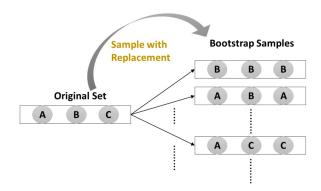
## **Ensemble Methods: Bagging**

One way to get diverse classifiers is to use very different training algorithms, as described in the ensemble method rationale. Another approach is to use the same training algorithm for every feature but to train them on different random subsets of the training set. This approach is called bagging (short for bootstrap (重複抽樣) aggregating) based on the bootstrap, a widely applicable and extremely powerful statistical tool.

The basic idea of **bootstrap** or **bootstrapping** is that inference about a population from sample data (sample  $\rightarrow$  population) can be modeled by resampling and performing inference about a sample from resampled data (resampled  $\rightarrow$  sample). In short, **bootstrap** resamples the data with replacement as illustrated in the figure below. When done properly, we will have:

sample  $\rightarrow$  population  $\approx$  resampled  $\rightarrow$  sample



## 1. Theoretical Minimum for Bagging

**Bagging** is a general-purpose procedure for <u>reducing the variance</u> of a statistical learning method. We <u>resample the data with replacement</u> and then train a classifier on the newly sampled data. Then, we combine the outputs of each of the individual classifiers using a majority-voting scheme or similar schemes.

Let us consider a given set of n independent (or uncorrelated) observations  $Z_1, Z_2, \dots, Z_n$ , each with variance  $\sigma^2$ . The variance of the mean  $\mathbb{V}ar\bar{Z}$  of the observations is given by  $\frac{\sigma^2}{n}$ . In other words, averaging a set of observations reduces variance.

Hence a natural way to reduce the variance and increase the prediction accuracy of a statistical learning method is to take <u>many training sets from the population</u>, build a separate prediction model using each

training set, and average the resulting predictions. In other words, we could calculate  $g^{(1)}(\mathbf{x})$ ,  $g^{(2)}(\mathbf{x})$ , ...,  $g^{(B)}(\mathbf{x})$  using **B** separate training sets, and average them to obtain a single low-variance statistical learning model,

$$g_{\text{avg}}(\mathbf{x}) = \frac{1}{B} \sum_{b=1}^{B} g^{(b)}(\mathbf{x})$$

**Remark:**  $g_{\text{avg}}(\mathbf{x}) \approx \bar{g}(\mathbf{x})$  as we discussed in the note on bias and variance.

Fun Time: Is this approach (to take <u>many training sets from the population</u>) practical? (1) Yes (2)

Instead, we can **bootstrap** by taking repeated samples from the single training data set. In this approach, we generate B different bootstrapped training data sets. We then train our method on the  $b^{th}$  bootstrapped training set to get  $g^{(*b)}(x)$ , and finally average all the predictions to obtain the bootstrapped aggregated estimator or bagged estimator:

$$g_{\text{bag}}(\mathbf{x}) = \frac{1}{B} \sum_{b=1}^{B} g^{(*b)}(\mathbf{x})$$

## Remarks:

- 1. It is important to remember that  $g_{\text{bag}}$  is not exactly equal to  $g_{\text{avg}}$ . Thus  $g_{\text{bag}}$  might perform worse than the original estimator g.
- 2. The bagging procedure can be further enhanced by introducing random forests, which will be discussed next.

## 2. Python Example

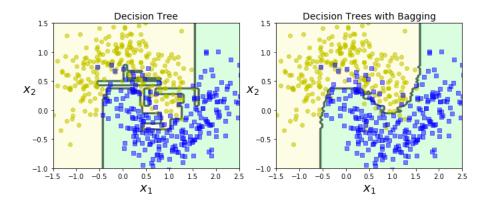
Scikit-Learn offers a simple API for bagging with the BaggingClassifier class (or BaggingRegressor for regression). The following code trains an ensemble of 500 Decision Tree classifiers, each trained on 100 training instances, randomly sampled from the 500 data generated from make\_moon with replacement. The n\_jobs parameter tells Scikit-Learn the number of CPU cores to use for training and predictions (-1 tells Scikit-Learn to use all available cores):

```
from sklearn.ensemble import BaggingClassifier
from sklearn.tree import DecisionTreeClassifier

bag_clf = BaggingClassifier(
    DecisionTreeClassifier(random_state=42), n_estimators=500,
    max samples=100, bootstrap=True, n jobs=-1, random state=42)
```

```
bag_clf.fit(X_train, y_train)
y pred = bag clf.predict(X test)
```

Figure below compares the decision boundary of a single Decision Tree with the decision boundary of a bagging ensemble of 500 trees (from the preceding code).



**Q**: what have you observed?

A:

As you can see, the decision boundary from the bagging ensemble is much smoother (low variance), and the ensemble's predictions will likely generalize much better than the single Decision Tree's predictions (0.904 vs 0.856).

You can download the complete source code Bagging.ipynb from the course website.