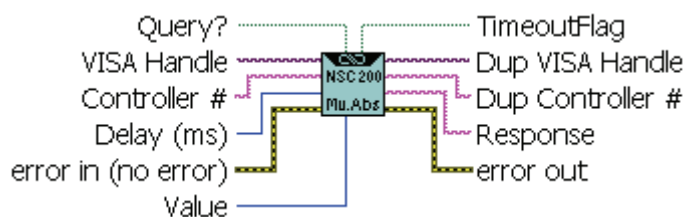
### 2.4 Knob Mode.vi



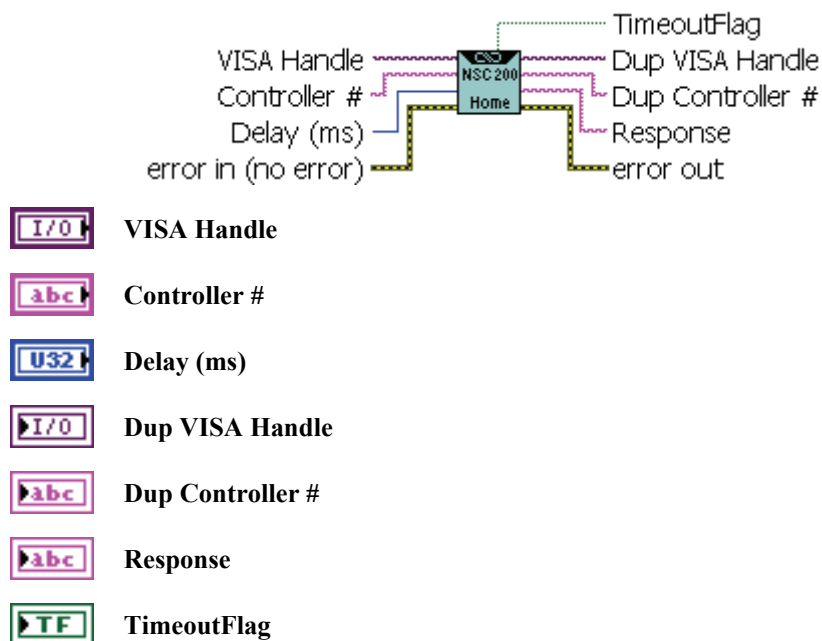
## 2.5 Motion Done?.vi



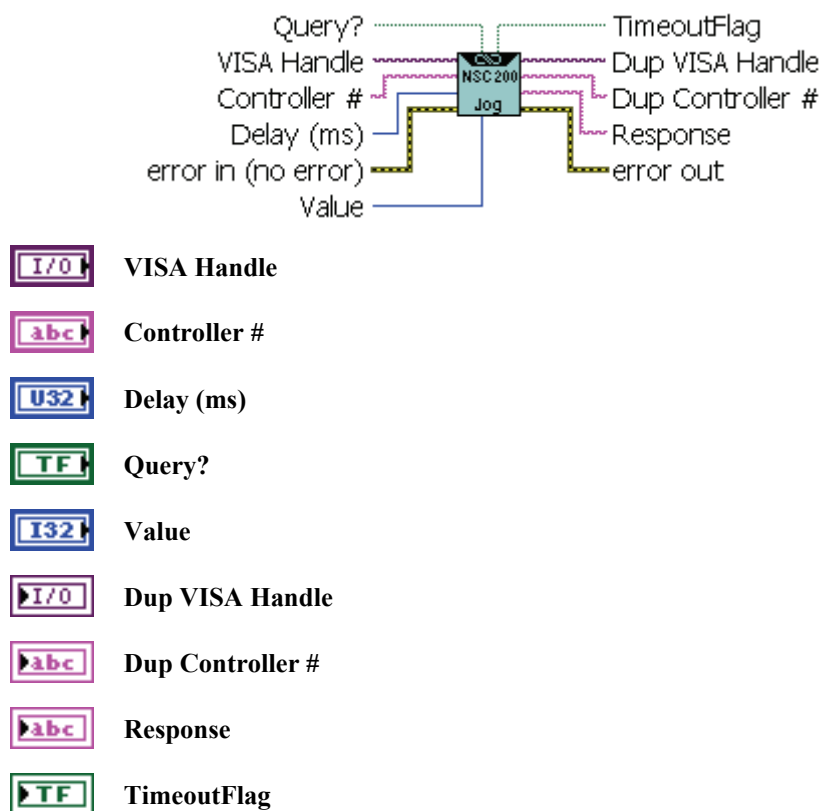
## 2.6 Motion, Absolute.vi



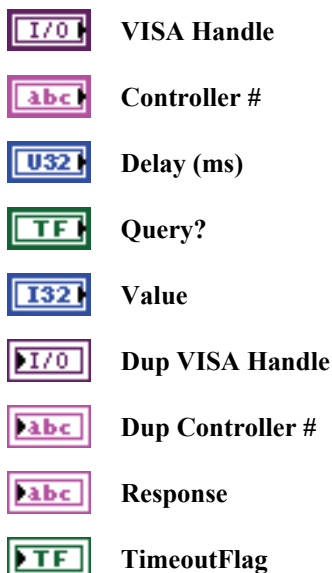
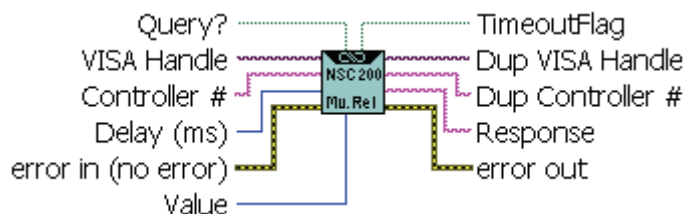
## 2.7 Motion, Home Search.vi



