

₁ 1. Introduction

2. Hu-Washizu's formulation of complementary energy for thin shell

2.1. Kinematics for thin shell

$$\varepsilon_{\alpha\beta} = \frac{1}{2}(\mathbf{a}_\alpha \cdot \mathbf{v}_{,\beta} + \mathbf{a}_\beta \cdot \mathbf{v}_{,\alpha}) \quad (1)$$

$$\theta_{\mathbf{n}} = \mathbf{a}_3 \cdot \mathbf{v}_{,\alpha} n^\alpha \quad (2)$$

$$\kappa_{\alpha\beta} = (\Gamma_{\alpha\beta}^\gamma \mathbf{v}_{,\gamma} - \mathbf{v}_{,\alpha\beta}) \cdot \mathbf{a}_3 = -\mathbf{v}_{,\alpha}|_\beta \cdot \mathbf{a}_3 \quad (3)$$

$$\mathbf{t} = \mathbf{t}_N + \mathbf{t}_M \quad (4)$$

$$\mathbf{t}_N = \mathbf{a}_\alpha N^{\alpha\beta} n_\beta \quad (5)$$

$$\mathbf{t}_M = (\mathbf{a}_3 M^{\alpha\beta})|_\beta n_\alpha + (\mathbf{a}_3 M^{\alpha\beta} s_\alpha n_\beta)_{,\gamma} s^\gamma \quad (6)$$

$$M_{\mathbf{n}\mathbf{n}} = M^{\alpha\beta} n_\alpha n_\beta \quad (7)$$

$$\mathbf{b} = \mathbf{b}_N + \mathbf{b}_M \quad (8)$$

$$\mathbf{b}_N = (\mathbf{a}_\alpha N^{\alpha\beta})|_\beta \quad (9)$$

$$\mathbf{b}_M = (\mathbf{a}_3 M^{\alpha\beta})_{,\alpha}|_\beta \quad (10)$$

$$P = -[[M^{\alpha\beta} s_\alpha n_\beta]] \quad (11)$$

2.2. Galerkin weak form for Hu-Washizu principle of complementary energy

In accordance with the Hu-Washizu variational principle of complementary energy [1], the corresponding complementary functional, denoted by Π , is listed as follow:

$$\begin{aligned} & \Pi(\mathbf{v}, \varepsilon_{\alpha\beta}, \kappa_{\alpha\beta}, N^{\alpha\beta}, M^{\alpha\beta}) \\ &= \int_\Omega \frac{h}{2} \varepsilon_{\alpha\beta} C^{\alpha\beta\gamma\eta} \varepsilon_{\gamma\eta} d\Omega + \int_\Omega \frac{h^3}{24} \kappa_{\alpha\beta} C^{\alpha\beta\gamma\eta} \kappa_{\gamma\eta} d\Omega \\ &+ \int_\Omega \varepsilon_{\alpha\beta} (N^{\alpha\beta} - h C^{\alpha\beta\gamma\eta} \varepsilon_{\gamma\eta}) d\Omega + \int_\Omega \kappa_{\alpha\beta} (M^{\alpha\beta} - \frac{h^3}{12} C^{\alpha\beta\gamma\eta} \kappa_{\gamma\eta}) d\Omega \\ &- \int_{\Gamma_v} \mathbf{t} \cdot \bar{\mathbf{v}} d\Gamma + \int_{\Gamma_\theta} M_{\mathbf{n}\mathbf{n}} \bar{\theta}_{\mathbf{n}} d\Gamma - (P \mathbf{a}_3 \cdot \bar{\mathbf{v}})_{\mathbf{x} \in C_w} \\ &+ \int_{\Gamma_M} \theta_{\mathbf{n}} (M_{\mathbf{n}\mathbf{n}} - \bar{M}_{\mathbf{n}\mathbf{n}}) d\Gamma - \int_{\Gamma_t} \mathbf{v} \cdot (\mathbf{t} - \bar{\mathbf{t}}) d\Gamma - \mathbf{v} \cdot \mathbf{a}_3 (P - \bar{P})_{\mathbf{x} \in C_P} \\ &- \int_\Omega \mathbf{v} \cdot (\mathbf{b} - \bar{\mathbf{b}}) d\Omega \end{aligned} \quad (12)$$

8 Introducing a standard variational argument to Eq. (12), $\delta\Pi = 0$, and
 9 considering the arbitrariness of virtual variables, $\delta\mathbf{v}$, $\delta\varepsilon_{\alpha\beta}$, $\delta\kappa_{\alpha\beta}$, $N^{\alpha\beta}$, $M^{\alpha\beta}$
 10 lead to the following weak form:

$$-\int_{\Omega} h\delta\varepsilon_{\alpha\beta}C^{\alpha\beta\gamma\eta}\varepsilon_{\gamma\eta}d\Omega + \int_{\Omega} \delta\varepsilon_{\alpha\beta}N^{\alpha\beta}d\Omega = 0 \quad (13a)$$

$$-\int_{\Omega} \frac{h^3}{12}\delta\kappa_{\alpha\beta}C^{\alpha\beta\gamma\eta}\kappa_{\gamma\eta}d\Omega + \int_{\Omega} \delta\kappa_{\alpha\beta}M^{\alpha\beta}d\Omega = 0 \quad (13b)$$

$$\begin{aligned} \int_{\Omega} \delta N^{\alpha\beta}\varepsilon_{\alpha\beta}d\Omega - \int_{\Gamma} \delta\mathbf{t}_N \cdot \mathbf{v}d\Gamma + \int_{\Omega} \delta\mathbf{b}_N \cdot \mathbf{v}d\Omega \\ + \int_{\Gamma_v} \delta\mathbf{t}_N \cdot \mathbf{v}d\Gamma = \int_{\Gamma_v} \delta\mathbf{t}_N \cdot \bar{\mathbf{v}}d\Gamma \end{aligned} \quad (13c)$$

$$\begin{aligned} \int_{\Omega} \delta M^{\alpha\beta}\kappa_{\alpha\beta}d\Omega - \int_{\Gamma} \delta M_{nn}\theta_n d\Gamma + \int_{\Gamma} \delta\mathbf{t}_M \cdot \mathbf{v}d\Gamma + (\delta P\mathbf{a}_3 \cdot \mathbf{v})_{\mathbf{x} \in C} + \int_{\Omega} \delta\mathbf{b}_M \cdot \mathbf{v}d\Omega \\ + \int_{\Gamma_{\theta}} \delta M_{nn}\theta_n d\Gamma - \int_{\Gamma_v} \delta\mathbf{t}_M \cdot \mathbf{v}d\Gamma - (\delta P\mathbf{a}_3 \cdot \mathbf{v})_{\mathbf{x} \in C_v} \\ = \int_{\Gamma_{\theta}} \delta M_{nn}\bar{\theta}_n d\Gamma - \int_{\Gamma_v} \delta\mathbf{t}_M \cdot \bar{\mathbf{v}}d\Gamma - (\delta P\mathbf{a}_3 \cdot \bar{\mathbf{v}})_{\mathbf{x} \in C_v} \end{aligned} \quad (13d)$$

$$\begin{aligned} \int_{\Gamma} \delta\theta_n M_{nn}d\Gamma - \int_{\Gamma} \delta\mathbf{v} \cdot \mathbf{t}d\Gamma - (\delta\mathbf{v} \cdot \mathbf{a}_3 P)_{\mathbf{x} \in C} + \int_{\Omega} \delta\mathbf{v} \cdot \mathbf{b}d\Omega \\ - \int_{\Gamma_{\theta}} \delta\theta_n M_{nn}d\Gamma + \int_{\Gamma_v} \delta\mathbf{v} \cdot \mathbf{t}d\Gamma + (\delta\mathbf{v} \cdot \mathbf{a}_3 P)_{\mathbf{x} \in C_v} = - \int_{\Gamma_t} \delta\mathbf{v} \cdot \bar{\mathbf{t}}d\Gamma - \int_{\Omega} \delta\mathbf{v} \cdot \bar{\mathbf{b}}d\Omega \end{aligned} \quad (13e)$$

15 where the geometric relationships of Eq. () is used herein.

16 **3. Mixed meshfree formulation for modified Hellinger-Reissner weak** 17 **form**

18 *3.1. Reproducing kernel approximation for displacement*

19 In this study, the displacement is approximated by traditional reproducing
20 kernel approximation. As shown in Fig,

$$\mathbf{v}(\boldsymbol{\xi}) = \sum_{I=1}^{n_p} \Psi_I(\boldsymbol{\xi}) \mathbf{d}_I \quad (14)$$

21 *3.2. Reproducing kernel gradient smoothing approximation for effective stress* 22 *and strain*