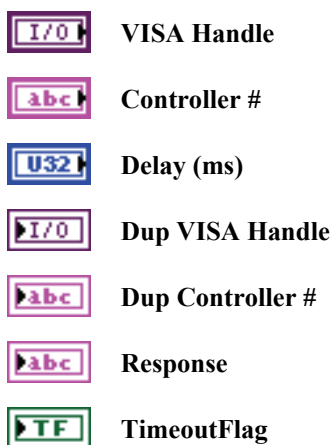
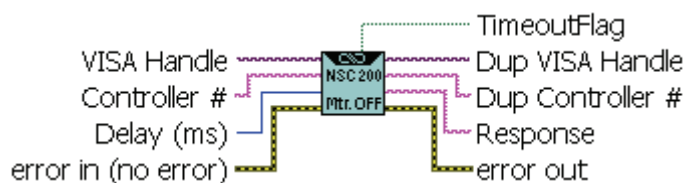
## 2.8 Motion, Jog.vi



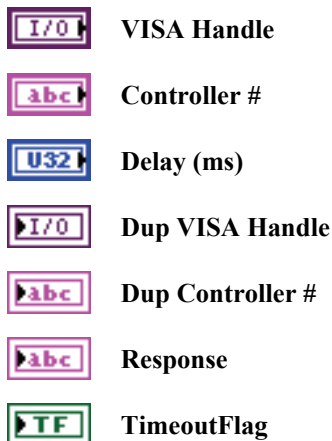
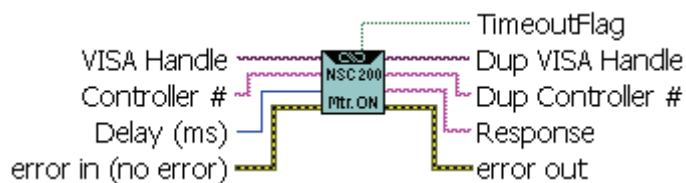
## 2.9 Motion, Relative.vi



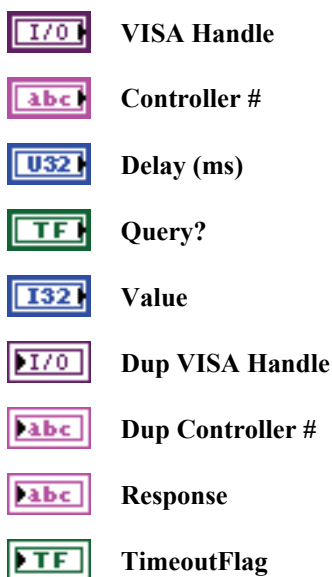
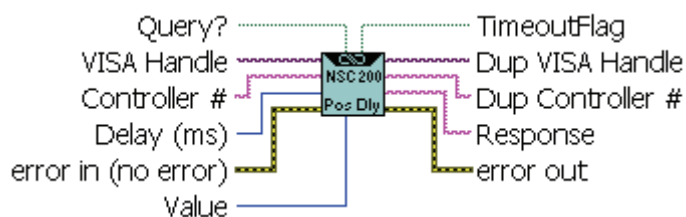
## 2.10 Motor OFF.vi



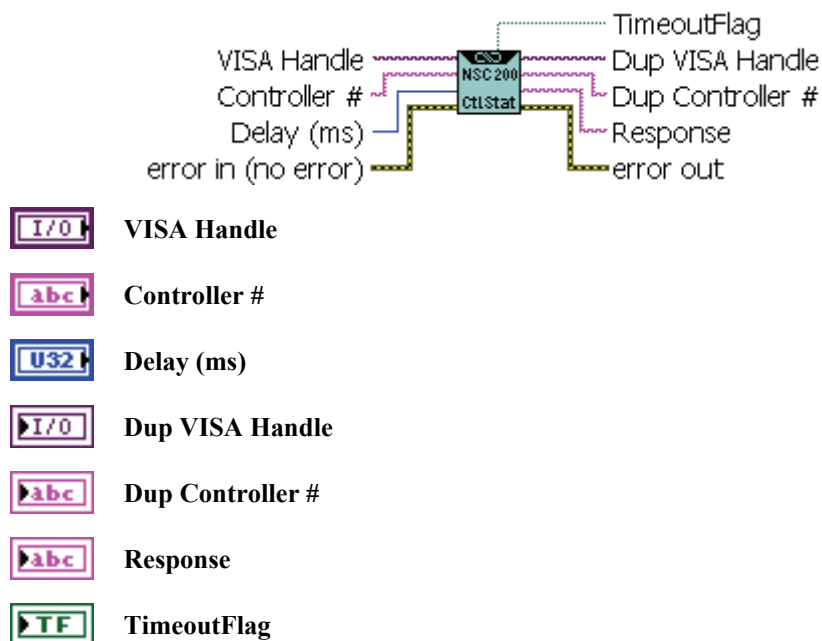
## 2.11 Motor ON.vi



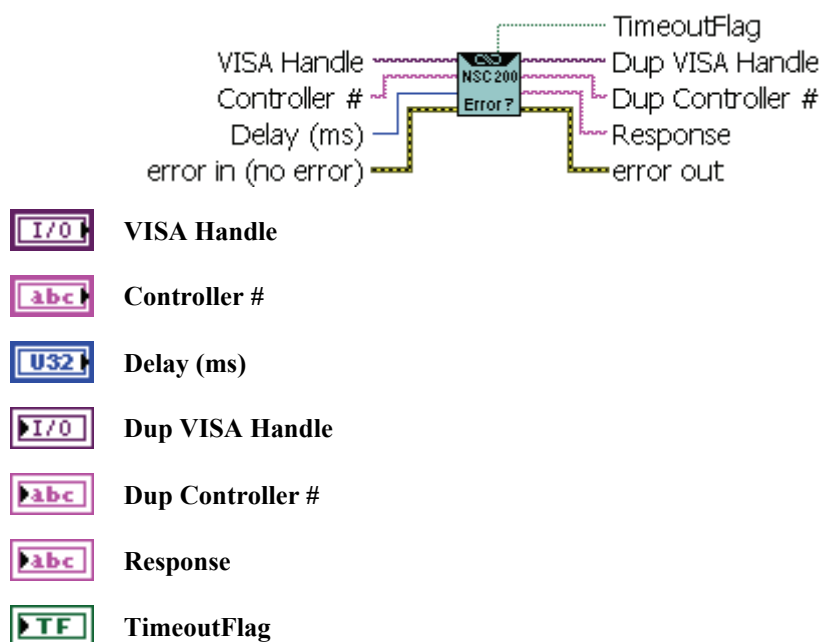
## 2.12 Position Delay in Knob Control.vi