23 In Galerkin meshfree formulation, the mid-plane of thin shell Ω is split by
24 a set of integration cells Ω_C 's, $\cup_{C=1}^{n_e} \Omega_C \approx \Omega$. With the inspiration of repro-
25 ducing kernel smoothing framework, the Cartesian and covariant derivatives of
26 displacement, $\mathbf{v}_{,\alpha}$ and $-\mathbf{v}_{,\alpha}|_{\beta}$, in strains $\varepsilon_{\alpha\beta}$, $\kappa_{\alpha\beta}$ are approximated by $(p-1)$ -th
27 order polynomials in each integration cells. The approximated derivatives and
28 strains denoted by $\mathbf{v}_{,\alpha}^h$, $\varepsilon_{\alpha\beta}$ and $-\mathbf{v}_{,\alpha}|_{\beta}$, $\kappa_{\alpha\beta}$ can be expressed by:

$$\mathbf{v}_{,\alpha}(\boldsymbol{\xi}) = \mathbf{q}^T(\boldsymbol{\xi}) \mathbf{d}_{\alpha}^{\varepsilon}, \quad \varepsilon_{\alpha\beta}(\boldsymbol{\xi}) = \mathbf{q}^T(\boldsymbol{\xi}) \frac{1}{2} (\mathbf{a}_{\alpha} \cdot \mathbf{d}_{\beta}^{\varepsilon} + \mathbf{a}_{\beta} \cdot \mathbf{d}_{\alpha}^{\varepsilon}) \quad (15)$$

$$-\mathbf{v}_{,\alpha}|_{\beta}(\boldsymbol{\xi}) = \mathbf{q}^T(\boldsymbol{\xi}) \mathbf{d}_{\alpha\beta}^{\kappa}, \quad \kappa^{\alpha\beta}(\boldsymbol{\xi}) = -\mathbf{q}^T(\boldsymbol{\xi}) \mathbf{a}_3 \cdot \mathbf{d}_{\alpha\beta}^{\kappa} \quad (16)$$

29 where \mathbf{q} is the $(p-1)$ th order polynomial vector and has the following form:

$$\mathbf{q} = \{1, \xi^1, \xi^2, \dots, (\xi^2)^{p-1}\}^T \quad (17)$$

30 and the

$$N^{\alpha\beta}(\mathbf{x}) = \mathbf{p}^T(\mathbf{x}) \mathbf{a}^{\alpha} \cdot \mathbf{d}_{\beta}^N, \quad \mathbf{a}_{\alpha} N^{\alpha\beta} = \mathbf{p}^T(\mathbf{x}) \mathbf{d}_{\beta}^N \quad (18)$$

$$M^{\alpha\beta}(\mathbf{x}) = \mathbf{p}^T(\mathbf{x}) \mathbf{a}_3 \cdot \mathbf{d}_{\alpha\beta}^M, \quad \mathbf{a}_3 M^{\alpha\beta} = \mathbf{p}^T(\mathbf{x}) \mathbf{d}_{\alpha\beta}^M \quad (19)$$

³² 4. Naturally variational enforcement for essential boundary condi-
³³ tions

34 **5. Numerical examples**

	Linear patch test		Quadratic patch test	
	L_2 -Error	H_e -Error	L_2 -Error	H_e -Error
35 GI-Penalty				
GI-Nitsche				
RKGSi-Penalty				
RKGSi-Nitsche				
RKGSi-HR				

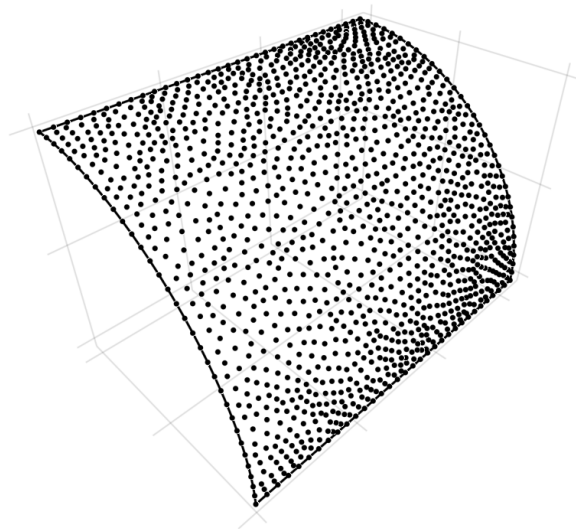


Figure 1: Meshfree discretization for patch test

³⁶ **References**

- ³⁷ [1] H. Dah-wei, A method for establishing generalized variational principle 6 (6)
³⁸ 501–509. doi:10.1007/BF01876390.
³⁹ URL <http://link.springer.com/10.1007/BF01876390>