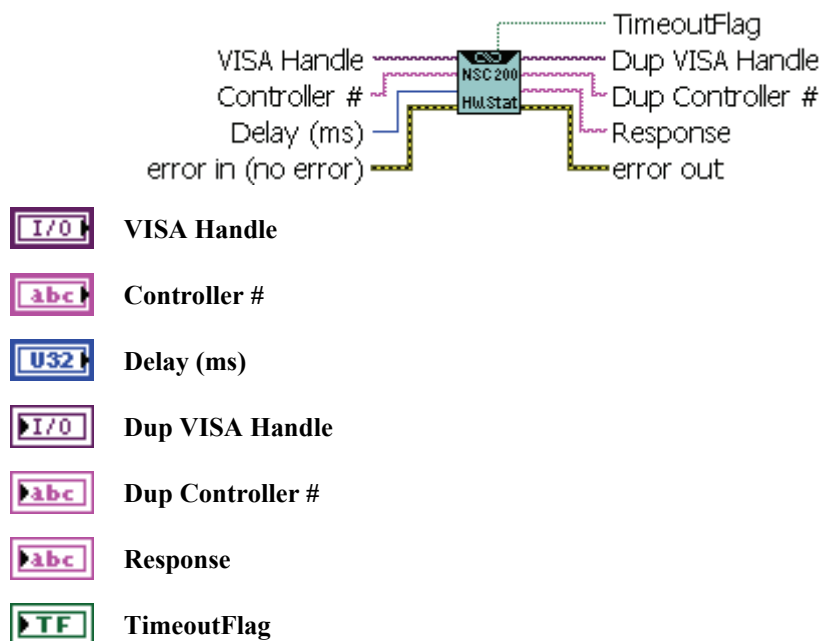
### 2.13 Read Controller Status.vi



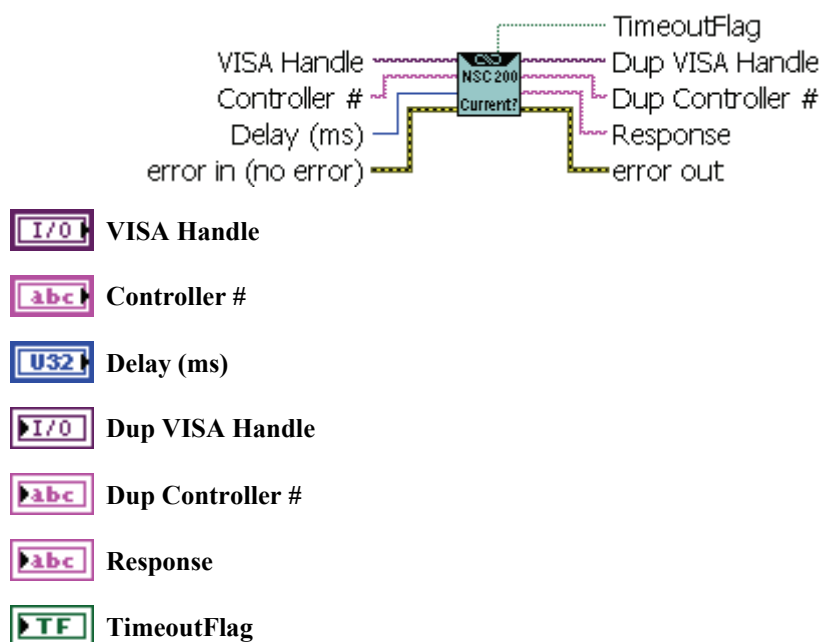
### 2.14 Read Error.vi



## 2.15 Read Hardware Status.vi

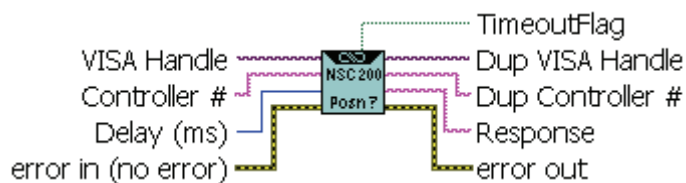


## 2.16 Read Motor Current.vi





## 2.17 Read Position.vi



 VISA Handle

 Controller #

 Delay (ms)

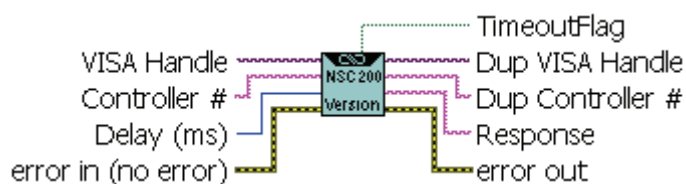
 Dup VISA Handle

 Dup Controller #

 Response

 TimeoutFlag

## 2.18 Read Version.vi



 VISA Handle

 Controller #

 Delay (ms)

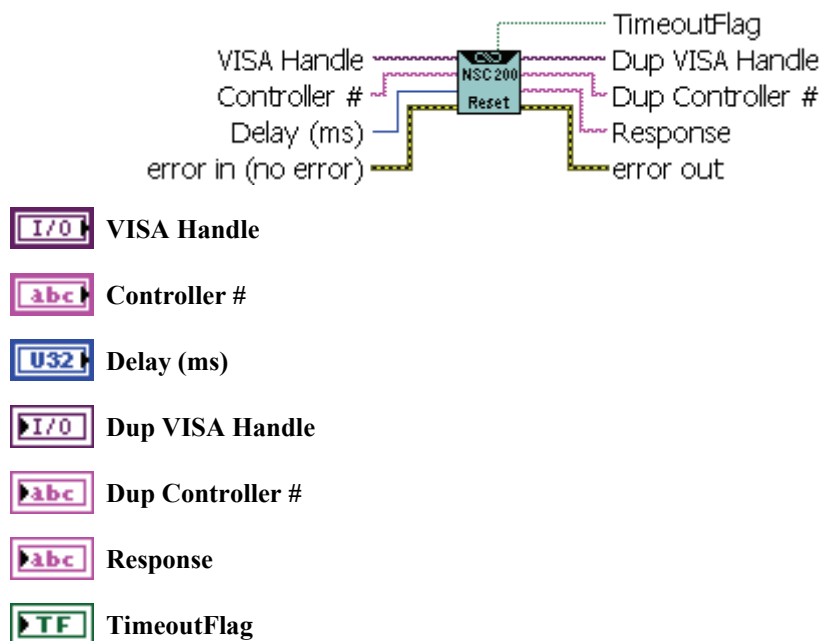
 Dup VISA Handle

 Dup Controller #

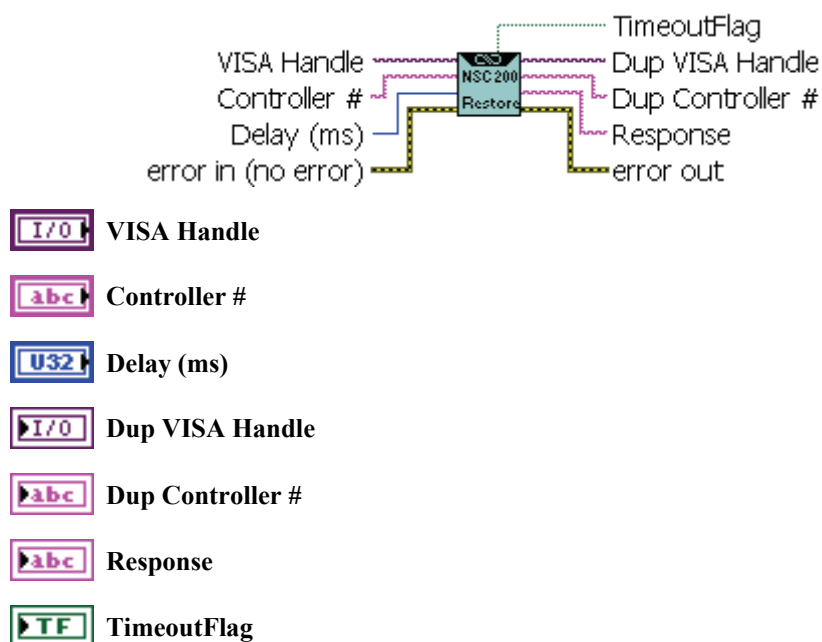
 Response

 TimeoutFlag

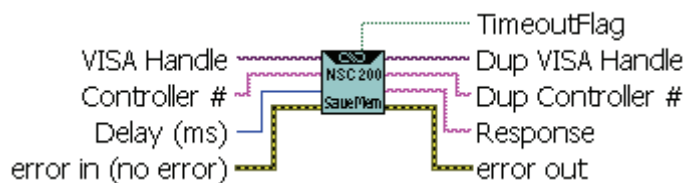
## 2.19 Reset Controller.vi



## 2.20 Restore EEPROM Content to Default.vi



## 2.21 Save Memory.vi



 VISA Handle

 Controller #

 Delay (ms)

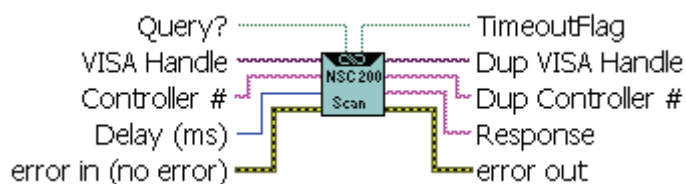
 Dup VISA Handle

 Dup Controller #

 Response

 TimeoutFlag

## 2.22 Scan Switchbox.vi



 VISA Handle

 Controller #

 Delay (ms)

 Query?

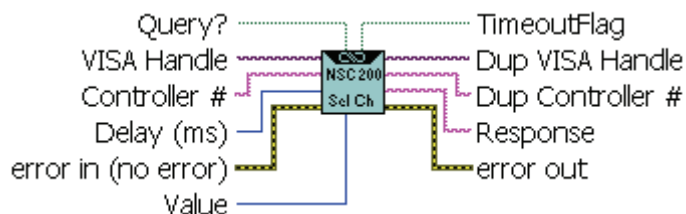
 Dup VISA Handle

 Dup Controller #

 Response

 TimeoutFlag

## 2.23 Select, Switch Box Channel.vi



 VISA Handle

 Controller #

 Delay (ms)

 Query?

 Value

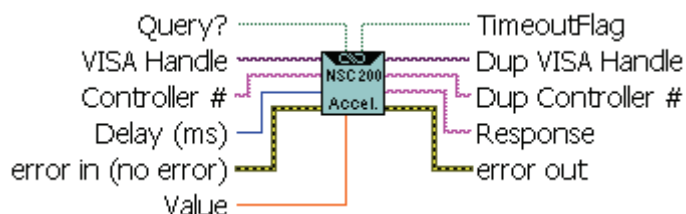
 Dup VISA Handle

 Dup Controller #

 Response

 TimeoutFlag

## 2.24 Set Acceleration.vi



 VISA Handle

 Controller #

 Delay (ms)

 Query?

 Value

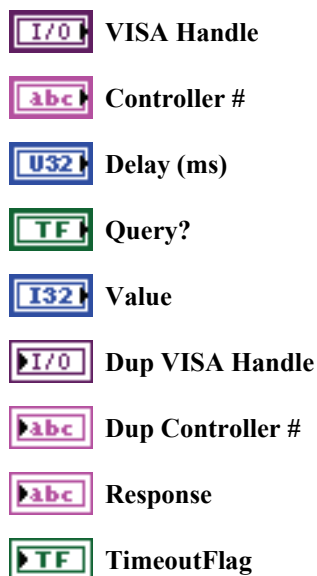
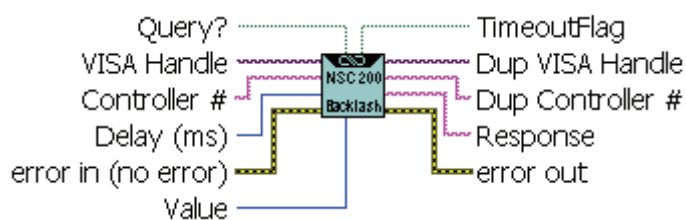
 Dup VISA Handle

 Dup Controller #

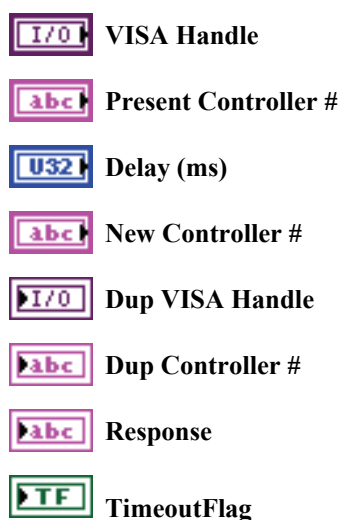
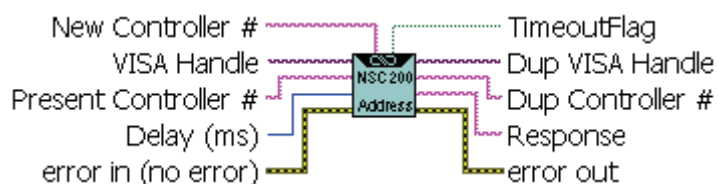
 Response

 TimeoutFlag

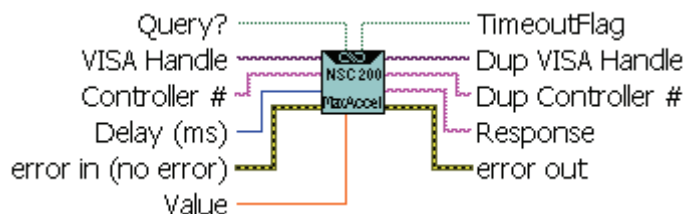
## 2.25 Set Backlash Compensation.vi



## 2.26 Set Controller Address.vi



## 2.27 Set Maximum Acceleration.vi



 VISA Handle

 Controller #

 Delay (ms)

 Query?

 Value

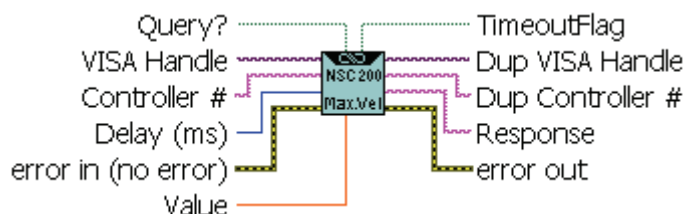
 Dup VISA Handle

 Dup Controller #

 Response

 TimeoutFlag

## 2.28 Set Maximum Velocity.vi



 VISA Handle

 Controller #

 Delay (ms)

 Query?

 Value

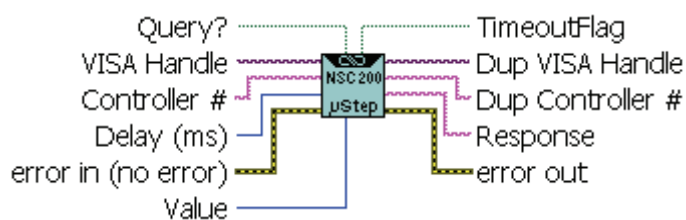
 Dup VISA Handle

 Dup Controller #

 Response

 TimeoutFlag

## 2.29 Set Microstep Factor.vi



 VISA Handle

 Controller #

 Delay (ms)

 Query?

 Value

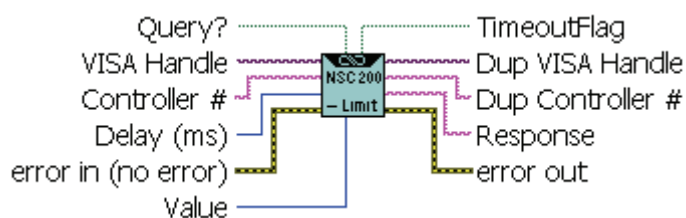
 Dup VISA Handle

 Dup Controller #

 Response

 TimeoutFlag

## 2.30 Set Negative Travel Limit.vi



 VISA Handle

 Controller #

 Delay (ms)

 Query?

 Value

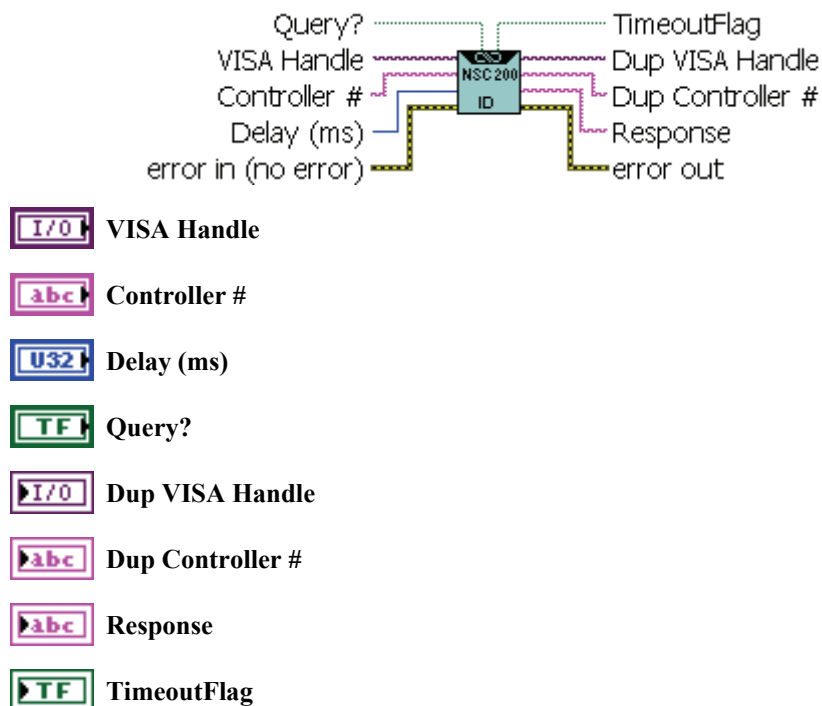
 Dup VISA Handle

 Dup Controller #

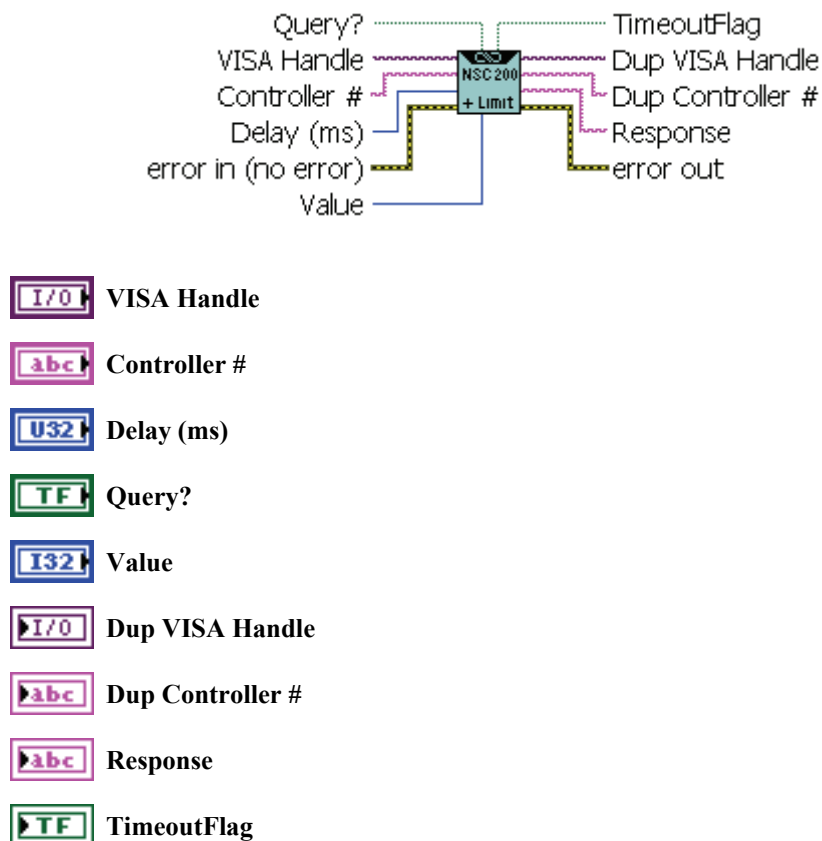
 Response

 TimeoutFlag

### 2.31 Set Positioner Identification.vi

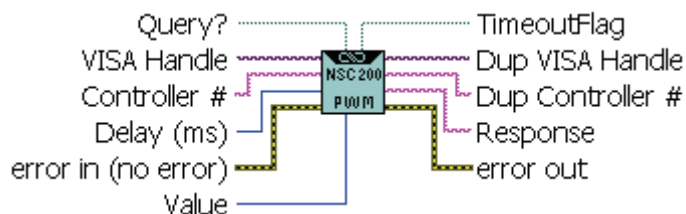











### 2.32 Set Positive Travel Limit.vi



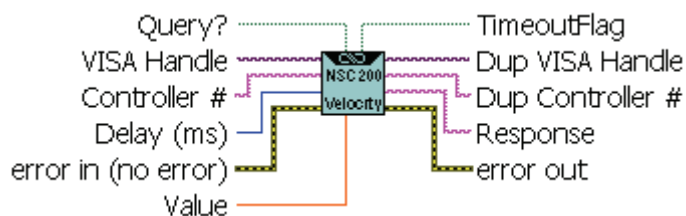











## 2.33 Set PWM Phase.vi



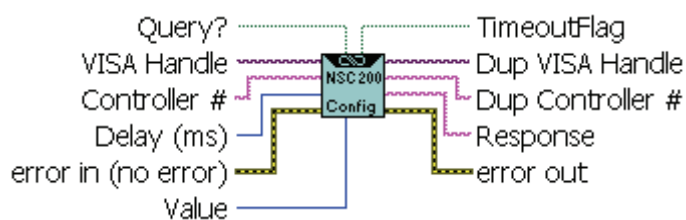
-  VISA Handle
-  Controller #
-  Delay (ms)
-  Query?
-  Value
-  Dup VISA Handle
-  Dup Controller #
-  Response
-  TimeoutFlag










## 2.34 Set Velocity.vi



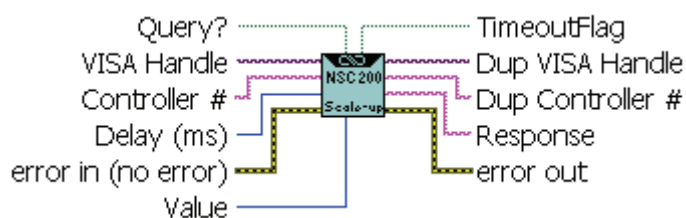
-  VISA Handle
-  Controller #
-  Delay (ms)
-  Query?
-  Value
-  Dup VISA Handle
-  Dup Controller #
-  Response
-  TimeoutFlag










### 2.35 Set, Hardware Configuration.vi



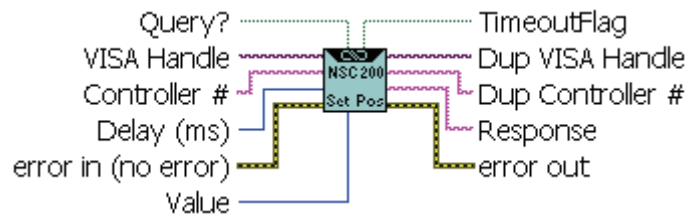
-  VISA Handle
-  Controller #
-  Delay (ms)
-  Query?
-  Value
-  Dup VISA Handle
-  Dup Controller #
-  Response
-  TimeoutFlag










### 2.36 Set, Jog Scale-up Factor.vi



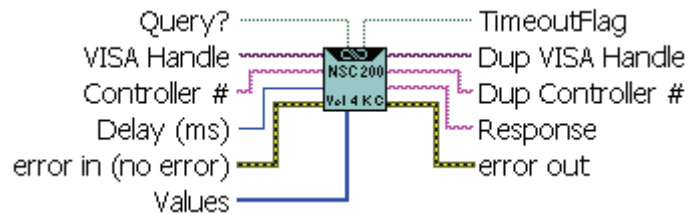
-  VISA Handle
-  Controller #
-  Delay (ms)
-  Query?
-  Value
-  Dup VISA Handle
-  Dup Controller #
-  Response
-  TimeoutFlag











### 2.37 Set, Position for Knob Control.vi



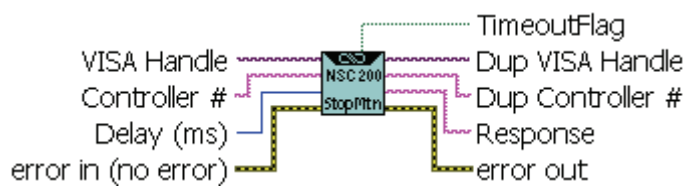
-  VISA Handle
-  Controller #
-  Delay (ms)
-  Query?
-  Value
-  Dup VISA Handle
-  Dup Controller #
-  Response
-  TimeoutFlag







### 2.38 Set, Velocities for Knob Control.vi



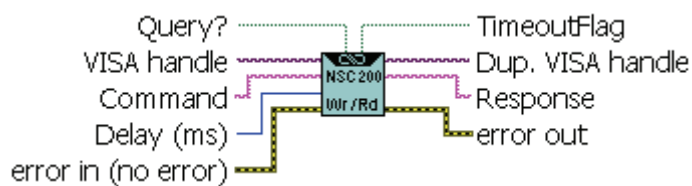
-  VISA Handle
-  Controller #
-  Delay (ms)
-  Query?
-  Values
-  Value n1
-  Dup VISA Handle
-  Dup Controller #
-  Response
-  TimeoutFlag








## 2.39 Stop Motion.vi



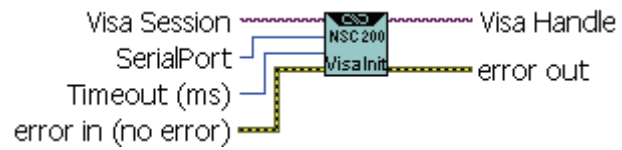
-  VISA Handle
-  Controller #
-  Delay (ms)
-  Dup VISA Handle
-  Dup Controller #
-  Response
-  TimeoutFlag

## 2.40 VisaCommWrapper.vi



-  VISA Handle
-  Controller #
-  Delay (ms)
-  Dup VISA Handle
-  Dup Controller #
-  Response
-  TimeoutFlag

## 2.41 VisaInit.vi



## 2.42 NSC200 VI Tree.vi



## 2.43 Sample Controller Init.vi



## 2.44 Sample Cycle Program.vi



## 2.45 Sample Simple Control.vi

### Controller Sample Cycle Program

- STOP button will stop sample
- MOVE button will perform relative move based on input value.

This sample program does the following:

- Initialize Controller
- Home Controller
- Convert Controller# to string and send with commands.
- Upon press of MOVE button, do a relative move for the distance specified (in counts)
- Read Position string
- Read Errors and display if found.

#### Inputs:

- Position 1 - Position to go to
  - Move Relative Distance - Relative move amount of micro steps
- NSC200 Visa Handle - Handle for RS232 port or virtual port for communication (see Control Panel -> Device Manager in Windows if unknown)
- Delay (2000 ms default) - How long before reading response
- Controller # - Index for controller to receive the communication.

#### Output:

- Num String - controller number.
- Error out - Any errors on device.

See VISACommWrapper.vi for other connection descriptions.



## Your Local Representative

Tel.: \_\_\_\_\_

Fax: \_\_\_\_\_

Name: \_\_\_\_\_

Company: \_\_\_\_\_

Address: \_\_\_\_\_

Country: \_\_\_\_\_

P.O. Number: \_\_\_\_\_

Item(s) Being Returned: \_\_\_\_\_

Model#: \_\_\_\_\_

Return authorization #: \_\_\_\_\_

(Please obtain prior to return of item)

Date: \_\_\_\_\_

Phone Number: \_\_\_\_\_

Fax Number: \_\_\_\_\_

Serial #: \_\_\_\_\_

Description: \_\_\_\_\_

Reasons of return of goods (please list any specific problems): \_\_\_\_\_

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Newport Corporation  
1791 Deere Ave.  
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e-mail: [sales@newport.com](mailto:sales@newport.com)

**Technical Support**

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9, rue du Bois Sauvage  
91055 Évry CEDEX  
France

**Sales**

Tel.: +33 (0)1.60.91.68.68  
e-mail: [france@newport.com](mailto:france@newport.com)

**Technical Support**

e-mail: [tech\\_europe@newport.com](mailto:tech_europe@newport.com)

**Service & Returns**

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